

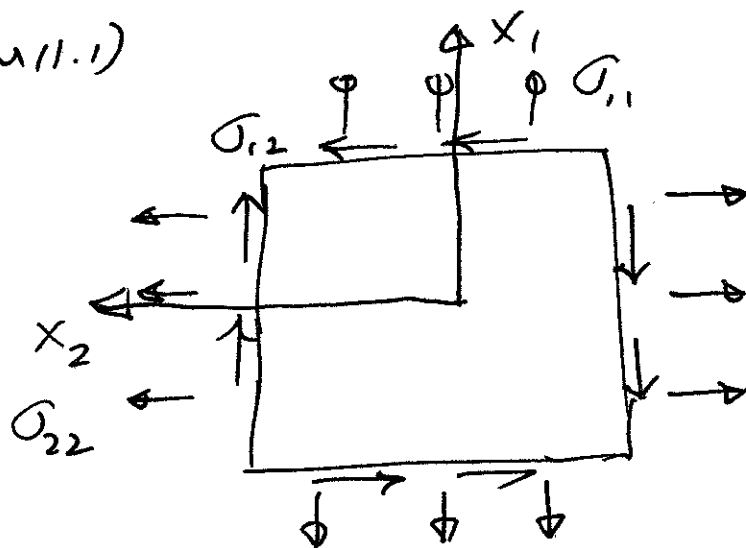
Unified Engineering

Problem Set 10 - week 11

Fall, 2008

SOLUTIONS

M18(M11.1)



$$\sigma_{11} = -24 \text{ ksi}$$

$$\sigma_{22} = 16 \text{ ksi}$$

$$\sigma_{12} = -8 \text{ ksi}$$

(a) For plane stress, the principal stresses are the roots of the equation:

$$\tau^2 - \tau(\sigma_{11} + \sigma_{22}) + (\sigma_{11}\sigma_{22} - \sigma_{12}^2) = 0$$

We do this relative to the original loading axes, using these stresser gives:

$$\tau^2 - \tau(-24 \text{ ksi} + 16 \text{ ksi}) + [(-24 \text{ ksi})(16 \text{ ksi}) - (-8 \text{ ksi})^2] = 0$$

$$\Rightarrow \tau^2 - (-8 \text{ ksi})\tau - 448 (\text{ksi})^2 = 0$$

Solve via the quadratic formula:

$$\text{roots} = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a} \text{ for } ax^2 + bx + c = 0$$

$$\text{Here: } a = 1; b = +8 \text{ ksi}; c = -448 (\text{ksi})^2$$

$$\Rightarrow \tau = \frac{-(+8 \text{ ksi}) \pm \sqrt{(+8 \text{ ksi})^2 - 4(1)(-448) (\text{ksi})^2}}{2(1)}$$

$$= \frac{-8 \pm \sqrt{1728}}{2} \text{ ksi}$$

$$= \frac{-8 \pm 41.6}{2} \text{ ksi}$$

$$\Rightarrow \tau = -24.8 \text{ ksi}, 16.8 \text{ ksi}$$

$$\Rightarrow \begin{cases} \sigma_I = -24.8 \text{ ksi} \\ \sigma_{II} = +16.8 \text{ ksi} \end{cases}$$

to find the associated directions, use the expression:

$$\theta_p = \frac{1}{2} \tan^{-1} \left( \frac{2\sigma_{12}}{\sigma_{11} - \sigma_{22}} \right)$$

$$\Rightarrow \theta_p = \frac{1}{2} \tan^{-1} \left( \frac{2(-8 \text{ ksi})}{-24 \text{ ksi} - (16 \text{ ksi})} \right)$$

$$= \frac{1}{2} \tan^{-1} \left( \frac{-16}{-40} \right)$$

$$= \frac{1}{2} \tan^{-1}(0.4)$$

$$\Rightarrow \theta_p = \frac{1}{2}(21.8^\circ)$$

$$\Rightarrow \theta_p = +10.9^\circ \text{ for } \sigma_I \text{ (check manually)}$$

with  $\sigma_{II}$  rotated  $90^\circ$  from that

so:

$\theta_{pI} = +10.9^\circ$ $\theta_{pII} = +100.9^\circ = -79.1^\circ$
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Check the angles via the transformation equations for shear and that shear stress goes to zero (definition of principal axes and stresses):

$$\tilde{\sigma}_{12} = -\sin \theta \cos \theta \sigma_{11} + \cos \theta \sin \theta \sigma_{22} + (\cos^2 \theta - \sin^2 \theta) \sigma_{12}$$

$$\text{for } \theta = +10.9^\circ:$$

$$\begin{aligned} \sigma &\stackrel{?}{=} - (+0.189)(0.982)(-24 \text{ ksi}) \\ &\quad + (0.482)(+0.189)(+16 \text{ ksi}) \\ &\quad + (0.964 - 0.036)(-8 \text{ ksi}) \end{aligned}$$

$$\Rightarrow \sigma \stackrel{?}{=} 4.45 \text{ ksi} + 2.97 \text{ ksi} - 7.42 \text{ ksi}$$

✓ (YES)

(same as for  $-79.1^\circ$  with  $\sigma_i$  for switched)

(b) Maximum shear stresses occur along planes/directions that are at  $45^\circ$  to the principal axes.

So: direction of maximum shear stress:

$$\theta_{p_I} + 45^\circ \text{ from } x_1 = +55.9^\circ$$

$$\theta_{p_{II}} + 45^\circ \text{ from } x_1 = -34.1^\circ$$

Directions of maximum shear =  $+55.9^\circ, -34.1^\circ$

The value of the maximum shear stresses in the  $x_1 - x_2$  plane is:

$$\frac{|\sigma_I - \sigma_{II}|}{2} = \frac{|-24.8 \text{ ksi} - (16.8 \text{ ksi})|}{2}$$

⇒ value of maximum shear stress = 20.8 ksi  
 (this takes on a sign of + and -)

NOTE: This value can also be determined by using the stress transformation equation for  $\tau_{12}$  and the direction of maximum shear relative to the original loading axes. So we:

$$\tilde{\tau}_{12} = -\sin \theta \cos \theta \sigma_{11} + \cos \theta \sin \theta \sigma_{22} + (\cos^2 \theta - \sin^2 \theta) \tau_{12}$$

with:

$$\sigma_{11} = -24 \text{ ksi}$$

$$\sigma_{22} = +16 \text{ ksi}$$

$$\tau_{12} = -8 \text{ ksi}$$

$$\text{and } \theta = +55.9^\circ, -34.1^\circ$$

→ There are two other maximum shear stresses out of the  $x_1 - x_2$  plane. For the case of plane stress, the out-of-plane principal stress is zero (i.e.  $\sigma_{III} = 0$ ).

