

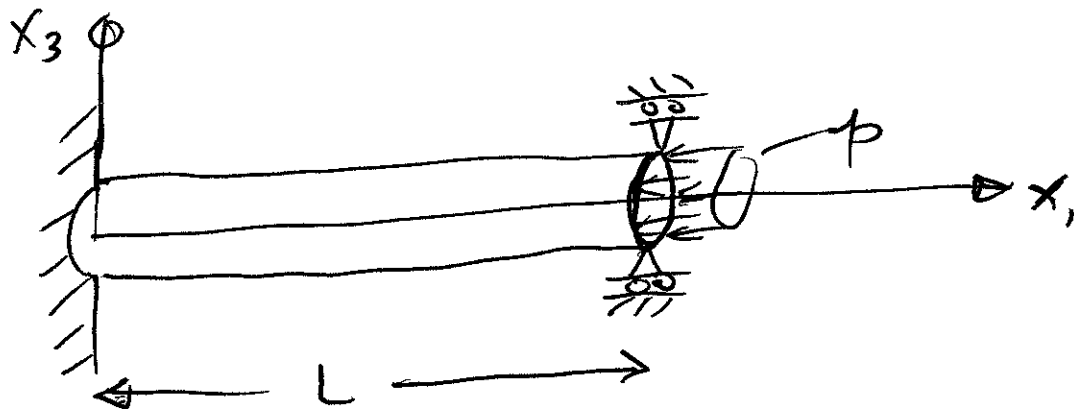
PAL
4/9/09Unified Engineering Problem Set 9

Week 11 Spring, 2009

SOLUTIONS

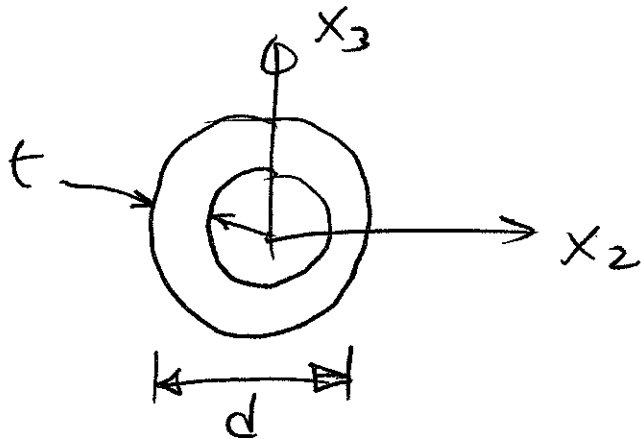
M15 (M11.1)

General configuration:



Note: $x_1 - x_3$ axes placed as in buckling work done in lecture

Consider the cross-section:



Use a general structural property characterization:

Cross-sectional Area = A

Moment of Inertia = I

Modulus = E

End Load = $P (= p A)$
 \swarrow pressure

With this characterization, the buckling behavior can be characterized without the specifics of the cross-section, but in terms of cross-section representations of I and A , along with the overall load P . The specifics of the cross-section can then be used.

→ Start with the basic governing equation:

$$\frac{d^2 u_3}{dx_1^2} + \frac{P}{EI} u_3 = 0 \quad (1)$$

with the general homogeneous solutions:

$$u_3 = A \sin\left(\sqrt{\frac{P}{EI}} x_1\right) + B \cos\left(\sqrt{\frac{P}{EI}} x_1\right) + C + Dx_1 \quad (2)$$

→ Look at the boundary conditions for this configuration

- At the clamped end ($x_1 = 0$):

$$u_3 = 0$$

$$\frac{du_3}{dx_1} = 0$$

- At the roller-supported end with applied load ($x_1 = l$):

$$u_3 = 0$$

$$M = 0 \Rightarrow \frac{d^2 u_3}{dx_1^2} = 0$$

→ To facilitate writing the expression for the solution, represent:

$$\lambda = \sqrt{\frac{P}{EI}}$$

So:

$$\frac{d^2 u_3}{dx_1^2} + \lambda^2 u_3 = 0 \quad (1')$$

and:

$$u_3 = A \sin \lambda x_1 + B \cos \lambda x_1 + C + Dx_1 \quad (2')$$

take the first two derivatives:

$$\frac{du_3}{dx_1} = \lambda A \cos \lambda x_1 - \lambda B \sin \lambda x_1 + D$$

$$\frac{d^2 u_3}{dx_1^2} = -\lambda^2 A \sin \lambda x_1 - \lambda^2 B \cos \lambda x_1$$

