

Distributed Constraint Satisfaction Problems: 2 Asynchronous Algorithms

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16.412J - Cognitive Robotics

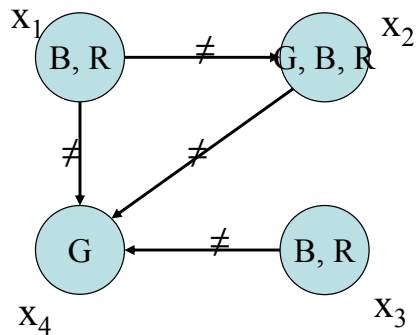
April 7, 2004

Presentation Outline

1. Introduction to CSPs and DCSPs
2. The Asynchronous Backtracking Algorithm
3. The Asynchronous Weak-Commitment Search Algorithm
4. Conclusion and Introduction to the Task Allocation Problem

M. Yokoo, E. Durfee, T. Ishida and K. Kuwabara, *Distributed Constraint Satisfaction Problem: Formalization and Algorithms*, IEEE Transactions on Knowledge and Data Engineering, VOL. 10, NO. 5, Sept/Oct 1998

1. Introduction to CSPs and DCSPs



1. Introduction to CSPs and DCSPs

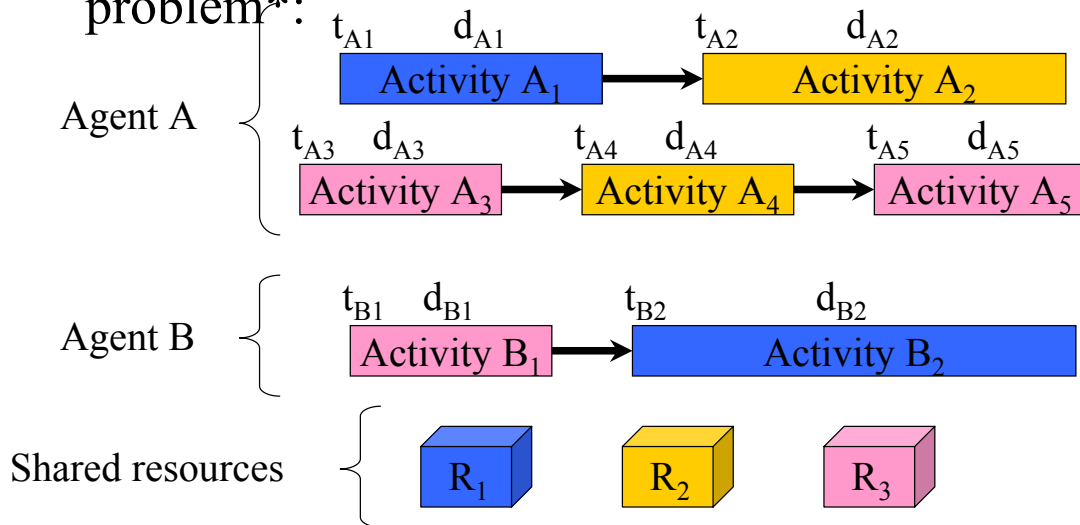
- Formal definition: a Constraint Satisfaction Problem (CSP) is a triple $(\mathcal{X}, \mathcal{D}, C)$, where
 - \mathcal{X} is a list of variables x_1, x_2, \dots, x_n
 - \mathcal{D} is a list of finite, discrete value domains D_1, D_2, \dots, D_n assigned to the variables
 - C is a set of constraints C_1, C_2, \dots, C_n on the variables, a constraint being a predicate:

$$C_k : D_{k_1} \times D_{k_2} \times \dots \times D_{k_j} \rightarrow \{true, false\}$$

- A solution to the problem is an assignment to the variables that satisfies all the constraints

1. Introduction to CSPs and DCSPs

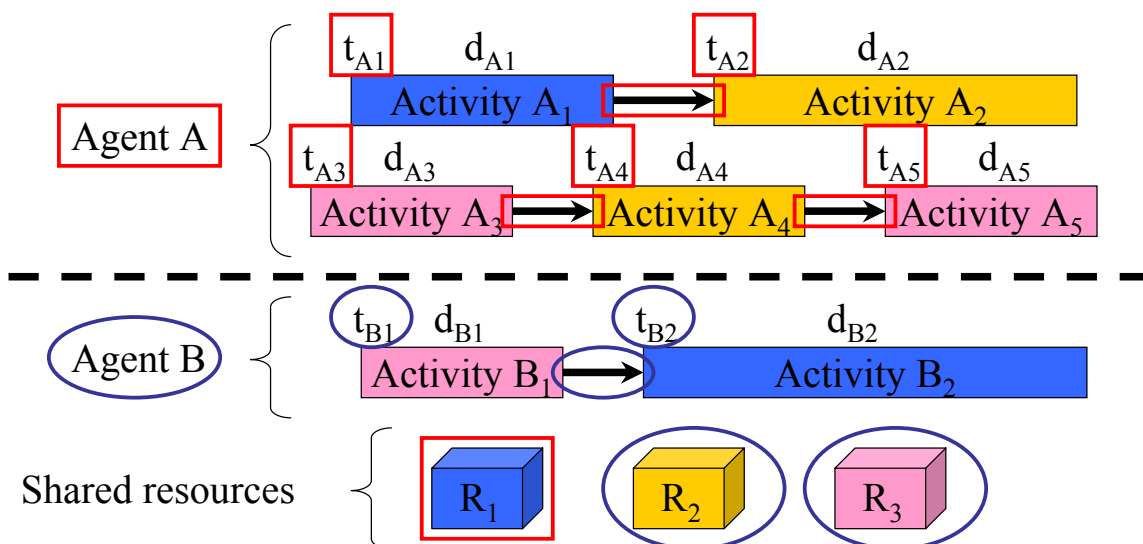
- Many AI problems can be formulated as CSPs
- Example of a multi-agent scheduling problem*:



* K. Sycara, S. Roth, N. Nadeh and M. Fox, *Distributed Constrained Heuristic Search*, IEEE Transactions on Systems, Man, and Cybernetics, VOL. 21, NO. 6, Nov/Dec 1991

1. Introduction to CSPs and DCSPs

- Split the problem in coupled sub-problems: distribute the variables AND the constraints among the agents



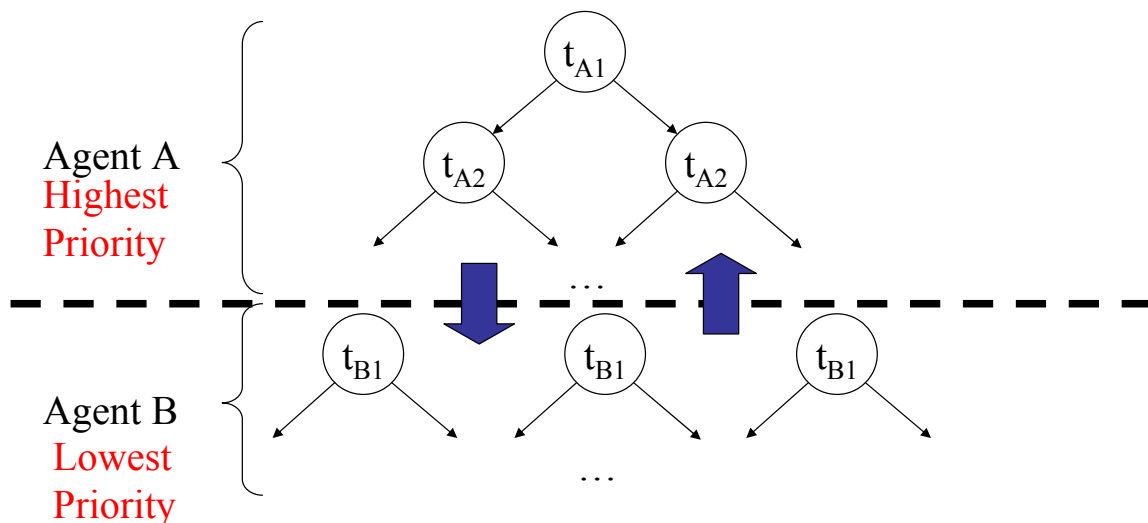
* K. Sycara, S. Roth, N. Nadeh and M. Fox, *Distributed Constrained Heuristic Search*, IEEE Transactions on Systems, Man, and Cybernetics, VOL. 21, NO. 6, Nov/Dec 1991

1. Introduction to CSPs and DCSPs

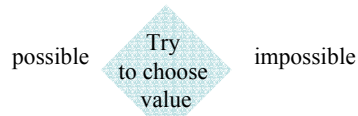
- Centralized method: one leader agent gathers all the information from other agents and solves the problem
 - Prohibitive cost of collecting information
 - Security/Privacy reasons
 - Not computationally efficient

1. Introduction to CSPs and DCSPs

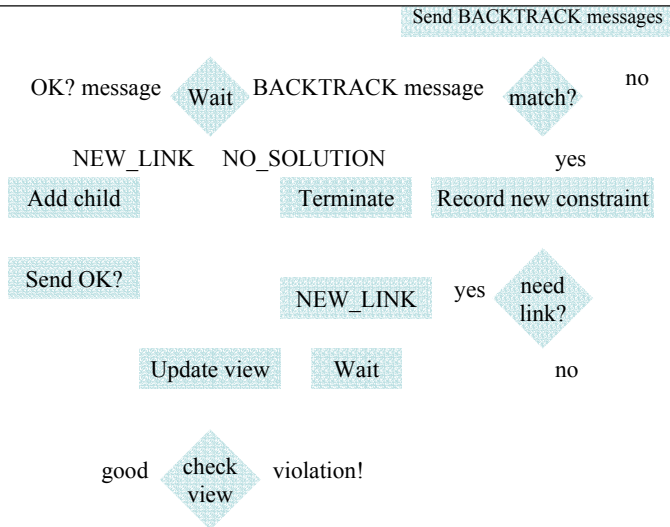
- Synchronous Backtracking method:



- Sequential \Rightarrow not computationally efficient



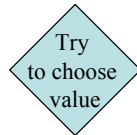
2. The Asynchronous Backtracking Algorithm



2. Asynchronous Backtracking

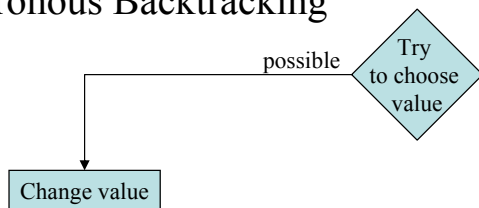
- Assumptions:
 - Given priority order on the agents
 - An agent must be able to send messages to any other agent
 - Each agent has exactly ONE single variable
- Key ideas:
 - Agents work concurrently (= “asynchronously”), exchanging messages to collect required information
 - Conflict-directed search

2. Asynchronous Backtracking



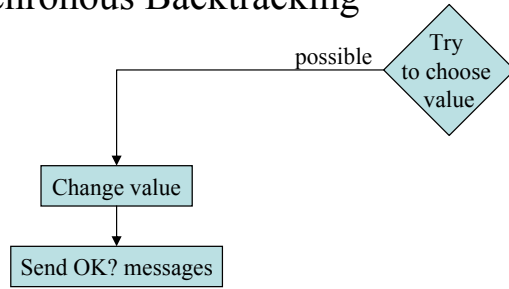
The agent selects a value for its variable satisfying the constraints whose enforcement it is responsible for

2. Asynchronous Backtracking



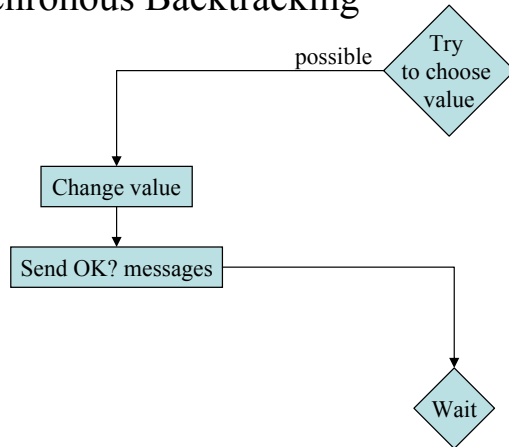
If there is at least one value satisfying the constraints, the agent picks one and changes the assignment to its variable

2. Asynchronous Backtracking



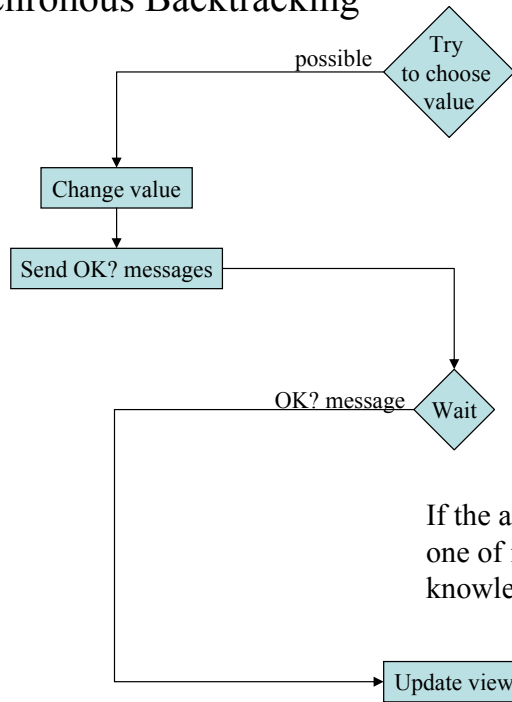
The agent communicates its new assignment to its children through “OK?” messages

2. Asynchronous Backtracking



The agent then waits for answers to his OK? messages from its children (and for other OK? messages from its parents)

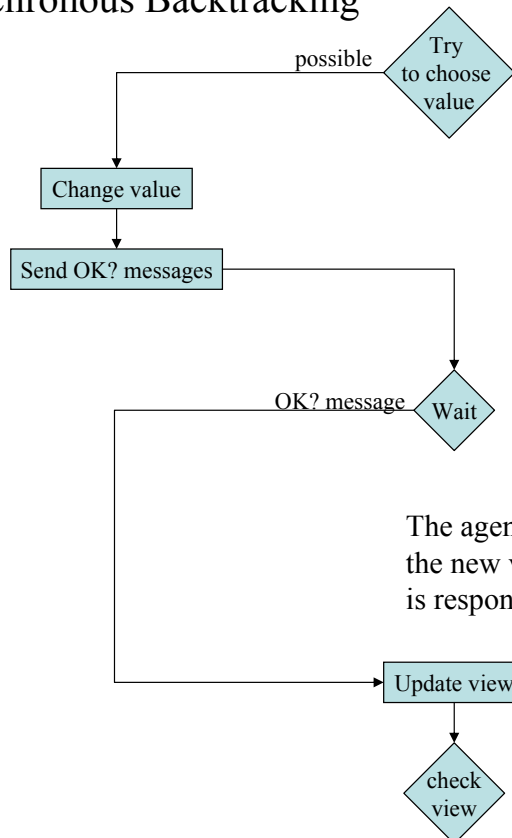
2. Asynchronous Backtracking



A's view	
B	1
C	?
D	3
E	4
F	?
G	?
H	?

If the agent receives an OK? message from one of its parents, it updates its "view", i.e. its knowledge of the values of the other variables

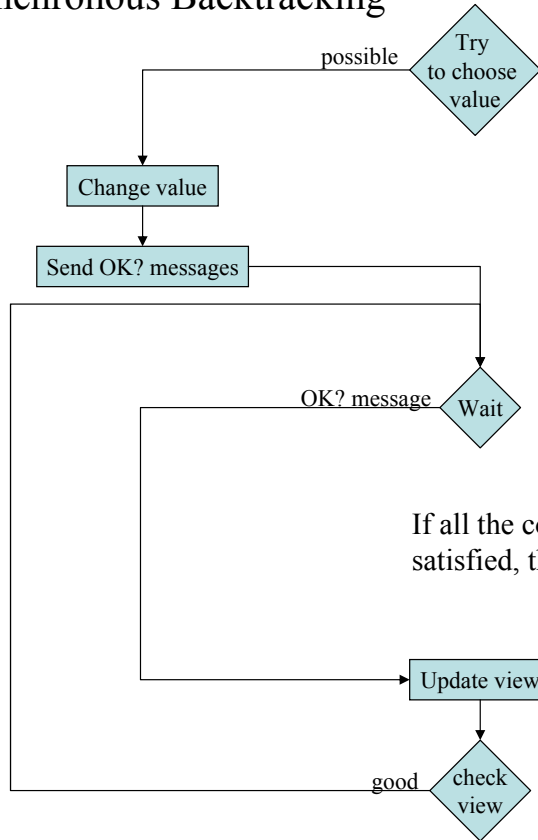
2. Asynchronous Backtracking



A's view	
B	1
C	?
D	3
E	4
F	?
G	?
H	?

The agent then checks its view, making sure that the new values do not violate any constraint it is responsible for

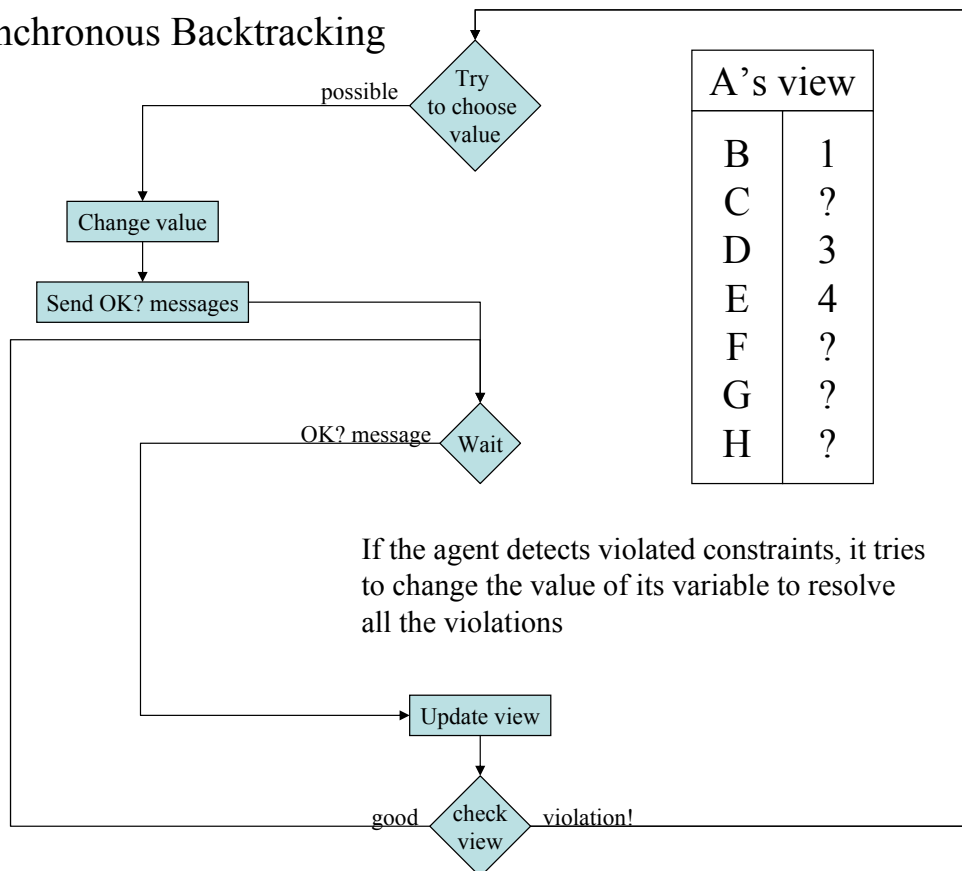
2. Asynchronous Backtracking



A's view	
B	1
C	?
D	3
E	4
F	?
G	?
H	?

If all the constraints it is responsible for are still satisfied, the agent keeps waiting for messages

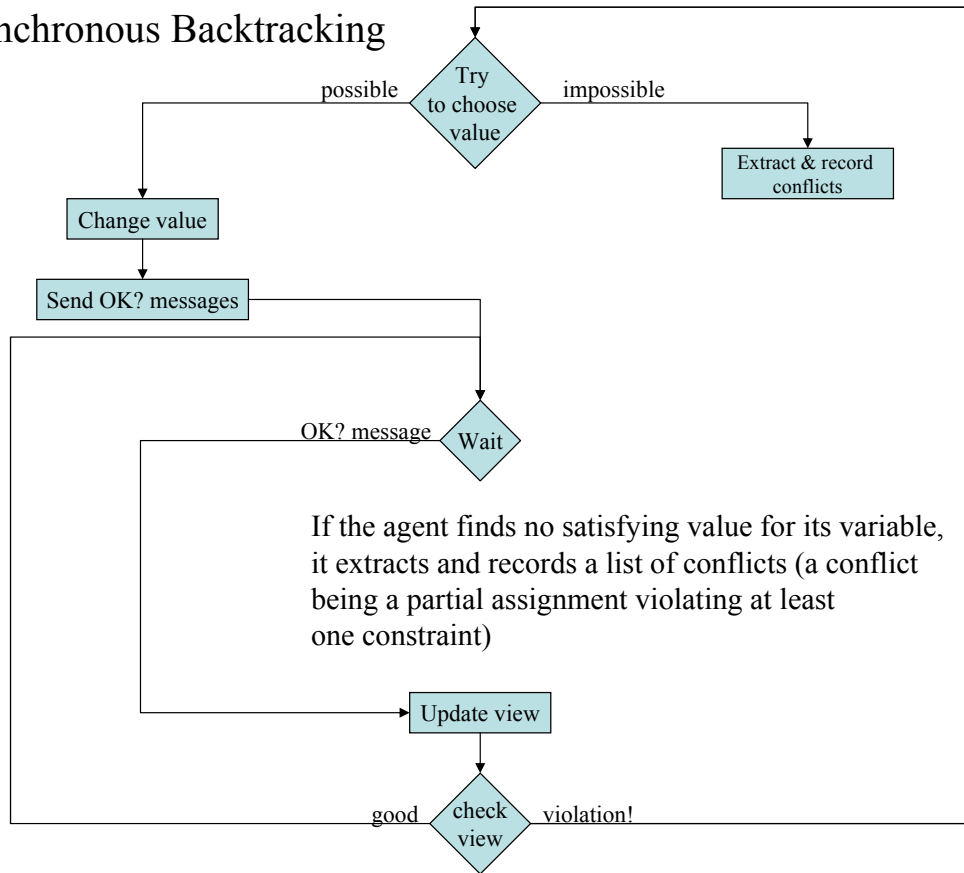
2. Asynchronous Backtracking



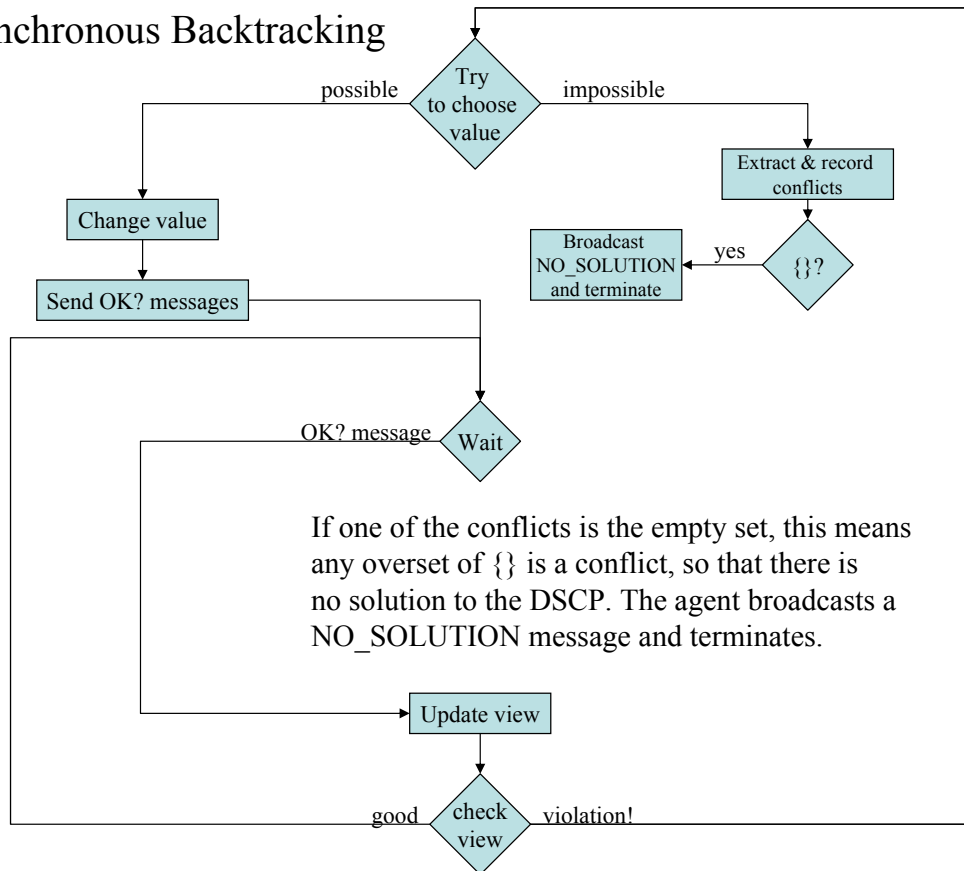
A's view	
B	1
C	?
D	3
E	4
F	?
G	?
H	?