So we have:

$$|\tau_{\max}| = \left| \frac{\sigma_I - \sigma_{III}}{2} \right| = \frac{24.8 \text{ ksi}}{2} = \boxed{12.4 \text{ ksi}}$$

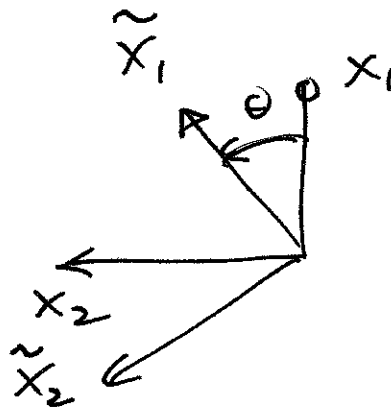
This is a plane at  $45^\circ$  to the  $x_1 - x_2$  plane rotated about the  $x_3$ -axis

and also:

$$|\tau_{\max}| = \left| \frac{\sigma_{II} - \sigma_{III}}{2} \right| = \frac{16.8 \text{ ksi}}{2} = \boxed{8.4 \text{ ksi}}$$

This is a plane at  $45^\circ$  to the  $x_1 - x_2$  plane rotated about the  $x_3$ -axis

(c) The direction of the axes for reference relative to the original loading axes (call  $\theta$ ):



do not change the base stress state  
 and thus the principal stresses and  
maximum shear stresses do not  
change

And... the principal directions and  
planes of the maximum stresses  
stay the same relative to the loading  
axes  $x_1 - x_2$ .

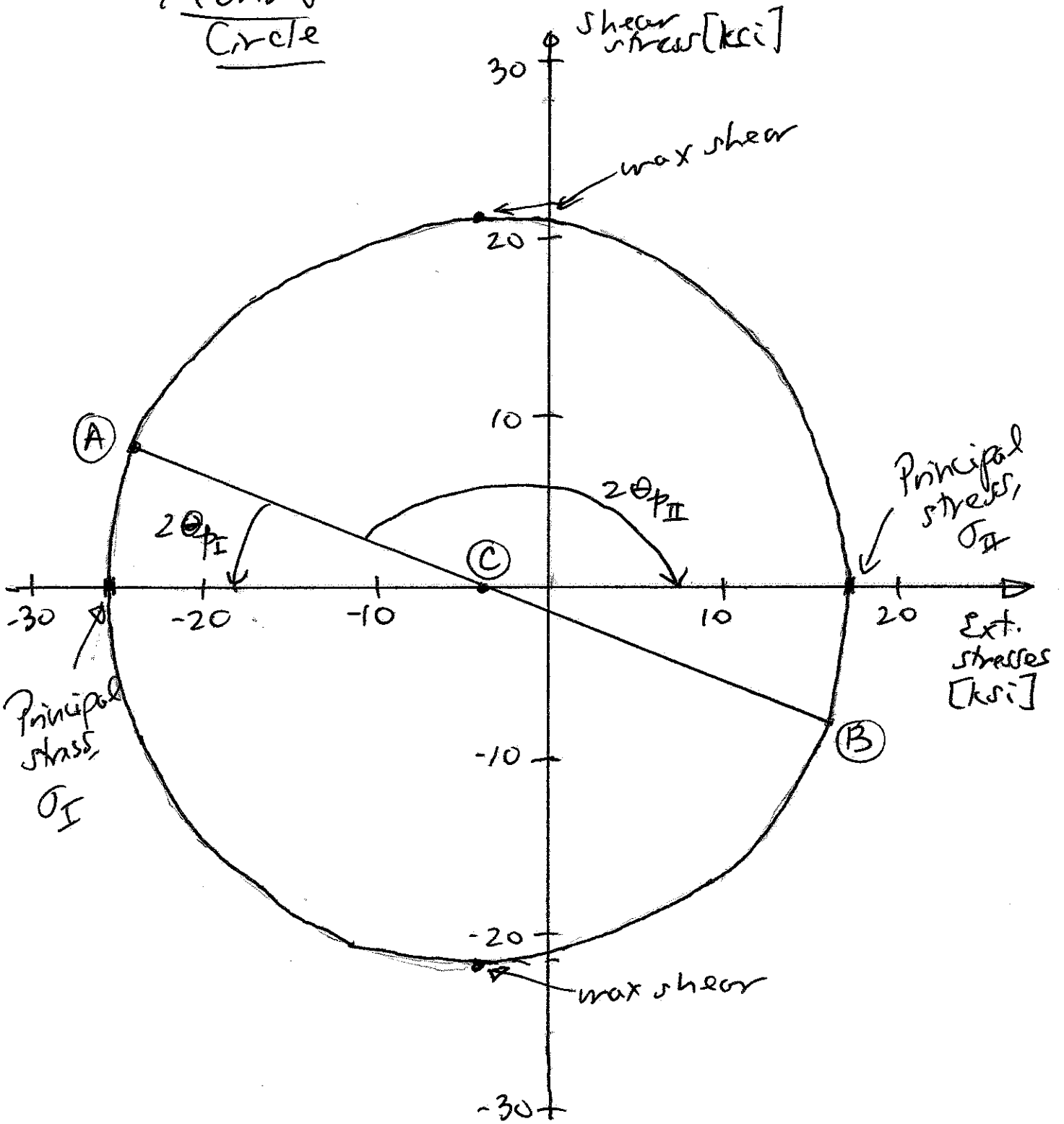
→ However, the angle relative to the initial axis system,  $\theta$ , from the original loading axes must be properly subtracted/added to get the direction(s) relative to these axes.

(d) Draw the Mohr's Circle as specified in the instructions (see associated figure)

- ① Plot  $\sigma_{11}, -\sigma_{12}$  ( $-24 \text{ ksi}, +8 \text{ ksi}$ ) as Point (A)
- ② Plot  $\sigma_{22}, \sigma_{21}$  ( $16 \text{ ksi}, -8 \text{ ksi}$ ) as Point (B)
- ③ Connect (A) and (B)
- ④ Draw circle of diameter of the line (A)-(B) about the point where this line crosses the horizontal axis (denote this point as (C)):

$$\begin{aligned}
 \text{point (C)} = \text{midpoint} &= \frac{\sigma_{11} + \sigma_{22}}{2} \\
 &= \frac{-24 \text{ ksi} + 16 \text{ ksi}}{2} \\
 &= -4 \text{ ksi}
 \end{aligned}$$

Moohr's Circle





→ Principal stresses and directions (2-D)  
(part (a))

The intersection of the circle with the horizontal axis gives the two values of the principal stresses. By sight these are of the same value corresponding to the results of part (a):  $-24.8 \text{ ksi}$  and  $+16.8 \text{ ksi}$ .

One can be more formal by finding the circle diameter  $(= 2 \sqrt{(\frac{\sigma_{11} - \sigma_{22}}{2})^2 + \sigma_{12}})$  and then adding and subtracting half of this from the mid point value (point C)  $= -4.0 \text{ ksi}$ .

Directions (angles) can be measured via a protractor and half the angle from line A-B to the horizontal axis of the two points (2 directions)

→ Maximum shear stresses (part (b))

These are the upper and lower "reaches" of the circle along the vertical direction. It can be read off to be just about  $21.0 \text{ ksi}$  (and  $-21.0 \text{ ksi}$ ). This is very close to the value calculated in part (b) of  $\pm 20.8 \text{ ksi}$ . Note that the value found via Mohr's circle is exactly the radius of the circle  $(= \sqrt{\frac{\sigma_{11} - \sigma_{22}}{2}} = 20.8 \text{ ksi})$ .

The direction(s) of the maximum shear stress(es) are  $90^\circ$  on Mohr's circle from that of the principal stresses or these two associated lines are perpendicular. Divide by 2, since this is twice the rotation angle, and that is  $45^\circ$  added on to  $\theta_{P_{II}}$  as in (b).

