

16.070

Introduction to Computers & Programming

Theory of computation: More on CFG, CNF, Turing machines, complexity

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So far ...

- Two different, though equivalent, methods of describing languages: **finite automata** and **regular expressions**.
 - Many, but not all languages can be described in that way, e.g., **not** the following: $\{0^n 1^n \mid n \geq 0\}$
- **Context free grammars**, a more powerful method of describing languages.
 - Can describe features that have a recursive structure.
 - An important application of CFGs occurs in the specification and compilation of programming languages.
 - **Push down automata**, a class of machines recognizing the context-free languages.

A context free grammar

- A 4-tuple $(\mathbf{V}, \mathbf{S}, \mathbf{R}, \mathbf{S})$
 - \mathbf{V} is a finite set called the *variables*
 - \mathbf{S} is a finite set, disjoint from \mathbf{V} , called the *terminals*
 - \mathbf{R} is a finite set of *rules*, with each rule being a variable and a string variables and terminals
 - $\mathbf{S} \in \mathbf{V}$ is the *start variable*
- If u , v , and w are strings of variables and terminals, and $A \rightarrow w$ is a rule of the grammar, we say that uAv *yields* uwv , written $uAv \Rightarrow uwv$.

Write $u \Rightarrow v$ if $u = v$ or if a sequence u_1, u_2, \dots, u_k exists for $k \geq 0$ and

$$u \Rightarrow u_1 \Rightarrow u_2 \Rightarrow \dots \Rightarrow u_k \Rightarrow v$$

Example

- Grammar $\mathbf{G} = (\{S\}, \{a, b\}, R, S)$.
- The set of rules, R , is: $S \rightarrow aSb \mid SS \mid \varepsilon$
- This grammar generates strings such as *abab*, *aaabbb*, and *aababb*.
- $L(G)$ is the language of all strings of properly nested parentheses
(if you think of *a* as being a “(“ and *b* being a “)”)”

Chomsky Normal Form

- **Chomsky Normal Form** (CNF) is a simple and useful form of a CFG
- A CFG is in CNF if every rule is of the form
$$A \rightarrow BC$$
$$A \rightarrow a$$
- Where a is any terminal and A, B, C are any variables except B and C may not be the start variable
 - There are two and only two variables on the right hand side of the rule

Theorem

- Any context free language may be generated by a context free grammar in Chomsky Normal Form
- To show how this is possible we must be able to **convert any CFG into CNF**
 1. Eliminate all ϵ rules of the form $A \rightarrow \epsilon$
 1. **Exception:** $S \rightarrow \epsilon$ is permitted where S is the start variable
 2. Eliminate all unit rules of the form $A \rightarrow B$
 3. Convert any remaining rules into the form $A \rightarrow BC$

Proof

- First **add a new start symbols** S_0 and the rule $S_0 \rightarrow S$ where S was the original start symbol
 - This guarantees the new start symbol is not on the RHS of any rule
- **Remove all ϵ rules.**
 - Remove a rule $A \rightarrow \epsilon$ where A is not the start symbol. For each occurrence of A on the RHS of a rule, add a new rule with that occurrence of A deleted
 - Ex:
 $R \rightarrow uAv$ becomes $R \rightarrow uv$
 - This must be done for each occurrence of A , e.g.:
 $R \rightarrow uAvAw$ becomes $R \rightarrow uvAw \mid uAvw \mid uvw$

Repeat until all ϵ rules are removed, not including the start

Proof

- Next **remove all unit rules** of the form $A \rightarrow B$
 - Whenever a rule $B \rightarrow u$ appears, add the rule $A \rightarrow u$.
 - u may be a string of variables and terminals
 - Repeat until all unit rules are eliminated
- Convert all remaining rules into the form with **two variables on the right**
 - The rule $A \rightarrow u_1 u_2 u_3 \dots u_k$ becomes
 - $A \rightarrow u_1 A_1 \quad A_1 \rightarrow u_2 A_2 \quad \dots \quad A_{k-2} \rightarrow u_{k-1} u_k$
 - Where the A_i 's are new variables. u may be a variable or a terminal (and in fact a terminal must be converted to a variable since CNF does not allow a mixture of variables and terminals on the right hand side)

