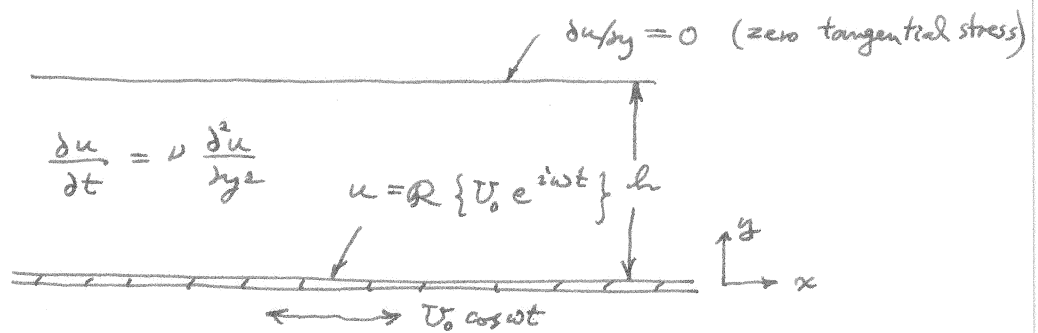


Take-Home Exam; Solutions

Wednesday, May 14, 2014

Problem 1

By symmetry, $\underline{q} = u(y,t) \underline{e}_x$



Solve by letting $u = \mathcal{R} \{ f(y) e^{i\omega t} \}$,

where $f(y)$ satisfies: $\frac{d^2 f}{dy^2} - \frac{i\omega}{\nu} f = 0$ ($0 < y < h$)

$$\left. \begin{aligned} f(0) &= U_0 \\ \frac{df}{dy}(h) &= 0 \end{aligned} \right\}$$

f is a linear combination of $\exp \left\{ \pm \frac{(1+i)}{\sqrt{2}} \sqrt{\frac{\omega}{\nu}} y \right\}$

In compact form,

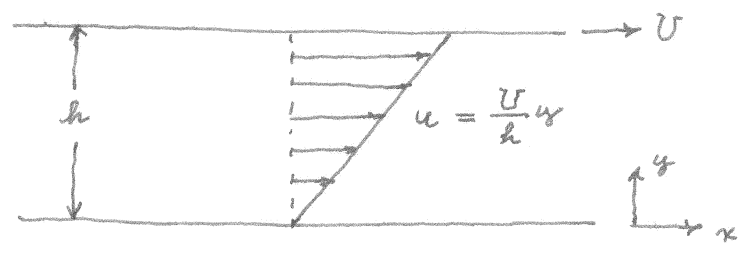
$$f = U_0 \frac{\cosh k(y-h)}{\cosh kh}, \quad k = \frac{1+i}{\sqrt{2}} \sqrt{\frac{\omega}{\nu}}$$

$$\Rightarrow u = \mathcal{R} \left\{ U_0 \frac{\cosh k(y-h)}{\cosh kh} e^{i\omega t} \right\}$$

As $\underline{wh^2/\nu} \gg 1$ ($|kh| \gg 1$): the motion is confined in (thin) Stokes layer $O((\nu/\omega)^{1/2})$ close to the plate

$\underline{wh^2/\nu} \ll 1$ ($|kh| \ll 1$): $\cosh k(y-h) \sim \cosh kh \sim 1$
the fluid oscillates with the plate, essentially as a rigid body

Problem 2



In general, the dye concentration is governed by the convection - diffusion equation:

$$\frac{\partial C}{\partial t} + \frac{\partial}{\partial x} (u C) = D \left(\frac{\partial^2 C}{\partial x^2} + \frac{\partial^2 C}{\partial y^2} \right)$$

For $t \gg h^2/D$, we expect the horizontal extent $= O(L)$ of C to be much larger than h : $h/L = \epsilon \ll 1$

Non-dimensionalize: $x \rightarrow Lx, y \rightarrow hy, u \rightarrow Uu, t \rightarrow \frac{L}{U} t$

$$\Rightarrow \left. \begin{aligned} \epsilon Pe \left(\frac{\partial C}{\partial t} + \frac{\partial}{\partial x} (u C) \right) &= \frac{\partial^2 C}{\partial y^2} + \epsilon^2 \frac{\partial^2 C}{\partial x^2} \\ \frac{\partial C}{\partial y} &= 0 \quad (y=0,1) \end{aligned} \right\}$$

where $u = y$ and $Pe = \frac{Uh}{D}$ is assumed $O(1)$

To investigate the long-time evolution of C we use multiple-time-scale analysis

$$t_{\text{lat. diff.}} \sim \frac{h^2}{D} \Rightarrow \underline{\tau = t/\epsilon}, \quad t_{\text{long diff.}} \sim \frac{L^2}{D} \Rightarrow \underline{T = \epsilon t}$$

$$C(x, y, t) \Rightarrow C(x, y; \tau, t, T)$$

$$\frac{\partial}{\partial t} \rightarrow \frac{1}{\epsilon} \frac{\partial}{\partial \tau} + \frac{\partial}{\partial t} + \epsilon \frac{\partial}{\partial T}$$

