

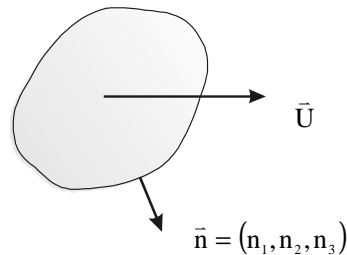
13.021 - Marine Hydrodynamics Lecture 10

3.5 - Boundary Conditions for Potential Flow

Types of Boundary Conditions:

1. Kinematic Boundary Conditions - specify the flow velocity \vec{v} at boundaries.
 2. Dynamic Boundary Conditions - specify force \vec{F} or pressure p at flow boundary.
- Kinematic Boundary Conditions on an impermeable boundary (no flux condition):

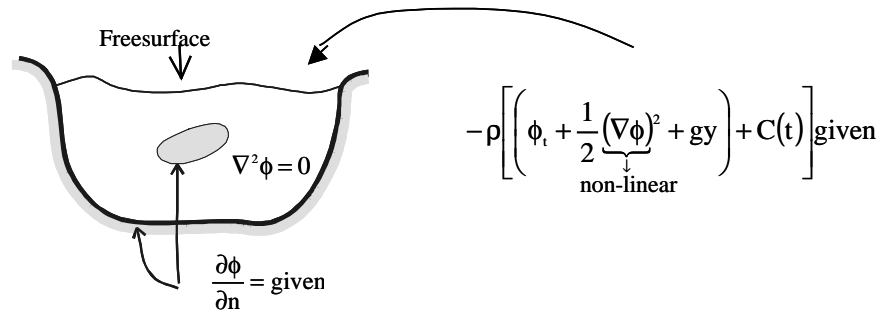
$$\begin{aligned}\vec{n} \cdot \vec{v} &= \vec{n} \cdot \vec{U} = U_n \quad (\text{given}) \quad \text{where} \quad \vec{v} = \nabla \phi \\ \vec{n} \cdot \nabla \phi &= U_n \longrightarrow \frac{\partial \phi}{\partial n} = U_n \\ \frac{\partial}{\partial n} &= \left(n_1 \frac{\partial}{\partial x_1} + n_2 \frac{\partial}{\partial x_2} + n_3 \frac{\partial}{\partial x_3} \right)\end{aligned}$$



- Dynamic Boundary Conditions: Pressure is prescribed in general.

$$p = -\rho \left(\phi_t + \frac{1}{2} (\nabla \phi)^2 + gy \right) + C(t) \quad (\text{prescribed})$$

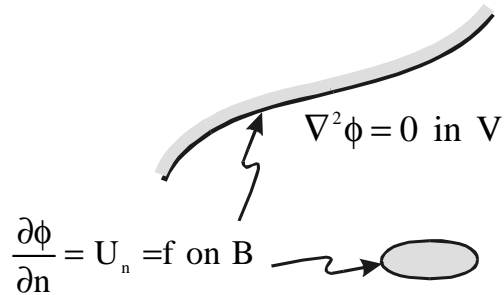
In general:



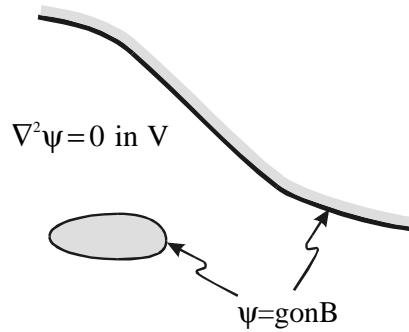
Linear Superposition for Potential Flow

In the **absence** of **dynamic boundary conditions**, the potential flow boundary value problem is **linear**.

- Potential function ϕ .



- Stream function ψ .



Linear Superposition: if ϕ_1, ϕ_2, \dots are harmonic functions, i.e. $\nabla^2 \phi_i = 0$, then $\phi = \sum \alpha_i \phi_i$, where α_i are constants, are also harmonic, and is the solution for the boundary value problem provided the boundary conditions (kinematic boundary condition) are satisfied, i.e.

$$\frac{\partial \phi}{\partial n} = \frac{\partial}{\partial n} (\alpha_1 \phi_1 + \alpha_2 \phi_2 + \dots) = U_n \quad \text{on } B.$$

The key is to combine known solution of the Laplace equation in such a way as to satisfy the K.B.C. (kinematic boundary condition).