Example

- Convert the following grammar into CNF

$$S \rightarrow ASA \mid aB$$

$$A \rightarrow B \mid S$$

$$B \rightarrow b \mid \varepsilon$$

First add a new start symbol S_0 :

$$S_0 \rightarrow S$$

$$S \rightarrow ASA \mid aB$$

$$A \rightarrow B \mid S$$

$$B \rightarrow b \mid \varepsilon$$

Example

- Next remove the epsilon transition from rule B

$$S_0 \rightarrow S$$

$$S \rightarrow ASA \mid aB \mid \mathbf{a}$$

$$A \rightarrow B \mid S \mid \mathbf{e}$$

$$B \rightarrow b \mid \mathbf{e}$$

- We must repeat this for rule A:

$$S_0 \rightarrow S$$

$$S \rightarrow ASA \mid aB \mid a \mid \mathbf{AS} \mid \mathbf{SA} \mid \mathbf{S}$$

$$A \rightarrow B \mid S \mid \mathbf{e}$$

$$B \rightarrow b$$

Example

- Next remove unit rules, starting with $S_0 \rightarrow S$ and $S \rightarrow S$ can also be removed

$S_0 \rightarrow \mathbf{ASA} \mid \mathbf{aB} \mid \mathbf{a} \mid \mathbf{AS} \mid \mathbf{SA}$

$S \rightarrow \mathbf{ASA} \mid \mathbf{aB} \mid \mathbf{a} \mid \mathbf{AS} \mid \mathbf{SA}$

$A \rightarrow B \mid S$

$B \rightarrow b$

- Next remove the rule for $A \rightarrow B$

$S_0 \rightarrow ASA \mid aB \mid a \mid AS \mid SA$

$S \rightarrow ASA \mid aB \mid a \mid AS \mid SA$

$A \rightarrow \mathbf{b} \mid S$

$B \rightarrow b$

- Next remove the rule for $A \rightarrow S$

$S_0 \rightarrow ASA \mid aB \mid a \mid \mathbf{AS} \mid \mathbf{SA}$

$S \rightarrow ASA \mid aB \mid a \mid \mathbf{AS} \mid \mathbf{SA}$

$A \rightarrow b \mid \mathbf{ASA} \mid \mathbf{aB} \mid \mathbf{a} \mid \mathbf{AS} \mid \mathbf{SA}$

$B \rightarrow b$

Example

- Finally convert the remaining rules to the proper form by adding variables and rules when we have more than three things on the RHS

$$S_0 \rightarrow ASA \mid aB \mid a \mid AS \mid SA$$

$$S \rightarrow ASA \mid aB \mid a \mid AS \mid SA$$

$$A \rightarrow b \mid ASA \mid aB \mid a \mid AS \mid SA$$

$$B \rightarrow b$$

- Becomes

$$S_0 \rightarrow \mathbf{AA_1} \mid \mathbf{A_2B} \mid a \mid AS \mid SA$$

$$\mathbf{A_1} \rightarrow \mathbf{SA}$$

$$\mathbf{A_2} \rightarrow \mathbf{a}$$

$$S \rightarrow \mathbf{AA_1} \mid \mathbf{A_2B} \mid a \mid AS \mid SA$$

$$A \rightarrow b \mid \mathbf{AA_1} \mid \mathbf{A_2B} \mid a \mid AS \mid SA$$

$$B \rightarrow b$$

We are done!