Therefore, C satisfies

$$\left. \begin{aligned} Pe \frac{\partial C}{\partial z} + \epsilon Pe \left(\frac{\partial C}{\partial t} + u(y) \frac{\partial C}{\partial x} \right) + \epsilon^2 Pe \frac{\partial C}{\partial t} \\ = \frac{\partial^2 C}{\partial y^2} + \epsilon^2 \frac{\partial C}{\partial x^2} \\ \frac{\partial C}{\partial y} = 0 \quad (y=0,1) \end{aligned} \right\}$$

and IC: $C = C_0 \quad (z=0)$

$$\underline{O(1)}: \left. \begin{aligned} Pe \frac{\partial C}{\partial z} &= \frac{\partial^2 C}{\partial y^2} \\ \frac{\partial C}{\partial y} &= 0 \quad (y=0,1) \\ C &= C_0 \quad (z=0) \end{aligned} \right\} \begin{array}{l} \text{Lateral diffusion only} \\ \text{(May solve by} \\ \text{separation of variables)} \end{array}$$

As $z \gg 1$ (ie, $t_{dim} \gg h^2/D \sim h^2/U$), $C \rightarrow \underline{\underline{C_1(x; t, T)}}$

Expand: $C = C_1(x; t, T) + \epsilon C_2(x, y; t, T) + \epsilon^2 C_3 + \dots$

$$\underline{O(\epsilon)}: \left. \begin{aligned} \frac{\partial^2 C_2}{\partial y^2} &= Pe \left(\frac{\partial C_1}{\partial t} + u(y) \frac{\partial C_1}{\partial x} \right) \\ \frac{\partial C_2}{\partial y} &= 0 \quad (y=0,1) \end{aligned} \right\}$$

To ensure that this forced BVP has solution, the RHS must satisfy the solvability condition:

$$\int_0^1 (\text{RHS}) dy = 0 \Rightarrow \frac{\partial C_1}{\partial t} + \langle u \rangle \frac{\partial C_1}{\partial x} = 0$$

$$\Rightarrow \underline{\underline{C_1 = C_1(\xi; T), \quad \xi = x - \langle u \rangle t}}$$

where $\langle u \rangle = \int_0^1 u dy = \int_0^1 y dy = \frac{1}{2}$

May now solve for $C_2(x, y; t, T)$:

$$\frac{\partial^2 C_2}{\partial y^2} = \text{Pe} \left(\frac{\partial C_1}{\partial t} + u(y) \frac{\partial C_1}{\partial x} \right) = \text{Pe} \tilde{u}(y) \frac{\partial C_1}{\partial \xi}$$

$$-\langle u \rangle \frac{\partial C_1}{\partial x} = -\frac{1}{2} \frac{\partial C_1}{\partial \xi} \quad (\tilde{u} = y - \frac{1}{2})$$

$\therefore C_2 = \text{Pe} \frac{\partial C_1}{\partial \xi} B(y)$, where $B(y)$ satisfies

$$\left. \begin{aligned} \frac{d^2 B}{dy^2} &= y - \frac{1}{2} \\ \frac{dB}{dy} &= 0 \quad (y=0,1) \end{aligned} \right\} \Rightarrow B(y) = \frac{y^3}{6} - \frac{y^2}{4} + \frac{1}{24}$$

$$\text{s.t. } \langle B \rangle = 0 \Rightarrow \langle C \rangle = C_1$$

$$\text{i.e., } C_2 = \text{Pe} \frac{\partial C_1}{\partial \xi} \frac{(4y^3 - 6y^2 + 1)}{24}$$