If the agent detects violated constraints, it tries to change the value of its variable to resolve all the violations

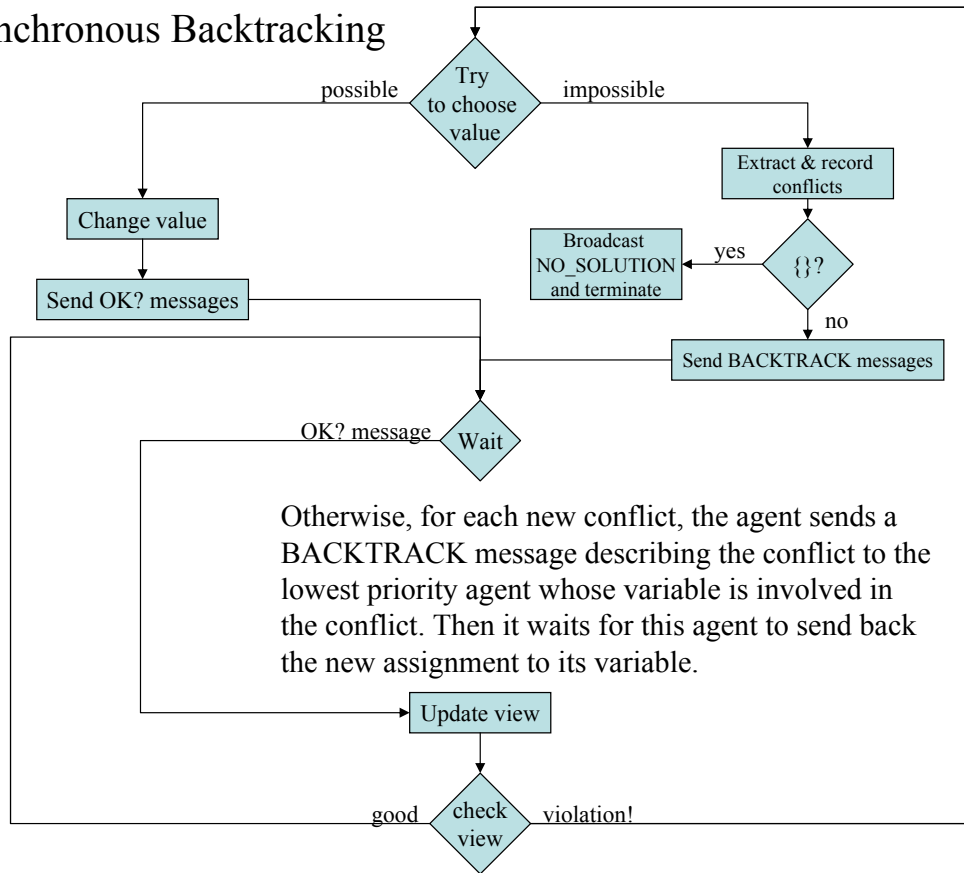
2. Asynchronous Backtracking



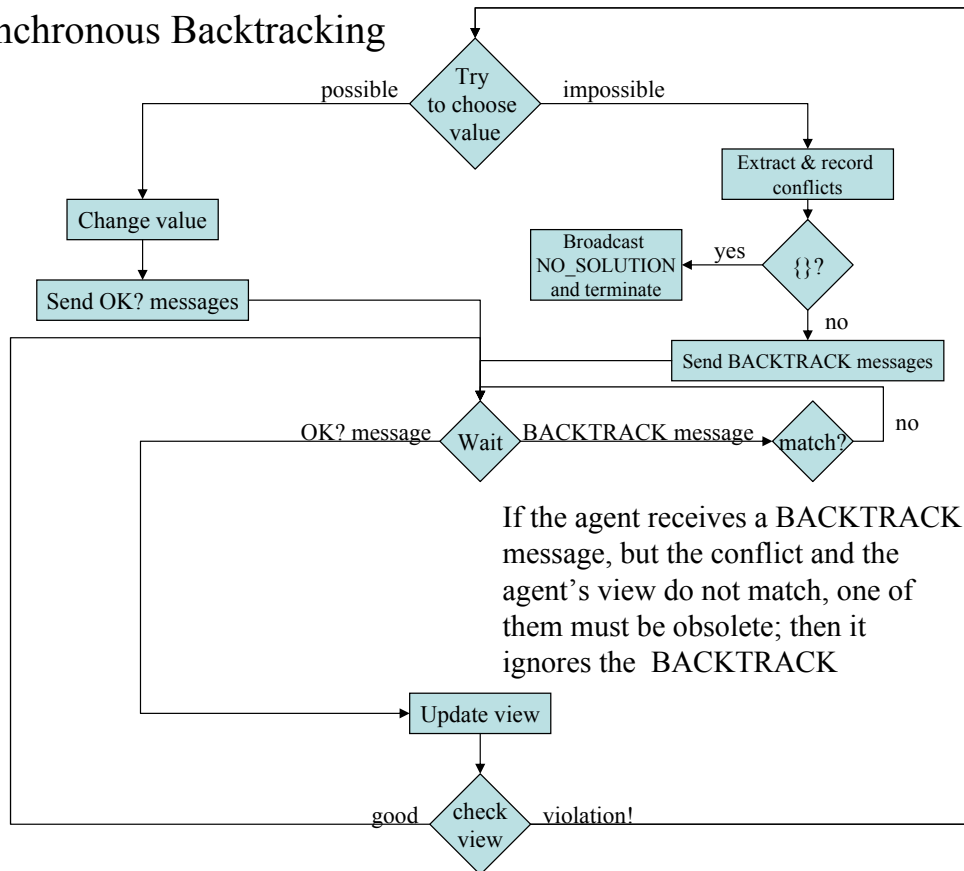
2. Asynchronous Backtracking



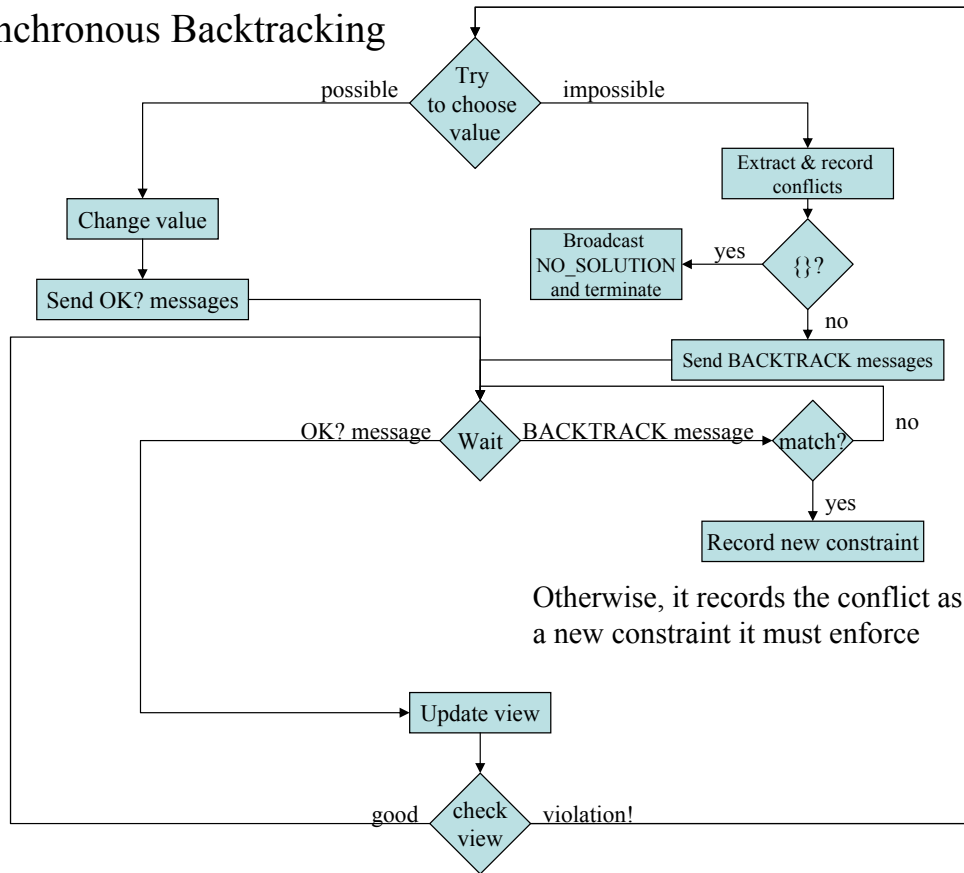
2. Asynchronous Backtracking



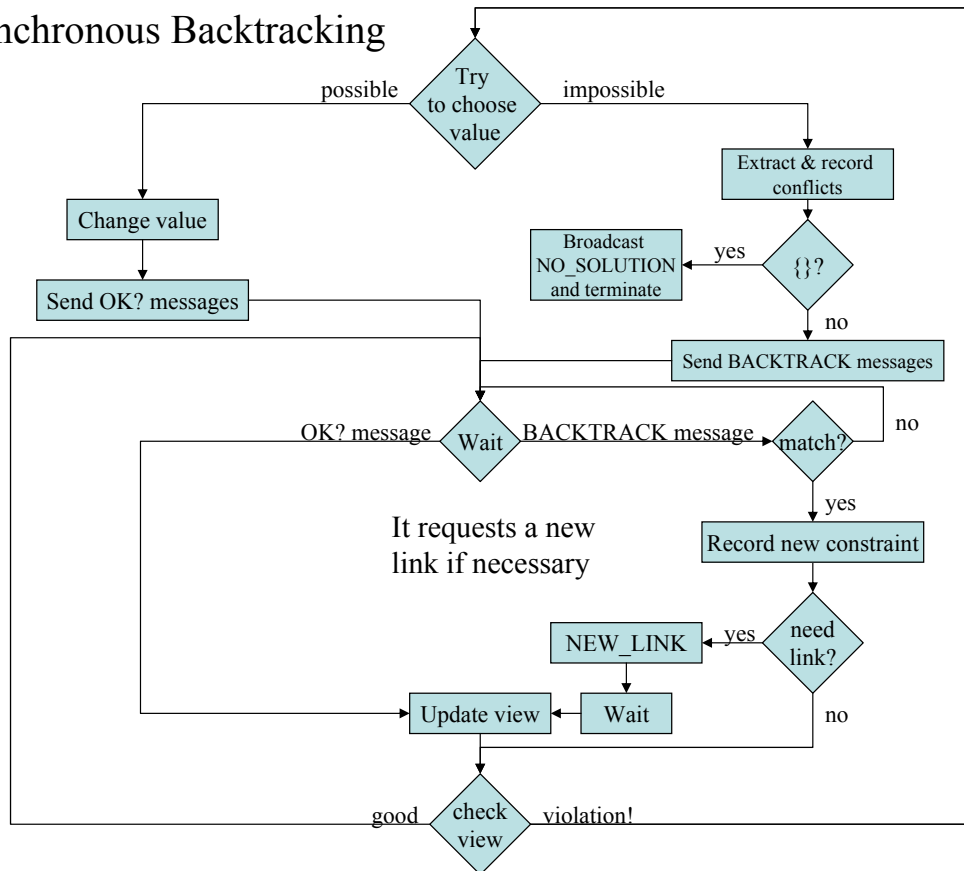
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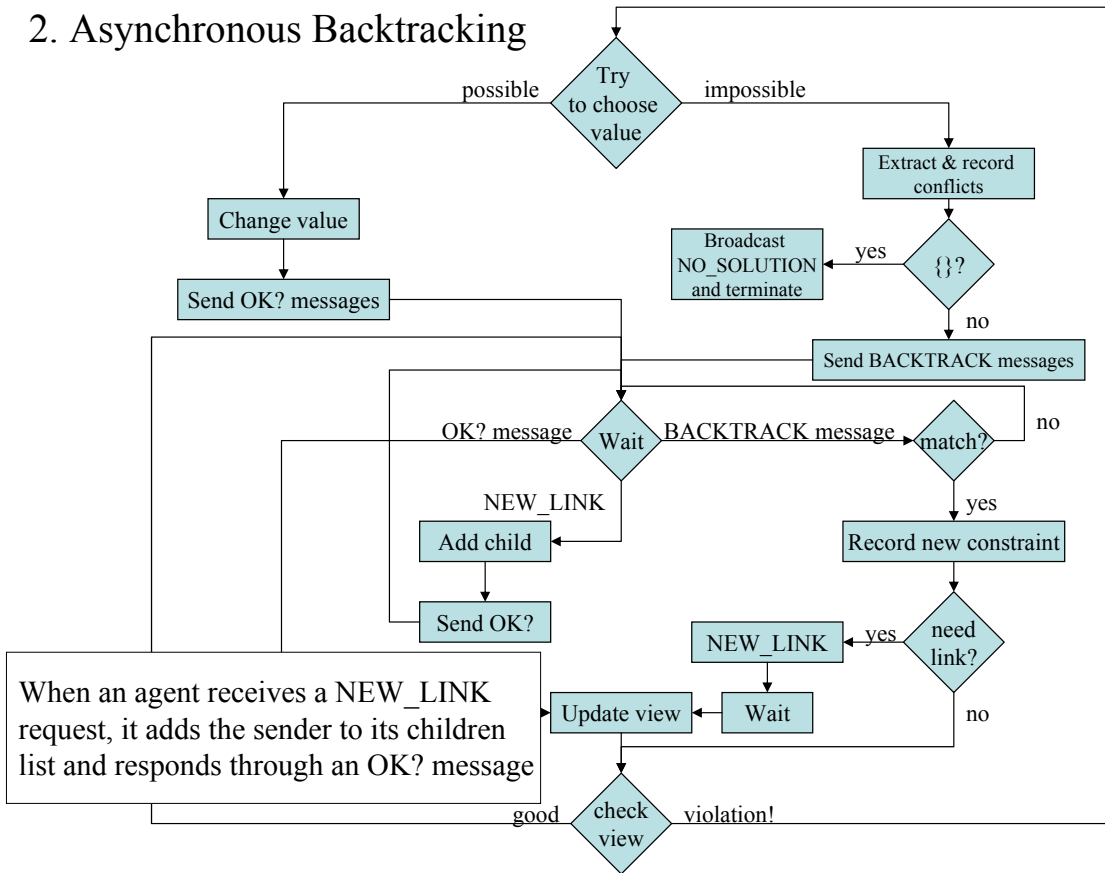
2. Asynchronous Backtracking



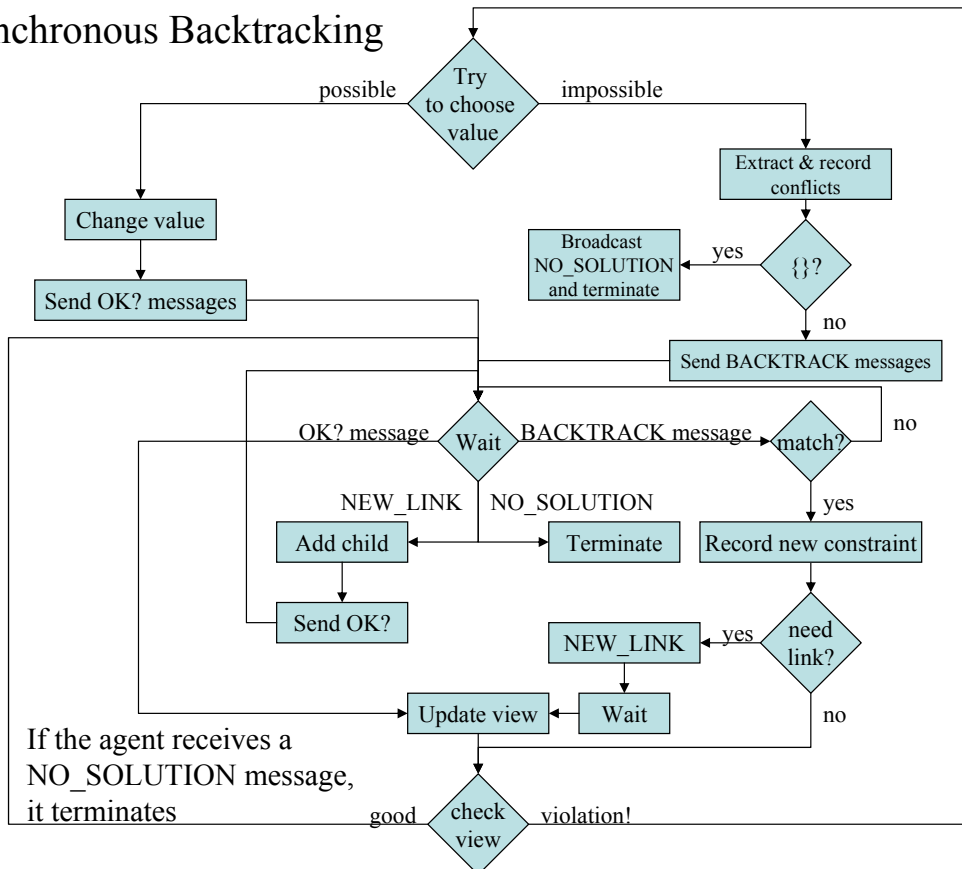
2. Asynchronous Backtracking



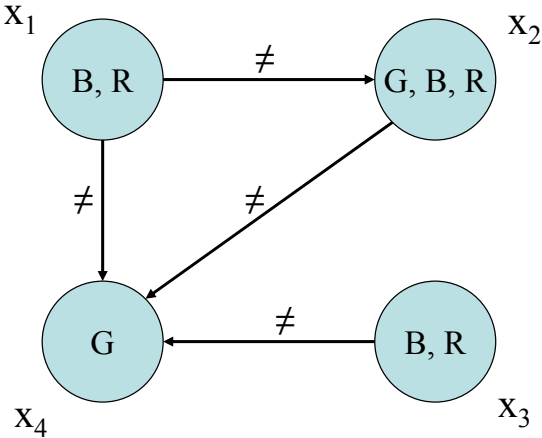
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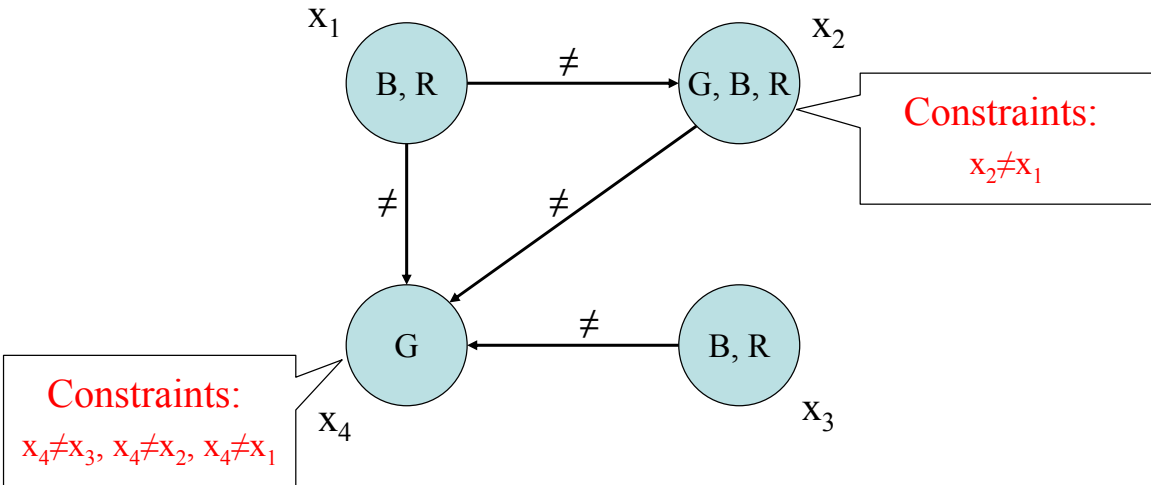
2. Asynchronous Backtracking



2. Asynchronous Backtracking: The Graph Coloring Example



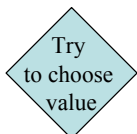
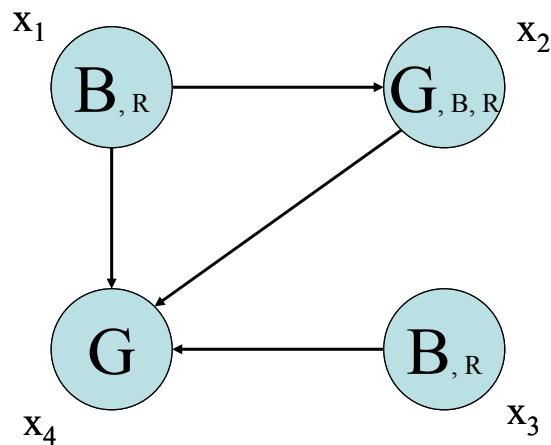
2. Asynchronous Backtracking: The Graph Coloring Example



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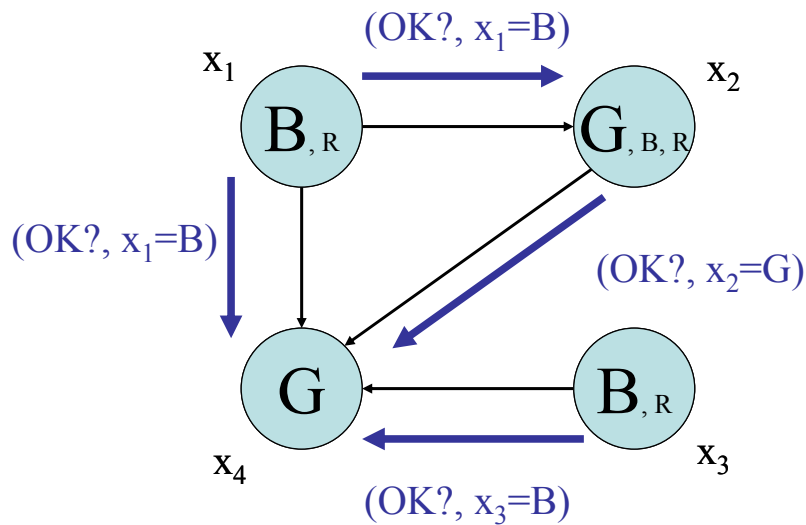
NAME	VALUE		DOMAIN
VIEW	CHILDREN	PARENTS	
	KNOWN CONFLICTS		
	CONSTRAINTS TO ENFORCE		

2. Asynchronous Backtracking: The Graph Coloring Example



Each agent chooses an assignment to its variable

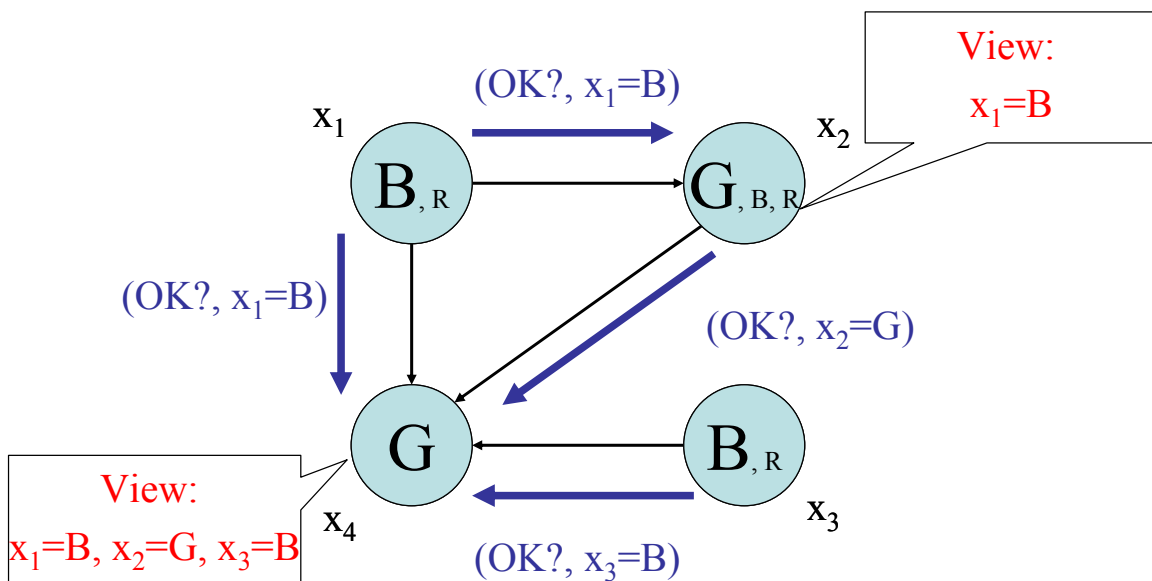
2. Asynchronous Backtracking: The Graph Coloring Example