→ Now apply each of the 4 Boundary conditions to get 4 equations:

$$\textcircled{a} \quad x_1 = 0, \quad u_3 = 0 \quad \Rightarrow \quad B + C = 0 \quad (3)$$

$$\textcircled{b} \quad x_1 = 0, \quad \frac{du_3}{dx_1} = 0 \quad \Rightarrow \quad \lambda A + D = 0 \quad (4)$$

$$\textcircled{c} \quad x_1 = L, \quad u_3 = 0 \quad \Rightarrow \quad A \sin \lambda L + B \cos \lambda L + C + DL = 0 \quad (5)$$

$$\textcircled{d} \quad x_1 = L, \quad \frac{d^2 u_3}{dx_1^2} = 0 \quad \Rightarrow \quad -\lambda^2 A \sin \lambda L + \lambda^2 B \cos \lambda L = 0$$

yielding: $A \sin \lambda L + B \cos \lambda L = 0 \quad (6)$

→ Manipulate these resulting equations....

use (6) in (5)

$$\Rightarrow C + DL = 0$$

$$\text{giving: } \boxed{C = -DL}$$

use this result in (3) to get:

$$\boxed{B = DL}$$

work directly with (4) to get:

$$\boxed{A = -D/\lambda}$$

→ All constants are now in terms of one constant D . Use these expressions the overall solution (2'):

$$u_3 = -\frac{D}{\lambda} \sin \lambda x_1 + DL \cos \lambda x_1 - DL + Dx_1,$$

$$\Rightarrow u_3 = D \left(-\frac{1}{\lambda} \sin \lambda x_1 + L \cos \lambda x_1 - L + x_1 \right)$$

This give two possible solutions:

$$D = 0 \text{ (trivial)}$$

or

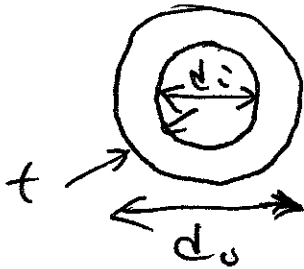
$$-\frac{1}{\lambda} \sin \lambda x_1 + L \cos \lambda x_1 - L + x_1 = 0$$

Any of which $\lambda = \sqrt{\frac{P}{EI}}$ yields:

$$-\sqrt{\frac{EI}{P}} \sin \sqrt{\frac{P}{EI}} x_1 + L \cos \left(\sqrt{\frac{P}{EI}} x_1 \right) - L + x_1 = 0$$

→ Go to the cross-section criteria to incorporate p , d , and E into λ

→ With a tube, area and moment of inertia can be determined by subtracting the inner portion from the outer portions



$$\text{with } d_i = d_0 - 2t$$

$$\text{finding: } r_o = \frac{d_0}{2} \quad r_i = \frac{d_i}{2} = \frac{d_0}{2} - t \\ = r_o - t$$

$$\text{circular area} = \pi r^2$$

$$\Rightarrow A = \pi \left[\left(\frac{d_0}{2} \right)^2 - \left(\frac{d_0}{2} - t \right)^2 \right] \\ = \pi \left[\frac{d_0^2}{4} - \frac{d_0^2}{4} + d_0 t - t^2 \right] \\ = \pi t (d_0 - t)$$

$$\text{circular moment of inertia} = \frac{\pi r^4}{4}$$

$$\Rightarrow I = \pi \left[\frac{\left(\frac{d_0}{2} \right)^4}{4} - \frac{1}{4} \left(\frac{d_0}{2} - t \right)^4 \right] \\ = \frac{\pi}{4} \left[\frac{d_0^4}{16} - \left(\frac{d_0}{2} - t \right)^4 \right]$$

with $\lambda = \sqrt{\frac{P}{EI}}$

$$\Rightarrow \lambda = \left[\frac{p \pi t (d_o - t)}{E \frac{\pi}{4} \left\{ \frac{d_o^4}{16} - \left(\frac{d_o}{2} - t \right)^4 \right\}} \right]^{1/2}$$

Finally:

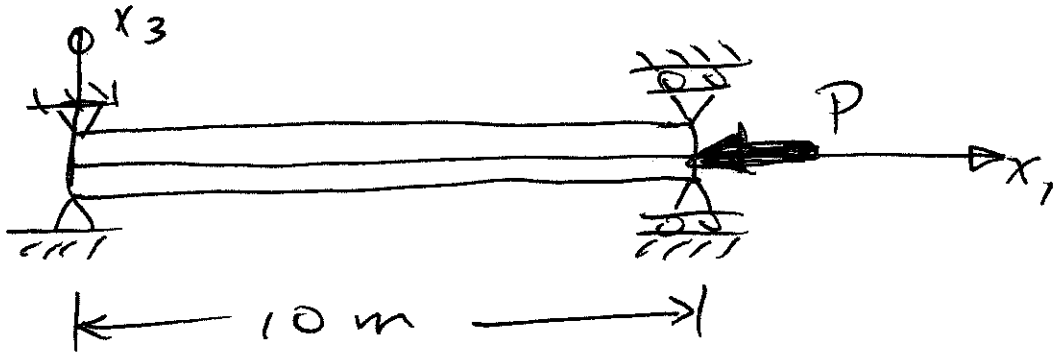
$$\lambda = \frac{4 p t (d_o - t)}{\sqrt{E \left[\frac{d_o^4}{16} - \left(\frac{d_o}{2} - t \right)^4 \right]}}$$

and:

$$-\frac{1}{\lambda} \sin \lambda x_1 + L \cos \lambda x_1 - L + x_1 = 0$$

These two expressions are to be used to find the buckling load (actually the buckling pressure) by finding the eigenvalues that satisfy this, now in terms of p . With these values put back in the governing expression, the eigenvectors, and thus the buckling mode can be determined.

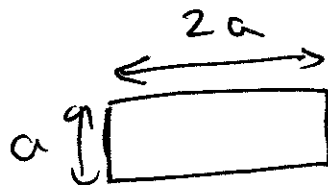
M16 (11.2)



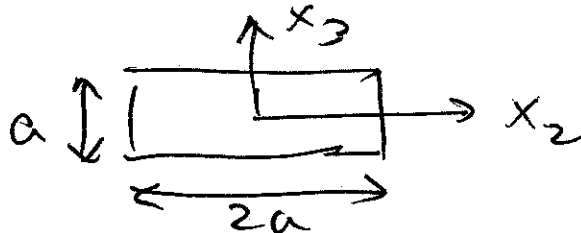
(a) Model this as a simply-supported column. For a simply-supported configuration:

$$P_{cr} = \frac{\pi^2 EI}{L^2}$$

Cross-section:



Buckling will occur in the direction where the cross-section is "shortest". Thus x_3 is aligned with the dimension a .



for a rectangular cross-section:

$$I = \frac{bh^3}{12}$$

Here: $b=2a$, $h=a$

$$\Rightarrow I = \frac{2a^4}{12} = \frac{a^4}{6}$$

The value of E for aluminium as per this case is 70 GPa ($= 70 \times 10^9 \frac{\text{N}}{\text{m}^2}$). The length is 10 m ($= L$).

→ Use these in the expression for P_{cr} :

$$P_{cr} = \frac{\pi^2 (70 \times 10^9 \frac{\text{N}}{\text{m}^2}) (\frac{a^4}{6})}{(10 \text{ m})^2}$$

Working through this gives:

$$P_{cr} = (11.5 \times 10^8 \frac{\text{N}}{\text{m}^4}) a^4$$

P_{cr} in $[\text{N}]$

a in $[\text{m}]$

Normally cross-section dimensions are in centimeters.

Redo these units:

$$100 \text{ cm} = 1 \text{ m}$$

$$\Rightarrow 11.5 \times 10^8 \frac{\text{N}}{\text{m}^2} \cdot \left(\frac{1 \text{ m}}{100 \text{ cm}} \right)^4$$

gives

$$P_{cr} = 11.5 a^4$$

$$a \text{ in [cm]}$$

$$P \text{ in [N]}$$

(b) To determine the squashing load, the material compressive ultimate is needed.