$O(\epsilon^2)$:

$$\frac{\partial^2 C_3}{\partial y^2} = \text{Pe} \frac{\partial C_1}{\partial T} - \frac{\partial^2 C_1}{\partial \xi^2} + \text{Pe} \left(\frac{\partial C_2}{\partial t} + u(y) \frac{\partial C_2}{\partial x} \right) - \text{Pe} \langle u \rangle \frac{\partial^2 C_1}{\partial \xi^2} B(y)$$

$$\Rightarrow \left. \begin{aligned} \frac{\partial^2 C_3}{\partial y^2} &= \text{Pe} \frac{\partial C_1}{\partial T} - \left(1 - \text{Pe}^2 \tilde{u}(y) B(y) \right) \frac{\partial^2 C_1}{\partial \xi^2} \\ \frac{\partial C_3}{\partial y} &= 0 \quad (y=0,1) \end{aligned} \right\}$$

Again, applying solvability condition,

$$\int_0^1 dy \text{ RHS} = 0 \Rightarrow \text{Pe} \frac{\partial C_1}{\partial T} = E \frac{\partial^2 C_1}{\partial \xi^2},$$

where

$$E = 1 - \text{Pe}^2 \langle \tilde{u} B \rangle$$

$$\langle \tilde{u} B \rangle = \int_0^1 dy \left(y - \frac{1}{2} \right) \left(\frac{y^3}{6} - \frac{y^2}{4} + \frac{1}{24} \right) = -\frac{1}{120}$$

Finally, for plane Couette flow,

$$\left(\begin{array}{c} \text{effective} \\ \text{diffusivity} \end{array} \right) \quad \underline{E = 1 + \frac{Pe^2}{120}} \quad (\text{in dimensionless form})$$

or, in dimensional variables, $C_1 = \langle C \rangle$

satisfies

$$\frac{\partial}{\partial t} \langle C \rangle + \langle u \rangle \frac{\partial \langle C \rangle}{\partial x} = DE \frac{\partial^2 \langle C \rangle}{\partial x^2}$$

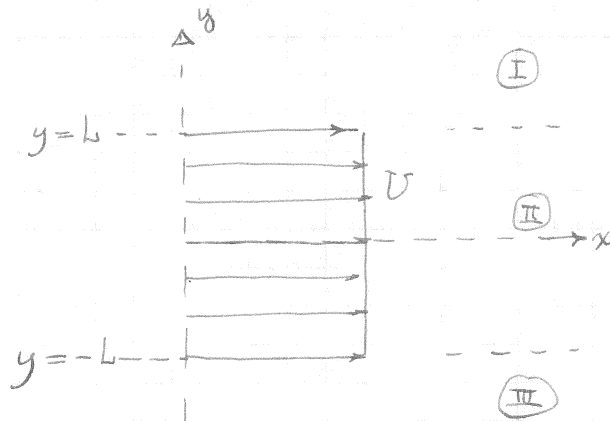
where

$$\underline{DE = \underbrace{D}_{\text{molecular}} + \underbrace{\frac{1}{120} \frac{U^2 h^2}{D}}_{\text{due to shear}}} \quad \underline{\text{effective diffusivity}}$$

For $t_{\text{dim}} \gg h/U \sim h^2/D$,

The depth-averaged concentration $\langle C \rangle$ will translate (convect) with the average flow speed $\frac{1}{2}U = \langle u \rangle$ and diffuse in streamwise direction with $D_{\text{eff}} = D + \frac{1}{120} \frac{U^2 h^2}{D}$

Problem 3 Stability of 'top-hat' jet profile



For 2-D inviscid perturbations, streamfunction

$$\Psi = f(y) e^{iR(x-ct)}$$

where $f(y)$ satisfies the Rayleigh equation:

$$(U(y)-c) \left\{ \frac{d^2 f}{dy^2} - R^2 f \right\} - \frac{d^2 U}{dy^2} f = 0$$

Divide the flow into 3 regions:

$$\text{(I)} : \frac{d^2 f}{dy^2} - R^2 f = 0 \Rightarrow f = C_I e^{-|R|y} \quad (f \rightarrow 0, y \rightarrow \infty)$$

$$\text{(II)} : \frac{d^2 f}{dy^2} - R^2 f = 0 \Rightarrow f = C_{II}^S \sinh ky + C_{II}^C \cosh ky$$

$$\text{(III)} : \frac{d^2 f}{dy^2} - R^2 f = 0 \Rightarrow f = C_{III} e^{+|R|y} \quad (f \rightarrow 0, y \rightarrow -\infty)$$