NOTE: Only the maximum shear stress in the  $x_1-x_2$  plane can be determined since Mohr's circle only allows rotation in the  $x_1-x_2$  plane.

M19 (M11.2) Begin by writing out the transformation equations for in-plane strains (as for the case of plane stress):

$$\begin{aligned}\tilde{\epsilon}_{11} &= \cos^2 \theta \epsilon_{11} + \sin^2 \theta \epsilon_{22} + 2 \cos \theta \sin \theta \epsilon_{12} \\ \tilde{\epsilon}_{22} &= \sin^2 \theta \epsilon_{11} + \cos^2 \theta \epsilon_{22} - 2 \cos \theta \sin \theta \epsilon_{12} \\ \tilde{\epsilon}_{12} &= -\sin \theta \cos \theta \epsilon_{11} + \cos \theta \sin \theta \epsilon_{22} \\ &\quad + (\cos^2 \theta - \sin^2 \theta) \epsilon_{12}\end{aligned}$$

Considering this, one can see that no matter what direction an elongation strain is measured, one cannot get a result for the shear strain  $\epsilon_{12}$  --  $\epsilon_{11}$  and  $\epsilon_{22}$  are involved in these expressions. So:

measuring one elongation strain  
is not sufficient

Further consideration of these transformation equations shows that knowing three strains ( $\epsilon_{11}$ ,  $\epsilon_{22}$ ,  $\epsilon_{12}$ ) and an angle of rotation allows one to characterize the state of strain in any direction. Working with this one can say:

- ① Any 3 strains fully characterize the state of in-plane strain of a body along with the knowledge of the strain direction.
- ② Measuring 3 elongation strains and using the knowledge of their directions will yield the shear strain in one set of axes.

Demonstrate this via the equations:

1. Measure  $\tilde{\epsilon}_{11}$  and have  $\theta$
2. Measure  $\epsilon_{11}$
3. Measure  $\epsilon_{22}$
4. Use all in the first transformation equation:

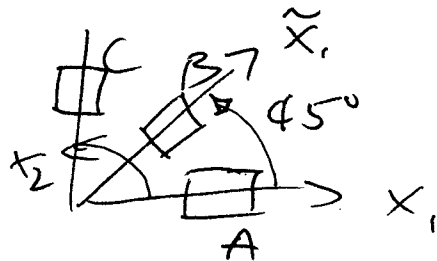
$$\tilde{\epsilon}_{11} = \cos^2 \theta \epsilon_{11} + \sin^2 \theta \epsilon_{22} + 2 \cos \theta \sin \theta \epsilon_{12}$$

and solve for  $\epsilon_{12}$ :

$$\epsilon_{12} = \frac{\tilde{\epsilon}_{11} - \cos^2 \theta \epsilon_{11} - \sin^2 \theta \epsilon_{22}}{2 \cos \theta \sin \theta}$$

So: 3 measurements are needed

Note 1: Such a "shear strain gage" normally measures elongational strain along axes of  $0^\circ$ ,  $45^\circ$ , and  $90^\circ$ :



So in the  $\epsilon_{12}$  equation,  $\theta = 45^\circ$ . If the reading for  $\epsilon_{11}$  is  $A$ ; for  $\tilde{\epsilon}_{11}$  is  $B$ ; for  $\epsilon_{22}$  is  $C$ ;

then:

$$\epsilon_{12} = B - \frac{1}{2}(A+C)$$

CAUTION!! This is tensorial shear strain.

In engineering shear strain, there is a factor of 2:  $\gamma_{12} = 2B - (A+C)$

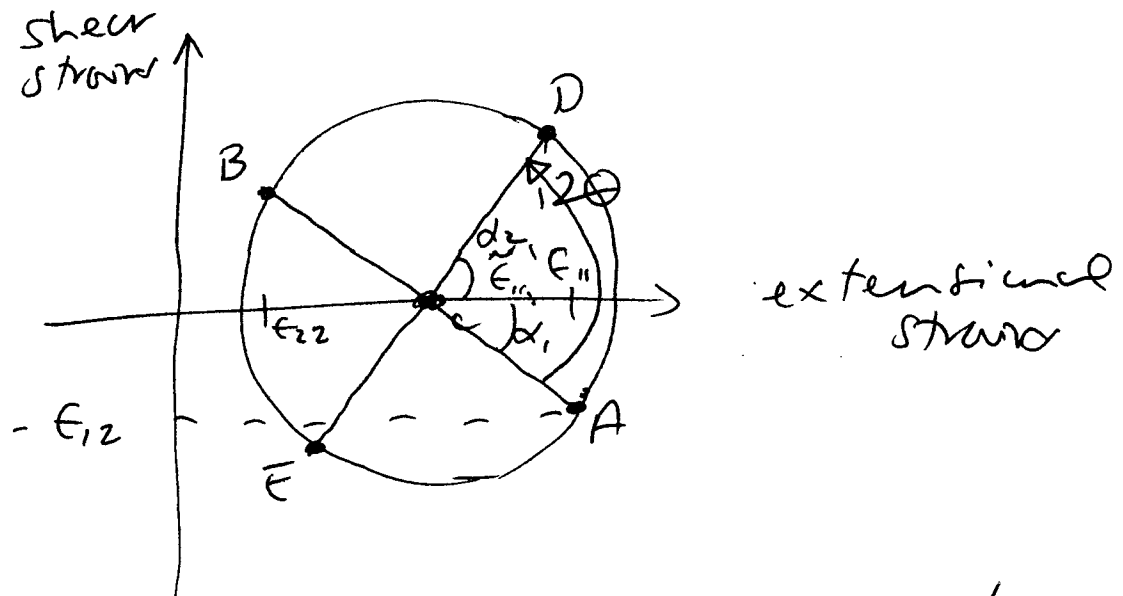
Note 2: The same reasoning can be followed through using the Mohr's circle as a basis. Again, three readings (and associated directions) of longitudinal strain are needed to characterize the circle.

How? Consider the invariants to first. The pertinent one is that which gives

the midpoint :  $\frac{\epsilon_{11} + \epsilon_{22}}{2}$

A measurement of  $\tilde{\epsilon}_{11}$  gives an  $\tilde{\epsilon}_{22}$

Now draw the circle :



Considering geometry one can show the angle to principal strain is :

$$R \cos \alpha_1 = \epsilon_{11} - \frac{\epsilon_{11} + \epsilon_{22}}{2} = \frac{\epsilon_{11} - \epsilon_{22}}{2}$$

$$\text{and } R \sin \alpha_1 = \epsilon_{12}$$

In a similar way :

factor of 2 in Mohr's circle

$$R \cos \alpha_2 = \frac{\tilde{\epsilon}_{11} - \tilde{\epsilon}_{22}}{2}$$

Finally :  $\alpha_2 = 2\theta - \alpha_1$   
 $\Rightarrow \cot \alpha_2 = \cot(2\theta - \alpha_1) = \cot 2\theta \cot \alpha_1 + \frac{1 + \cot^2 2\theta}{2 \cot \alpha_1}$

(using trigonometric expansion) PAL

working this last item with what is known:

$$\frac{\tilde{\epsilon}_{11} - \tilde{\epsilon}_{22}}{2R} = \cos 2\theta \left( \frac{\epsilon_{11} - \epsilon_{22}}{2R} \right) + \sin 2\theta \frac{\epsilon_{12}}{R}$$