The same is true for the stream function ψ . K.B.C.s specify the value of ψ on the boundaries.

Example:

$\phi_i(\vec{x})$ is a unit-source flow with source at \vec{x}_i
i.e.

$$\begin{aligned} \phi_i(\vec{x}) &\equiv \phi_{\text{source}}(\vec{x}, \vec{x}_i) = \frac{1}{2\pi} \ln |\vec{x} - \vec{x}_i| \quad (\text{in 2D}) \\ &= - (4\pi |\vec{x} - \vec{x}_i|)^{-1} \quad (\text{in 3D}), \end{aligned}$$

then find m_i such that:

$$\phi = \sum_i m_i \phi_i(\vec{x}) \quad \text{satisfies KBC on } B$$

Caution: ϕ must be regular for $x \in V$, so it is required that $\vec{x} \notin V$.

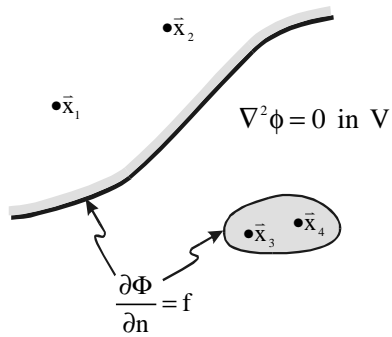


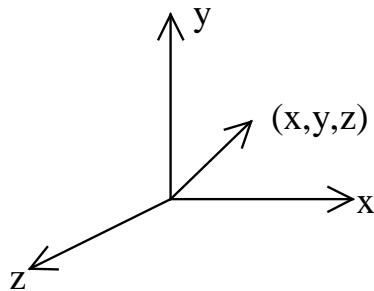
Figure 1: Note: $\vec{x}_j, j = 1, \dots, 4$ are *not* in the fluid domain V .

Laplace equation in different coordinate systems (cf Hildebrand §6.18)

1. Cartesian (x,y,z)

$$\vec{v} = \left(\hat{i}, \hat{j}, \hat{k} \right) = \nabla \phi = \left(\frac{\partial \phi}{\partial x}, \frac{\partial \phi}{\partial y}, \frac{\partial \phi}{\partial z} \right)$$

$$\nabla^2 \phi = \left(\frac{\partial^2 \phi}{\partial x^2} + \frac{\partial^2 \phi}{\partial y^2} + \frac{\partial^2 \phi}{\partial z^2} \right)$$



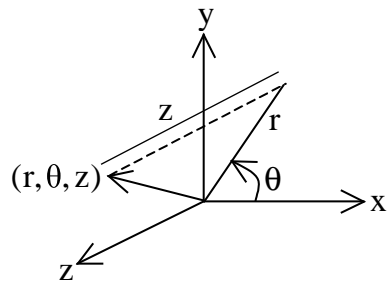
2. Cylindrical (r,θ,z)

$$r^2 = x^2 + y^2,$$

$$\theta = \tan^{-1}(y/x)$$

$$\vec{v} = \left(\hat{e}_r, \hat{e}_\theta, \hat{e}_z \right) = \left(\frac{\partial \phi}{\partial r}, \frac{1}{r} \frac{\partial \phi}{\partial \theta}, \frac{\partial \phi}{\partial z} \right)$$

$$\nabla^2 \phi = \left(\underbrace{\frac{\partial^2 \phi}{\partial r^2} + \frac{1}{r} \frac{\partial \phi}{\partial r}}_{\frac{1}{r} \frac{\partial \phi}{\partial r} \left(r \frac{\partial \phi}{\partial r} \right)} + \frac{1}{r^2} \frac{\partial^2 \phi}{\partial \theta^2} + \frac{\partial^2 \phi}{\partial z^2} \right)$$