Send OK? messages

Each agent sends OK? messages to its children

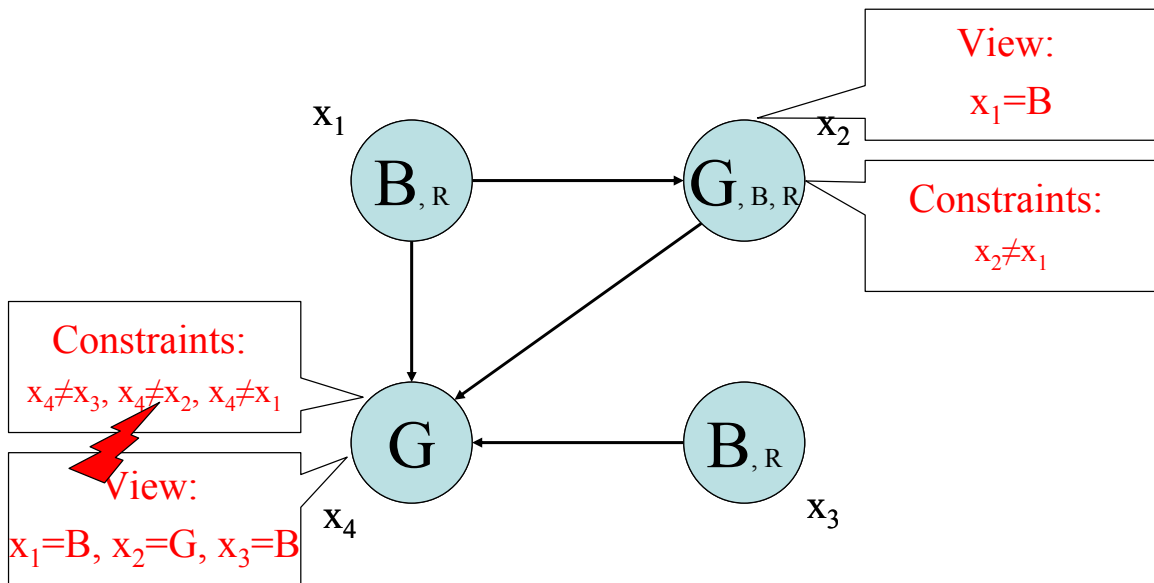
2. Asynchronous Backtracking: The Graph Coloring Example



Update view

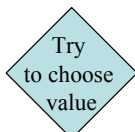
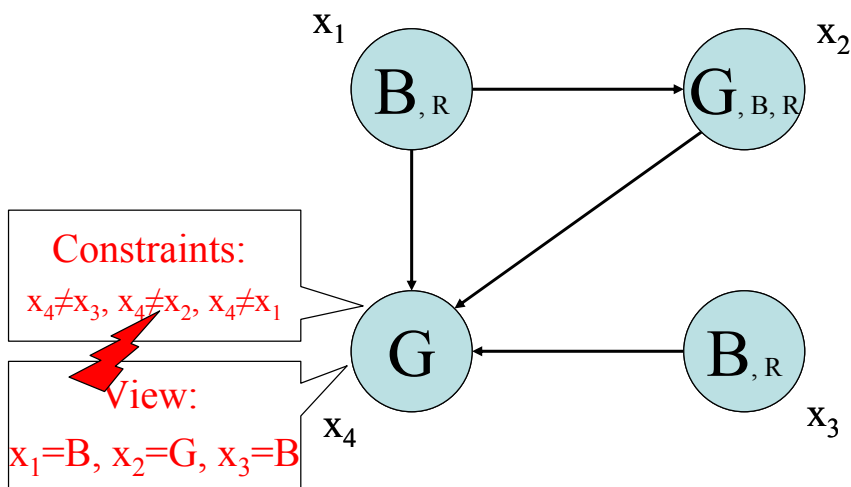
Agent x_2 and Agent x_4 update their view

2. Asynchronous Backtracking: The Graph Coloring Example



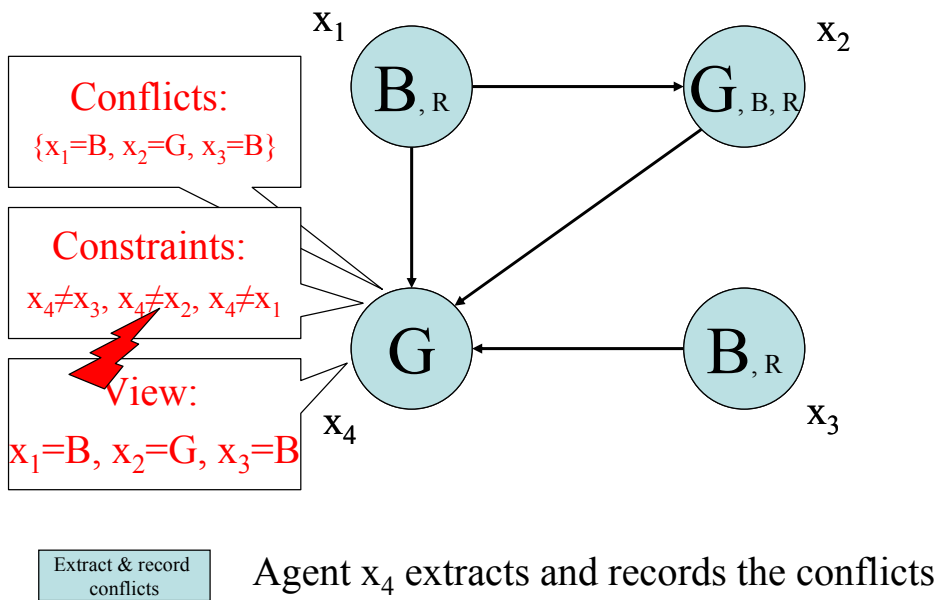
Agent x_2 and Agent x_4 check their view against their constraints, and Agent x_4 discovers a violation

2. Asynchronous Backtracking: The Graph Coloring Example

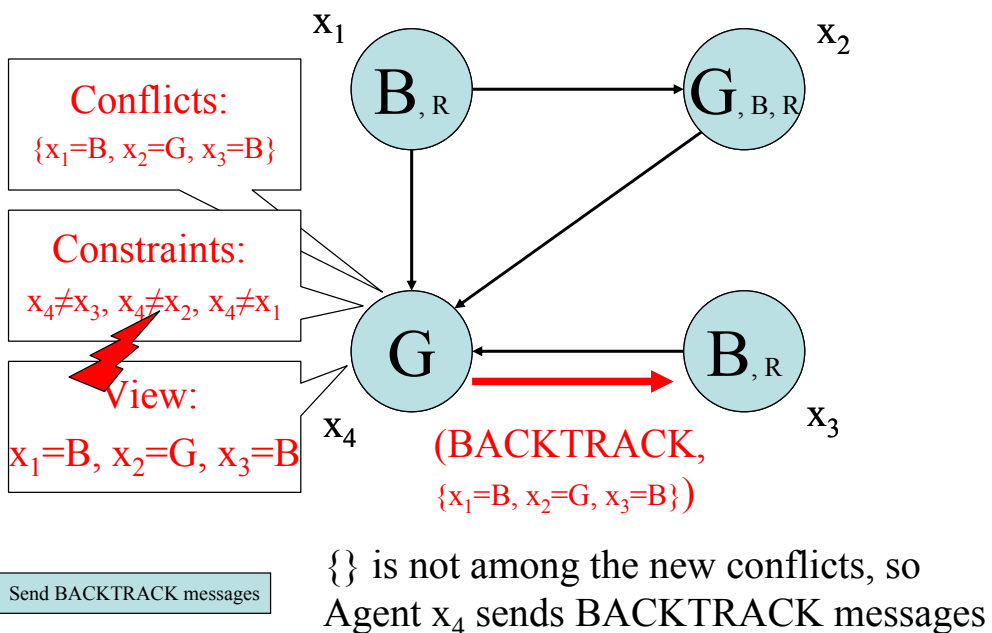


Agent x_4 tries to change its assignment, which is impossible

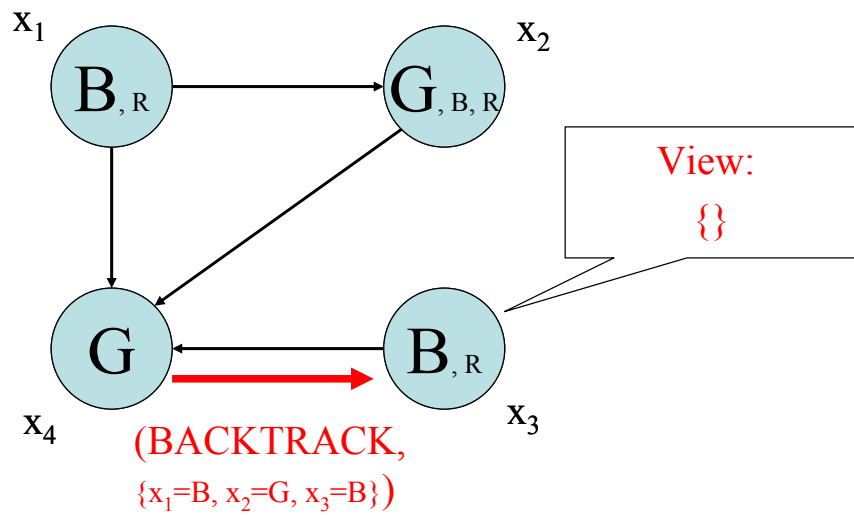
2. Asynchronous Backtracking: The Graph Coloring Example



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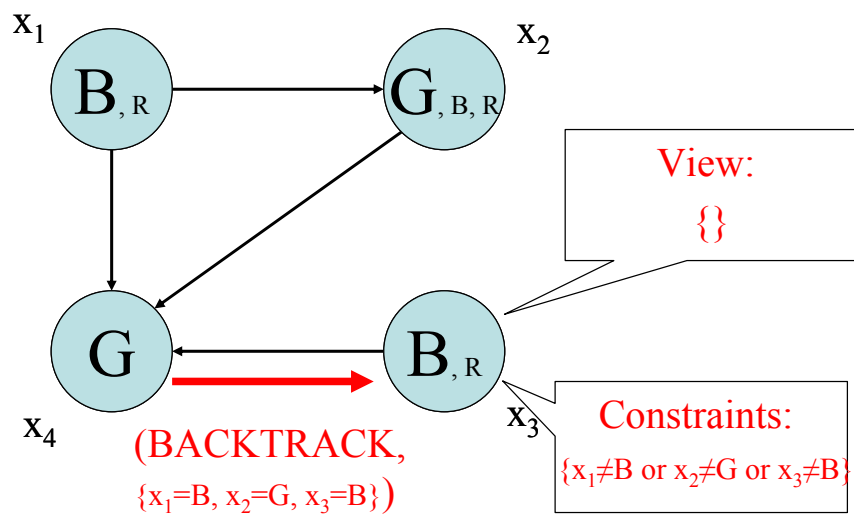


2. Asynchronous Backtracking: The Graph Coloring Example



Agent x_3 receives the message and checks the conflict against its view

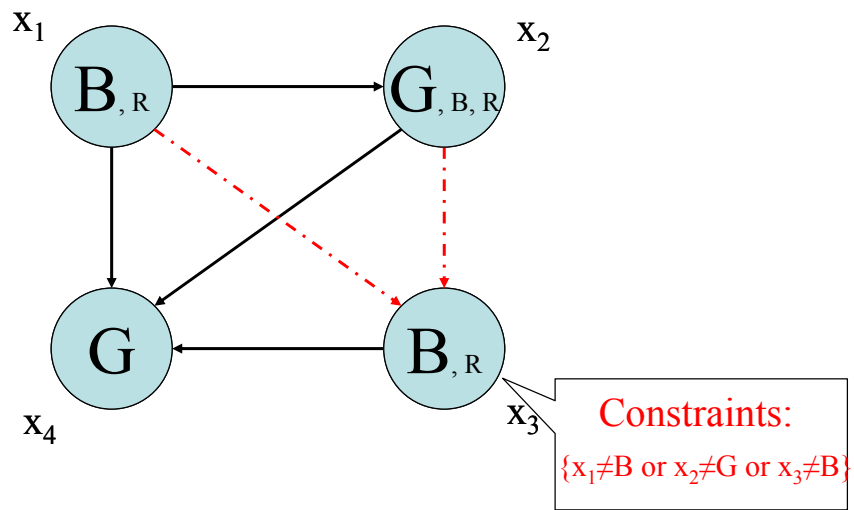
2. Asynchronous Backtracking: The Graph Coloring Example



Record new constraint

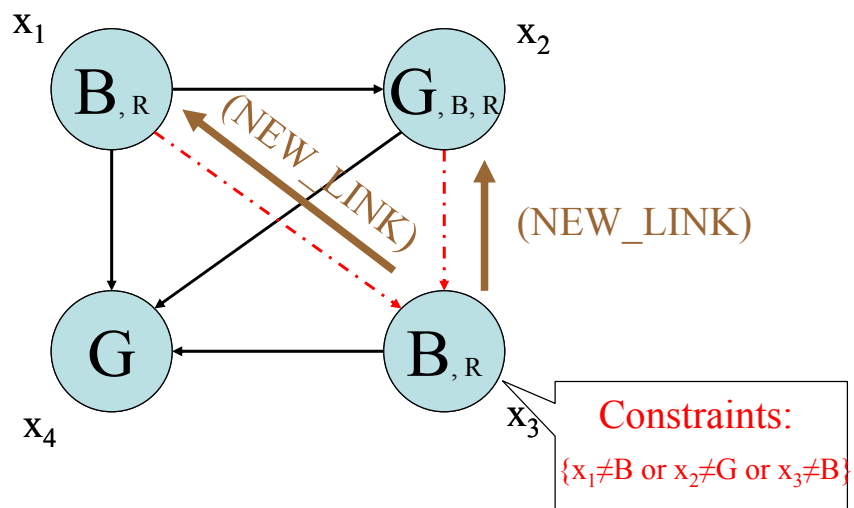
Agent x_3 records the conflict as a new constraint

2. Asynchronous Backtracking: The Graph Coloring Example



Agent x_3 checks if it needs new links to enforce it

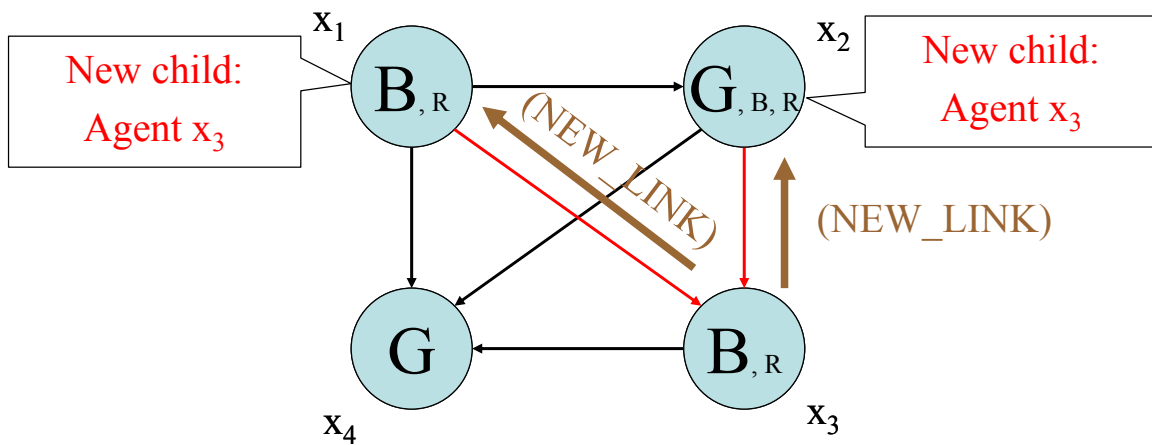
2. Asynchronous Backtracking: The Graph Coloring Example



NEW_LINK

Agent x_3 sends NEW_LINK requests

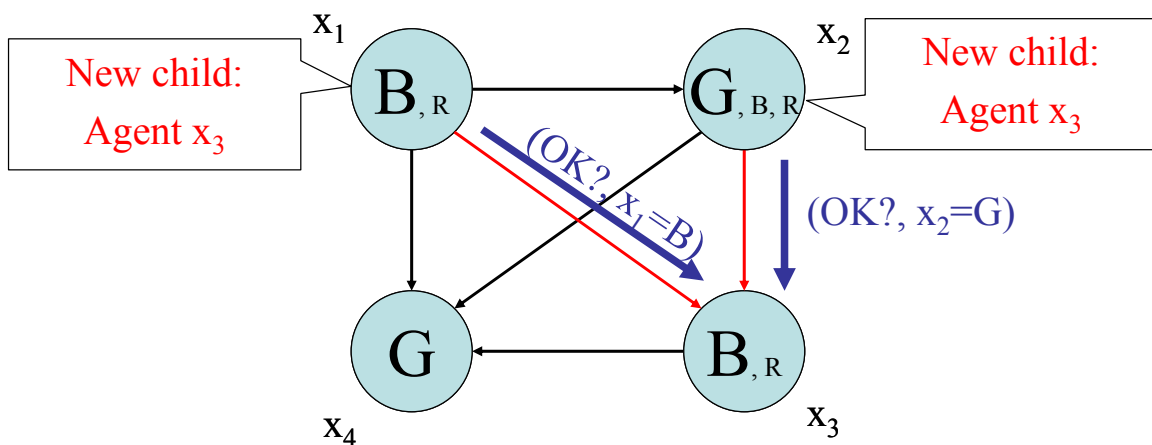
2. Asynchronous Backtracking: The Graph Coloring Example



Add child

Agents x_1 and x_2 receive the NEW_LINK requests and add Agent x_3 to their children list

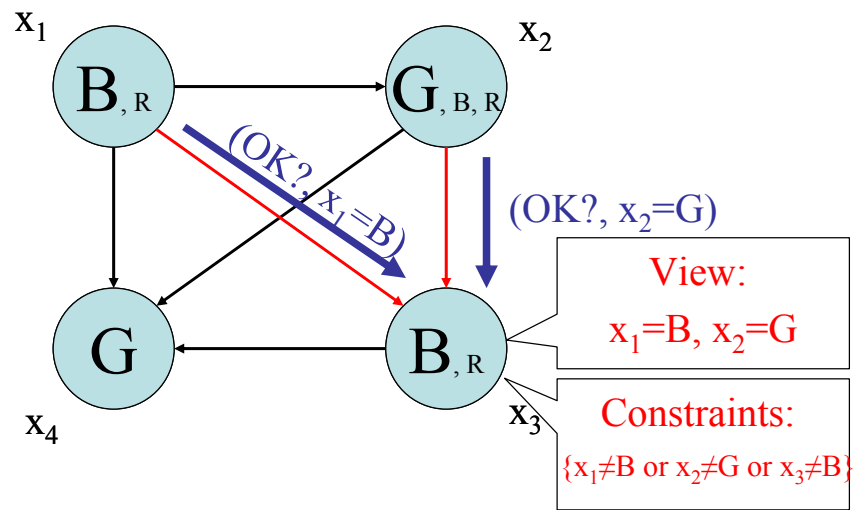
2. Asynchronous Backtracking: The Graph Coloring Example



Send OK?

Agents x_1 and x_2 send $OK?$ to confirm new links

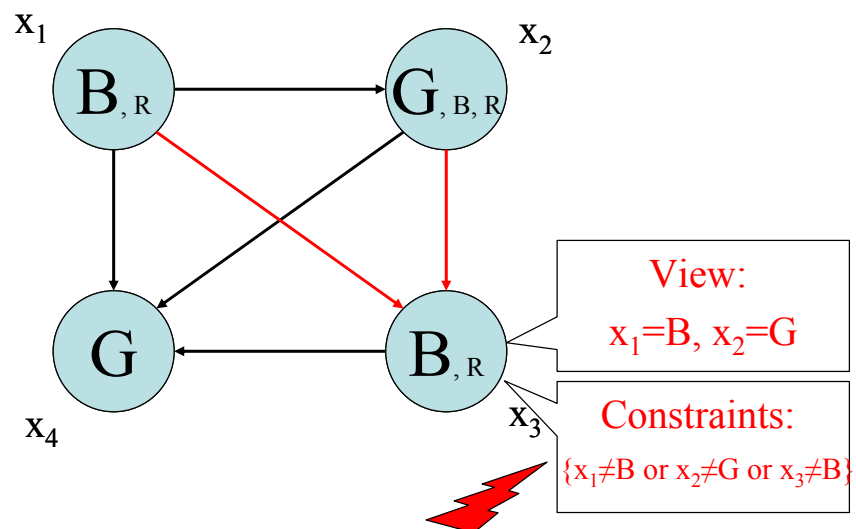
2. Asynchronous Backtracking: The Graph Coloring Example



Update view

Agent x_3 receives messages and updates its view

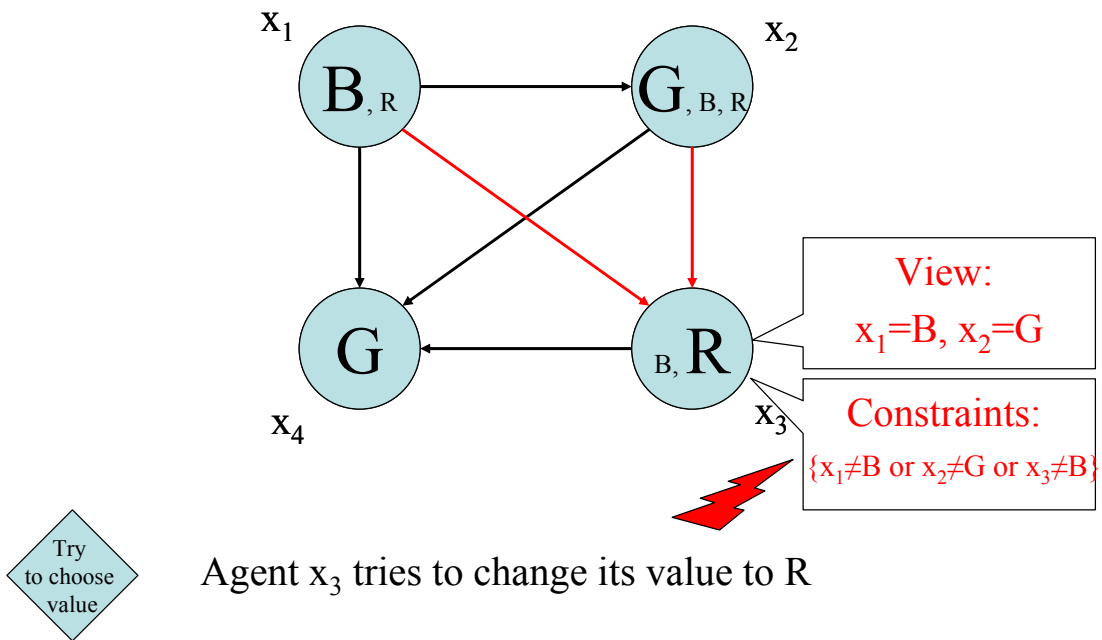
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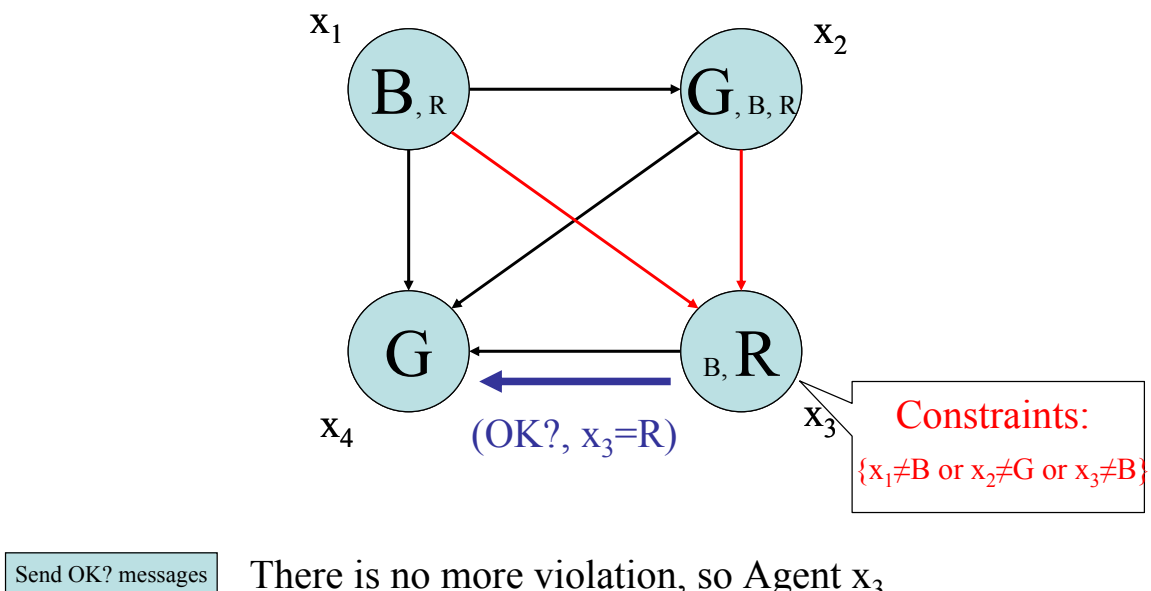
check view

Agent x_3 checks its view, and discovers that one constraint (the new one) is violated