At the 'interface' $y=L$ kinematic $\Rightarrow \left[\frac{f}{U-c} \right]_{y=L^-}^{y=L^+} = 0$

$$\Rightarrow \frac{C_I e^{-|R|L}}{-c} = \frac{1}{(U-c)} \left\{ C_{II}^S \sinh kL + C_{II}^C \cosh kL \right\}$$

Dynamic (pressure) $\Rightarrow \left[(U-c) \frac{df}{dy} - \frac{dU}{dy} f \right]_{y=L^-}^{y=L^+} = 0$

$$\Rightarrow c|k| C_I e^{-|R|L} = (U-c)k \left\{ C_{II}^S \cosh kL + C_{II}^C \sinh kL \right\}$$

Similarly, at the 'interface' $y=L$:

$$\text{kinematic} \Rightarrow \left\{ -C_{II}^S \sinh kL + C_{II}^C \cosh kL \right\} \frac{1}{U-c} = \frac{C_{III} e^{-|k|L}}{-c}$$

$$\text{dynamic} \Rightarrow (U-c)k \left\{ C_{II}^S \cosh kL - C_{II}^C \sinh kL \right\} = -c|k| C_{III} e^{-|k|L}$$

Therefore, $C_I, C_{II}^S, C_{II}^C, C_{III}$ satisfy the linear homogeneous system:

$$\begin{bmatrix} \frac{(U-c)}{c} e^{-|k|L} & \sinh kL & \cosh kL & 0 \\ -c|k| e^{-|k|L} & (U-c)k \cosh kL & (U-c)k \sinh kL & 0 \\ 0 & -\sinh kL & \cosh kL & \frac{(U-c)}{c} e^{-|k|L} \\ 0 & (U-c)k \cosh kL & -(U-c)k \sinh kL & c|k| e^{-|k|L} \end{bmatrix} \begin{Bmatrix} C_I \\ C_{II}^S \\ C_{II}^C \\ C_{III} \end{Bmatrix} = 0$$

May divide disturbances into

$$(i) \text{ symmetric: } C_{II}^S = 0, C_I = C_{III}$$

These satisfy

$$\begin{bmatrix} \frac{(U-c)}{c} e^{-|k|L} & \cosh kL \\ -c|k| e^{-|k|L} & (U-c)k \sinh kL \end{bmatrix} \begin{Bmatrix} C_I \\ C_{II}^C \end{Bmatrix} = 0$$

$$\Rightarrow \underline{(U-c)^2 \sinh |k|L + c^2 \cosh kL = 0}$$

Since both terms are positive for c real, for this equation to be satisfied, c has to be complex \Rightarrow unstable for all k

(ii) antisymmetric: $C_{II}^c = 0$, $C_I = -C_{III}$

These satisfy

$$\begin{bmatrix} \frac{U-c}{c} e^{-|k|L} & \sinh kL \\ -c|k| e^{-|k|L} & (U-c)k \cosh kL \end{bmatrix} \begin{Bmatrix} C_I \\ C_{III}^s \end{Bmatrix} = 0$$

$$\Rightarrow \underline{\underline{(U-c)^2 \cosh kL + c^2 \sinh |k|L = 0}}$$

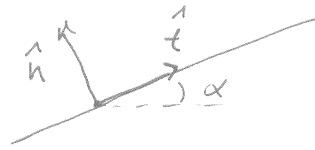
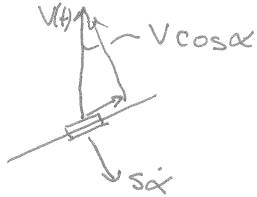
Again, for this equation to be satisfied (for k real),
 c has to be complex \Rightarrow instability for all k

$$\alpha(t) = \alpha_0 \cos(\omega t)$$

$$x(t) = \frac{L_0}{2} [1 + \sin(\omega t)]$$

$$\dot{\alpha} = -\omega \alpha_0 \sin(\omega t)$$

$$\dot{x} = \frac{L_0 \omega}{2} \cos(\omega t)$$



$$\hat{t} = \cos \alpha \hat{x} + \sin \alpha \hat{y}$$

$$\hat{n} = -\sin \alpha \hat{x} + \cos \alpha \hat{y}$$

$$d\underline{F} = -C_{\perp} \dot{\alpha} \hat{n} ds - C_{\perp} V \cos \alpha \hat{n} ds - C_{\parallel} V \sin \alpha \hat{t} ds$$

$$\underline{F} = -C_{\perp} \frac{L_0^2}{2} \dot{\alpha} \hat{n} - C_{\perp} V \cos \alpha L_0 \hat{n} - C_{\parallel} V \sin \alpha L_0 \hat{t}$$

$$= - \left(C_{\perp} \frac{L_0^2}{2} \dot{\alpha} + C_{\perp} V \cos \alpha L_0 \right) (-\sin \alpha \hat{x} + \cos \alpha \hat{y})$$

$$- C_{\parallel} V \sin \alpha L_0 (\cos \alpha \hat{x} + \sin \alpha \hat{y})$$