3. Spherical (r, theta, phi)

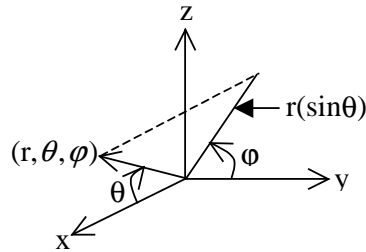
$$r^2 = x^2 + y^2 + z^2,$$

$$\theta = \cos^{-1}(x/r) \text{ or } x = r (\cos \theta)$$

$$\varphi = \tan^{-1}(z/y)$$

$$\vec{v} = \nabla \phi = \left(\hat{e}_r, \hat{e}_\theta, \hat{e}_\varphi \right) = \left(\frac{\partial \phi}{\partial r}, \frac{1}{r} \frac{\partial \phi}{\partial \theta}, \frac{1}{r(\sin \theta)} \frac{\partial \phi}{\partial \varphi} \right)$$

$$\nabla^2 \phi = \left(\underbrace{\frac{\partial^2 \phi}{\partial r^2} + \frac{2}{r} \frac{\partial \phi}{\partial r}}_{\frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial \phi}{\partial r} \right)} + \frac{1}{r^2 \sin \theta} \frac{\partial}{\partial \theta} \left(\sin \theta \frac{\partial \phi}{\partial \theta} \right) + \frac{1}{r^2 \sin^2 \theta} \frac{\partial^2 \phi}{\partial \varphi^2} \right)$$



3.7 - Simple Potential flows

1. Uniform Stream: $\nabla^2(ax + by + cz + d) = 0$

$$1D: \quad \phi = Ux + \text{constant} \quad \psi = Uy + \text{constant} \quad \vec{v} = (U, 0, 0)$$

$$2D: \quad \phi = Ux + Vy + \text{constant} \quad \psi = Uy - Vx + \text{constant} \quad \vec{v} = (U, V, 0)$$

$$3D: \quad \phi = Ux + Vy + Wz + \text{constant} \quad \vec{v} = (U, V, W)$$

2. Source (sink) flow:

2D: Polar coordinates

$$\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}, \text{ with } r = \sqrt{x^2 + y^2}$$

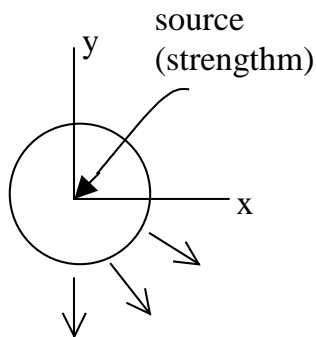
An axisymmetric solution: $\phi = \ln r$ (verify)

Define 2D source of strength m at $r = 0$:

$$\phi = \frac{m}{2\pi} \ln r$$

It satisfies $\nabla^2 \phi = 0$, except at $r = \sqrt{x^2 + y^2} = 0$ (so must exclude $r = 0$ from flow)

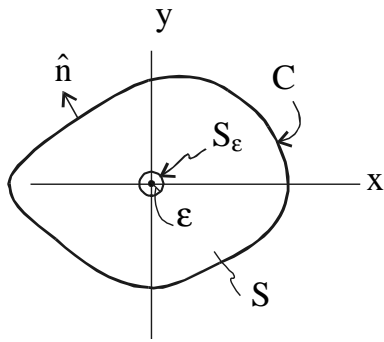
$$\nabla \phi = \frac{\partial \phi}{\partial r} \hat{e}_r = \frac{m}{2\pi r} \hat{e}_r, \text{ i.e. } v_r = \frac{m}{2\pi r}, v_\theta = 0$$



Net outward volume flux is

$$\oint_C \vec{v} \cdot \hat{n} ds = \iint_S \nabla \cdot \vec{v} ds = \iint_{S_\varepsilon} \nabla \cdot \vec{v} ds$$

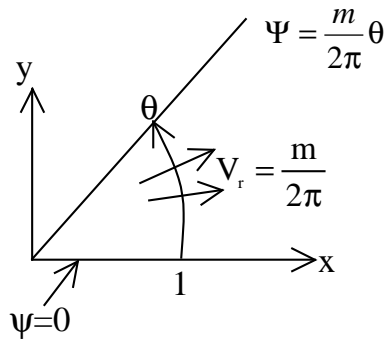
$$\oint_{C_\varepsilon} \vec{v} \cdot \hat{n} ds = \int_0^{2\pi} \underbrace{V_r}_{\frac{m}{2\pi r_\varepsilon}} r_\varepsilon d\theta = \underbrace{m}_{\text{source strength}}$$