→ R cancels out

→  $\theta, \epsilon_{11}, \epsilon_{22}, \tilde{\epsilon}_{11}$  are measured

→  $\tilde{\epsilon}_{22}$  results since  $\epsilon_{11} + \epsilon_{22} = \tilde{\epsilon}_{11} + \tilde{\epsilon}_{22}$   
 $\Rightarrow \tilde{\epsilon}_{22} = \epsilon_{11} + \epsilon_{22} - \tilde{\epsilon}_{11}$

$$\text{So: } 2\tilde{\epsilon}_{11} - \epsilon_{11} - \epsilon_{22} = (\epsilon_{11} - \epsilon_{22}) \cos 2\theta + 2 \sin 2\theta \epsilon_{12}$$

and solve for  $\epsilon_{12}$

for the case of  $\theta = 45^\circ$

$$\text{and } \tilde{\epsilon}_{11} = B$$

$$\epsilon_{11} = A$$

$$\epsilon_{22} = C$$

$$\Rightarrow \cos 2\theta = 0, \sin 2\theta = 1$$

$$\text{finally: } 2B - A - C = 2\epsilon_{12}$$

$$\Rightarrow \epsilon_{12} = B - \frac{1}{2}(A + C)$$

as before!

**M20 (M11.3)** The following answers, as asked for in the problem statement, include a brief sentence on the primary functional requirement that needs to be met for each of the given cases. This includes the loads (e.g. tension, compression, shear, impact, cyclic, thermal, electrical) and five material properties that are most relevant to meeting this requirement. Note that the items listed are just *some* of the possible requirements, loads, and properties. (**NOTE:** Problem set answers will vary according to what the individual student indicates are the relevant loads and properties.)

(a) Compressor blades of a jet engine: Must maintain desired shape during operation of engine.

Types of loads:           1. Impact  
                                  2. Tension and Compression  
                                  3. Aerodynamic/Pressure  
                                  4. Wear

Material properties:   1. Strength - High  
                                  2. Modulus - High  
                                  3. Impact - High  
                                  4. Corrosion - High  
                                  5. Cyclic - High

(b) Cable used for towing large trucks: Must provide load-carrying capacity and resistance to environment for loads and items encountered in towing

Types of loads:           1. Tension (pulling, from bumps)  
                                  2. Impact  
                                  3. Thermal (due to baseline temperature from environment)  
                                  4. Wear

Material properties:   1. Strength - High  
                                  2. Abrasion and wear - High  
                                  3. Modulus - High  
                                  4. Corrosion - High  
                                  5. Price - Low

(c) Components of a truss for a radio tower: Must provide load-carrying capacity for loads that a radio tower undergoes.

Types of loads:           1. & 2. Tension and Compression (depending on design -- mainly compression due to gravity)  
                                  3. Assembly  
                                  4. Environmental (Thermal, Aerodynamic)

Material properties:   1. Corrosion - High  
                                  2. Modulus - High  
                                  3. Strength - Medium



4. Fabrication & Joining - High
5. Price - Low

(d) Components of a space truss: Must provide load-carrying capacity for loads that a space truss undergoes.

- Types of loads:
1. Impact (docking)
  2. Thermal (solar)
  3. & 4. Tension and Compression (depending on design)
  5. Cyclic

- Material properties:
1. Thermal - High
  2. Density - Low
  3. Modulus - High
  4. Joining - Medium
  5. Longevity - High

(e) Reentry shield on the space shuttle: Must insulate the shuttle structure and its passengers from the extreme heat of reentry.

- Types of loads:
1. Thermal
  2. Cyclic
  3. Impact

- Material properties:
1. Thermal - High
  2. Density - Low
  3. Oxidation Resistance - High
  4. Hardness - Medium
  5. Strength - Medium

(f) Tiles for a house floor: Must provide an “aesthetic” and durable surface for a house floor.

- Types of loads:
1. Impact
  2. Compression
  3. Thermal
  4. Environmental

- Material properties:
1. Price - Low
  2. Availability - High
  3. Hardness - Medium
  4. Appearance - High
  5. Finishing - High

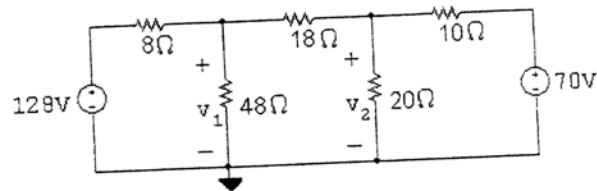
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**Solution for Problem S5 (Signals and Systems)**

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1.

[a]



$$\frac{v_1 - 128}{8} + \frac{v_1}{48} + \frac{v_1 - v_2}{18} = 0$$

$$\frac{v_2 - v_1}{18} + \frac{v_2}{20} + \frac{v_2 - 70}{10} = 0$$

In standard form,

$$v_1 \left( \frac{1}{8} + \frac{1}{48} + \frac{1}{18} \right) + v_2 \left( -\frac{1}{18} \right) = \frac{128}{8}$$

$$v_1 \left( -\frac{1}{18} \right) + v_2 \left( \frac{1}{18} + \frac{1}{20} + \frac{1}{10} \right) = \frac{70}{10}$$

Solving,  $v_1 = 96$  V;  $v_2 = 60$  V

$$i_a = \frac{128 - 96}{8} = 4 \text{ A}$$

$$i_b = \frac{96}{48} = 2 \text{ A}$$

$$i_c = \frac{96 - 60}{18} = 2 \text{ A}$$

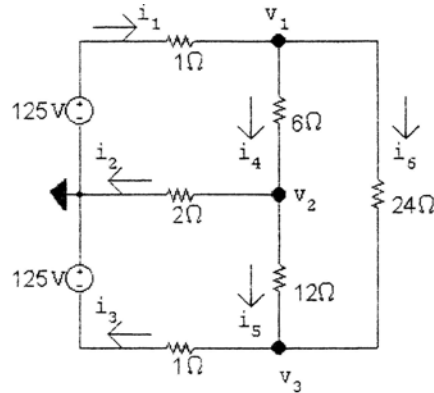
$$i_d = \frac{60}{20} = 3 \text{ A}$$

$$i_e = \frac{60 - 70}{10} = -1 \text{ A}$$

[b]  $p_{\text{dev}} = 128(4) + 70(1) = 582 \text{ W}$

2.