CNF and Parse Trees

- Chomsky Normal Form is useful to interpret a grammar as a parse tree
 - CNF forms a **binary tree!**
 - Consider the string **babaaa** on the **previous grammar**

$S_0 \rightarrow AS \rightarrow bS \rightarrow bAS \rightarrow bASS \rightarrow baSS \rightarrow baASS \rightarrow$
 $babSS \rightarrow babSAS \rightarrow babaAS \rightarrow babaaS \rightarrow \mathbf{babaaa}$

$S_0 \rightarrow AA_1 \mid A_2B \mid a \mid AS \mid SA$

$A_1 \rightarrow SA$

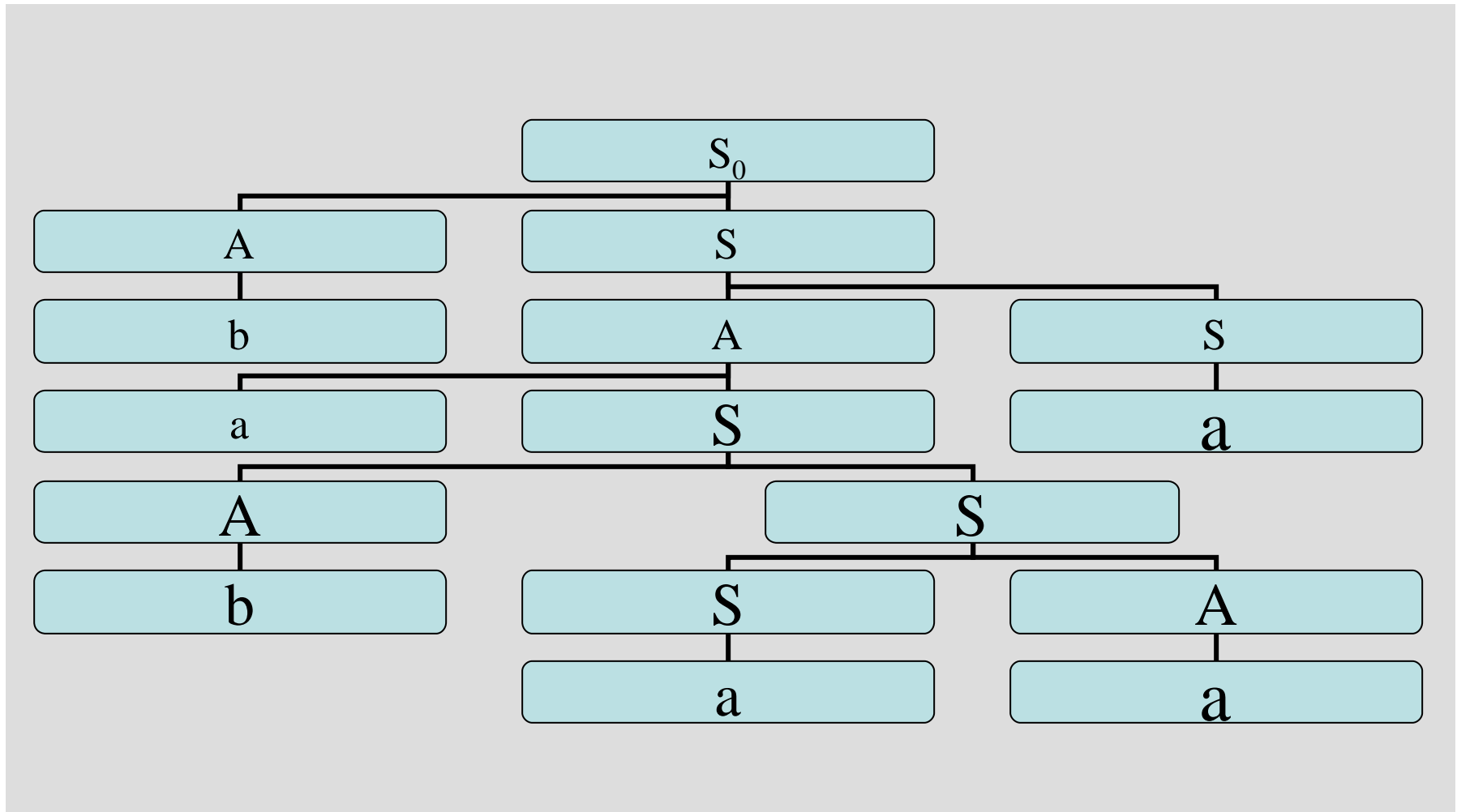
$A_2 \rightarrow a$

$S \rightarrow AA_1 \mid A_2B \mid a \mid AS \mid SA$

$A \rightarrow b \mid AA_1 \mid A_2B \mid a \mid AS \mid SA$

$B \rightarrow b$

Grammar as a Parse Tree



Why is this useful?