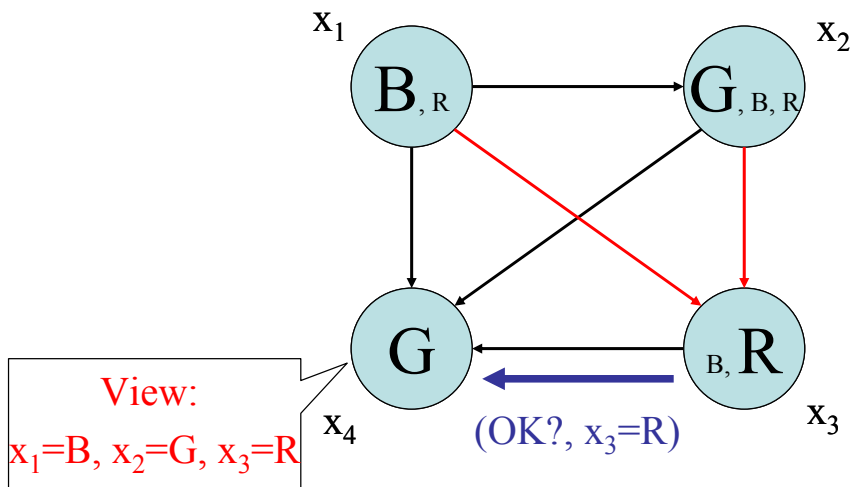
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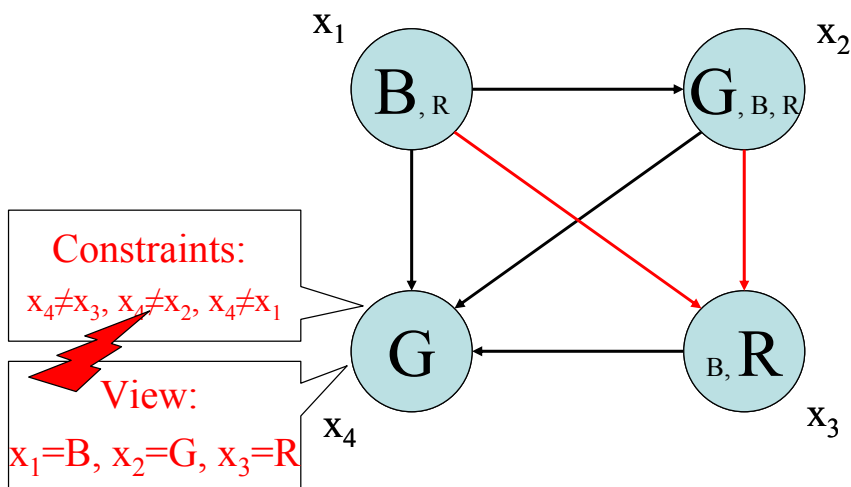
2. Asynchronous Backtracking: The Graph Coloring Example



Update view

Agent x_4 receives the OK? message and updates its view

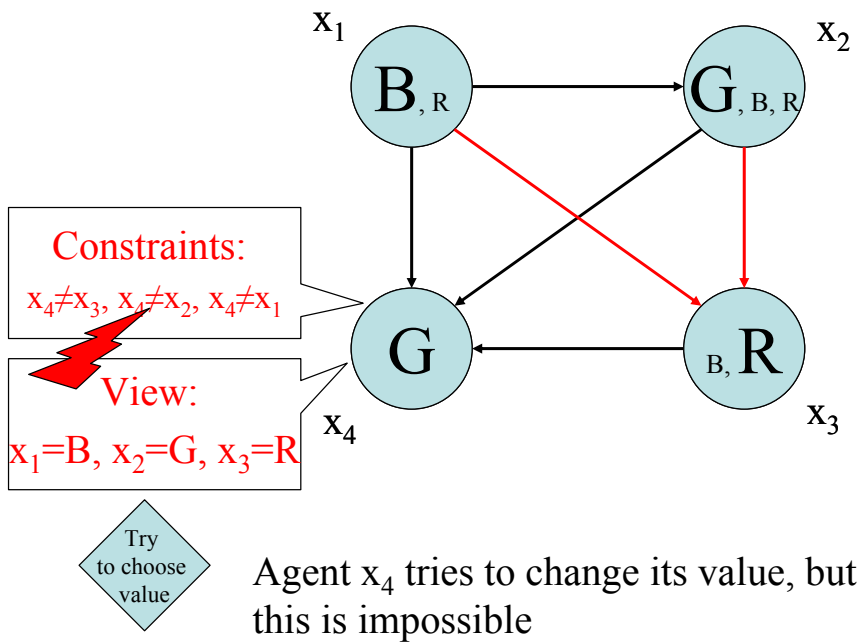
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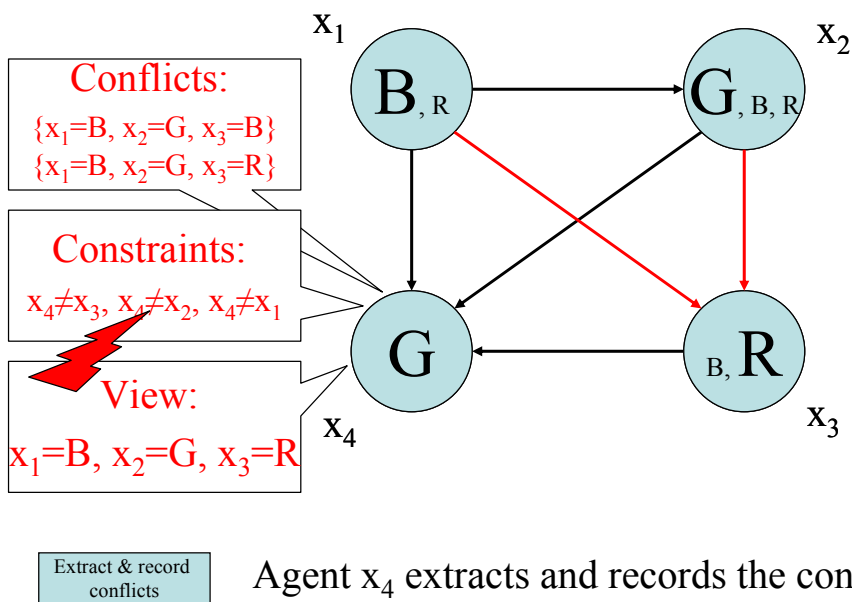
check view

Agent x_4 checks its view against its constraints and sees the violation has not been resolved...

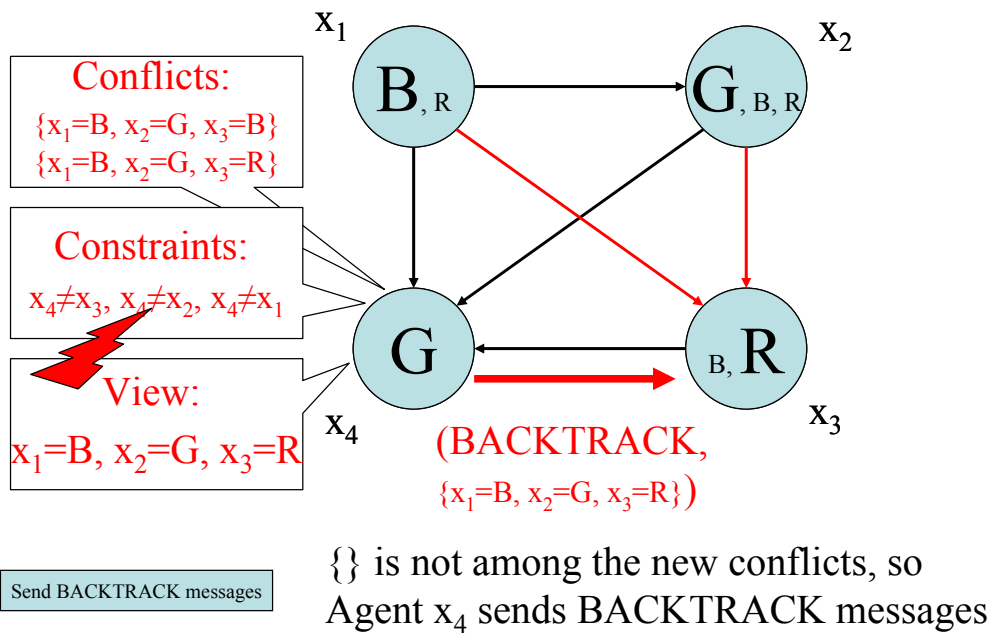
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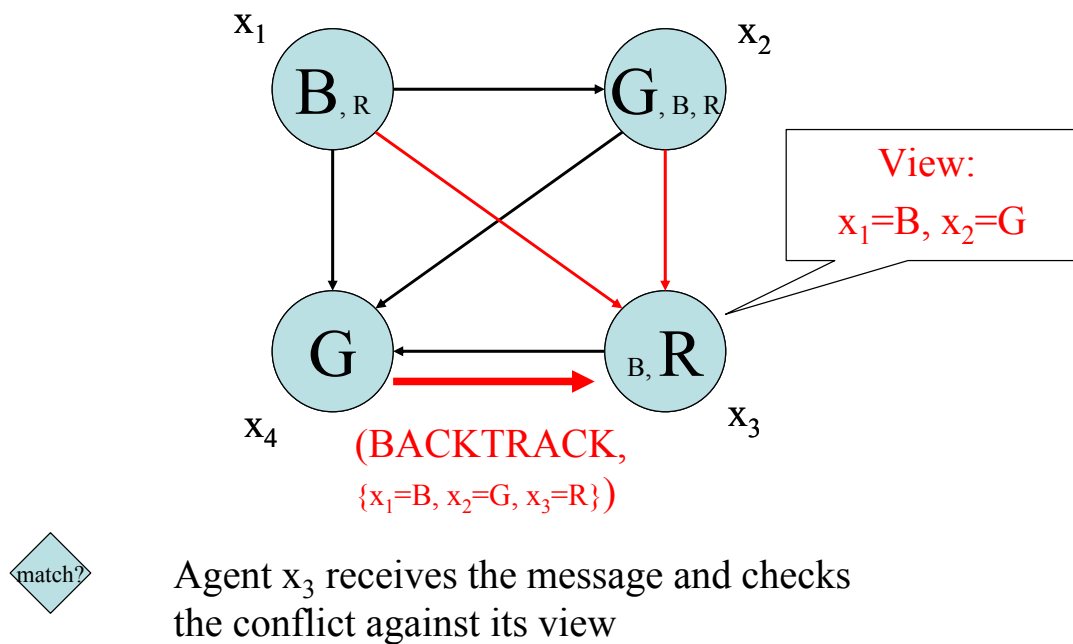
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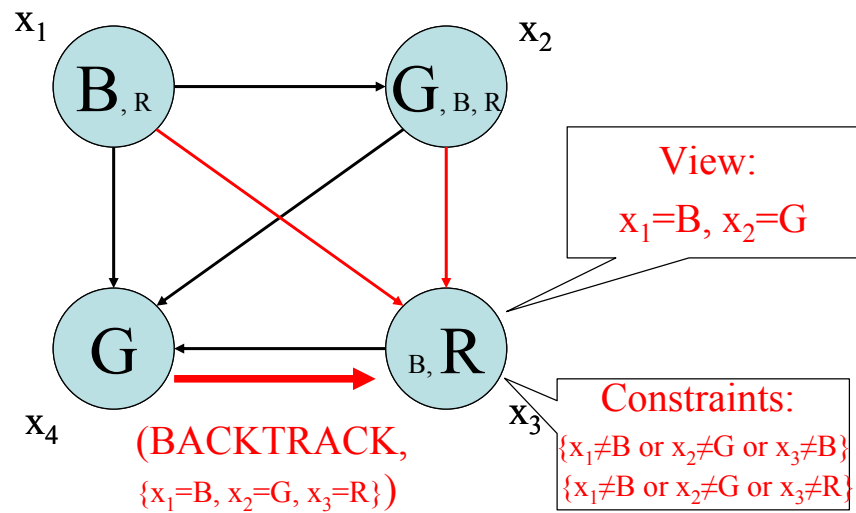
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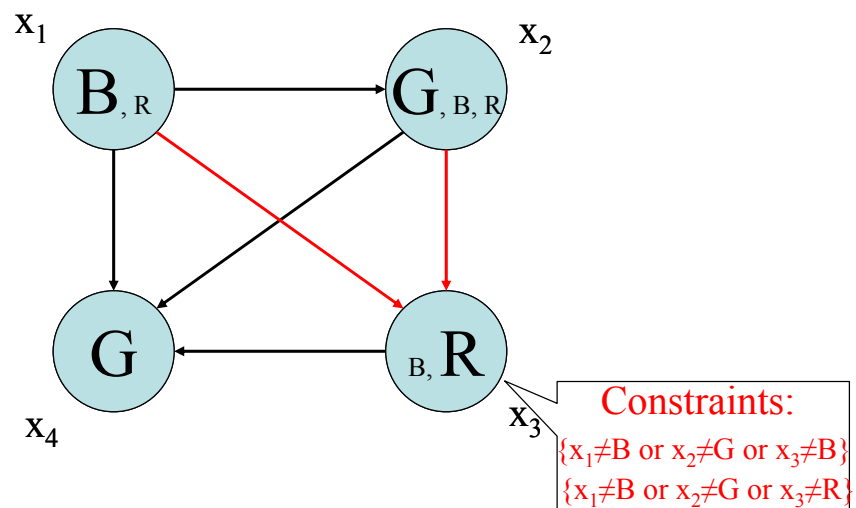
2. Asynchronous Backtracking: The Graph Coloring Example



Record new constraint

Agent x_3 records the conflict as a new constraint

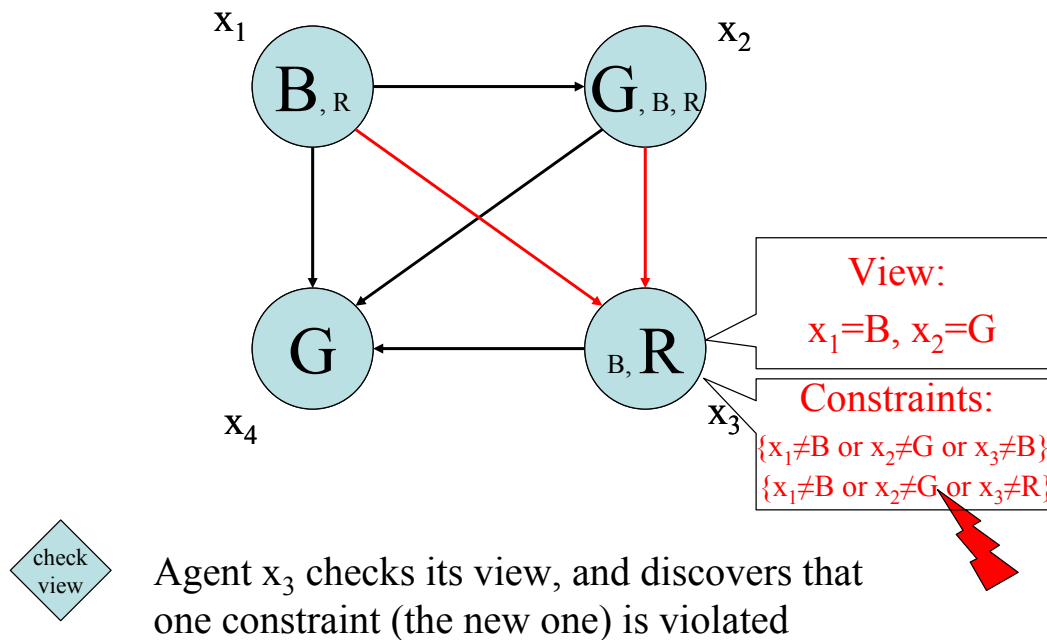
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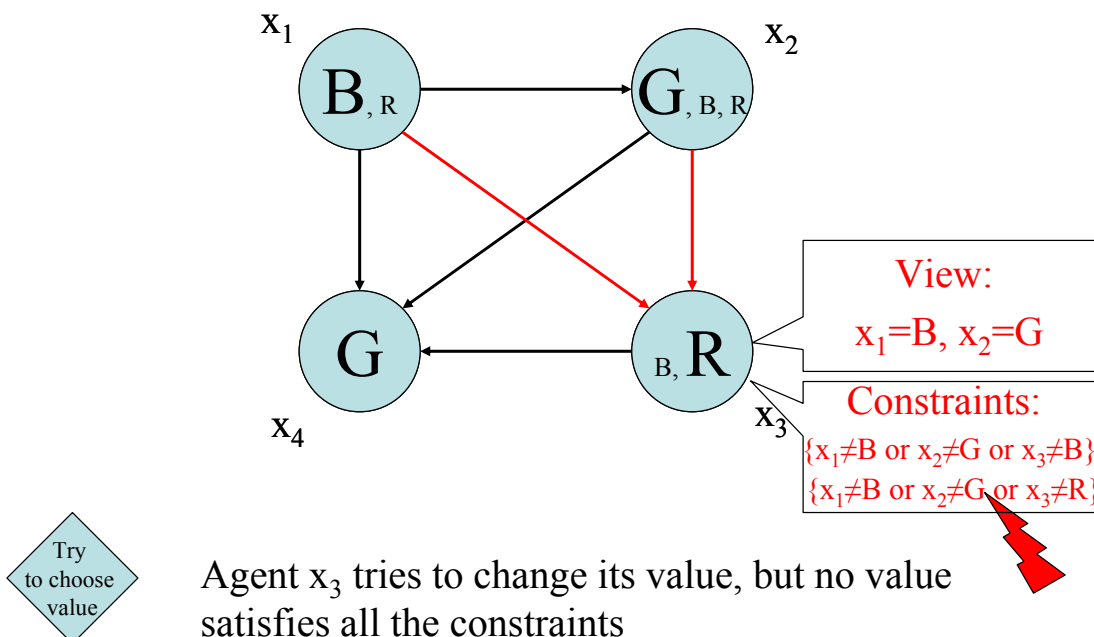
need link?

Agent x_3 needs no new link to enforce it

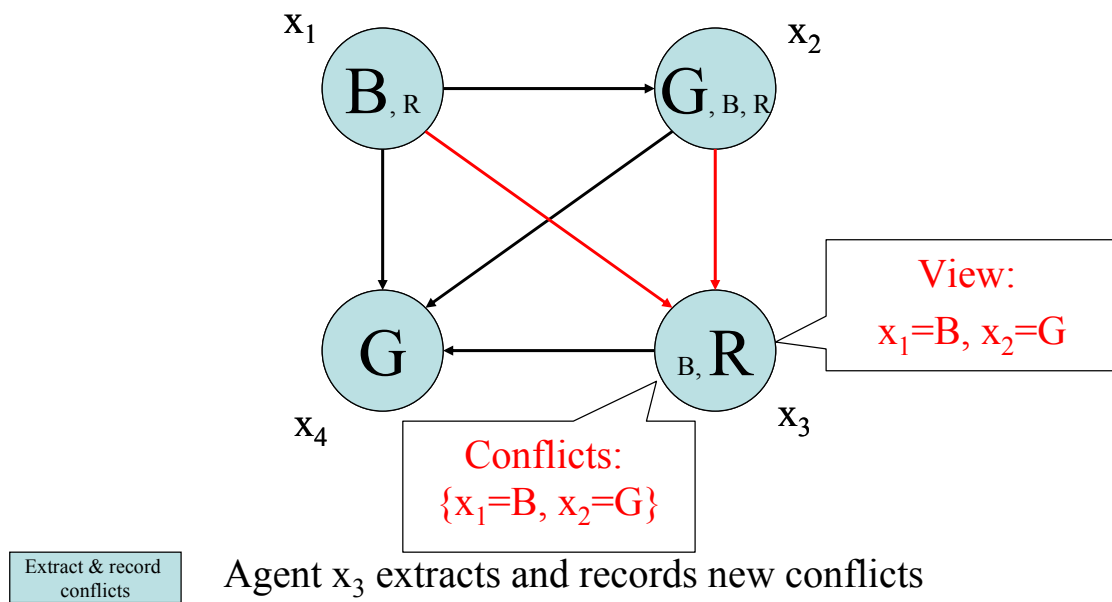
2. Asynchronous Backtracking: The Graph Coloring Example



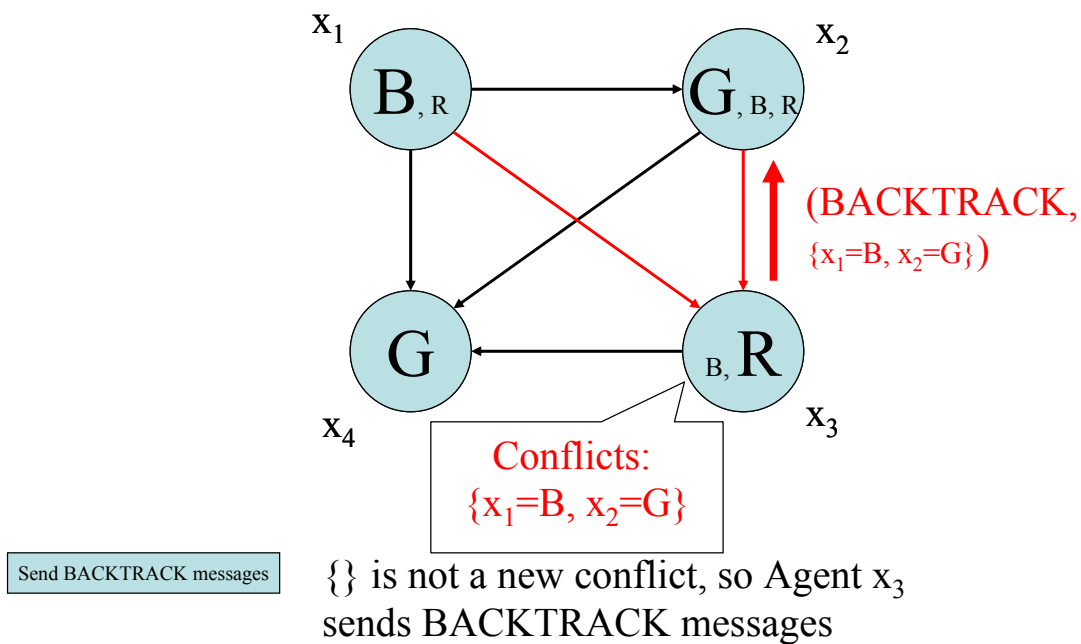
2. Asynchronous Backtracking: The Graph Coloring Example



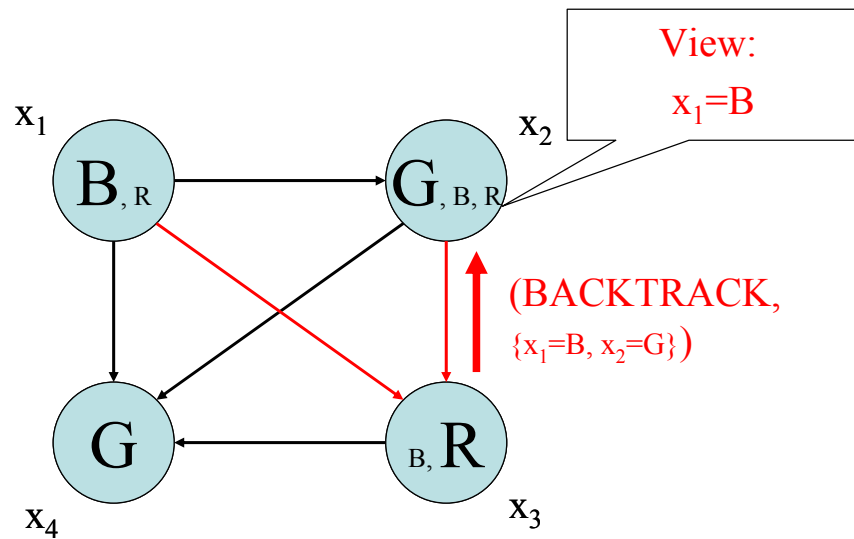
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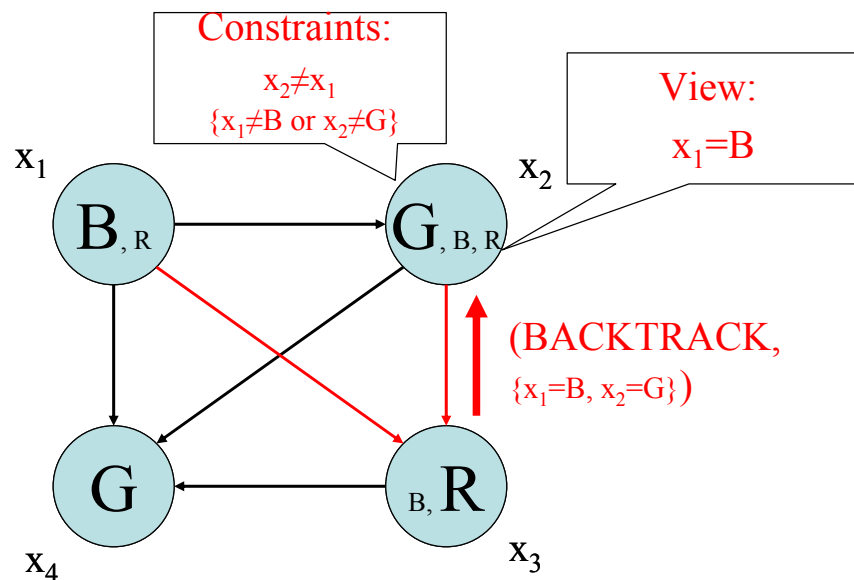


