Spring Semester, 1999

G. Design Equations and Procedure for Beam-Columns (Braced Frame)

There is no *standard* set of design steps but the following procedure may be suggested.

Step 1: Design Load

Moments should be computed at both the top and bottom of the column. M_{ntx} and M_{nty} are the maximum design moments in the x- and y-axis of the member.

$$P_u = 1.2 P_D + 1.6 P_L$$

 $M_{ntx} = 1.2 M_{Dx} + 1.6 M_{Lx}$
 $M_{nty} = 1.2 M_{Dy} + 1.6 M_{Ly}$

Step 2: Initial Member Selection. (Equivalent Axial Load Method)

Beam-column design is a trial and error process in which a trial section is checked for compliance with the AISC interaction equations (H1-1a) and (H1-1b). Initial guess of the member is made by using AISC Table 3-2 and the Column Tables. AISC/LRFD Specification (H1-a) can be rewritten, by multiplying each term by ϕP_n , as

$$P_u + rac{8\phi P_n}{9\phi_b M_{nx}}M_{ux} + rac{8\phi P_n}{9\phi_b M_{ny}}M_{uy} \leq \phi P_n$$

or at the limit state,

$$P_u + \frac{8\phi P_n}{9\phi_b M_{nx}} M_{ux} + \frac{8\phi P_n}{9\phi_b M_{ny}} M_{uy} = \phi P_n$$

Multiplication of the third term by M_{nx}/M_{nx} and letting

$$m = \frac{8\phi P_n}{9\phi_b M_{nx}}$$
 and $u = \frac{M_{nx}}{M_{ny}}$

the equivalent load (P_{ueq}) is obtained

$$P_u + mM_{ux} + muM_{uy} = \phi P_n = P_{ueq}$$

where the values m (bending factor) are found in the AISC Table 3-2 and u are obtained by guessing from the Column Tables.

Step 3: Check member.

(a) **Column Effect:** Calculate the axial strength = $\phi_c P_n$. It is useful to compute the slenderness parameter λ_c for both the *x*- and *y*-axis for steps (d) and (e):

$$egin{aligned} \lambda_{cx} &= rac{K_x L_x}{r_x} \sqrt{rac{F_y}{\pi^2 E}} \ \lambda_{cy} &= rac{K_y L_y}{r_y} \sqrt{rac{F_y}{\pi^2 E}} \end{aligned}$$

- (b) **Beam Effect** (*x*-direction): Calculate the bending design strength = $\phi_b M_{nx}$ for the *x*-axis. Check both LB and LTB.
- (c) **Beam Effect** (y-direction): Calculate the bending design strength = $\phi_b M_{ny}$ for the y-axis. This analysis is similar to step (b) except that y-axis properties (S_y and Z_y) are used. Consider only LB in the flange since there will be no LTB in the y-axis.
- (d) **Moment Magnification** (*x*-axis direction): Calculate C_{mx} for the *x*-axis moments using:

$$C_{mx} = 0.6 - 0.4 \left(\frac{M_1}{M_2}\right)_x \tag{H1-4}$$

Here, M_1 and M_2 are the end moments with the condition $|M_1| \le |M_2|$ and the sign of the value M_1/M_2 is:

$$(M_1/M_2)_x > 0$$
 for reverse curvature
 $(M_1/M_2)_x \le 0$ for single curvature

Calculate B_{1x} for the x-axis using the formula:

$$B_{1x} = \frac{C_{mx}}{1 - P_u / P_{e1x}} \ge 1 \tag{H1-3}$$

The Euler buckling load, P_{e1x} , is calculated using the x-axis properties regardless of which axis is weaker:

$$P_{e1x} = \frac{\pi^2 E A_g}{K_x L_x} = \frac{F_y A_g}{\lambda_{cx}^2}$$

(e) **Moment Magnification** (*y*-axis direction): Repeat step (d) for the *y*-axis using the formulas:

$$C_{my} = 0.6 - 0.4 \left(\frac{M_1}{M_2}\right)_y \tag{H1-4}$$

$$B_{1y} = \frac{C_{my}}{1 - P_u/P_{e1y}} \ge 1 \tag{H1-3}$$

The Euler buckling load, P_{e1y} , is calculated using the *y*-axis properties regardless of which axis is weaker:

$$P_{e1y} = \frac{\pi^2 E A_g}{K_y L_y} = \frac{F_y A_g}{\lambda_{cy}^2}$$

(f) Interaction:

If $P_u/\phi_c P_n \ge 0.2$ then

$$\frac{P_u}{\phi_c P_n} + \frac{8}{9} \left(\frac{M_{ux}}{\phi_b M_{nx}} + \frac{M_{uy}}{\phi_b M_{ny}} \right) = \text{interaction ratio} \le 1$$
(H1-1a)

If
$$P_u/\phi_c P_n < 0.2$$
 then

$$\frac{P_u}{2\phi_c P_n} + \left(\frac{M_{ux}}{\phi_b M_{nx}} + \frac{M_{uy}}{\phi_b M_{ny}}\right) = \text{interaction ratio} \le 1$$
(H1-1a)

(g) **Redesign:** If the interaction ratio falls in the range between 0.95 and 1.0, then no redesign may be necessary. Otherwise, it is necessary to check a new section using the general formula:

New Weight = Old Weight
$$\times \frac{\text{Load}}{\text{Capacity}} = \text{Old Weight} \times \text{Interaction}$$