- Because we know lots of things about binary trees
- We can now apply these things to context-free grammars since any CFG can be placed into the CNF format
- For example
 - If yield of the tree is a terminal string w
 - If n is the height of the longest path in the tree
 - Then $|w| \leq 2^{n-1}$

Non-context-free languages

- Certain languages are not context-free. For example:
 - The language $B = \{a^n b^n c^n \mid n \geq 0\}$ is not context-free
 - The language $C = \{a^i b^j c^k \mid 0 \leq i \leq j \leq k\}$ is not context-free

Turing Machines and Complexity

Devices of Increasing Computational Power

- So far:
 - **Finite Automata** – good for devices with small amounts of memory, relatively simple control
 - **Pushdown Automata** – stack-based automata
- But both have limitations for even simple tasks, too restrictive as general purpose computers
- Enter the **Turing Machine**
 - First proposed by Alan Turing in 1936
 - More powerful than either of the above
 - Essentially a finite automaton but with unlimited memory
 - Although theoretical, can do everything a general purpose computer of today can do
 - **If a TM can't solve it, neither can a computer**
- What does it mean to be able to compute a function?
 - Alonzo Church and Alan Turing independently arrived at equivalent conclusions: *A function is computable if it can be computed by a Turing machine.*

Computability

- We will start to examine **problems** that are **at the threshold** and **beyond the theoretical limits of what is possible to compute using computers today**.
- We will examine the following issues with the help of TM's

Recursively Enumerable Languages

- We use the simplicity of the TM model to prove formally that there are specific problems (i.e. languages) that the TM cannot solve.

When we start a TM on an input, three outcomes are possible: The machine may *accept*, *reject*, *loop* (the machine simply does not halt)

Two classes of languages:

- **recursively enumerable** : TM can **accept** the strings in the language but **cannot tell for certain that a string is not in the language**. Sometimes these are called “decidable” or “non-decidable” problems.
- **non-recursively enumerable** : no TM can even recognize the members of the language.

P and NP

- We then look at problems (languages) that do have **TM's that accept them and always halt**;
 - i.e. they not only recognize the strings in the language, but they tell us when they are sure the string is not in the language.
- The classes **P** and **NP** are those languages recognizable by deterministic and nondeterministic TM's, respectively, that halt within a time that is some polynomial in the input.
 - Polynomial is as close as we can get, because real computers and different models of (deterministic) TM's can differ in their running time by a polynomial function, e.g., a problem might take $O(n^2)$ time on a real computer and $O(n^6)$ time on a TM

P and NP

- **P** is the class of languages that are decidable in polynomial time on a deterministic (single-tape) Turing machine.
 - Example: A directed graph G contains nodes s and t . The PATH problem is to determine whether a directed path exists from s to t .
 - We can in many cases/problems avoid brute-force search and obtain polynomial time solutions.