2. Asynchronous Backtracking: The Graph Coloring Example



Agent x_2 receives the message and checks the conflict against its view

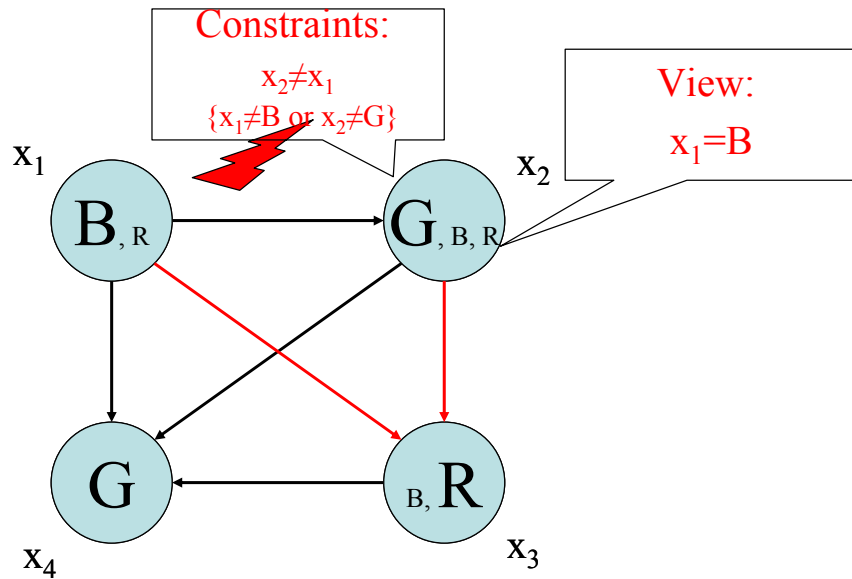
2. Asynchronous Backtracking: The Graph Coloring Example



Record new constraint

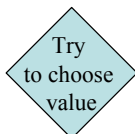
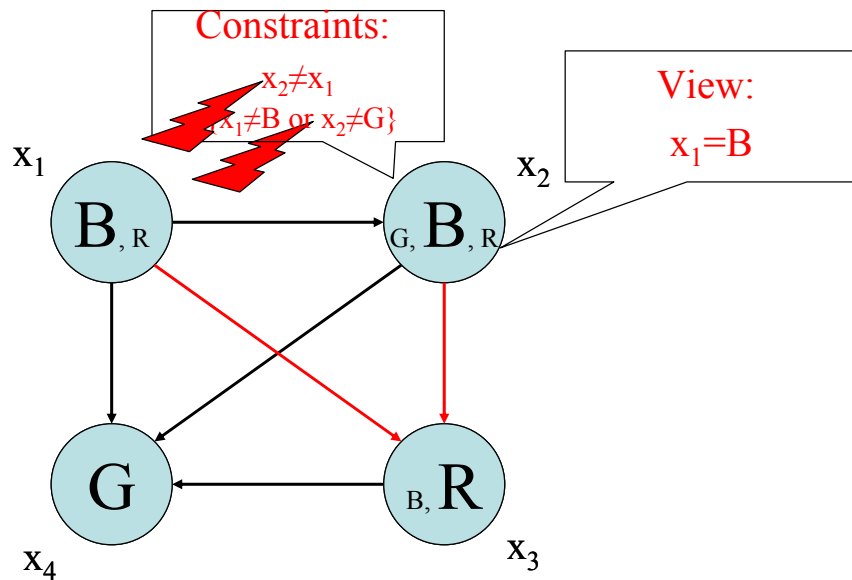
Agent x_2 records the conflict as a new constraint

2. Asynchronous Backtracking: The Graph Coloring Example



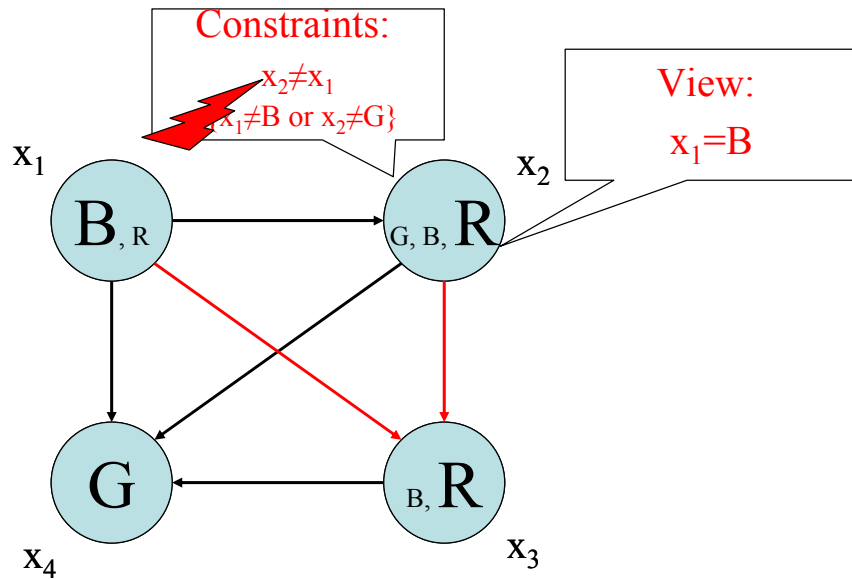
Agent x_3 checks its view, and discovers that one constraint (the new one) is violated

2. Asynchronous Backtracking: The Graph Coloring Example



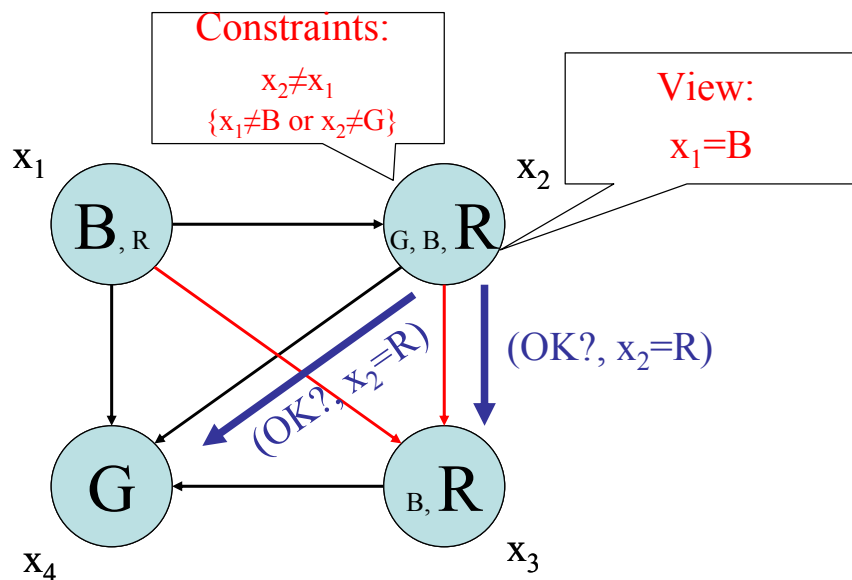
Agent x_2 tries to change its value to B , but it would violate the first constraint

2. Asynchronous Backtracking: The Graph Coloring Example



Agent x_2 tries to change its value to R

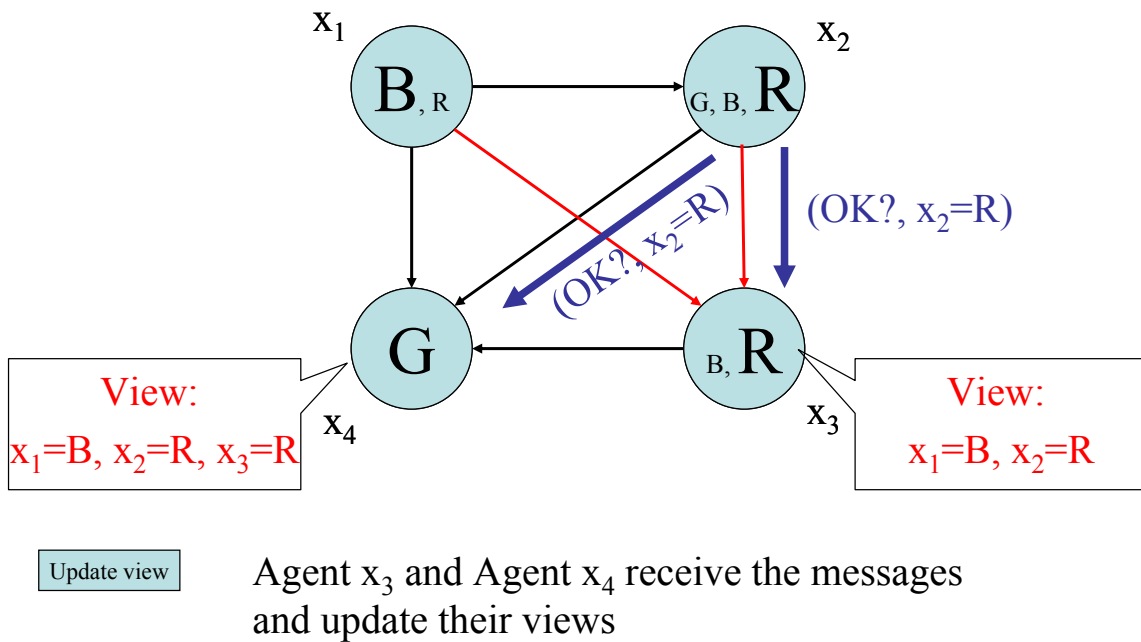
2. Asynchronous Backtracking: The Graph Coloring Example



Send OK? messages

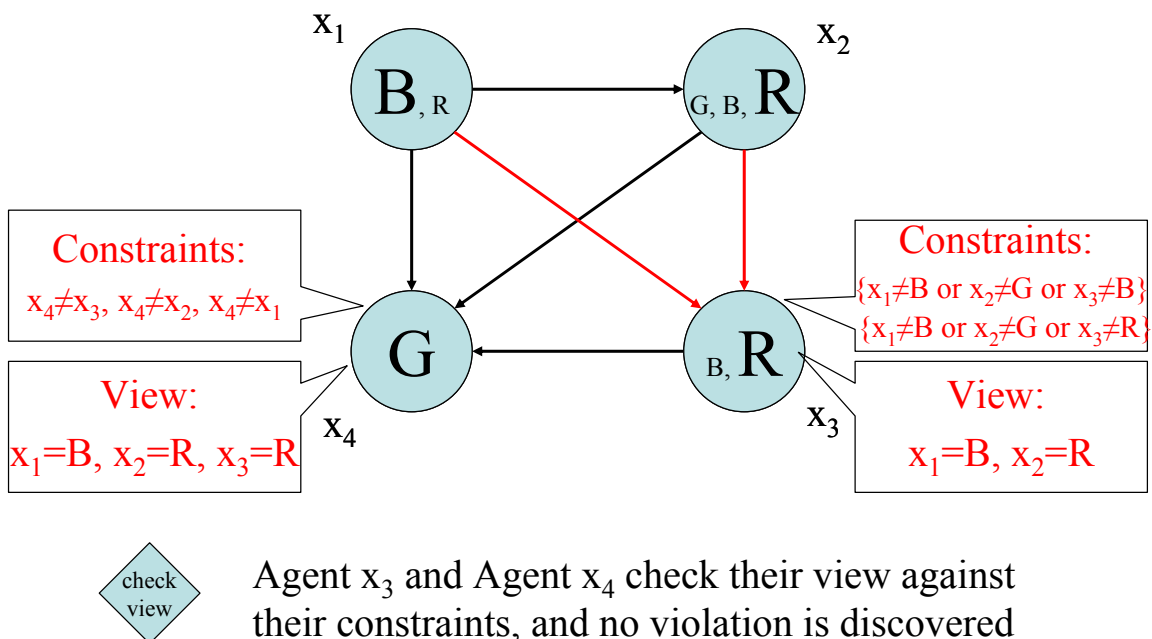
The constraint is no longer violated, so Agent x_2 chooses value R and communicates it to its children

2. Asynchronous Backtracking: The Graph Coloring Example



2. Asynchronous Backtracking: The Graph Coloring Example

SOLVED!



Weaknesses of the Asynchronous Backtracking Algorithm

- How to better choose the assignments?
 - Use a heuristic to make better choices
- The authors prove the algorithm always reaches a stable state within a finite number of steps, BUT it still lacks a termination procedure
 - Use a “Distributed Snapshot” external procedure

K. M. Chandy and L. Lamport, *Distributed Snapshots: Determining Global States of Distributed Systems*, ACM Transactions on Computer Systems, 1985

Weaknesses of the Asynchronous Backtracking Algorithm (cont.)

- Need of a judicious priority ordering among the agents
 - Do it beforehand? (might be difficult + need of a centralizing agent...)
 - Dynamic priority ordering: let the agents come up with a judicious ordering themselves, as they encounter conflicts

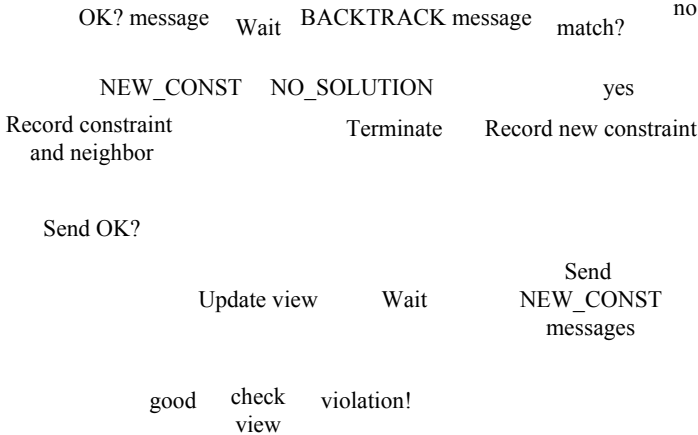
Weaknesses of the Asynchronous Backtracking Algorithm (cont.)

- How to extract conflicts?
 - Open to all conflict extraction policies
 - There is a trade off between taking the time to extract minimal conflicts, and trying to speed up the algorithm by using the agent's view as a super-conflict but wasting time by backtracking more often

possible Try
 to choose
 value impossible

Extract & record
conflicts

3. The Asynchronous Weak-Commitment Search Algorithm



3. The Asynchronous Weak-Commitment Search Algorithm

- Use a local min-conflict heuristic to guide the choices of assignments
- Judiciously change the priority ordering every time the search needs to backtrack

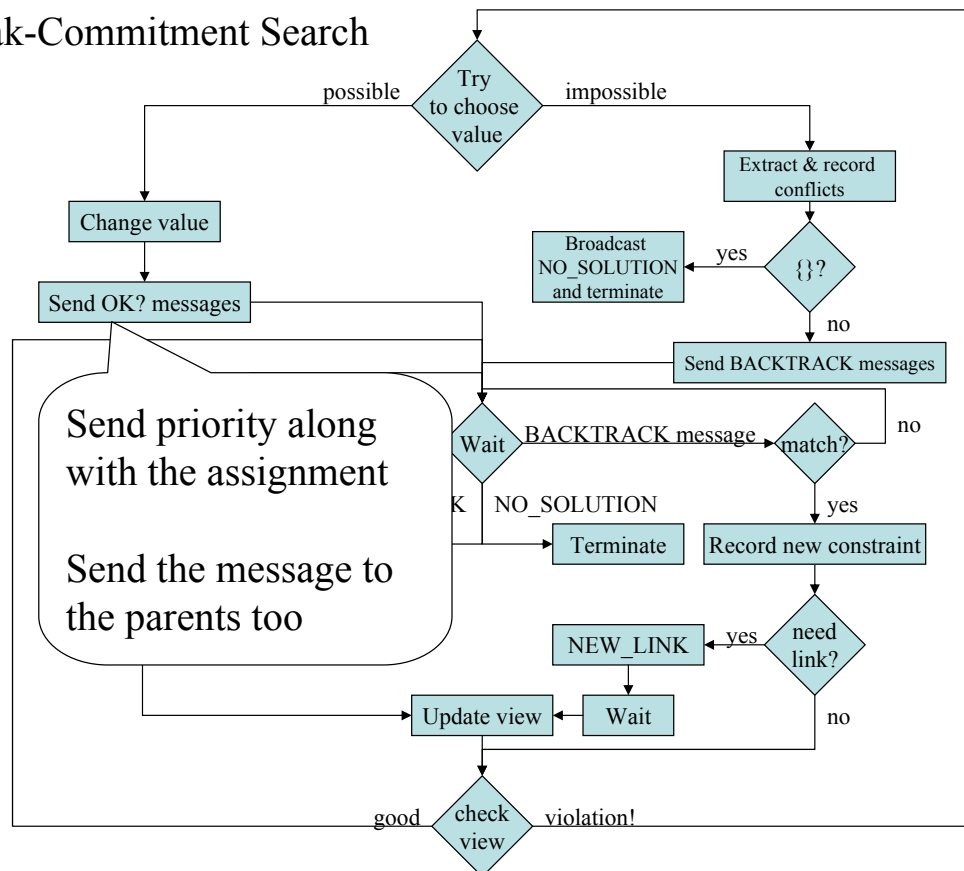
3. The Asynchronous Weak-Commitment Search Algorithm (cont.)

- “Weak-Commitment” Search:
 - A partial assignment to the variables is constructed step by step by extending it to variables with lower priority
 - The group of agents “weakly commits” itself to the partial assignment because the partial assignment is abandoned as soon as the algorithm needs to backtrack
 - The priority ordering is then modified so that the agent which failed to find a value to its variable consistent with the constraints “promotes itself” (i.e. it changes its priority value to locally become the agent with the highest priority)

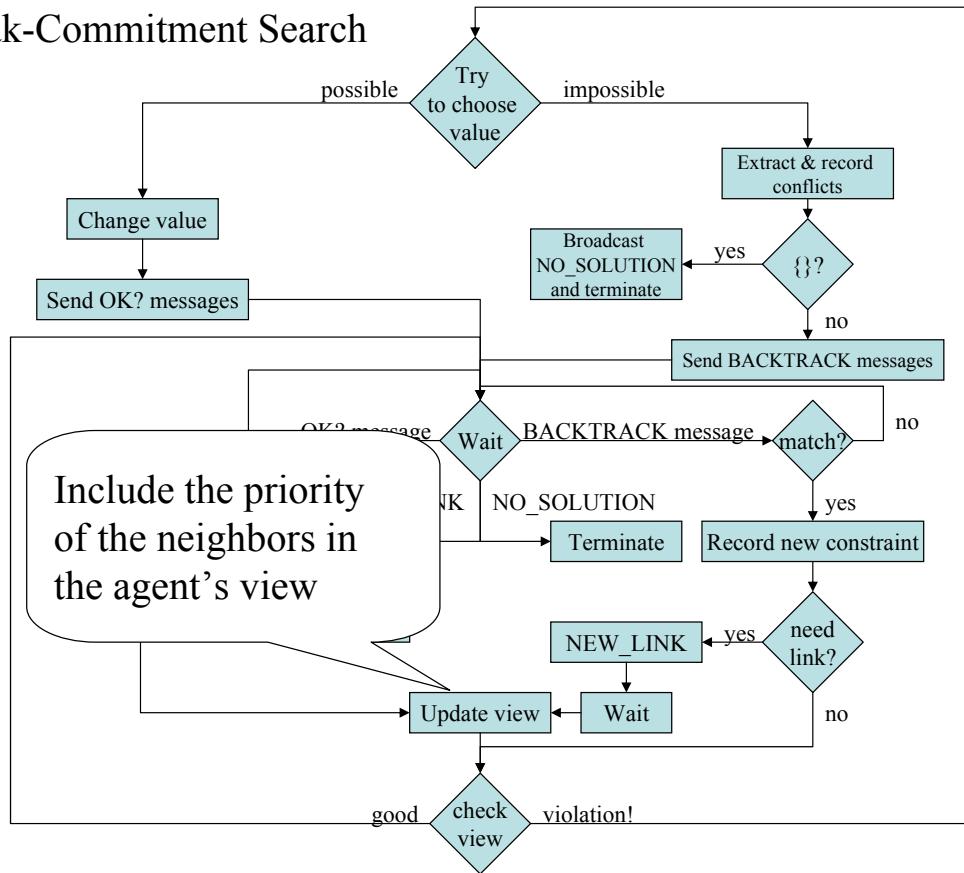
3. The Asynchronous Weak-Commitment Search Algorithm (cont.)

- ATTENTION! Tricky point:
 - Every time an agent discovers a known conflict in its view, it will abandon the partial solution
 - However, if, due to message delays, the agent's view is obsolete, it will abandon the partial assignment too early and perform an unnecessary change in its priority value
 - To avoid reacting to such unstable situations, the agent records the conflicts it has already sent, and it will temporarily ignore a conflict if it has already sent it before