If $m < 0 \Rightarrow$ sink. Source m at (x_0, y_0) :

$$\phi = \frac{m}{2\pi} \ln \sqrt{(x - x_0)^2 + (y - y_0)^2}$$

$$\phi = \frac{m}{2\pi} \ln r \text{ (Potential function)} \longleftrightarrow \psi = \frac{m}{2\pi} \theta \text{ (Stream function)}$$



3D: Spherical coordinates

$$\nabla^2 = \frac{1}{r^2} \frac{\partial}{\partial r} \left(r^2 \frac{\partial}{\partial r} \right) + \left(\frac{\partial}{\partial \theta}, \frac{\partial}{\partial \varphi}, \dots \right), \text{ where } r = \sqrt{x^2 + y^2 + z^2}$$

A spherically symmetric solution: $\phi = \frac{1}{r}$ (verify $\nabla^2\phi = 0$ except at $r = 0$)

Define 3D source of strength m at $r = 0$:

$$\phi = -\frac{m}{4\pi r}, \text{ then } V_r = \frac{\partial\phi}{\partial r} = \frac{m}{4\pi r^2}, V_\theta, V_\varphi = 0$$

Net outward volume flux is

$$\oiint V_r dS = 4\pi r_\epsilon^2 \cdot \frac{m}{4\pi r_\epsilon^2} = m \quad (m < 0 \text{ for a sink})$$

3. 2D point vortex

$$\nabla^2 = \frac{1}{r} \frac{\partial}{\partial r} \left(r \frac{\partial}{\partial r} \right) + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2}$$

Another particular solution: $\phi = a\theta + b$ (verify $\nabla^2\phi = 0$ except at $r = 0$)

Define the potential for a point vortex of circulation Γ at $r = 0$:

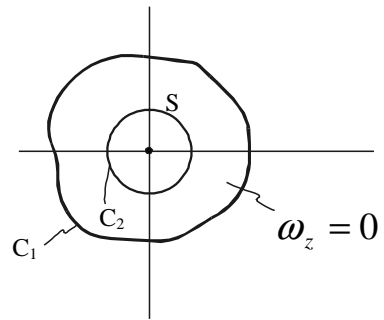
$$\phi = \frac{\Gamma}{2\pi} \theta, \text{ then } V_r = \frac{\partial\phi}{\partial r} = 0, V_\theta = \frac{1}{r} \frac{\partial\phi}{\partial \theta} = \frac{\Gamma}{2\pi r} \text{ and } \omega_z = \frac{1}{r} \frac{\partial}{\partial r} (r V_\theta) = 0 \text{ except at } r = 0$$

Stream function:

$$\psi = -\frac{\Gamma}{2\pi} \ln r$$

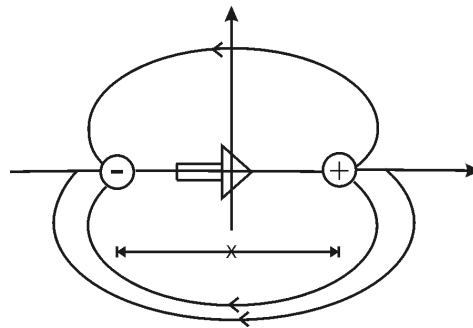
Circulation:

$$\int_{C_1} \vec{v} \cdot d\vec{x} = \int_{C_2} \vec{v} \cdot d\vec{x} + \underbrace{\int_{C_1-C_2} \vec{v} \cdot d\vec{x}}_{\int_S \omega_z dS = 0} = \int_0^{2\pi} \frac{\Gamma}{2\pi r} r d\theta = \underbrace{\Gamma}_{\text{vortex strength}}$$



4. Dipole (doublet flow)

A **Dipole** is a **superposition** of a **sink** and a **source** with the same strength.

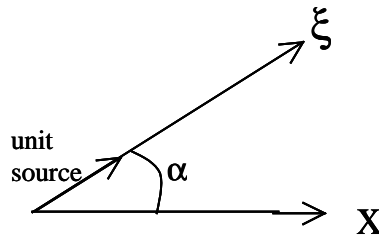


2D dipole:

$$\begin{aligned}
\phi &= \frac{m}{2\pi} \left[\ln \sqrt{(x-a)^2 + y^2} - \ln \sqrt{(x+a)^2 + y^2} \right] \\
\lim_{a \rightarrow 0} \phi &= \underbrace{\frac{\mu}{2\pi}}_{\substack{\mu = 2ma \\ \text{constant}}} \left. \frac{\partial}{\partial \xi} \ln \sqrt{(x-\xi)^2 + y^2} \right|_{\xi=0} \\
&= -\frac{\mu}{2\pi} \frac{x}{x^2 + y^2} = -\frac{\mu}{2\pi} \frac{x}{r^2}
\end{aligned}$$

2D dipole (doublet) of moment μ at the origin oriented in the +x direction.