$$\text{for the aluminium: } \sigma_{cu} = 425 \text{ MPa} \\ = 425 \times 10^6 \frac{\text{N}}{\text{m}^2}$$

$$\text{Have: } \frac{P_{\text{squash}}}{A} = \sigma_{cu}$$

$$\text{for this configuration: } A = (2a)a = 2a^2$$

$$\text{So: } P_{sq} = \left(850 \frac{\text{N}}{\text{m}^2} \times 10^6 \right) a^2$$

$$a \text{ in [m]}$$

$$P \text{ in [N]}$$

make the same unit change for the cross-section dimensions:

$$P_{sg} = 850 \times 10^6 \frac{N}{m^2} \left(\frac{1m}{100cm} \right)^2 a^2$$

$$\Rightarrow \boxed{P_{sg} = 85,000 a^2} \quad \begin{array}{l} a \text{ in [cm]} \\ P \text{ in [N]} \end{array}$$

→ It is also important to determine the start of the "transition" zone via:

$$\frac{P_{transition}}{A} = \sigma_{cy}$$

here: $\sigma_{cy} = 370 \text{ MPa} = 370 \frac{N}{m^2}$

using the same procedure yields:

$$\boxed{P_{flow} \text{ (yield)} = 74,000 a^2} \quad \begin{array}{l} a \text{ in [cm]} \\ P \text{ in [N]} \end{array}$$

(c) The key to drawing the design chart is to determine the points (P and a) where the mode of failure goes from "buckling" to "transition" to "crushing/squashing". Do this by equating the buckling case with the latter two, solving for a, and substituting the result to get P. Then plot each curve.

→ summarizing:

$$\begin{array}{l}
 \text{(A) Buckling: } P_{cr} = 11.5a^4 \\
 \text{(B) Transition: } P_{trans} = 74,000a^2 \text{ (yielding)} \\
 \text{(C) Squashing: } P_{sq} = 85,000a^2
 \end{array}
 \left. \vphantom{\begin{array}{l} \text{(A) Buckling: } P_{cr} = 11.5a^4 \\ \text{(B) Transition: } P_{trans} = 74,000a^2 \text{ (yielding)} \\ \text{(C) Squashing: } P_{sq} = 85,000a^2 \end{array}} \right\} \begin{array}{l} \text{All with:} \\ a \text{ in [cm]} \\ P \text{ in [N]} \end{array}$$

• going from (A) to (B):

$$11.5a^4 = 74,000a^2$$

$$\Rightarrow a^2 = 6435$$

$$\Rightarrow a = 80.2 \text{ cm giving } P = 476 \times 10^6 \text{ N}$$

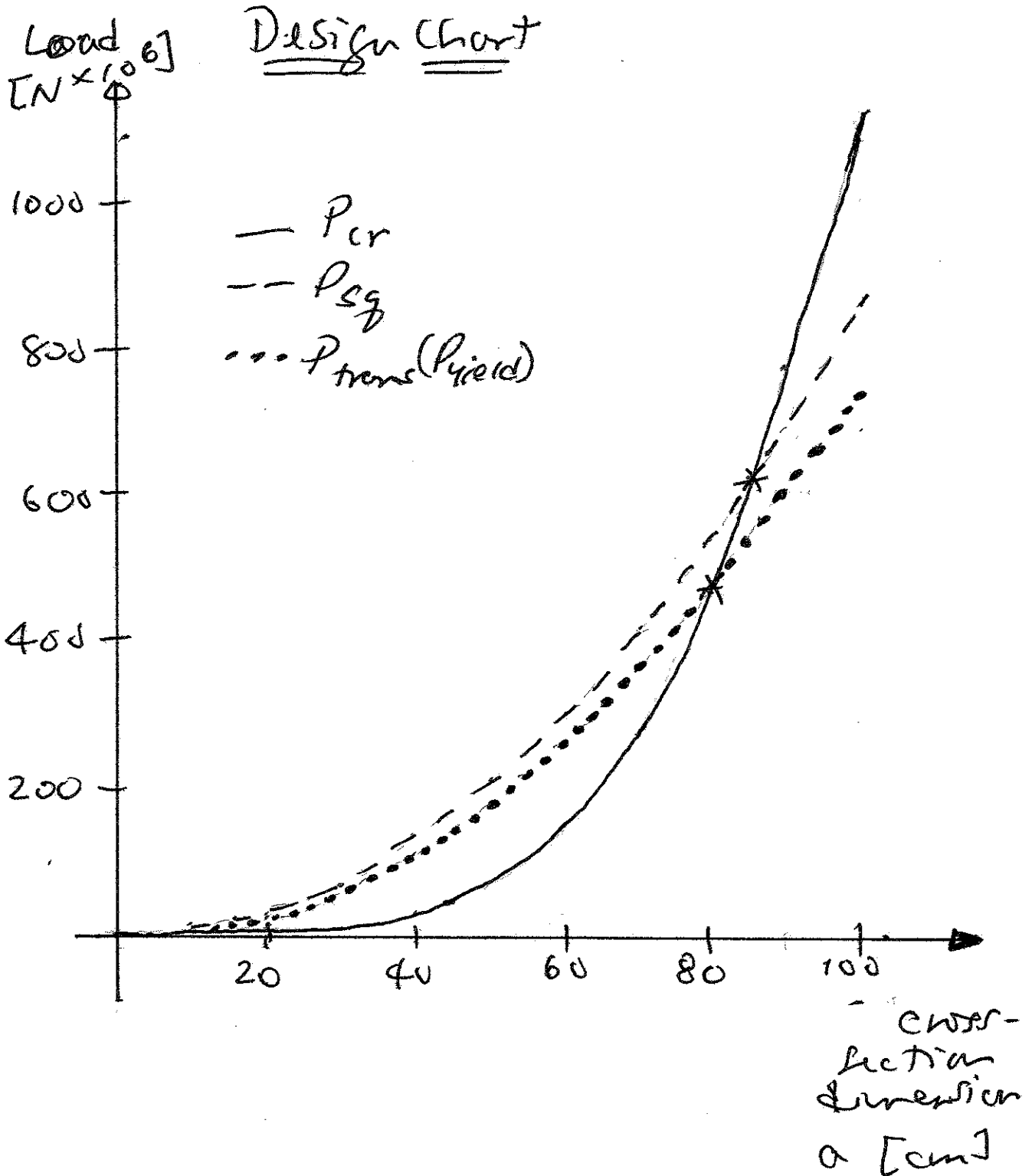
• going from (A) to (C):