P and NP

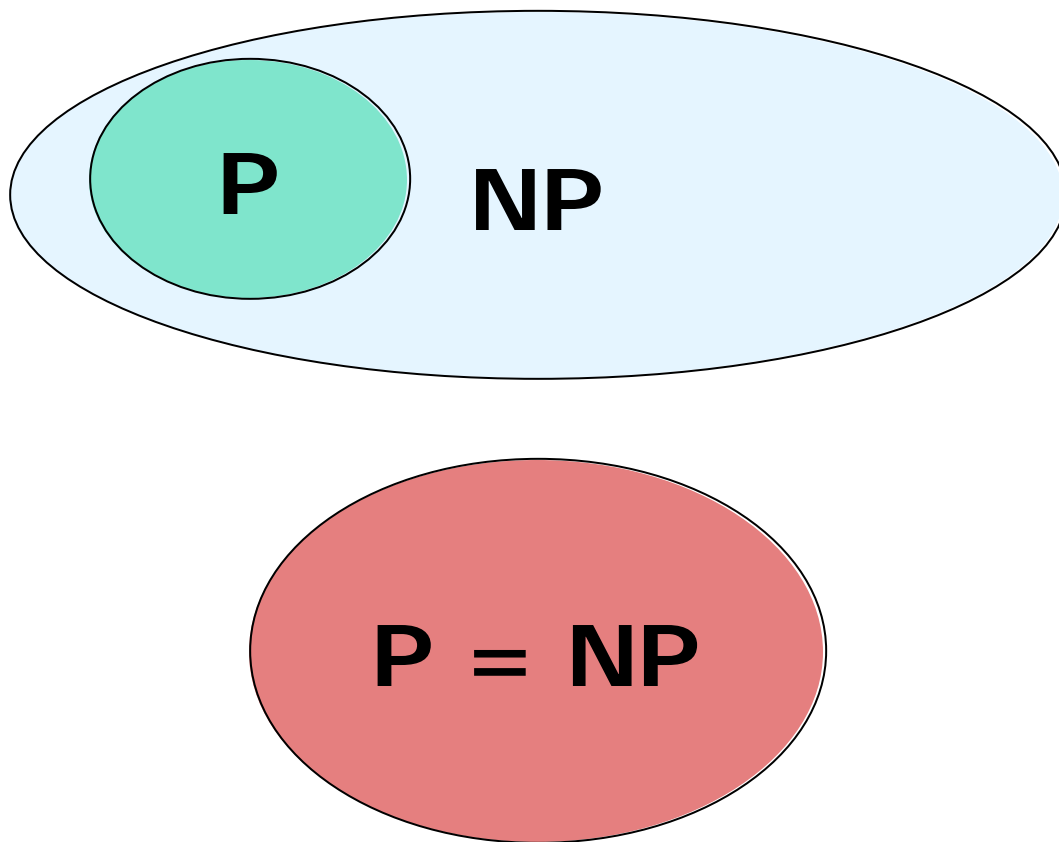
- Attempts to avoid brute force in many problems have not been successful, and polynomial time algorithms that solve them are not known to exist.
- Why have “we” been unsuccessful in finding polynomial time algorithms for these problems?
- The complexity of many problems are linked. The discovery of a polynomial time algorithm for one such problem can be used to solve an entire class of problems.

P = the class of languages where membership can be *decided* quickly

NP = the class of languages where membership can be *verified* quickly.

The P versus NP question

We are unable to prove the existence of a single language in NP that is not in P.



The question whether $P=NP$ is one of the greatest unsolved problems in theoretical CS and contemporary mathematics.

NP Complete

- These are in a sense the **“hardest” problems in NP**.
 - These problems correspond to languages that are recognizable by a nondeterministic TM.
 - However, we will also be able to show that in polynomial time we can reduce any NP-complete problem to any other problem in NP.
 - This means that if we could prove an NP Complete problem to be solvable in polynomial time, then $P = NP$.
- We will examine some specific problems that are NP-complete: satisfiability of Boolean (propositional logic) formulas, traveling salesman, etc.

Intuitive Argument for an Undecidable Problem

- Given a program that prints “hello, world” **is there another program that can test if a program given as input prints “hello, world”?**
- This is *tougher* than it may sound at first glance. For some programs it is easy to determine if it prints hello world. Here is perhaps the simplest:

```
#include "stdio.h"
void main()
{
    printf("hello, world\n");
}
```

Not as easy as it looks...

- It would be fairly easy to write a program to test to see if another program consisting solely of printf statements will output “hello, world”. But what we want is a **program that can take any arbitrary program** and determine if it prints “hello, world”.
- This is much more difficult. Consider the following program:

Obfuscated Hello World Program

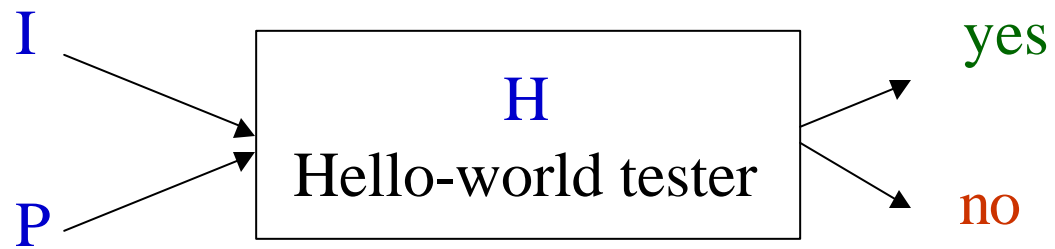
```
#include "stdio.h"
#define e 3
#define g (e/e)
#define h ((g+e)/2)
#define f (e-g-h)
#define j (e*e-g)
#define k (j-h)
#define l(x) tab2[x]/h
#define m(n,a) ((n&(a))==a)
long tab1[]={ 989L,5L,26L,0L,88319L,123L,0L,9367L };
int tab2[]={ 4,6,10,14,22,26,34,38,46,58,62,74,82,86 };

main(m1,s) char *s; {
    int a,b,c,d,o[k],n=(int)s;
    if(m1==1){ char b[2*j+f-g]; main(l(h+e)+h+e,b); printf(b); }
    else switch(m1-=h){
        case f:
            a=(b=(c=(d=g)<<g)<<g)<<g);
            return(m(n,a|c)|m(n,b)|m(n,a|d)|m(n,c|d));
        case h:
            for(a=f;a<j;++a)if(tab1[a]&&!(tab1[a]%((long)l(n))))return(a);
        case g:
            if(n<h)return(g);
            if(n<j){n-=g;c='D';o[f]=h;o[g]=f;}
            else{c='\r'-' \b';n-=j-g;o[f]=o[g]=g;}
            if((b=n)>=e)for(b=g<<g;b<n;++b)o[b]=o[b-h]+o[b-g]+c;
            return(o[b-g]%n+k-h);
        default:
            if(m1-=e) main(m1-g+e+h,s+g); else *(s+g)=f;
            for(*s=a=f;a<e;) *s=(*s<<e)|main(h+a++,(char *)m1);
    }
}
```

Hello World Tester

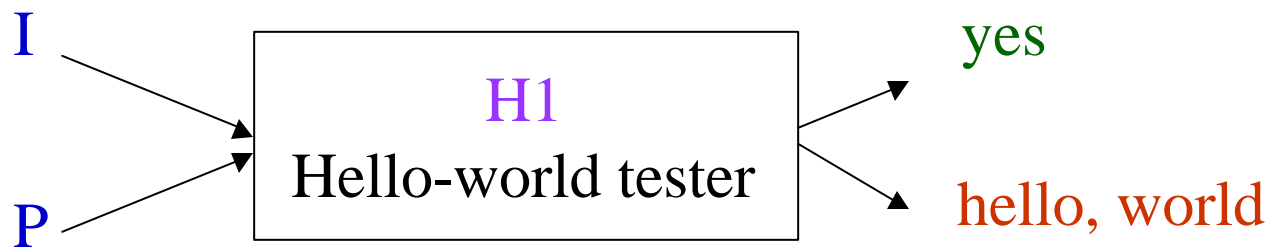
- **Problem:** Create a program that determines if any arbitrary program prints “hello world”
- We can show there is no program to solve that problem (called **undecidable**)
- Suppose that there were such a program **H**, the “hello-world-tester.”
- **H** takes as input a program **P** and an input file **I** for that program, and tells whether **P**, with input **I**, prints “hello world” and outputs “**yes**” if it does, “**no**” if it does not