NOTE: dipole = $\mu \frac{\partial}{\partial \xi}$ (unit source)



$$\phi = \frac{-\mu}{2\pi} \frac{x \cos \alpha + y \sin \alpha}{x^2 + y^2} = \frac{-\mu \cos \theta \cos \alpha + \sin \theta \sin \alpha}{2\pi r}$$

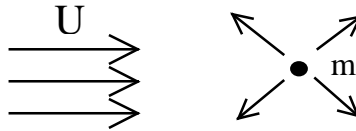
3D dipole:

$$\begin{aligned}
\phi &= \lim_{a \rightarrow 0} -\frac{m}{4\pi} \left(\frac{1}{\sqrt{(x-a)^2 + y^2 + z^2}} - \frac{1}{\sqrt{(x+a)^2 + y^2 + z^2}} \right) \text{ where } \mu = 2ma \text{ fixed} \\
&= -\frac{\mu}{4\pi} \frac{\partial}{\partial \xi} \left. \frac{1}{\sqrt{(x-\xi)^2 + y^2 + z^2}} \right|_{\xi=0} = -\frac{\mu}{4\pi} \frac{x}{(x^2 + y^2 + z^2)^{3/2}} = -\frac{\mu}{4\pi} \frac{x}{r^3}
\end{aligned}$$

3D dipole (doublet) of moment μ at the origin oriented in the $+x$ direction.

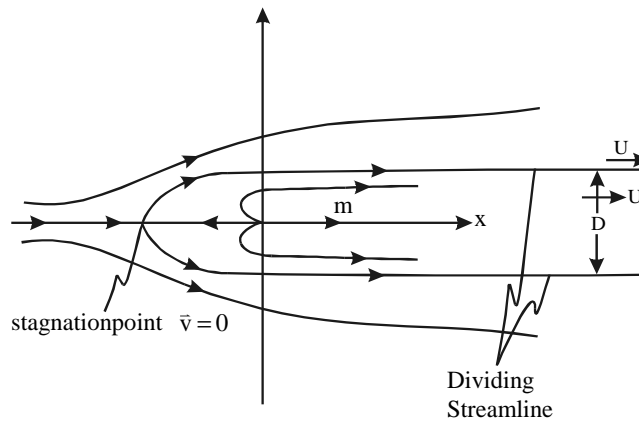
5. Stream and source: Rankine half-body

It is the **superposition** of a **uniform stream** of constant speed U and a **source** of strength m .



2D:

$$\phi = Ux + \frac{m}{2\pi} \ln \sqrt{x^2 + y^2}$$

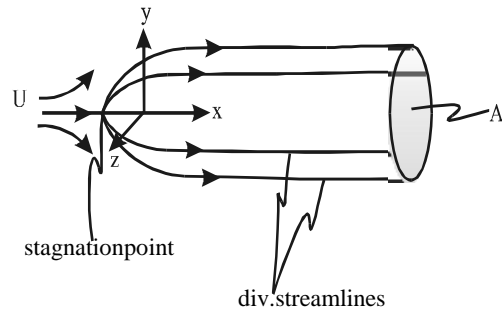


$$\begin{aligned} u &= \frac{\partial \phi}{\partial x} = U + \frac{m}{2\pi} \frac{x}{x^2 + y^2} \\ u|_{y=0} &= U + \frac{m}{2\pi x} \\ \therefore u &= 0 \text{ at } x = x_s = -\frac{m}{2\pi U} \end{aligned}$$

For large x , $u \rightarrow U$, and $UD = m$ by continuity, $\therefore D = \frac{m}{U}$.