[a]



$$\frac{v_1 - 125}{1} + \frac{v_1 - v_2}{6} + \frac{v_1 - v_3}{24} = 0$$

$$\frac{v_2 - v_1}{6} + \frac{v_2}{2} + \frac{v_2 - v_3}{12} = 0$$

$$\frac{v_3 + 125}{1} + \frac{v_3 - v_2}{12} + \frac{v_3 - v_1}{24} = 0$$

In standard form:

$$v_1 \left( \frac{1}{1} + \frac{1}{6} + \frac{1}{24} \right) + v_2 \left( -\frac{1}{6} \right) + v_3 \left( -\frac{1}{24} \right) = 125$$

$$v_1 \left( -\frac{1}{6} \right) + v_2 \left( \frac{1}{6} + \frac{1}{2} + \frac{1}{12} \right) + v_3 \left( -\frac{1}{12} \right) = 0$$

$$v_1 \left( -\frac{1}{24} \right) + v_2 \left( -\frac{1}{12} \right) + v_3 \left( \frac{1}{1} + \frac{1}{12} + \frac{1}{24} \right) = -125$$

Solving,  $v_1 = 101.24$  V;  $v_2 = 10.66$  V;  $v_3 = -106.57$  V

$$\text{Thus, } i_1 = \frac{125 - v_1}{1} = 23.76 \text{ A} \quad i_4 = \frac{v_1 - v_2}{6} = 15 \text{ A}$$

$$i_2 = \frac{v_2}{2} = 5.33 \text{ A} \quad i_5 = \frac{v_2 - v_3}{12} = 9.77 \text{ A}$$

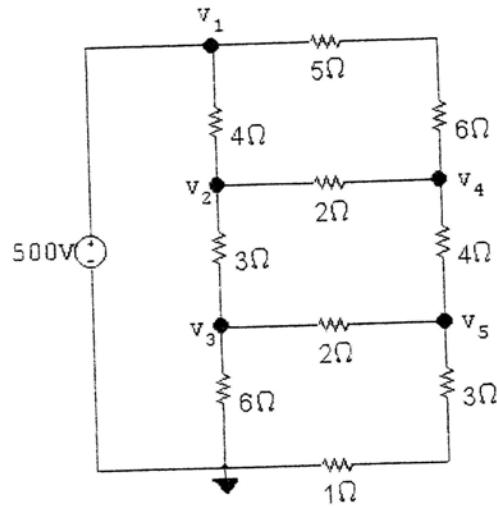
$$i_3 = \frac{v_3 + 125}{1} = 18.43 \text{ A} \quad i_6 = \frac{v_1 - v_3}{24} = 8.66 \text{ A}$$

$$[b] \sum P_{\text{dev}} = 125i_1 + 125i_3 = 5273.09 \text{ W}$$

$$\sum P_{\text{dis}} = i_1^2(1) + i_2^2(2) + i_3^2(1) + i_4^2(6) + i_5^2(12) + i_6^2(24) = 5273.09 \text{ W}$$

3.

[a]



$$\frac{v_2 - 500}{4} + \frac{v_2 - v_4}{2} + \frac{v_2 - v_3}{3} = 0$$

$$\text{so } 13v_2 - 4v_3 - 6v_4 + 0v_5 = 1500$$

$$\frac{v_3 - v_2}{3} + \frac{v_3}{6} + \frac{v_3 - v_5}{2} = 0$$

$$\text{so } -2v_2 + 6v_3 + 0v_4 - 3v_5 = 0$$

$$\frac{v_4 - v_2}{2} + \frac{v_4 - 500}{11} + \frac{v_4 - v_5}{4} = 0$$

$$\text{so } -22v_2 + 0v_3 + 37v_4 - 11v_5 = 2000$$

$$\frac{v_5 - v_3}{2} + \frac{v_5}{4} + \frac{v_5 - v_4}{4} = 0$$

$$\text{so } 0v_2 - 2v_3 - v_4 + 4v_5 = 0$$

Solving,  $v_2 = 300$  V;  $v_3 = 180$  V;  $v_4 = 280$  V;  $v_5 = 160$  V

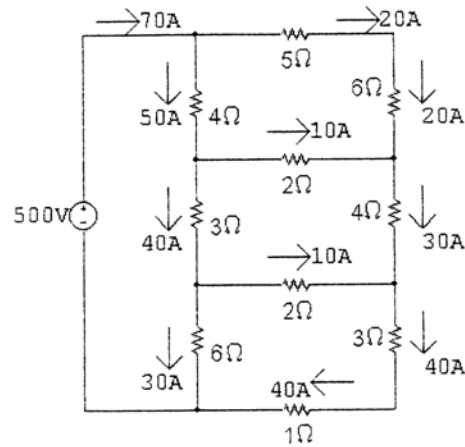
$$i_{5\Omega} = \frac{500 - v_4}{11} = \frac{500 - 280}{11} = 20 \text{ A}$$

$$p_{5\Omega} = (20)^2(5) = 2000 \text{ W}$$

$$\begin{aligned} \text{[b]} \quad i_{500\text{V}} &= \frac{v_1 - v_2}{4} + \frac{v_1 - v_4}{11} \\ &= \frac{500 - 300}{4} + \frac{500 - 280}{11} = 50 + 20 = 70 \text{ A} \end{aligned}$$

$$p_{500\text{V}} = 35,000 \text{ W}$$

Check:



$$\begin{aligned} \sum P_{\text{dis}} &= (50)^2(4) + (40)^2(3) + (30)^2(6) + (20)^2(11) + (10)^2(2) \\ &\quad + (30)^2(4) + (10)^2(2) + (40)^2(4) = 35,000 \text{ W} \end{aligned}$$

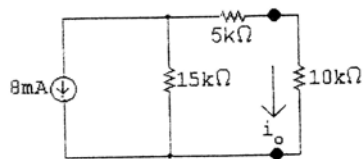
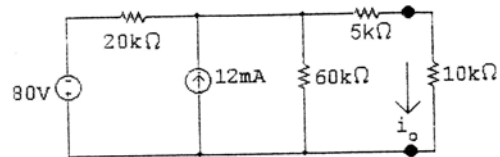
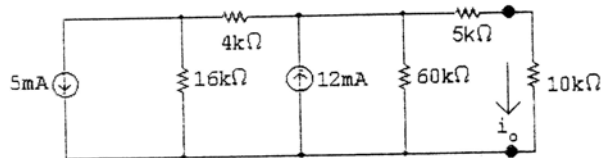
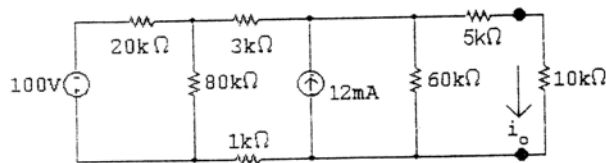
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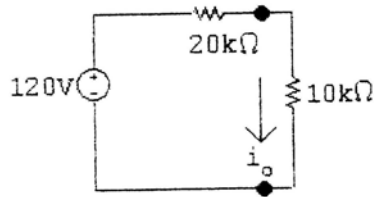
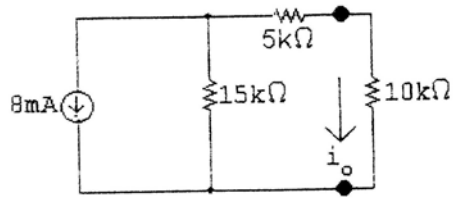
Solution for Problem S7 (Signals and Systems)

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1.