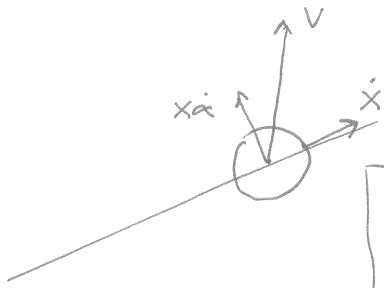
$F_x = 0$ by symmetry

$$F_y = 0 = - \left(C_{\perp} \frac{L_0^2}{2} \dot{\alpha} + C_{\perp} V \cos \alpha L_0 \right) \cos \alpha - C_{\parallel} V \sin \alpha L_0 \sin \alpha$$

$$\Rightarrow V = \frac{-C_{\perp} \frac{L_0^2}{2} \dot{\alpha}}{C_{\perp} \cos^2 \alpha L_0} = \omega \alpha_0 \sin(\omega t) \frac{L_0}{2}$$

$$\boxed{\underline{V} = 0}$$

(2)



$$\underline{V}_{\text{sphere}} = V(t)\hat{y} + \dot{x}\hat{t} + x\ddot{\alpha}\hat{n}$$

To find $V(t)$:

$$\underline{V}_{\text{sphere}} = V(t)\hat{y} + \dot{x}(\cos\alpha\hat{x} + \sin\alpha\hat{y}) + x\ddot{\alpha}(-\sin\alpha\hat{x} + \cos\alpha\hat{y})$$

$$\begin{aligned} F_y = 0 &= -\left(C_{\perp}\frac{L_0^2}{2}\ddot{\alpha} + C_{\perp}V\cos\alpha L_0\right)\cos\alpha - C_{\parallel}V\sin^2\alpha L_0 - 6\pi\mu R \underline{V}_{\text{sphere}} \cdot \hat{y} \\ &= -C_{\perp}\frac{L_0^2}{2}\ddot{\alpha} - C_{\perp}VL_0\left(1 - \frac{\alpha^2}{2}\right)^2 - C_{\parallel}V\alpha^2 L_0 \\ &\quad - 6\pi\mu R(V + \dot{x}\alpha + x\ddot{\alpha}) \end{aligned}$$

$$V(t) \left[C_{\perp}L_0(1 - \alpha^2) + C_{\parallel}\alpha^2 L_0 + 6\pi\mu R \right] = -C_{\perp}\frac{L_0^2}{2}\ddot{\alpha} - 6\pi\mu R(\dot{x}\alpha + x\ddot{\alpha})$$

$$V(t) = \frac{-C_{\perp}\frac{L_0^2}{2}\ddot{\alpha} - \frac{6\pi\mu R}{C_{\perp}}(\dot{x}\alpha + x\ddot{\alpha})}{2C_{\perp}\frac{L_0}{2}(1 - \alpha^2) + C_{\parallel}\alpha^2\frac{L_0}{2} + \frac{6\pi\mu R}{C_{\perp}}} = k$$

$$= \frac{-L_0\ddot{\alpha} - k(\dot{x}\alpha + x\ddot{\alpha})}{(2 - 2\alpha^2 + \alpha^2 + k) = k+2 - \alpha^2} = \frac{-L_0\ddot{\alpha} - k(\dot{x}\alpha + x\ddot{\alpha})}{(k+2)\left(1 - \frac{\alpha^2}{k+2}\right)}$$

$$V(t) = \frac{-1}{(k+2)} \left[L_0\ddot{\alpha} + k(\dot{x}\alpha + x\ddot{\alpha}) \right] \left(1 + \frac{\alpha^2}{k+2}\right)$$

$$\overline{V(t)} = \frac{-1}{(k+2)^2} \left[L_0\alpha^2\ddot{\alpha} + k\alpha^2(\dot{x}\alpha + x\ddot{\alpha}) \right]$$

$$= \frac{-k}{(k+2)^2} \left[\alpha_0^2 \cos^2(\omega t) \right] \left\{ \frac{L_0\omega}{2} \cos(\omega t) \alpha_0 \cos(\omega t) + \frac{L_0}{2} [1 + \sin(\omega t)] (-\omega\alpha_0) \sin(\omega t) \right\}$$