3D:

$$\phi = Ux - \frac{m}{4\pi\sqrt{x^2 + y^2 + z^2}}$$



$$u = \frac{\partial \phi}{\partial x} = U + \frac{m}{4\pi} \frac{x}{(x^2 + y^2 + z^2)^{3/2}}$$

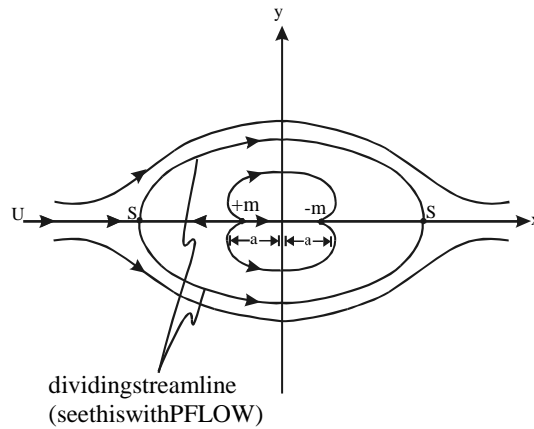
$$u|_{y=z=0} = U + \frac{m}{4\pi} \frac{x}{|x|^3}$$

$$u = 0 \text{ at } x = x_s = -\sqrt{\frac{m}{4\pi U}}$$

$$v = w = 0$$

For large x , $u \rightarrow U$ and $UA = m$ by continuity, $\therefore A = \frac{m}{U}$.

6. Stream + source/sink pair: Rankine closed bodies



To have a closed body, a necessary condition is to have $\sum m_{\text{in body}} = 0$

2D Rankine ovoid:

$$\phi = Ux + \frac{m}{2\pi} \left(\ell n \sqrt{(x+a)^2 + y^2} - \ell n \sqrt{(x-a)^2 + y^2} \right)$$

3D Rankine ovoid:

$$\phi = Ux - \frac{m}{4\pi} \left[\frac{1}{\sqrt{(x+a)^2 + y^2 + z^2}} - \frac{1}{\sqrt{(x-a)^2 + y^2 + z^2}} \right]$$

For Rankine Ovoid,

$$\begin{aligned} u = \frac{\partial \phi}{\partial x} &= U + \frac{m}{4\pi} \left[\frac{x+a}{((x+a)^2 + y^2 + z^2)^{3/2}} - \frac{x-a}{((x-a)^2 + y^2 + z^2)^{3/2}} \right] \\ u|_{y=z=0} &= U + \frac{m}{4\pi} \left[\frac{1}{(x+a)^2} - \frac{1}{(x-a)^2} \right] \\ &= U + \frac{m}{4\pi} \frac{(-4ax)}{(x^2 - a^2)^2} \\ u|_{y=z=0} &= 0 \text{ at } (x^2 - a^2)^2 = \left(\frac{m}{4\pi U} \right) 4ax \end{aligned}$$

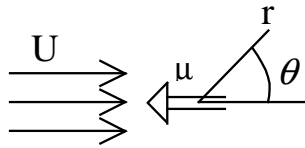
At $x = 0$,

$$u = U + \frac{m}{4\pi} \frac{2a}{(a^2 + R^2)^{3/2}} \text{ where } R = y^2 + z^2$$

Determine radius of body R_0 :

$$2\pi \int_0^{R_0} u R dR = m$$

7. Stream + Dipole: circles and spheres

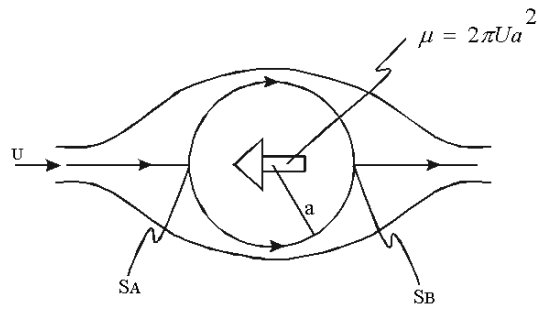


2D:

$$\begin{aligned} \phi &= Ux + \frac{\mu x}{2\pi r^2}, \text{ where } x = r \cos \theta \\ &= \cos \theta \left(Ur + \frac{\mu}{2\pi r} \right) \text{ then } V_r = \frac{\partial \phi}{\partial r} = \cos \theta \left(U - \frac{\mu}{2\pi r^2} \right) \end{aligned}$$

So $V_r = 0$ on $r = a = \sqrt{\frac{\mu}{2\pi U}}$ (which is the K.B.C. for a stationary circle radius **a**) or choose $\mu = 2\pi U a^2$.