Hello World Tester



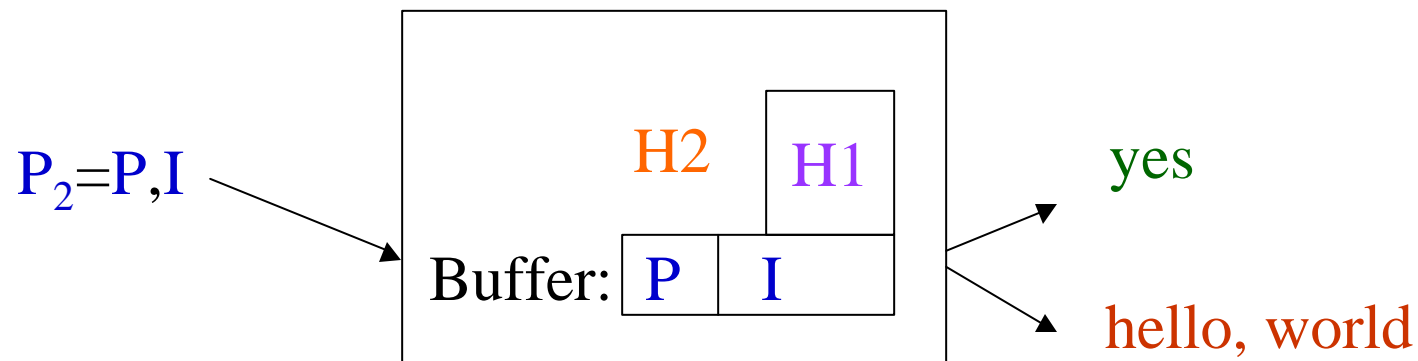
Hello World Tester

- Next we modify **H** to a new program **H1** that acts like **H**, but when **H** prints **no**, **H1** prints “**hello, world.**”
- To do this, we need to find where “**no**” is printed and instead output “**hello world**” instead:



Hello World Tester

- Next modify **H1** to **H2**. The program **H2** takes only one input, P_2 , instead of both P and I .
- To do this, the new input P_2 must include the data input I and the program P .
- The program P and data input I are all stored in a buffer in program **H2**. **H2** then simulates **H1**, but whenever **H1** reads input, **H2** feeds the input from the buffered copy. **H2** can maintain two index pointers into the buffered data to know what current data and code should be read next:



Hello World Tester

- However, **H2 cannot exist**. If it did, what would $H2(H2)$ do?
- That is, we give **H2** as input to itself:



If $H2$ on the left outputs = “yes”, then $H2$ given $H2$ as input will print “hello, world”. But we just supposed that the first output $H2$ makes is “yes” and not “hello world”.

The situation is paradoxical and we conclude that **H2** cannot exist and this problem is **undecidable**.

Problem Reducibility

- Once we have a single problem known to be undecidable we can determine that other problems are also undecidable by **reducing** a known undecidable problem to the new problem.
 - We will use this same idea later when we talk about proving problems to be NP-Complete.
- To use this idea, we must take a problem we know to be undecidable. Call this problem U . Given a new problem, P , if U can be reduced to P so that P can be used to solve U , then P must also be undecidable.

Problem Reducibility

- Important – we must show that U reduces to P , not vice versa
 - If we show that our P reduces to U then we have only shown that a new problem can be solved by the undecidable problem
 - It might still be possible to solve problem P by other means; e.g. we might be taking the tough path to solve P
- But if we can show the other direction, that P can solve U , then P must be at least as hard as U , which we already know to be undecidable.

Reducibility Example

- Does program Q ever call function foo?
 - This problem is also undecidable
- Just as we saw with the ‘hello world’ problem, it is easy to write a program that can determine if some programs call function foo.
- But we could have a program that contains lots of control logic to determine whether or not function foo is invoked. This general case is much harder, and in fact undecidable

Reducibility Example

- Use the reduction technique for the Hello-World problem
 - Rename the function “foo” in program Q and all calls to that function.
 - Add a function “foo” that does nothing and is not called.
 - Modify the program to remember the first 12 characters that it prints, storing them in array A
 - Modify the program so that whenever it executes any output statement, it checks the array A to see if the 12 characters written are “hello, world” and if so, invokes function foo.
 - If the final program prints “hello, world” then it must also invoke function foo. Similarly, if the program does not print “hello, world” then it does not invoke foo.

Foo Caller

- Say that we have a program F-Test that can determine if a program calls foo.
- If we run F-Test on the modified program above, not only can it determine if a program calls foo, it can also determine if the program prints “hello, world”.
- But we would then be solving the “hello-world-tester” problem which we already know is undecidable, therefore our F-Test problem must be undecidable as well