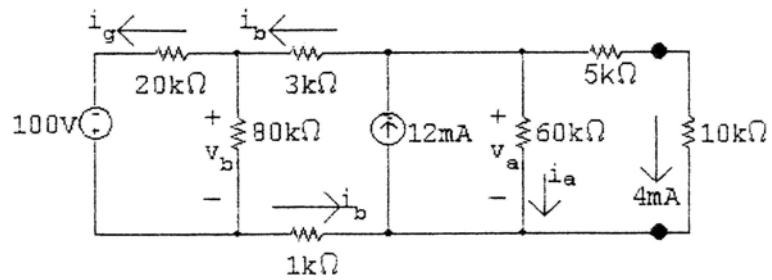
[a]





$$i_o = \frac{120}{30,000} = 4 \text{ mA}$$

[b]



$$v_a = (15,000)(0.004) = 60 \text{ V}$$

$$i_a = \frac{v_a}{60,000} = 1 \text{ mA}$$

$$i_b = 12 - 1 - 4 = 7 \text{ mA}$$

$$v_b = 60 - (0.007)(4000) = 32 \text{ V}$$

$$i_g = 0.007 - \frac{32}{80,000} = 6.6 \text{ mA}$$

$$p_{100\text{V}} = -(100)(6.6 \times 10^{-3}) = -660 \text{ mW}$$

Check:

$$p_{12\text{mA}} = -(60)(12 \times 10^{-3}) = -720 \text{ mW}$$

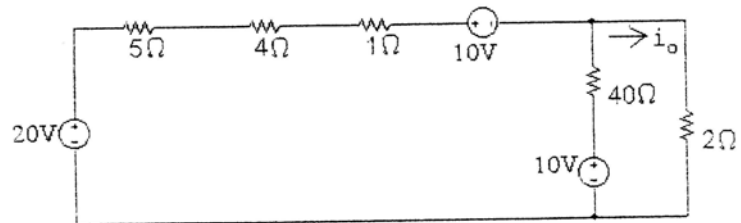
$$\sum P_{\text{dev}} = 660 + 720 = 1380 \text{ mW}$$

$$\begin{aligned} \sum P_{\text{dis}} &= (20,000)(6.6 \times 10^{-3})^2 + (80,000)(0.4 \times 10^{-3})^2 + (4000)(7 \times 10^{-3})^2 \\ &\quad + (60,000)(1 \times 10^{-3})^2 + (15,000)(4 \times 10^{-3})^2 \\ &= 1380 \text{ mW} \end{aligned}$$

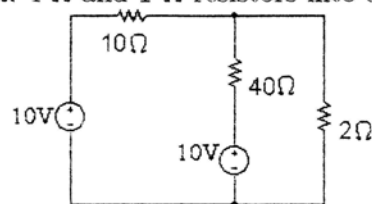


2.

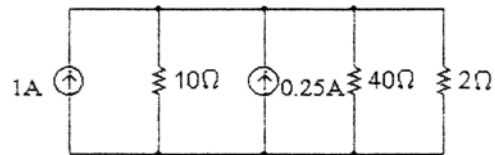
[a] Applying a source transformation to each current source yields



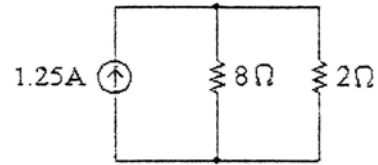
Now combine the 20 V and 10 V sources into a single voltage source and the 5 Ω, 4 Ω and 1 Ω resistors into a single resistor to get



Now use a source transformation on each voltage source, thus

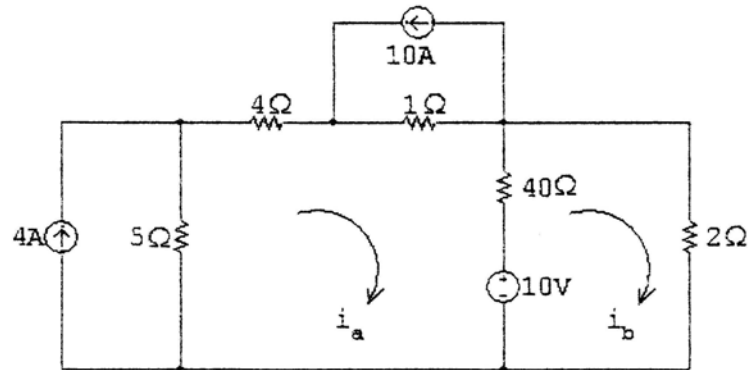


which can be reduced to



$$\therefore i_o = \frac{(1.25)(8)}{10} = 1 \text{ A}$$

[b]



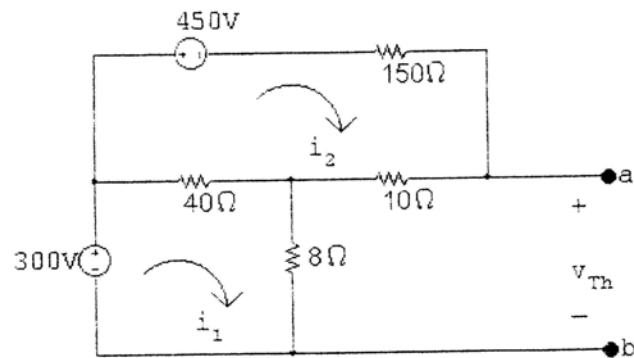
$$50i_a - 40i_b = 20 - 10 - 10 = 0$$

$$-40i_a + 42i_b = 10$$

$$\text{Solving, } i_b = \frac{N_b}{\Delta} = 1 \text{ A} = i_o$$

3.

After making a source transformation the circuit becomes



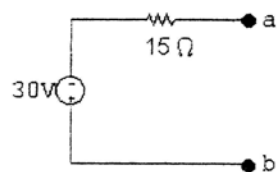
$$300 = 48i_1 - 40i_2$$

$$-450 = -40i_1 + 200i_2$$

$$\therefore i_1 = 5.25 \text{ A and } i_2 = -1.2 \text{ A}$$

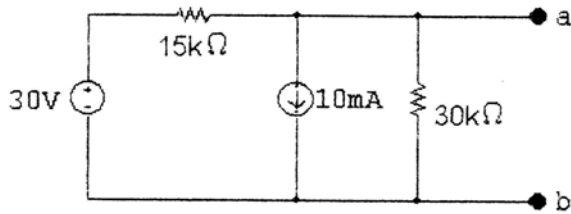
$$v_{Th} = 8i_1 + 10i_2 = 30 \text{ V}$$

$$R_{Th} = (40 \parallel 8 + 10) \parallel 150 = 15 \Omega$$

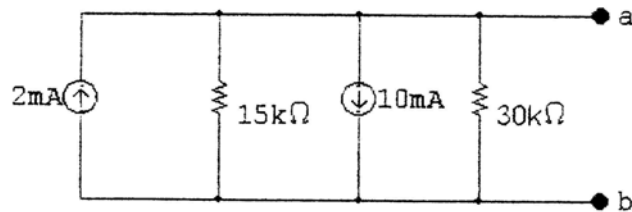


4.

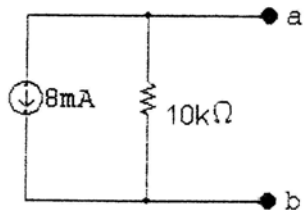
First we make the observation that the 8-mA current source and the  $20\text{ k}\Omega$  resistor will have no influence on the behavior of the circuit with respect to the terminals a,b. This follows because they are in parallel with an ideal voltage source. Hence our circuit can be simplified to



or



Therefore the Norton equivalent is



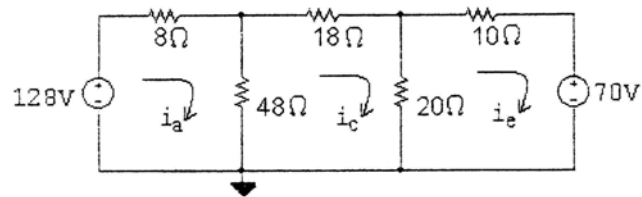
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Solution for Problem S6 (Signals and Systems)

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1.