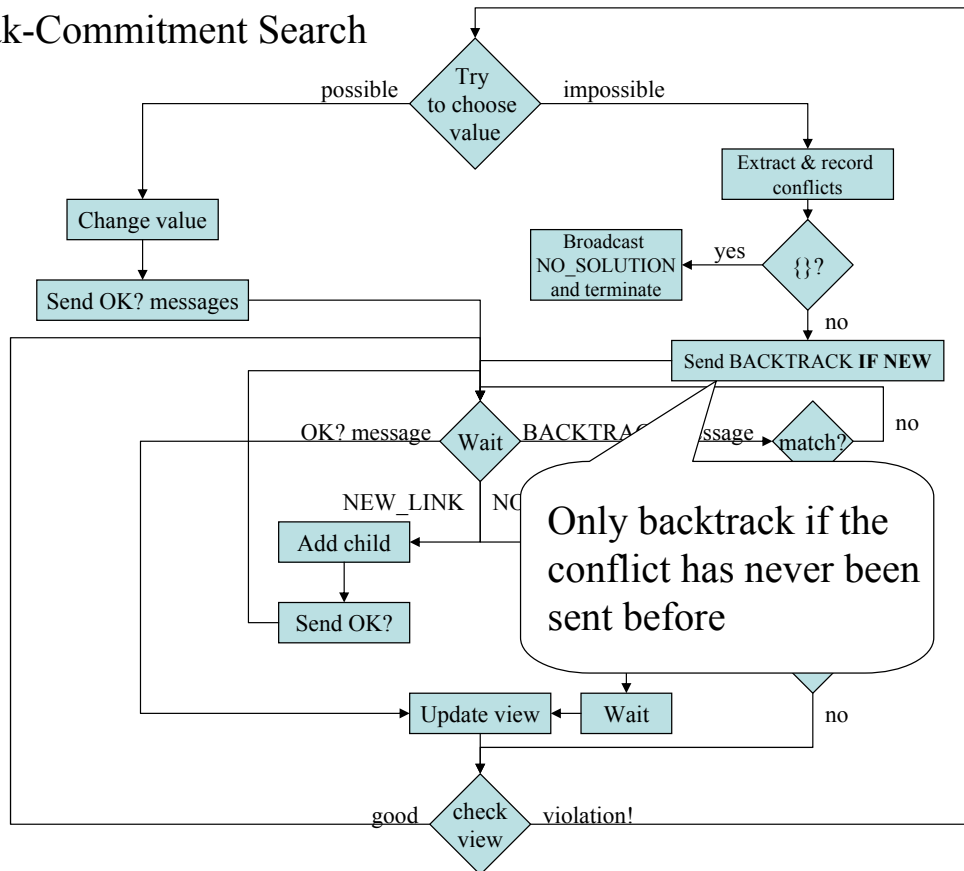
3. Weak-Commitment Search



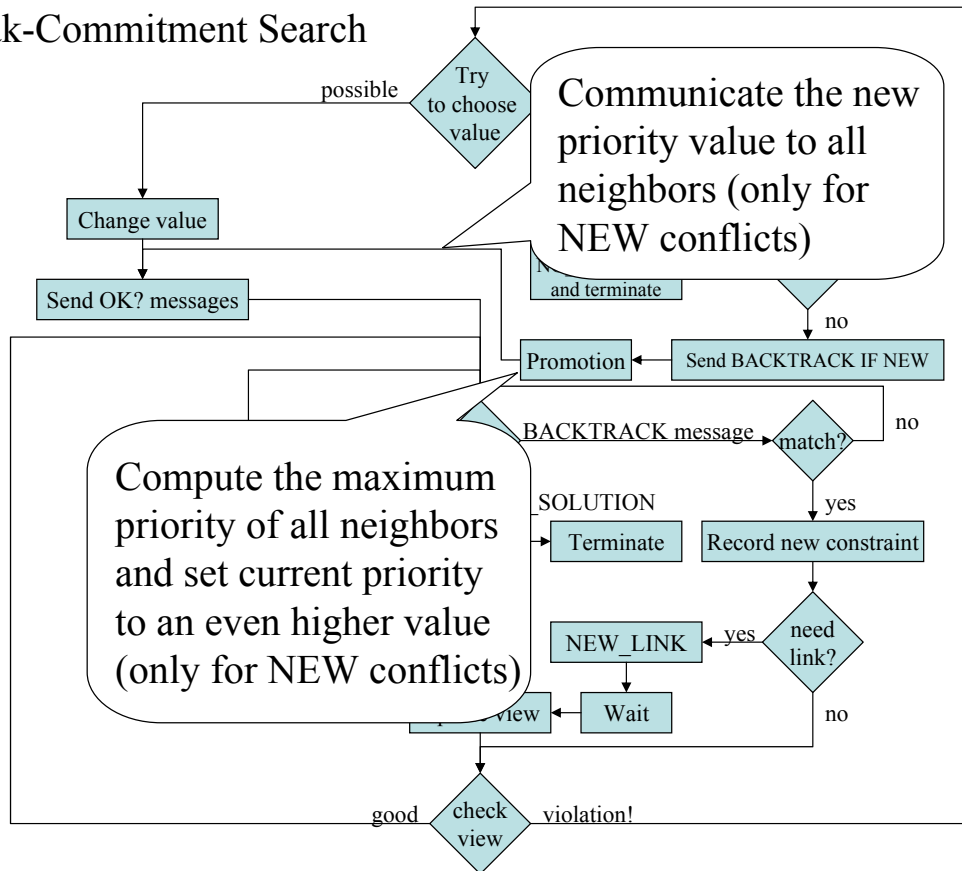
3. Weak-Commitment Search



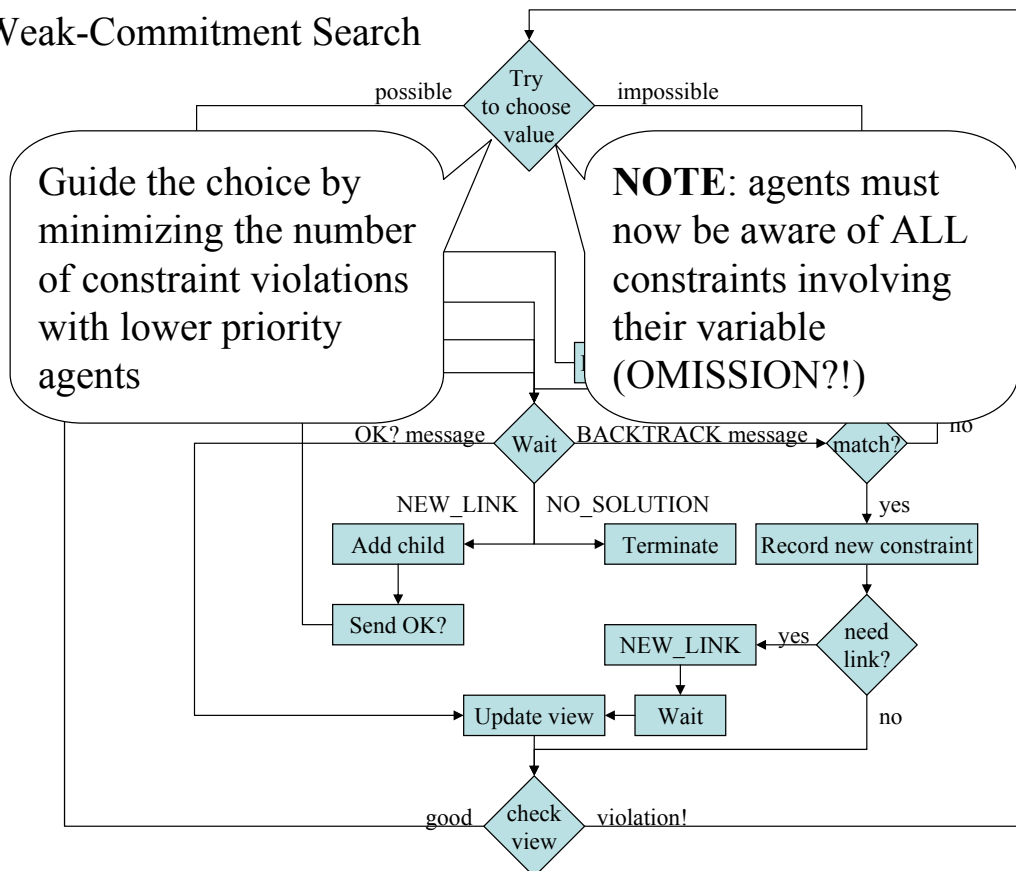
3. Weak-Commitment Search



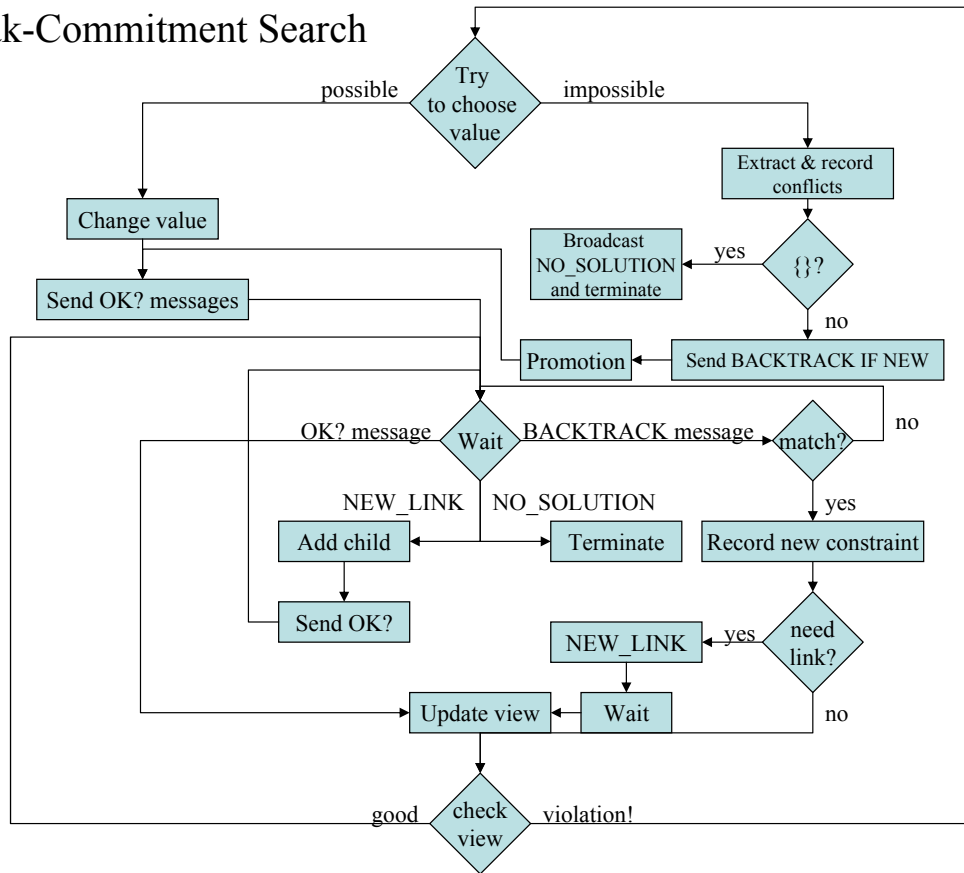
3. Weak-Commitment Search



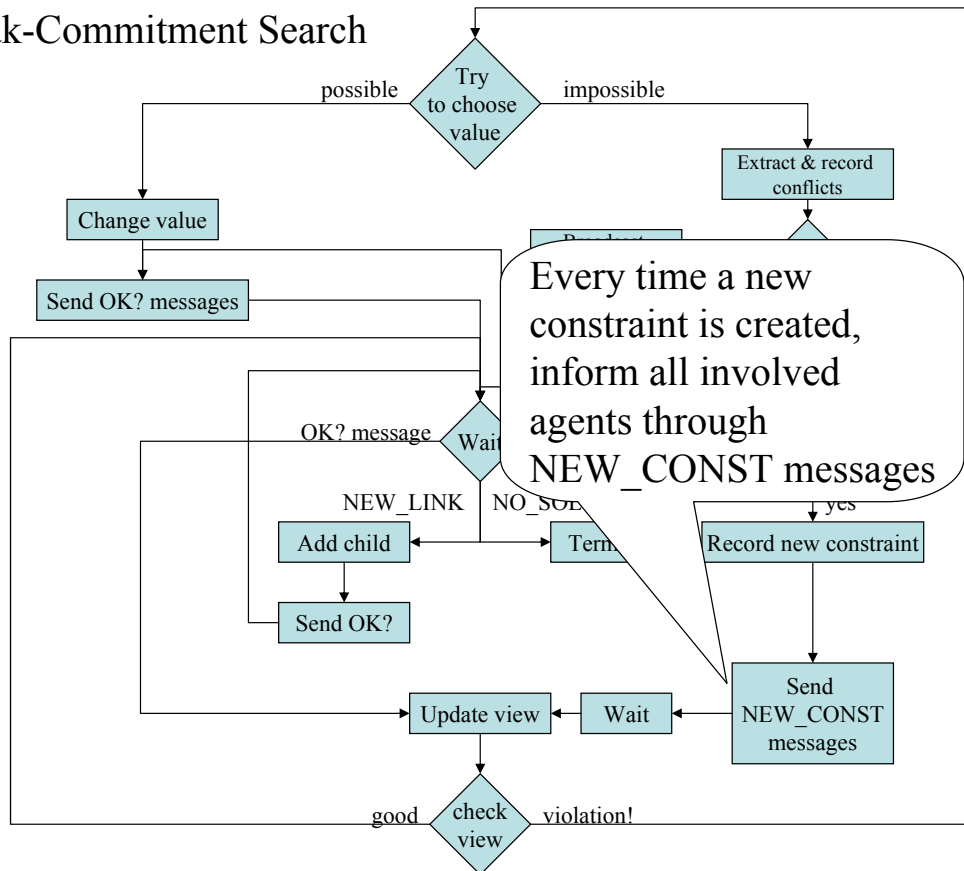
3. Weak-Commitment Search



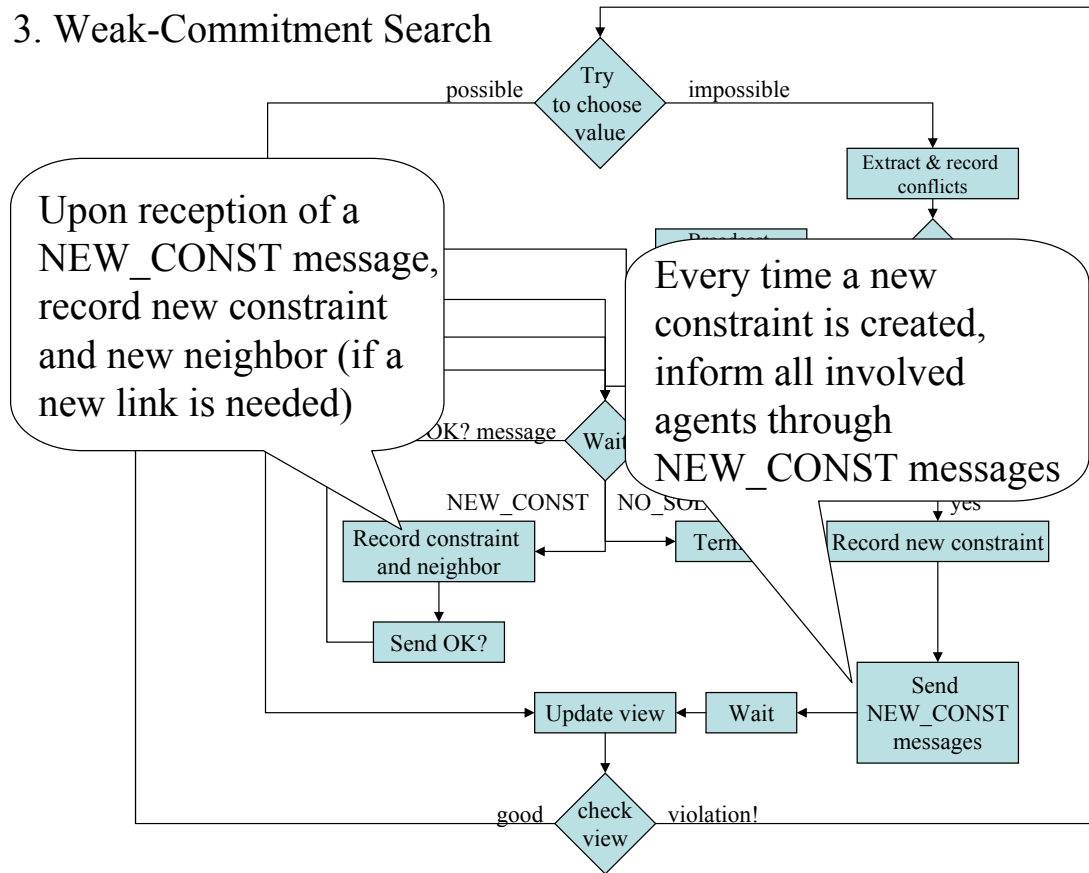
3. Weak-Commitment Search



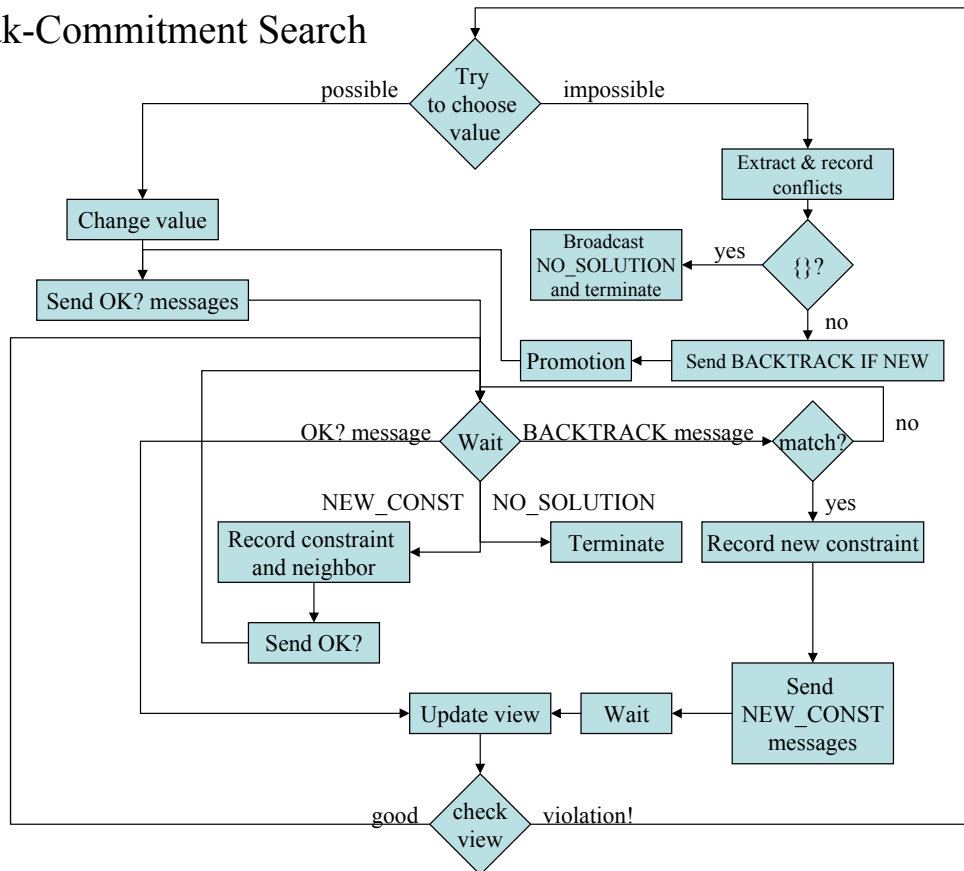
3. Weak-Commitment Search



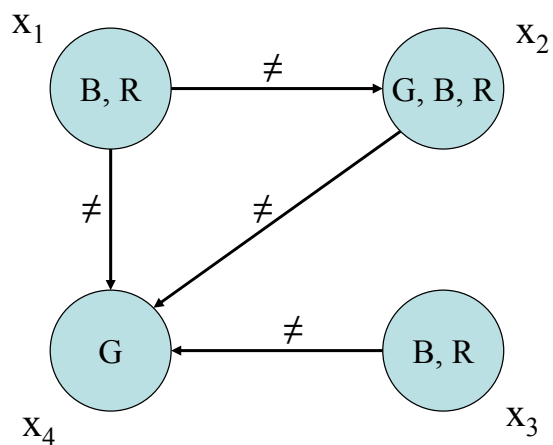
3. Weak-Commitment Search



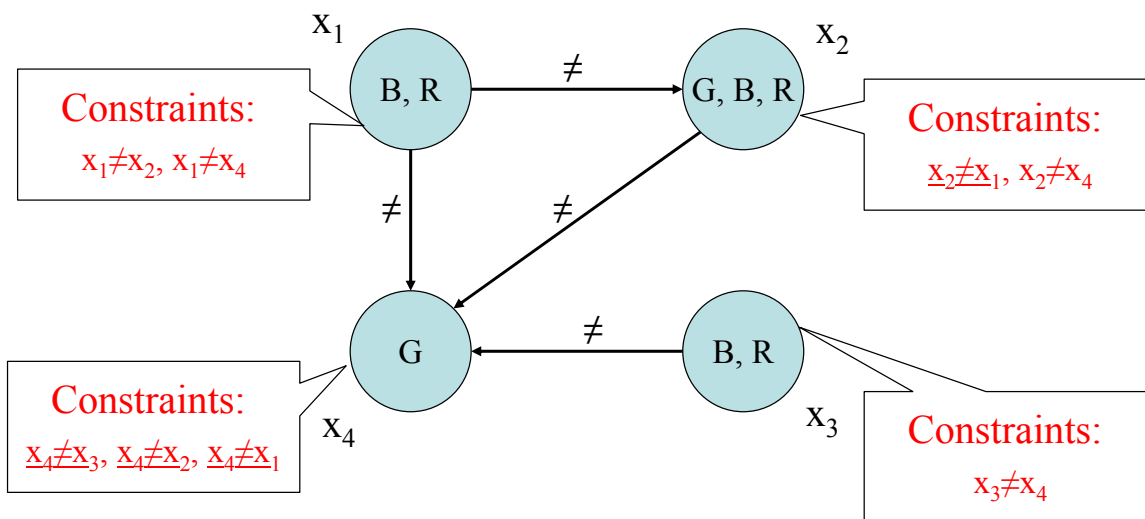
3. Weak-Commitment Search



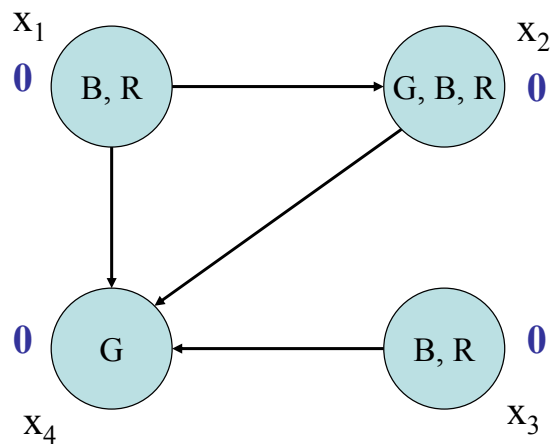
3. Weak-Commitment Search: The Graph Coloring Example



3. Weak-Commitment Search: The Graph Coloring Example

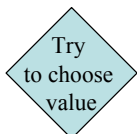
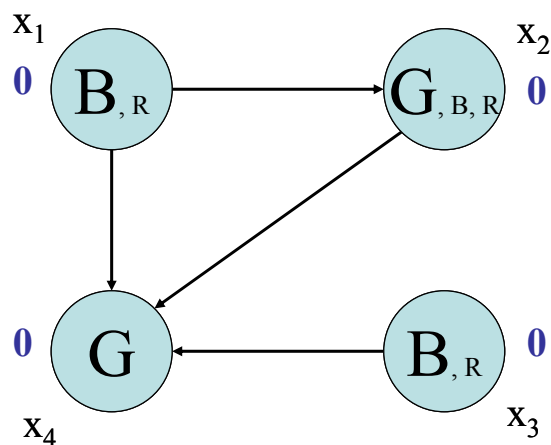


3. Weak-Commitment Search: The Graph Coloring Example



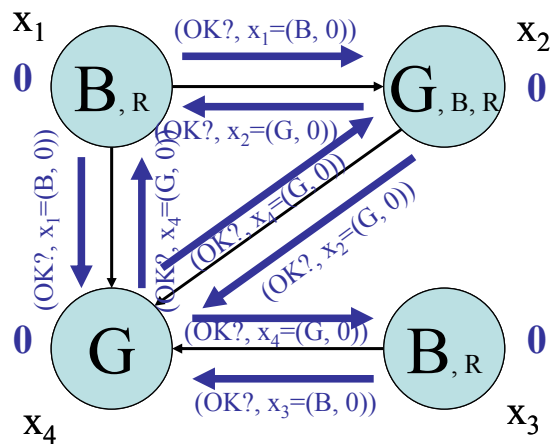
Initial priority values are all set to 0. Two agents with identical priorities are ordered with respect to their index

3. Weak-Commitment Search: The Graph Coloring Example



Each agent chooses an assignment to its variable (at the first time step, we cannot use the heuristic because agents still have empty views)

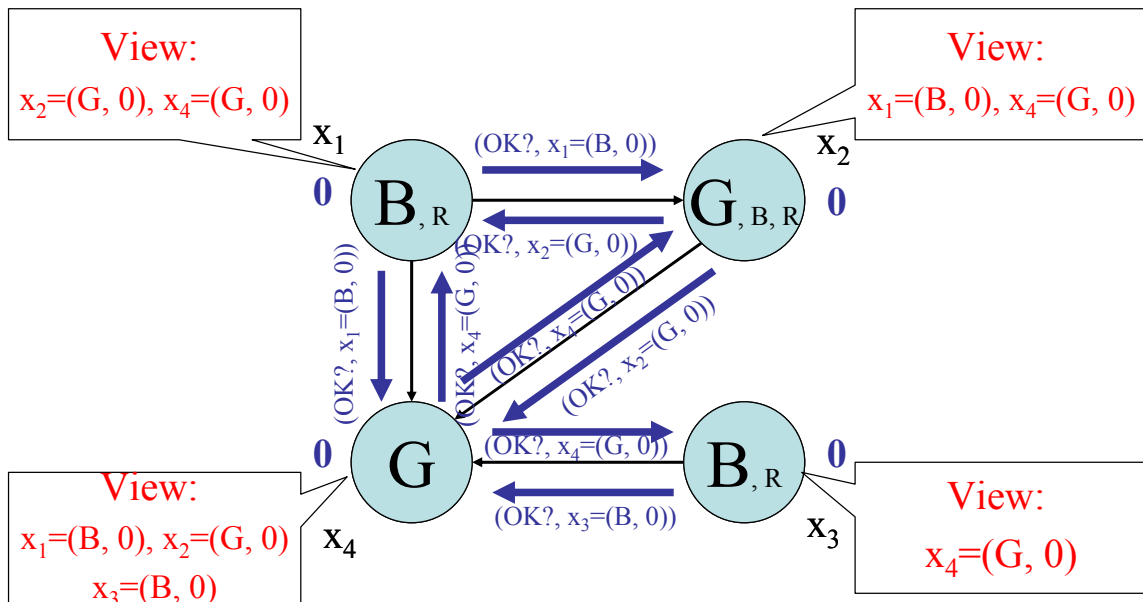
3. Weak-Commitment Search: The Graph Coloring Example



Send OK? messages

Each agent sends OK? messages to ALL of its neighbors

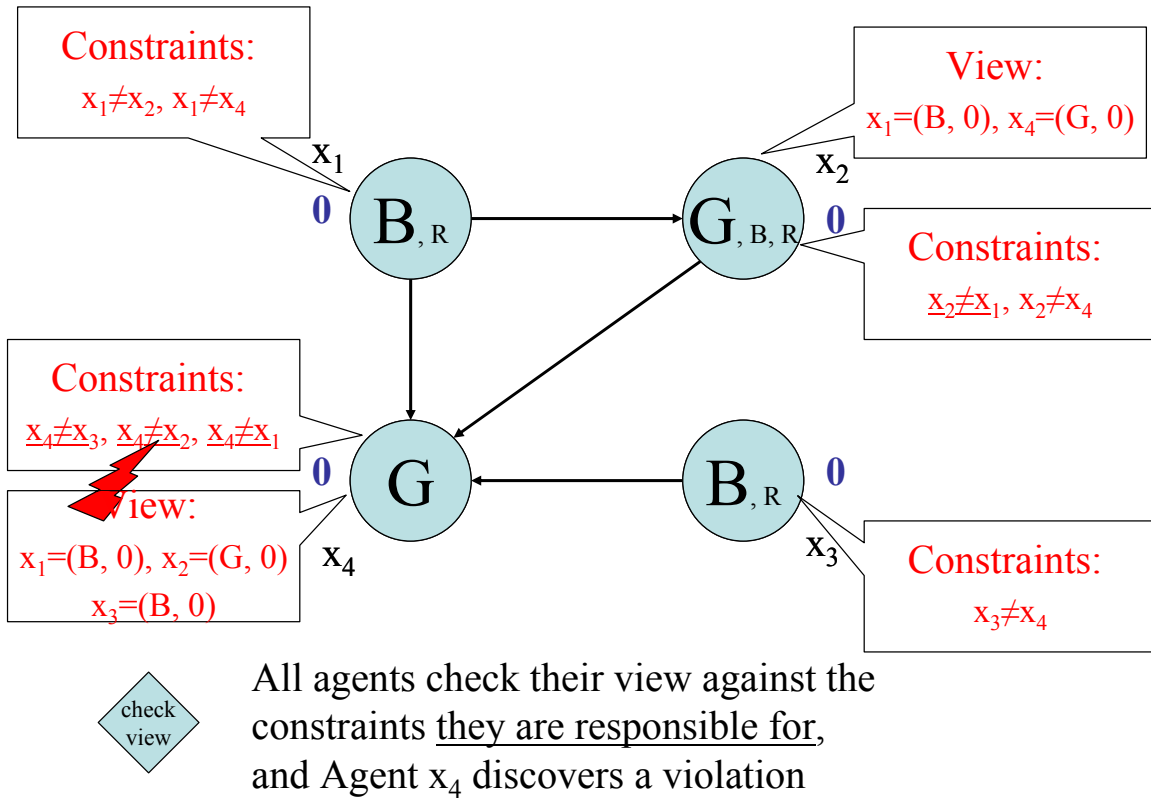
3. Weak-Commitment Search: The Graph Coloring Example