Steady flow past a circle (U,a):



$$\phi = U \cos \theta \left(r + \frac{a^2}{r} \right)$$

$$V_\theta = \frac{1}{r} \frac{\partial \phi}{\partial \theta} = -U \sin \theta \left(1 + \frac{a^2}{r^2} \right)$$

$$V_\theta|_{r=a} = -2U \sin \theta \begin{cases} = 0 & \text{at } \theta = 0, \pi \\ = \mp 2U & \text{at } \theta = \frac{\pi}{2}, \frac{3\pi}{2} \end{cases} \quad \begin{array}{l} S_A \text{ and } S_B - \text{stagnation points.} \\ \text{maximum tangential velocity} \end{array}$$

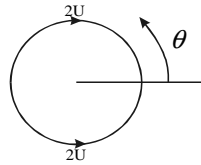
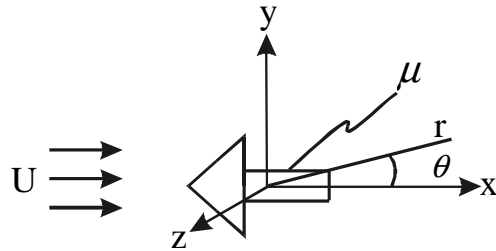


Illustration of the points where the flow reaches maximum speed around the circle.

3D:



$$\phi = Ux + \frac{\mu}{4\pi} \frac{\cos \theta}{r^2}, \quad x = r \cos \theta$$

$$V_r = \frac{\partial \phi}{\partial r} = \cos \theta \left(U - \frac{\mu}{2\pi r^3} \right)$$

$$\underbrace{V_r = 0 \text{ on } r = a}_{\text{K.B.C. on stationary sphere of radius } a} \rightarrow a = \sqrt[3]{\frac{\mu}{2\pi U}} \text{ or } \mu = 2\pi U a^3$$

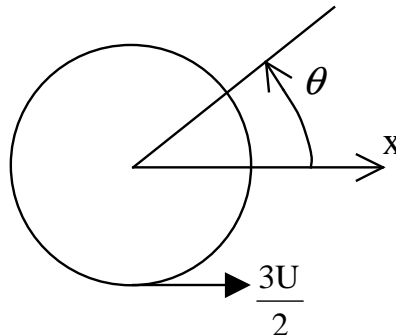
K.B.C. on
stationary
sphere of
radius a

Steady flow past a sphere (U, a):

$$\phi = U \cos \theta \left(r + \frac{a^3}{2r^2} \right)$$

$$V_\theta = \frac{1}{r} \frac{\partial \phi}{\partial \theta} = -U \sin \theta \left(1 + \frac{a^3}{2r^3} \right)$$

$$V_\theta |_{r=a} = -\frac{3U}{2} \sin \theta \begin{cases} = 0 & \text{at } \theta = 0, \pi \\ = -\frac{3U}{2} & \text{at } \theta = \frac{\pi}{2} \end{cases}$$



8. 2D corner flow

Potential function: $\phi = r^\alpha \cos \alpha\theta$, and the Stream function: $\psi = r^\alpha \sin \alpha\theta$

(a) $\nabla^2 \phi = \left(\frac{\partial^2}{\partial r^2} + \frac{1}{r} \frac{\partial}{\partial r} + \frac{1}{r^2} \frac{\partial^2}{\partial \theta^2} \right) \phi = 0$

(b)

$$u_r = \frac{\partial \phi}{\partial r} = \alpha r^{\alpha-1} \cos \alpha\theta$$

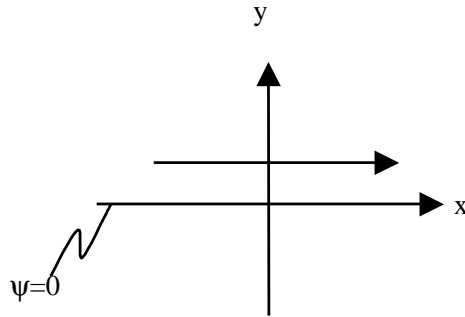
$$u_\theta = \frac{1}{r} \frac{\partial \phi}{\partial \theta} = -\alpha r^{\alpha-1} \sin \alpha\theta$$