(3)

$$\overline{V(t)} = \frac{-k}{(k+2)^2} \alpha_0^3 \frac{L_0 \omega}{2} \underbrace{\left[\frac{3\pi}{4} - \frac{\pi}{4} \right]}_{\pi/2} = \boxed{-(L_0 \omega) \alpha_0^3 \frac{k\pi}{4(k+2)^2}}$$

Efficiency: $\eta = \frac{\underline{F} \cdot \underline{V}}{\Phi}$



$$\underline{F} \cdot \underline{V} = 2(6\pi\mu R V)V + (2L_0 C V)V$$

C_{\perp} or C_{\parallel} depending
on which way
we drag.

$$= \boxed{(12\pi\mu R + 2L_0 C)(L_0 \omega)^2 \alpha_0^6 \left[\frac{k\pi}{4(k+2)^2} \right]^2}$$

$$\Phi = 2\Phi_{\text{sphere}} + 2\Phi_{\text{bar}}$$

$$\Phi_{\text{sphere}} = 6\pi\mu R V(t) \cdot V(t)$$

$$|V(t)|^2 = \left| \overset{\text{small}}{\left(V(t) + \dot{x} \sin \alpha + x \dot{\alpha} \cos \alpha \right) \hat{y}} + \left(\dot{x} \cos \alpha - x \dot{\alpha} \sin \alpha \right) \hat{x} \right|^2$$

$$\approx \left| (\dot{x} \dot{\alpha} + x \ddot{\alpha}) \hat{y} + (\dot{x} - x \ddot{\alpha}) \hat{x} \right|^2 \approx \dot{x}^2$$

$$\approx \left(\frac{L_0 \omega}{2} \right)^2 \cos^2(\omega t)$$

$$\Phi_{\text{sphere}}(t) = 6\pi\mu R \left(\frac{L_0 \omega}{2} \right)^2 \cos^2(\omega t)$$

$$\boxed{\overline{\Phi}_{\text{sphere}} = 6\pi^2 \mu R \left(\frac{L_0 \omega}{2} \right)^2}$$

$$\Phi_{\text{bar}}(t) = F(t) \cdot V(t)$$

$$d\underline{F} = +C_{\perp} ds \hat{n} [s \dot{\alpha} + V \cos \alpha] + C_{\parallel} ds \hat{t} V \sin \alpha$$

$$\underline{V} = s \dot{\alpha} \hat{n} + \underbrace{V \cos \alpha \hat{n}}_{O(\alpha^3)} + V \sin \alpha \hat{t}$$

$$d\underline{F} \cdot \underline{V} = C_{\perp} (s \dot{\alpha} + V \cos \alpha)^2 ds + C_{\parallel} (V \sin \alpha)^2 ds \approx C_{\perp} \dot{\alpha}^2 s^2 ds$$

(4)

$$\Phi_{\text{bar}}(t) \approx C_{\perp} \alpha^2 \frac{L_0^3}{3} = \frac{C_{\perp} L_0^3}{3} \omega^2 \alpha_0^2 \underbrace{\sin^2(\omega t)}_{\pi}$$

$$\eta = \frac{(12\pi\mu R + 2L_0 C) (\cancel{L_0 \omega})^2 \alpha_0^6 \left[\frac{k\pi}{4(k+2)^2} \right]^2}{12\pi^2 \mu R \left(\frac{L_0 \omega}{2} \right)^2 + \frac{2}{3} \pi C_{\perp} L_0^3 \omega^2 \alpha_0^2}$$

small

$$= \frac{(12\pi\mu R + 2L_0 C) \alpha_0^6 \left[\frac{k\pi}{4(k+2)^2} \right]^2}{3\pi^2 \mu R}$$

$$= \left(4 + \frac{2 \cdot 2L_0 C}{2 \cdot 3\pi^2 \mu R} \right) \alpha_0^6 \left[\frac{k\pi}{4(k+2)^2} \right]^2$$

$$= \left(4 + \frac{4}{k\pi} \right) \alpha_0^6 \left[\frac{k\pi}{4(k+2)^2} \right]^2 = \boxed{\frac{\alpha_0^6}{4} \left(1 + \frac{1}{k\pi} \right) \left[\frac{k\pi}{(k+2)^2} \right]^2}$$