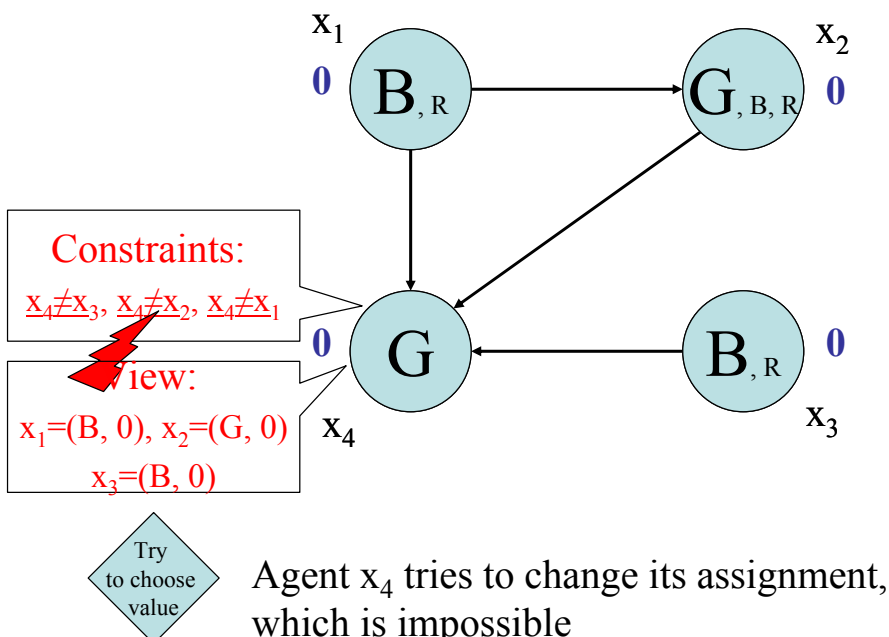
Update view

All agents update their view

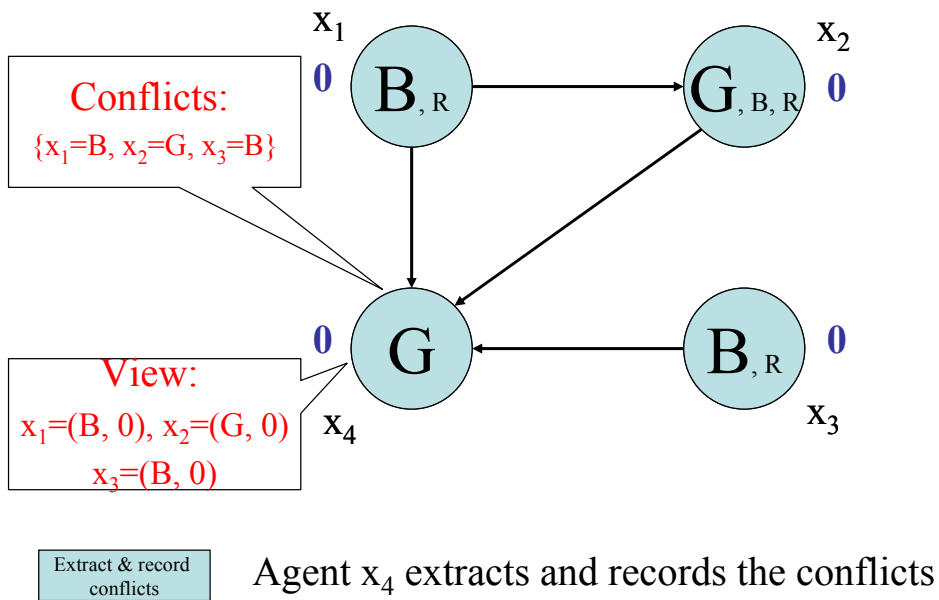
3. Weak-Commitment Search: The Graph Coloring Example



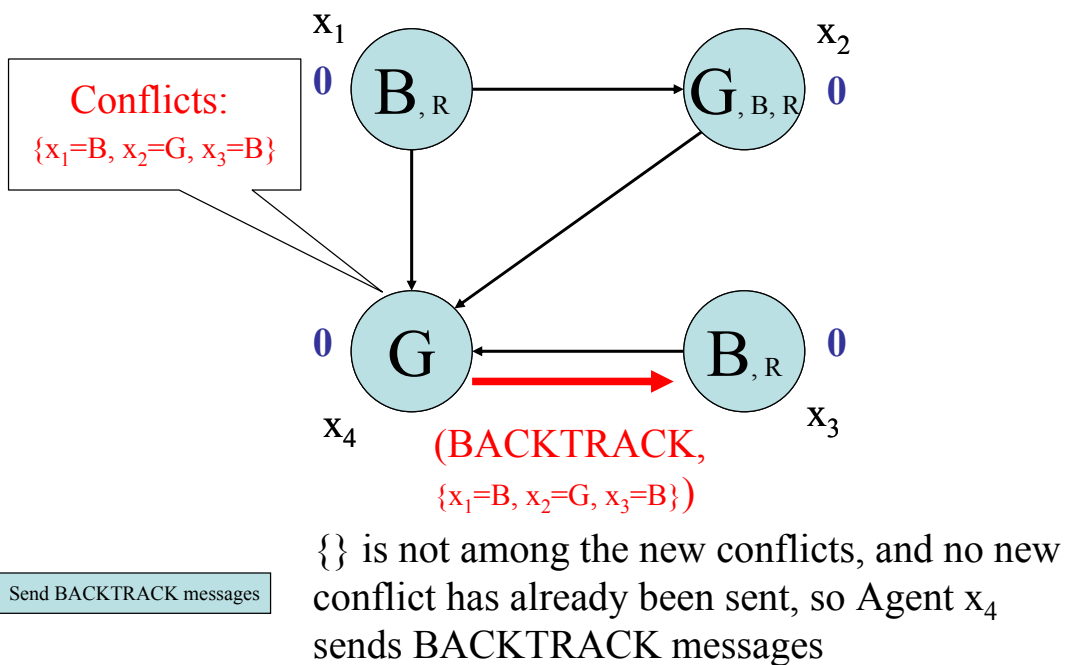
3. Weak-Commitment Search: The Graph Coloring Example



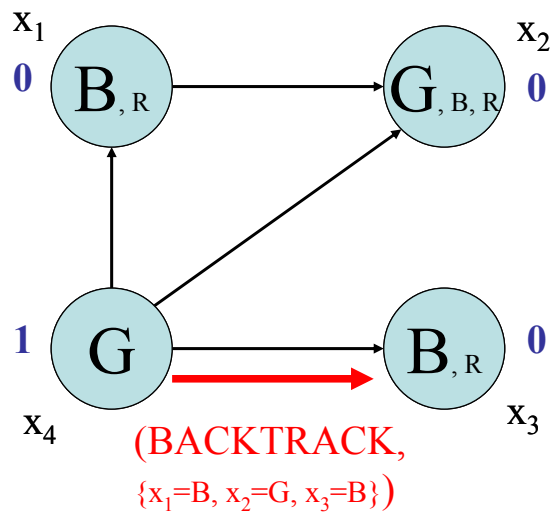
3. Weak-Commitment Search: The Graph Coloring Example



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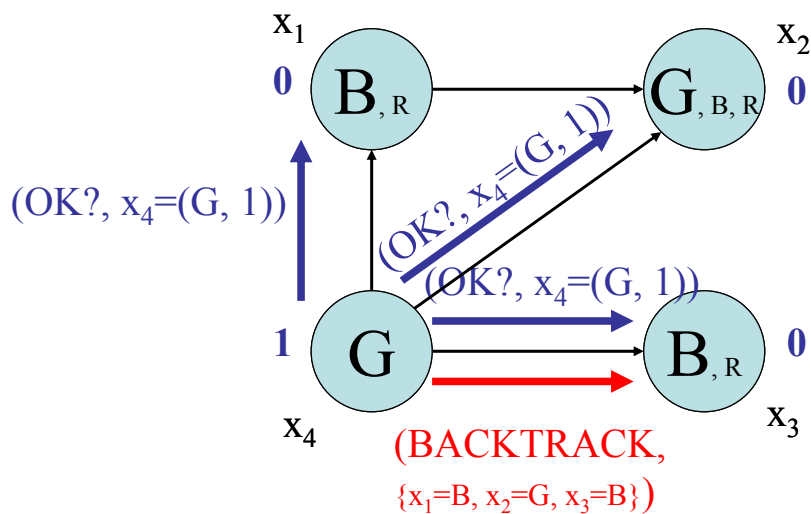
3. Weak-Commitment Search: The Graph Coloring Example



Promotion

Agent x_4 promotes itself, changing its priority value from 0 to 1

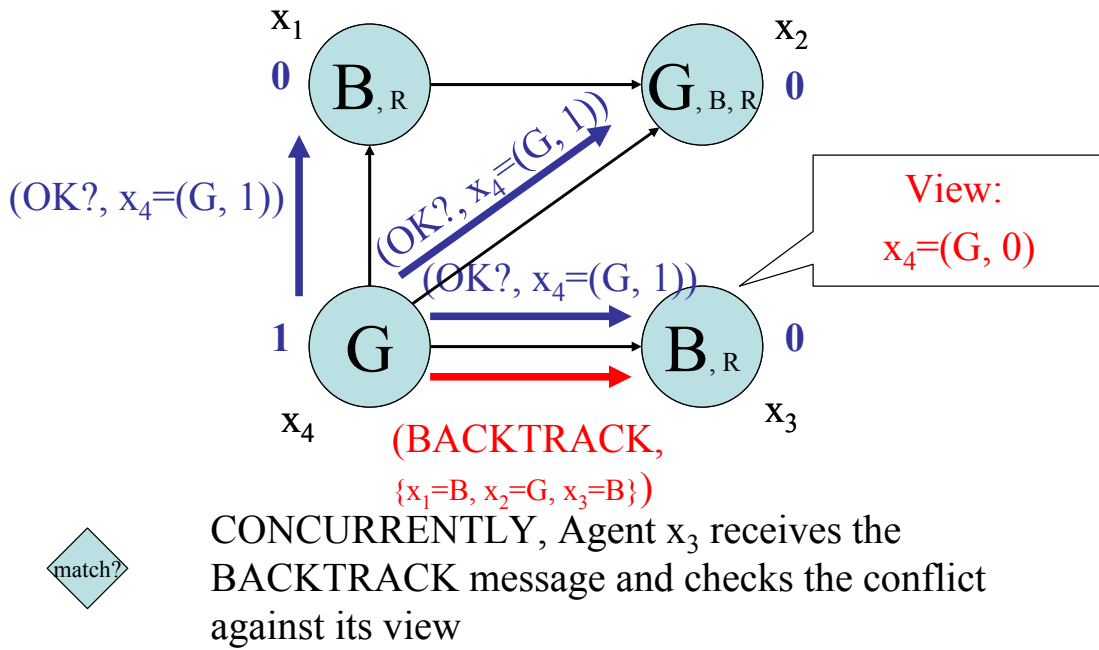
3. Weak-Commitment Search: The Graph Coloring Example



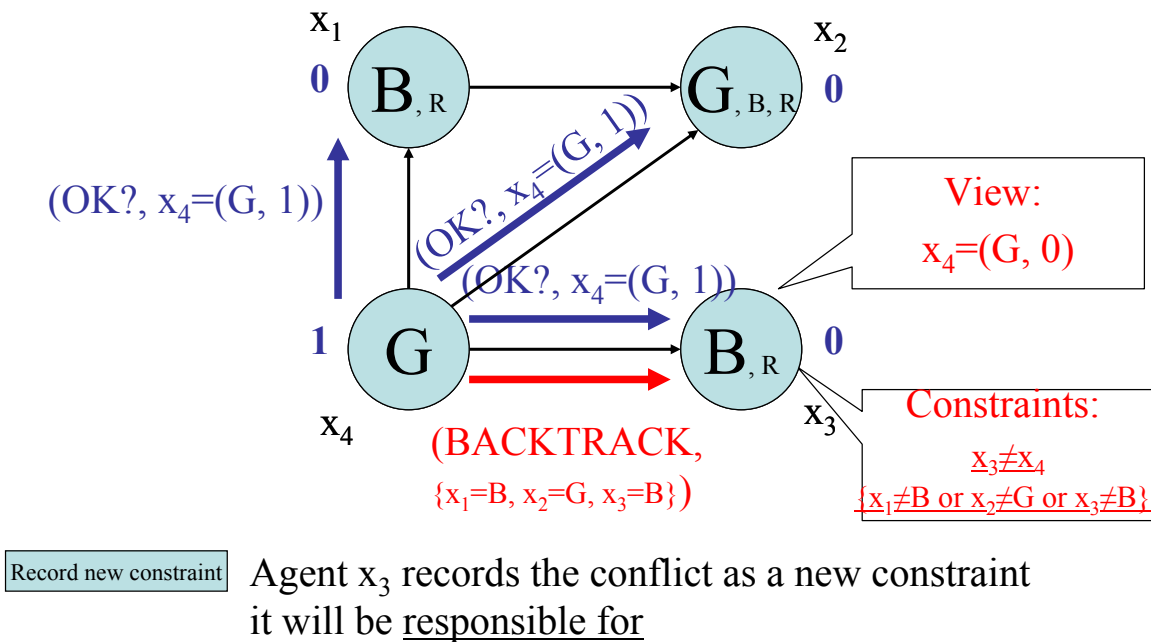
Send OK? messages

Agent x_4 communicates its new priority value to ALL its neighbors

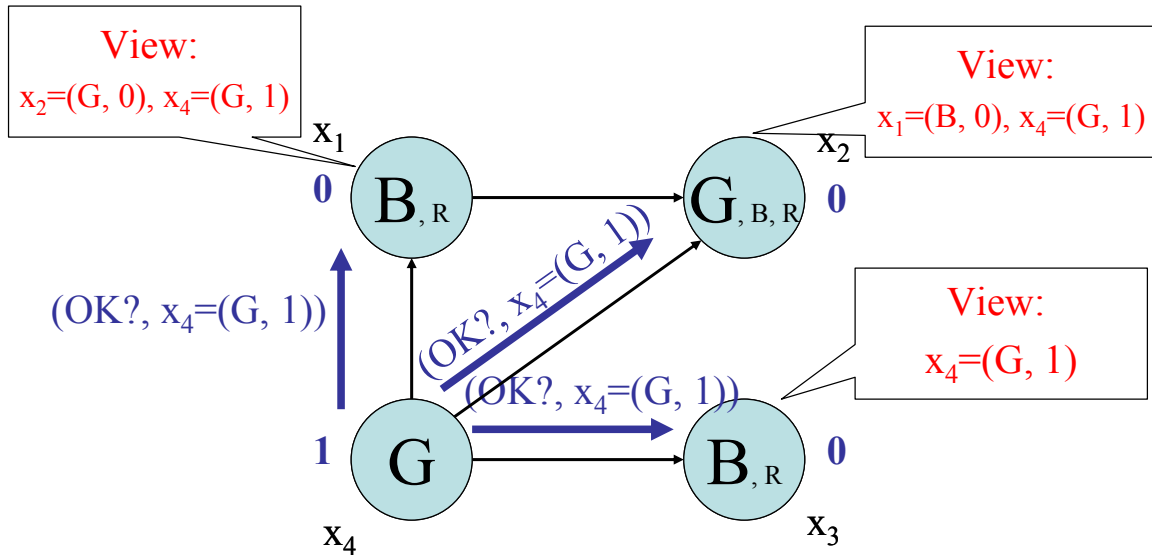
3. Weak-Commitment Search: The Graph Coloring Example



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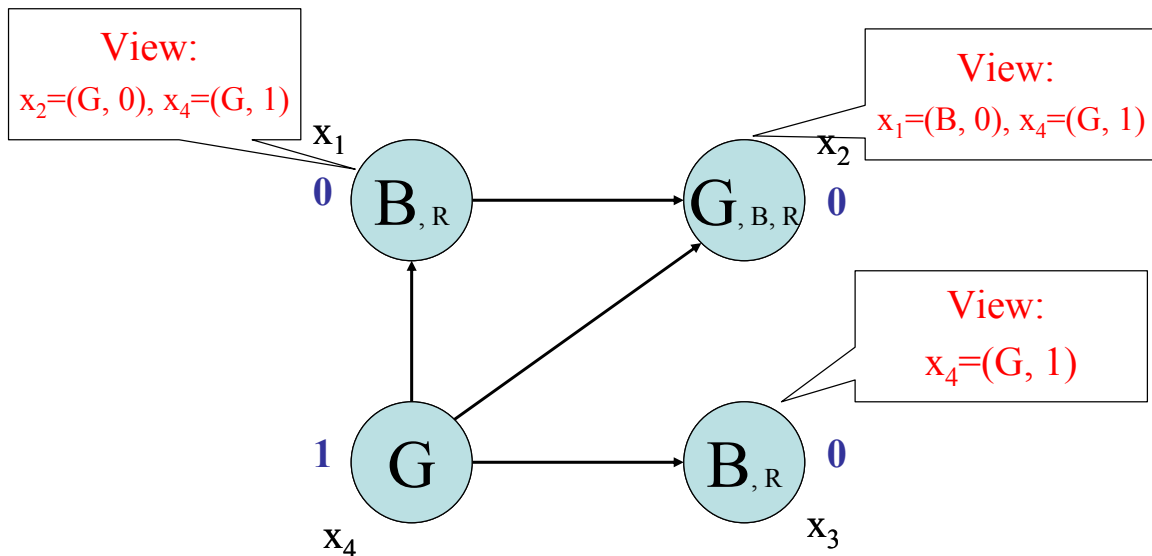


3. Weak-Commitment Search: The Graph Coloring Example



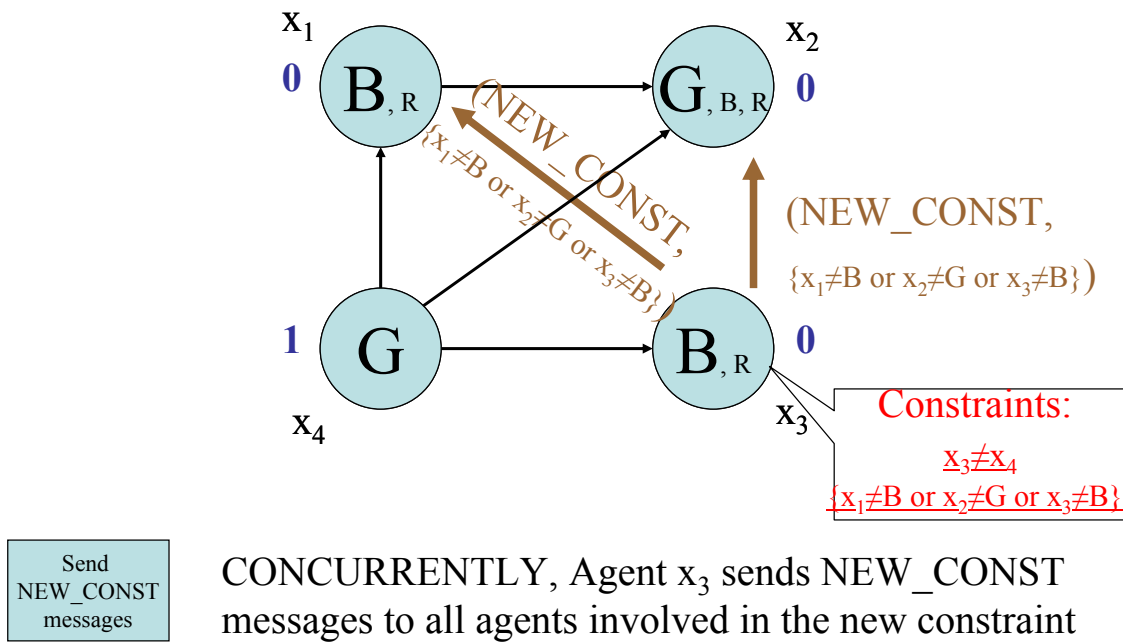
CONCURRENTLY, all agents receive the OK? messages and update their view

3. Weak-Commitment Search: The Graph Coloring Example

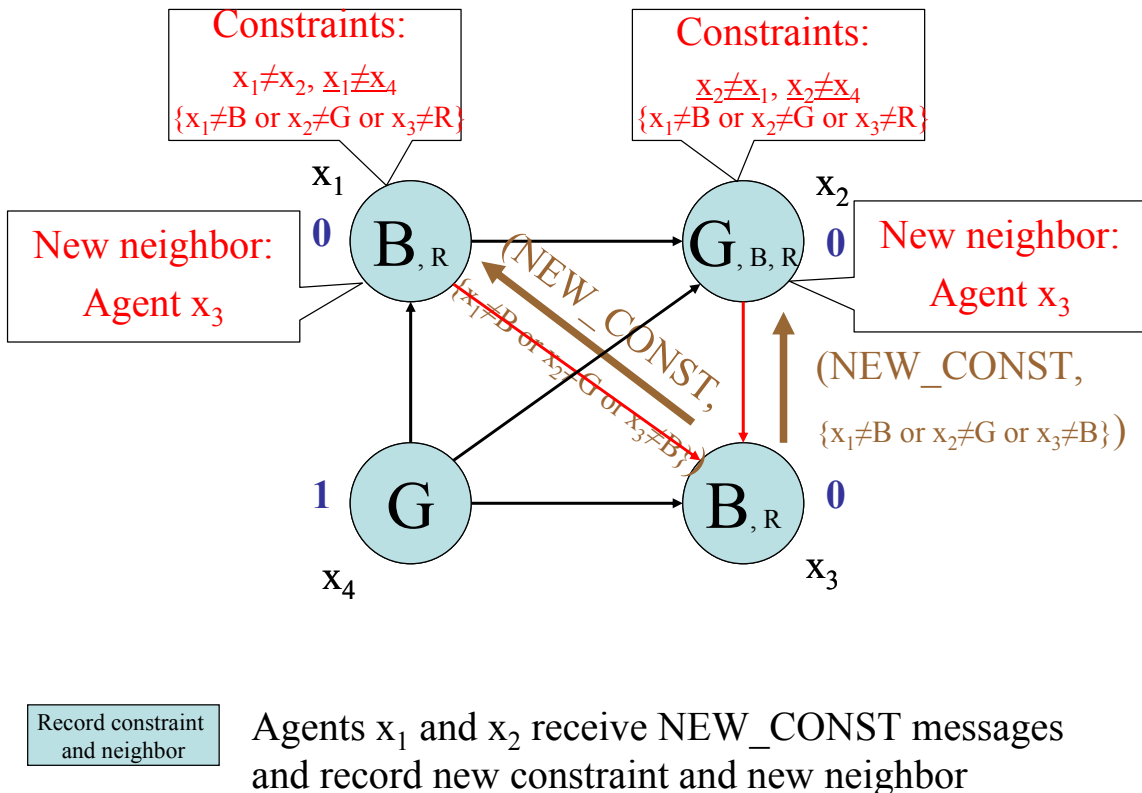


(Only the priority changed, so no new violation is discovered)

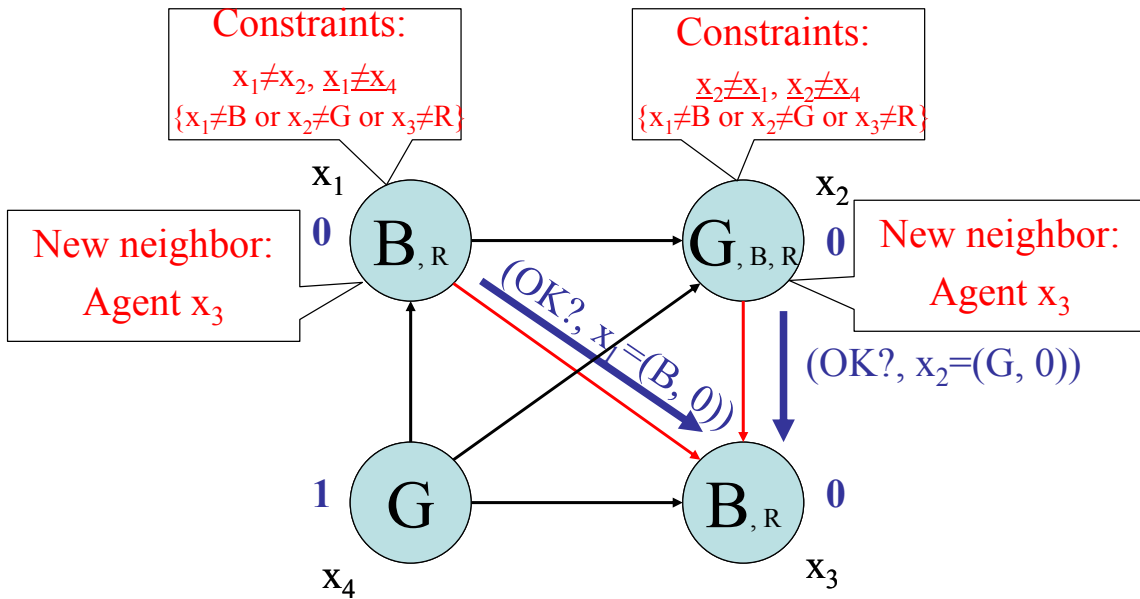
3. Weak-Commitment Search: The Graph Coloring Example