[a]



The three mesh current equations are:

$$-128 + 8i_a + 48(i_a - i_c) = 0$$

$$18i_c + 20(i_c - i_e) + 48(i_c - i_a) = 0$$

$$70 + 20(i_e - i_c) + 10i_e = 0$$

Place these equations in standard form:

$$i_a(8 + 48) + i_c(-48) + i_e(0) = 128$$

$$i_a(-48) + i_c(18 + 20 + 48) + i_e(-20) = 0$$

$$i_a(0) + i_c(-20) + i_e(20 + 10) = -70$$

Solving,  $i_a = 4$  A;  $i_c = 2$  A;  $i_e = -1$  A

Now calculate the remaining branch currents:

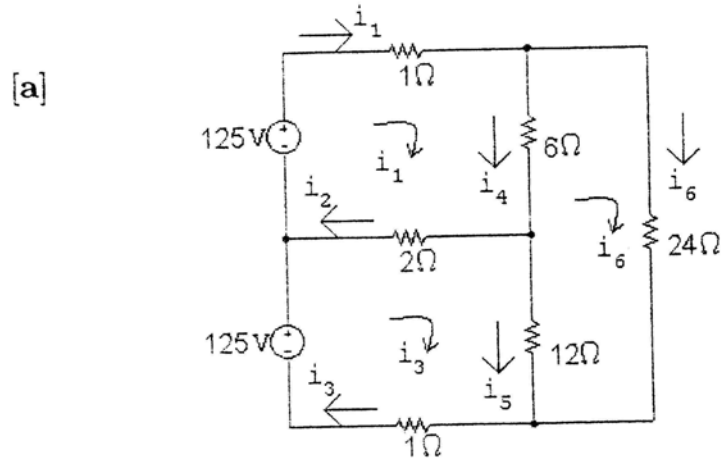
$$i_b = i_a - i_c = 2 \text{ A}$$

$$i_d = i_c - i_e = 3 \text{ A}$$

$$\begin{aligned} \text{[b]} \quad p_{\text{sources}} &= p_{128\text{V}} + p_{70\text{V}} = -(128)i_a + (70)i_e \\ &= -(128)(4) + (70)(-1) = -512 - 70 = -582 \text{ W} \end{aligned}$$

Thus, the power developed in the circuit is 582 W. Note that the resistors cannot develop power!

2.



The three mesh current equations are:

$$-125 + 1i_1 + 6(i_1 - i_6) + 2(i_1 - i_3) = 0$$

$$24i_6 + 12(i_6 - i_3) + 6(i_6 - i_1) = 0$$

$$-125 + 2(i_3 - i_1) + 12(i_3 - i_6) + 1i_3 = 0$$

Place these equations in standard form:

$$i_1(1 + 6 + 2) + i_3(-2) + i_6(-6) = 125$$

$$i_1(-6) + i_3(-12) + i_6(24 + 12 + 6) = 0$$

$$i_1(-2) + i_3(2 + 12 + 1) + i_6(-12) = 125$$

Solving,  $i_1 = 23.76$  A;  $i_3 = 18.43$  A;  $i_6 = 8.66$  A  
Now calculate the remaining branch currents:

$$i_2 = i_1 - i_3 = 5.33 \text{ A}$$

$$i_4 = i_1 - i_6 = 15.10 \text{ A}$$

$$i_5 = i_3 - i_6 = 9.77 \text{ A}$$



$$\begin{aligned} \text{[b]} \quad p_{\text{sources}} &= p_{\text{top}} + p_{\text{bottom}} = -(125)(23.76) - (125)(18.43) \\ &= -2970 - 2304 = -5274 \text{ W} \end{aligned}$$

Thus, the power developed in the circuit is 5274 W.  
Now calculate the power absorbed by the resistors:

$$p_{1\text{top}} = (23.76)^2(1) = 564.54 \text{ W}$$

$$p_2 = (5.33)^2(2) = 56.82 \text{ W}$$

$$p_{1\text{bot}} = (18.43)^2(1) = 339.66 \text{ W}$$

$$p_6 = (15.10)^2(6) = 1368.06 \text{ W}$$

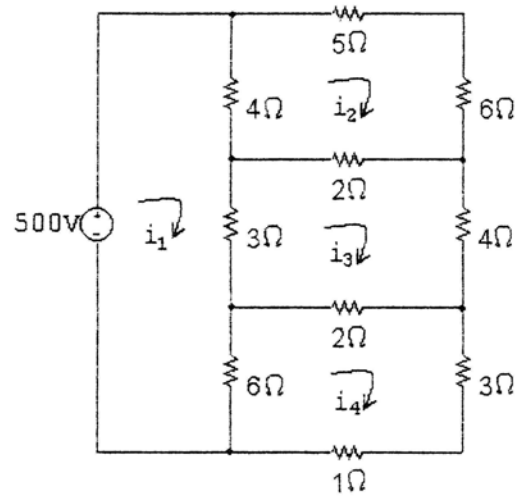
$$p_{12} = (9.77)^2(12) = 1145.43 \text{ W}$$

$$p_{24} = (8.66)^2(24) = 1799.89 \text{ W}$$

The power absorbed by the resistors is  
 $564.54 + 56.82 + 339.66 + 1368.06 + 1145.43 + 1799.89 = 5274 \text{ W}$  so the  
power balances.

3.

[a]



The four mesh current equations are:

$$-500 + 4(i_1 - i_2) + 3(i_1 - i_3) + 6(i_1 - i_4) = 0$$

$$5i_2 + 6i_2 + 2(i_2 - i_3) + 4(i_2 - i_1) = 0$$

$$4i_3 + 2(i_3 - i_4) + 3(i_3 - i_1) + 2(i_3 - i_2) = 0$$

$$3i_4 + 1i_4 + 6(i_4 - i_1) + 2(i_4 - i_3) = 0$$

Place these equations in standard form:

$$i_1(4 + 3 + 6) + i_2(-4) + i_3(-3) + i_4(-6) = 500$$

$$i_1(-4) + i_2(5 + 6 + 2 + 4) + i_3(-2) + i_4(0) = 0$$

$$i_1(-3) + i_2(-2) + i_3(2 + 4 + 2 + 3) + i_4(-2) = 0$$

$$i_1(-6) + i_2(0) + i_3(-2) + i_4(2 + 3 + 1 + 6) = 0$$

Solving,  $i_1 = 70$  A;  $i_2 = 20$  A;  $i_3 = 30$  A;  $i_4 = 40$  A

The power absorbed by the  $5\ \Omega$  resistor is

$$p_5 = i_2^2(5) = (20)^2(5) = 2000\ \text{W}$$

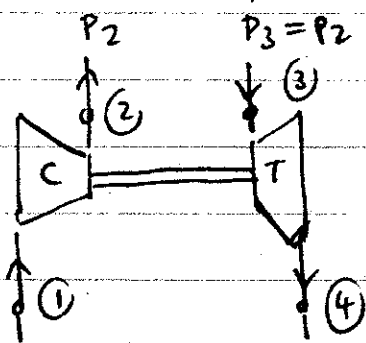
$$[\mathbf{b}] p_{500} = -(500)i_1 = -(500)(70) = -35\ \text{k W}$$