$$11.5a^4 = 85,000a^2$$

$$\Rightarrow a^2 = 7391$$

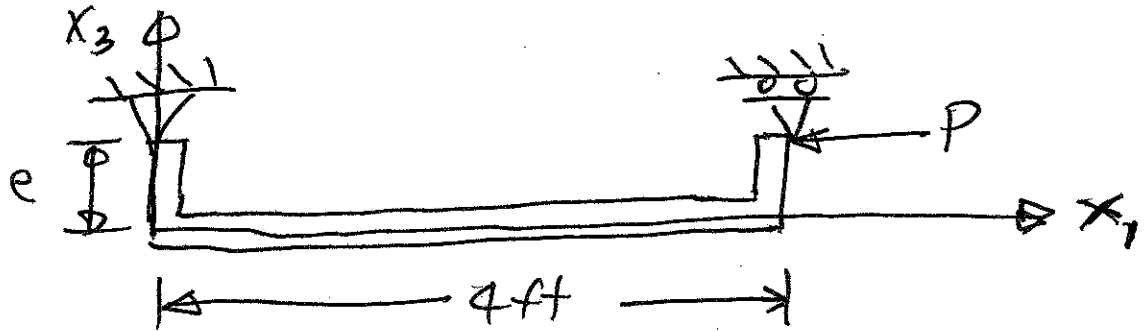
$$\Rightarrow a = 86.0 \text{ cm giving } P = 629 \times 10^6 \text{ N}$$

→ Draw the plots of each curve and label these key points:

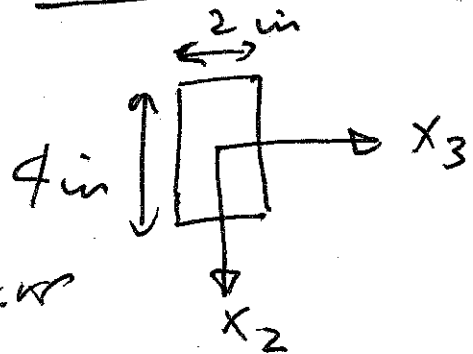


2-2

M17 (M11.3)



Cross-section



(Note: Buckling occurs in "weaker" direction \Rightarrow along x_3)

(a) The maximum load is the limit placed by the buckling load. This does not change due to the eccentric loading. This is a simply-supported configuration, so:

$$P_{cr} = \frac{\pi^2 EI}{L^2}$$

Have for titanium: $E = 18.5 \text{ Msi}$
 $= 18.5 \times 10^6 \frac{\text{lb}}{\text{in}^2}$