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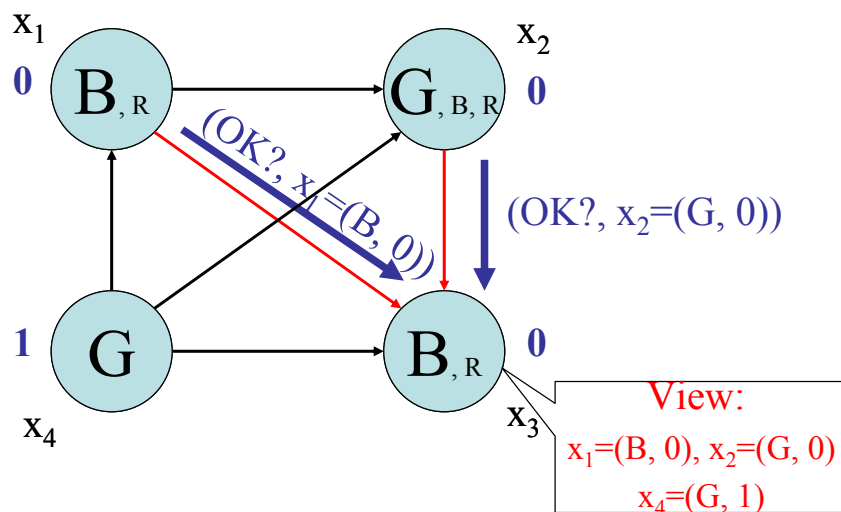
3. Weak-Commitment Search: The Graph Coloring Example



Send OK? messages

Agents x_1 and x_2 respond to the NEW_CONST through OK? messages

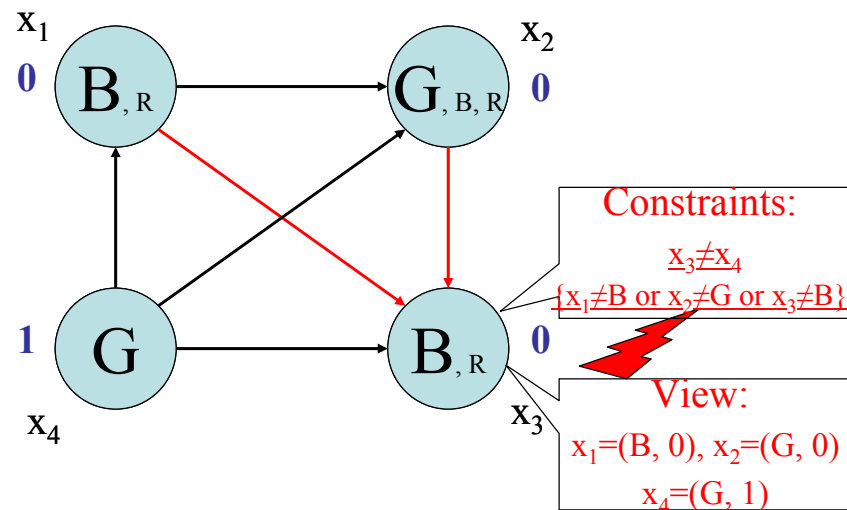
3. Weak-Commitment Search: The Graph Coloring Example



Update view

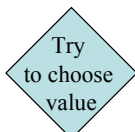
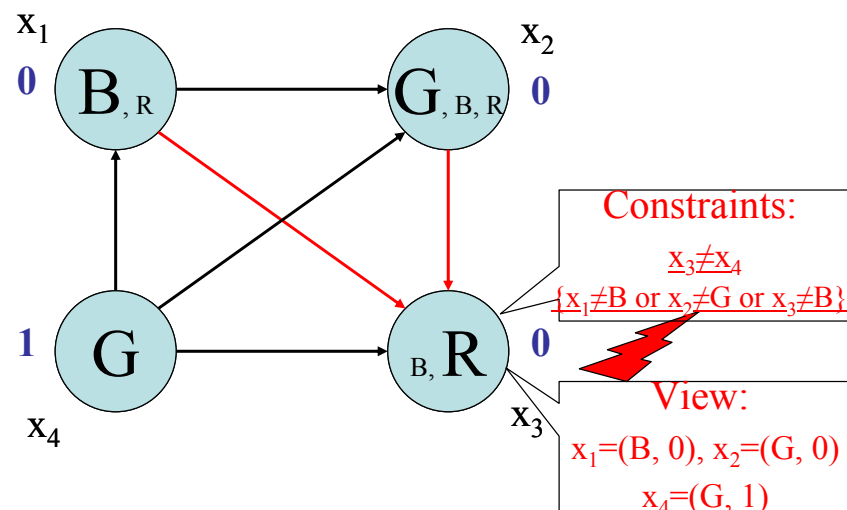
Agent x_3 receives messages and updates its view

3. Weak-Commitment Search: The Graph Coloring Example



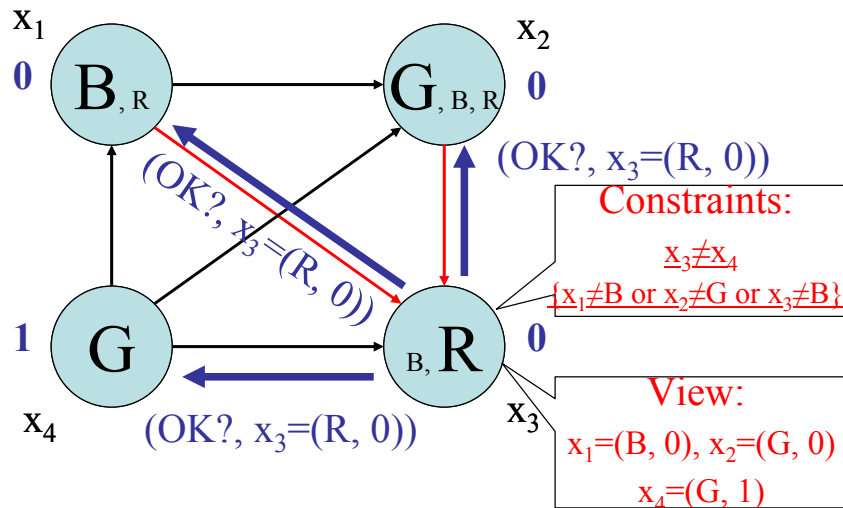
Agent x_3 checks its view, and discovers that one constraint it is responsible for (the new one) is violated

3. Weak-Commitment Search: The Graph Coloring Example



Agent x_3 tries to change its value to R , deleting all violations of constraints it is responsible for, and minimizing the number of violations of others

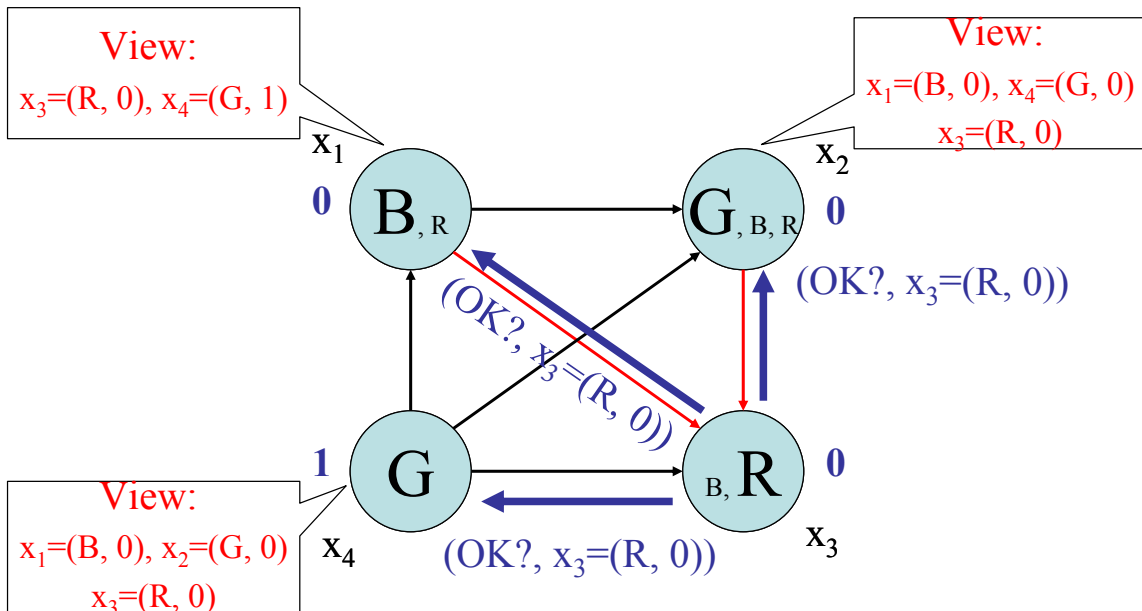
3. Weak-Commitment Search: The Graph Coloring Example



Send OK? messages

There is no more violations of constraints it is responsible for, so Agent x_3 communicates its new value to ALL neighbors

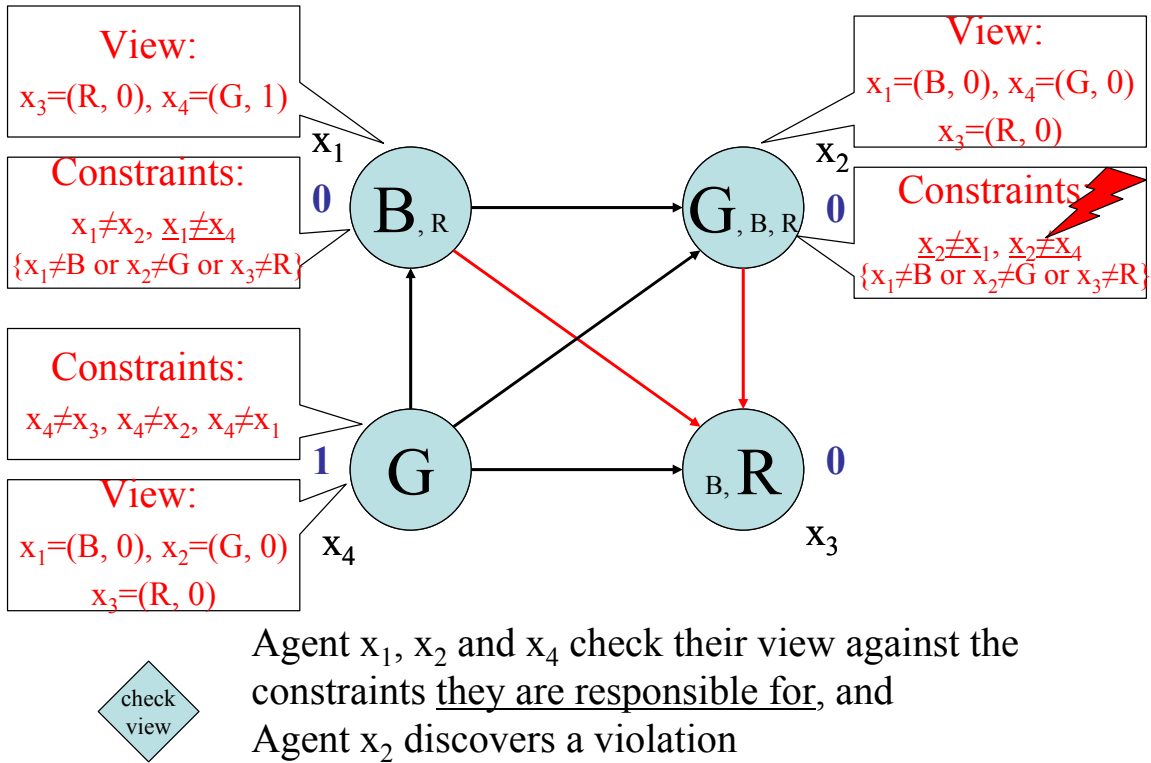
3. Weak-Commitment Search: The Graph Coloring Example



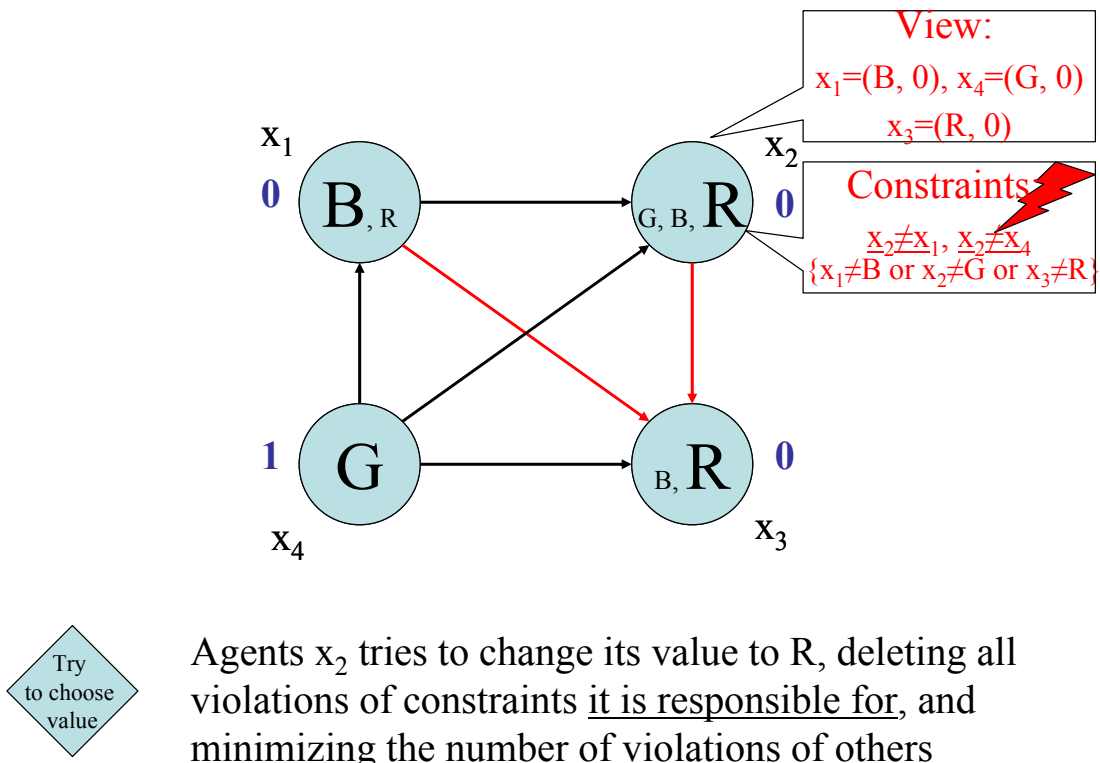
Update view

All agents receive the OK? messages and update their view

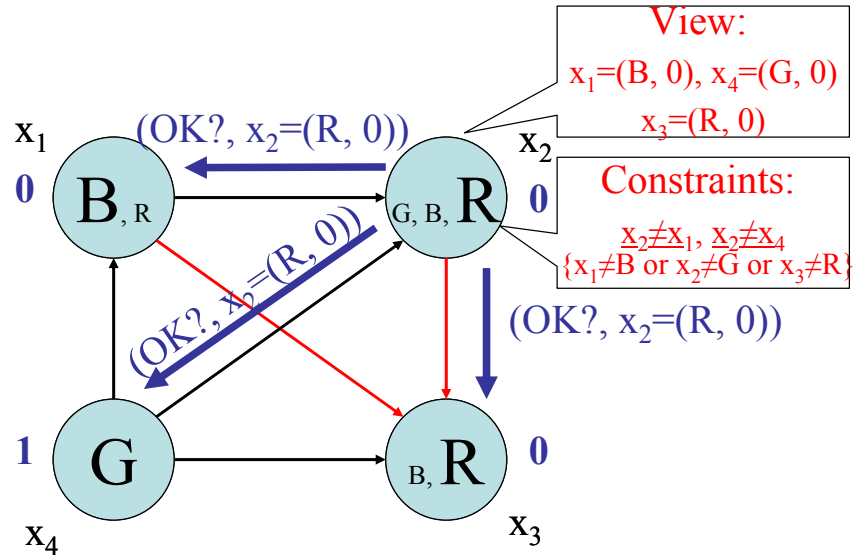
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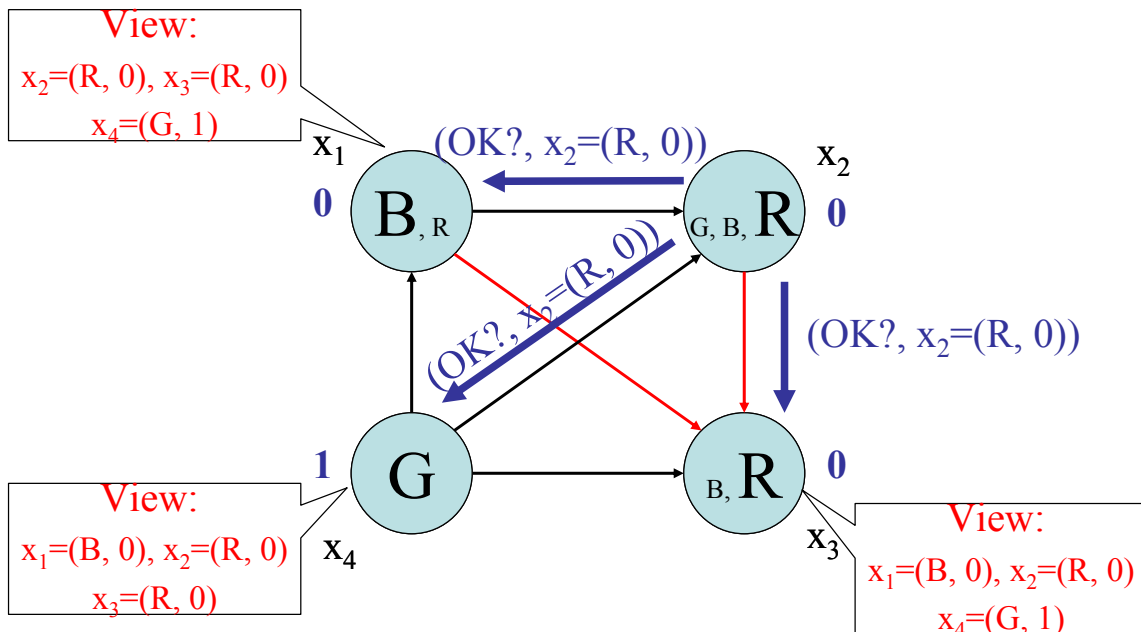
3. Weak-Commitment Search: The Graph Coloring Example



Send OK? messages

There is no more violations of constraints it is responsible for, so Agent x_3 communicates its new value to ALL neighbors

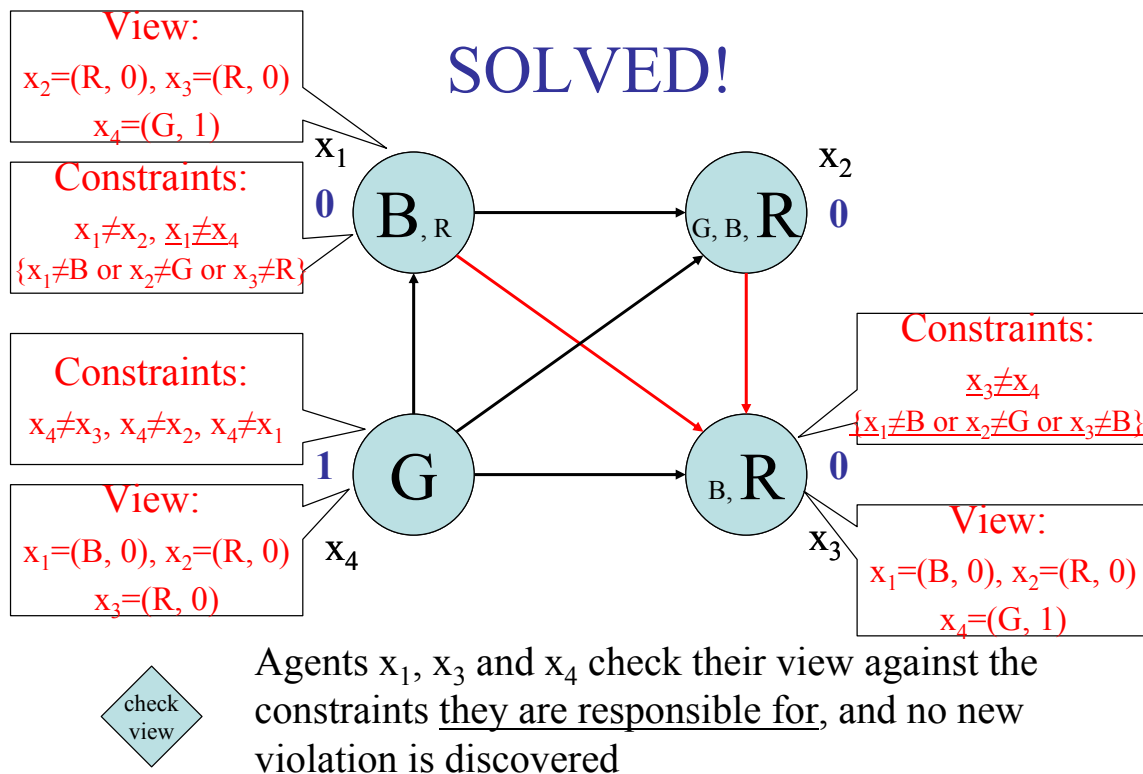
3. Weak-Commitment Search: The Graph Coloring Example



Update view

All agents receive the OK? messages and update their view

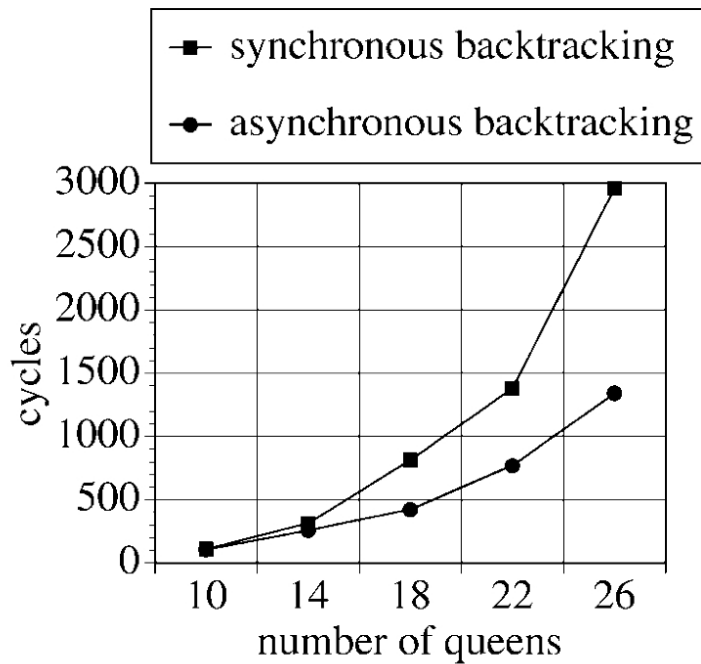
3. Weak-Commitment Search: The Graph Coloring Example



4. Conclusion

- Perform much better than the trivial algorithms

4. Conclusion



M. Yokoo, E. Durfee, T. Ishida and K. Kuwabara, *Distributed Constraint Satisfaction Problem: Formalization and Algorithms*, IEEE Transactions on Knowledge and Data Engineering, VOL. 10, NO. 5, Sept/Oct 1998

4. Conclusion

TABLE 1
COMPARISON BETWEEN ASYNCHRONOUS BACKTRACKING AND
ASYNCHRONOUS WEAK-COMMITMENT SEARCH (DISTRIBUTED N-QUEENS)

n	asynchronous backtracking		asynchronous backtracking with min-conflict heuristic		asynchronous weak-commitment	
	ratio	cycles	ratio	cycles	ratio	cycles
10	100%	105.4	100%	102.6	100%	41.5
50	50%	325.4	56%	326.8	100%	59.1
100	14%	510.0	30%	504.3	100%	50.8
1000	0%	—	16%	323.8	100%	29.6

M. Yokoo, E. Durfee, T. Ishida and K. Kuwabara, *Distributed Constraint Satisfaction Problem: Formalization and Algorithms*, IEEE Transactions on Knowledge and Data Engineering, VOL. 10, NO. 5, Sept/Oct 1998

4. Conclusion

- Perform much better than the trivial algorithms
- Single-variable agents \Rightarrow Task Allocation Problem

W.-M. Shen and B. Salemi, *Distributed and Dynamic Task Reallocation in Robot Organizations*

References

- M. Yokoo, E. Durfee, T. Ishida and K. Kuwabara, *Distributed Constraint Satisfaction Problem: Formalization and Algorithms*, IEEE Transactions on Knowledge and Data Engineering, VOL. 10, NO. 5, Sept/Oct 1998
- K. Sycara, S. Roth, N. Nadeh and M. Fox, *Distributed Constrained Heuristic Search*, IEEE Transactions on Systems, Man, and Cybernetics, VOL. 21, NO. 6, Nov/Dec 1991
- K. M. Chandy and L. Lamport, *Distributed Snapshots: Determining Global States of Distributed Systems*, ACM Transactions on Computer Systems, 1985
- W.-M. Shen and B. Salemi, *Distributed and Dynamic Task Reallocation in Robot Organizations*