T22

16. Unified Fall 08

25

IC engine



$P_1 = 1 \text{ bar}$

$T_1 = 288 \text{ K}$

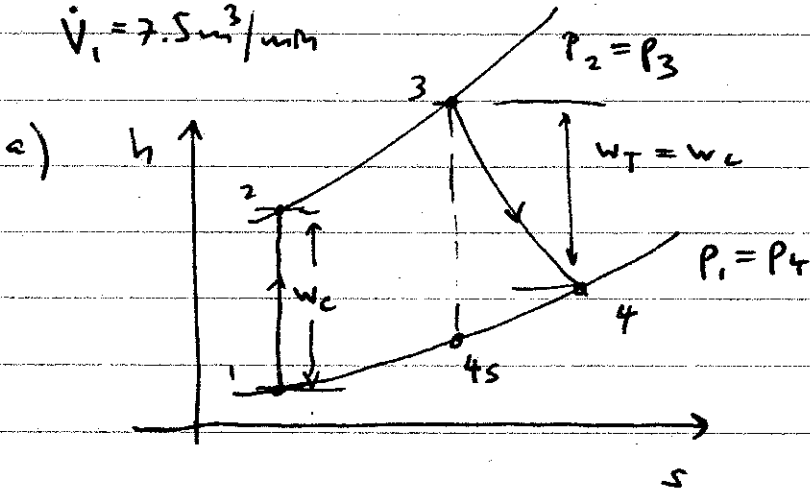
$\dot{V}_1 = 7.5 \text{ m}^3/\text{min}$

$P_4 = P_1$

$\pi_c = 1.5$

$W_T = \eta_T \cdot \Delta h_T^{is} \quad \eta_T = 0.7$

Assume: perfect gas, adiabatic comp., neglect KE effects



$\Delta h_T^{is} = c_p (T_3 - T_{4s})$

shaft power balance

$W_c = W_T = \eta_T \Delta h_T^{is}$

b)  $W_T = W_c = c_p (T_2 - T_1)$ ,  $T_2 = T_1 \cdot \pi_c^{\frac{\gamma-1}{\gamma}}$ ,  $\dot{m} = \dot{V}_1 \rho_1 = \dot{V}_1 \frac{P_1}{RT_1} = 0.15 \text{ kg/s}$   
 1st law cv

$\dot{W}_T = \dot{m} c_p T_1 (\pi_c^{\frac{\gamma-1}{\gamma}} - 1) = \frac{\dot{V}_1 P_1 c_p}{R} (\pi_c^{\frac{\gamma-1}{\gamma}} - 1)$

$\dot{W}_T = \frac{8}{8-1} P_1 \dot{V}_1 (\pi_c^{\frac{8-1}{8}} - 1) = 5.374 \text{ kW}$

c) shaft power balance (see above)  $c_p (\pi_c^{\frac{\gamma-1}{\gamma}} - 1) T_1 = \eta_T c_p (T_3 - T_{4s})$

$T_{4s} = T_3 \left(\frac{1}{\pi_c}\right)^{\frac{\gamma-1}{\gamma}} \rightarrow (\pi_c^{\frac{\gamma-1}{\gamma}} - 1) T_1 = \eta_T T_3 (1 - \pi_c^{-\frac{\gamma-1}{\gamma}})$

$T_3 = T_1 \frac{1}{\eta_T} \frac{\pi_c^{\frac{\gamma-1}{\gamma}} - 1}{1 - \pi_c^{-\frac{\gamma-1}{\gamma}}} = 462 \text{ K}$

$T_4 = T_3 - T_1 (\pi_c^{\frac{\gamma-1}{\gamma}} - 1) = 426.6 \text{ K}$

d)  $\Delta S_{tot} = \Delta S_c + \Delta S_T + \Delta S_{sur} = \Delta S_T$  (isentropic comp., no heat interaction with surr.)

$\Delta S_{tot} = \Delta S_{gen} > 0 \quad T ds = dh - v dp \rightarrow ds = c_p \frac{dT}{T} - R \frac{dp}{p}$

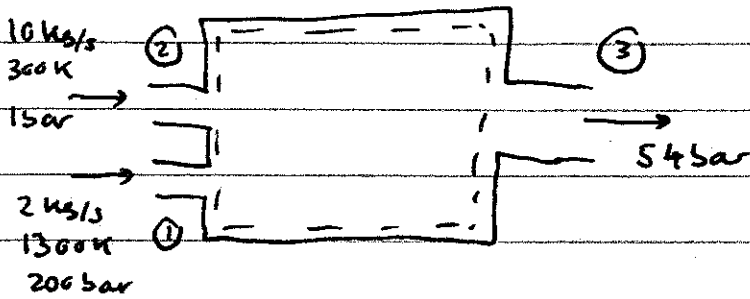
$\Delta S_{gen} = c_p \ln\left(\frac{T_4}{T_1}\right) - R \ln\left(\frac{P_4}{P_1}\right)$

$\Delta S_{gen} = 36.3 \text{ J/kg-K}$

T21

16. Unified Fall 08

25



Assume:

- adiabatic system
- air, perfect gas
- steady operation
- neglect  $\Delta KE, \Delta PE$

1st law: 
$$\frac{dE_{cv}}{dt} = \sum \dot{Q} + \sum \dot{W}_p + \sum \dot{W}_s + \sum \dot{m} \left( h + \frac{c^2}{2} + gz \right)$$

$0 = \dot{m}_1 h_1 + \dot{m}_2 h_2 - \dot{m}_3 h_3$

Cons of mass:  $\dot{m}_3 = \dot{m}_2 + \dot{m}_1 \quad \rightarrow \quad h_3 = \frac{\dot{m}_1 h_1 + \dot{m}_2 h_2}{\dot{m}_1 + \dot{m}_2}$

find  $T_3 = 466.7 \text{ K}$

2nd law:  $\Delta S_{total} \geq 0$ ?  $T ds = T dq + dp$  so entropy of an insulated system can only increase!

$\dot{m}_3 s_3 \geq \dot{m}_2 s_2 + \dot{m}_1 s_1 \quad ; \quad \dot{m}_1 (s_3 - s_1) + \dot{m}_2 (s_3 - s_2) \geq 0$ ?

entropy changes:  $T ds = dh - v dp \quad \rightarrow \quad \Delta s = c_p \ln\left(\frac{T_f}{T_i}\right) - R \ln\left(\frac{P_f}{P_i}\right)$

find  $s_3 - s_1 = c_p \ln\left(\frac{T_3}{T_1}\right) - R \ln\left(\frac{P_3}{P_1}\right) = -653.3 \text{ J/kg-K}$

$s_3 - s_2 = c_p \ln\left(\frac{T_3}{T_2}\right) - R \ln\left(\frac{P_3}{P_2}\right) = -701.0 \text{ J/kg-K}$

find:  $\dot{m}_2 (s_3 - s_2) + \dot{m}_1 (s_3 - s_1) = -8316.8 \text{ J/kg-K} < 0$  impossible!

The device cannot be made to operate in steady state

OR:  $P_3 \text{ max.} \rightarrow \dot{m}_1 (s_3 - s_1) + \dot{m}_2 (s_3 - s_2) = 0 \rightarrow$  find  $P_3$ ; show  $P_3 < P = 54 \text{ bar}$