→ Need moment of inertia:

$$I = \frac{bh^3}{12}$$

here, $h = 2 \text{ in}$ and $b = 4 \text{ in}$

$$\Rightarrow I = \frac{(4 \text{ in})(2 \text{ in})^3}{12} = 2.67 \text{ in}^4$$

→ Also change L in feet to inches

$$L = 4 \text{ ft} = 48 \text{ in}$$

→ All this in expression for P_{cr} gives:

$$P_{cr} = \frac{\pi^2 (18.5 \times 10^6 \frac{\text{lb}}{\text{in}^2}) (2.67 \text{ in}^4)}{(48 \text{ in})^2}$$

$$\Rightarrow \boxed{P_{cr} = 211,600 \text{ lb}}$$

→ check σ_{cr} to see if it is σ_{cy} and σ_{cu} :

$$\sigma_{cr} = \frac{P_{cr}}{A} = \frac{211,600 \text{ lb}}{(4 \text{ in})(2 \text{ in})} = 26,450 \frac{\text{lb}}{\text{in}^2}$$

This is well below the yield and ultimate stress of 98 ksi and 150 ksi

$$(\text{ksi} = 10^3 \text{ lb/in}^2)$$

(b) for the case of a simply-supported configuration loaded eccentrically, the governing equation is:

$$u_3 = e \left[\frac{(1 - \cos \sqrt{\frac{P}{EI}} L)}{\sin \sqrt{\frac{P}{EI}} L} \sinh \sqrt{\frac{P}{EI}} x_1 + \cos \sqrt{\frac{P}{EI}} x_1 - 1 \right]$$

→ use the pertinent values of P_{cr} , E , and I , along with L to determine the deflection at the column center ($x_1 = \frac{L}{2} = 24 \text{ in}$).

→ Normalize that deflection by the length and normalize the applied load by the critical load.

To do this....

• multiply P by $\frac{P_{cr}}{P_{cr}} = \frac{\pi^2 EI}{P_{cr} L^2}$

$$\Rightarrow \sqrt{\frac{P}{EI}} = \sqrt{\frac{P}{EI} \cdot \frac{\pi^2 EI}{P_{cr} L^2}} = \sqrt{\frac{P}{P_{cr}} \frac{\pi^2}{L^2}}$$

$$\text{so: } \sqrt{\frac{P}{EI}} = \frac{\pi}{L} \sqrt{\frac{P}{P_{cr}}}$$

Put this back into the earlier equation to get:

$$u_3 = e \left[\frac{1 - \cos\left(\frac{\pi}{L} \sqrt{\frac{P}{P_{cr}}} L\right)}{\sin\left(\frac{\pi}{L} \sqrt{\frac{P}{P_{cr}}} L\right)} \sin\left(\frac{\pi}{L} \sqrt{\frac{P}{P_{cr}}} x_1\right) + \cos\left(\frac{\pi}{L} \sqrt{\frac{P}{P_{cr}}} x_1\right) - 1 \right]$$

Continue on and dividing through by L :

$$\frac{u_3}{L} = \frac{e}{L} \left[\frac{1 - \cos \pi \sqrt{\frac{P}{P_{cr}}}}{\sin \pi \sqrt{\frac{P}{P_{cr}}}} \sin \left(\pi \sqrt{\frac{P}{P_{cr}}} \frac{x_1}{L} \right) + \cos \left(\pi \sqrt{\frac{P}{P_{cr}}} \frac{x_1}{L} \right) - 1 \right]$$

→ And at the center: $\frac{x_1}{L} = 0.5$, giving:

$$\frac{u_3}{L} = \frac{e}{L} \left[\frac{1 - \cos \pi \sqrt{\frac{P}{P_{cr}}}}{\sin \pi \sqrt{\frac{P}{P_{cr}}}} \sin \left(\frac{\pi}{2} \sqrt{\frac{P}{P_{cr}}} \right) + \cos \left(\frac{\pi}{2} \sqrt{\frac{P}{P_{cr}}} \right) - 1 \right]$$

same for all cases with e normalized by L

(c) Use this relationship to make plots for the five cases of:

$$\frac{e}{L} = 0, 0.01, 0.02, 0.05, 0.1$$

Normalized Load vs. Normalized Center Deflection