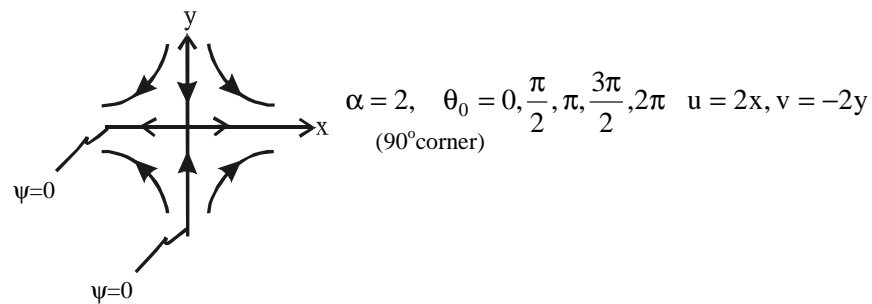
$$\therefore u_\theta = 0 \{ \text{ or } \psi = 0 \} \text{ on } \alpha\theta = n\pi, n = 0, \pm 1, \pm 2, \dots$$

i.e. on $\theta = \theta_0 = 0, \frac{\pi}{\alpha}, \frac{2\pi}{\alpha}, \dots (\theta_0 \leq 2\pi)$

i. **interior corner flow** – stagnation point origin: $\alpha > 1$.

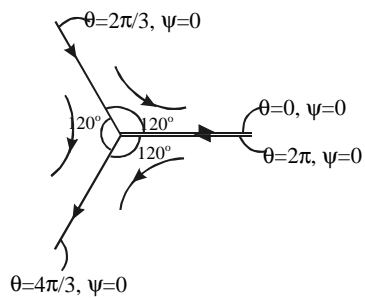
e.g. $\alpha = 1, \theta_0 = 0, \pi, 2\pi, \quad u = 1, \quad v = 0$

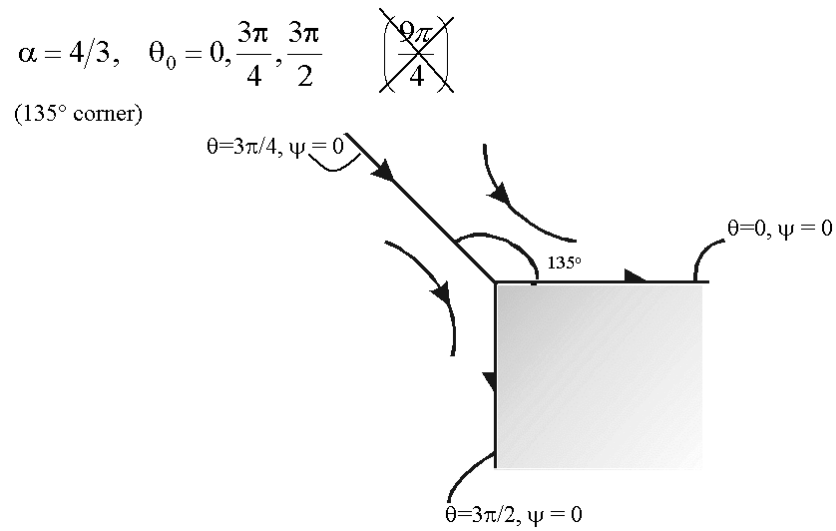




$$\alpha = 3/2, \quad \theta_0 = 0, \frac{2\pi}{3}, \frac{4\pi}{3}, 2\pi$$

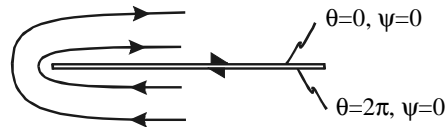
(120° corner)





ii. **Exterior corner flow**, $|v| \rightarrow \infty$ at origin: $\alpha < 1$ ($1/2 \leq \alpha < 1$). $\theta_0 = 0, \frac{\pi}{\alpha}$ only. Since we need $\theta_0 \leq 2\pi$, we therefore require $\frac{\pi}{\alpha} \leq 2\pi$, i.e. $\alpha \geq 1/2$ only.

e.g. $\alpha = 1/2, \theta_0 = 0, 2\pi$ ($1/2$ infinite plate, flow around a tip)



$\alpha = 2/3, \theta_0 = 0, \frac{3\pi}{2}$ (90° exterior corner)

