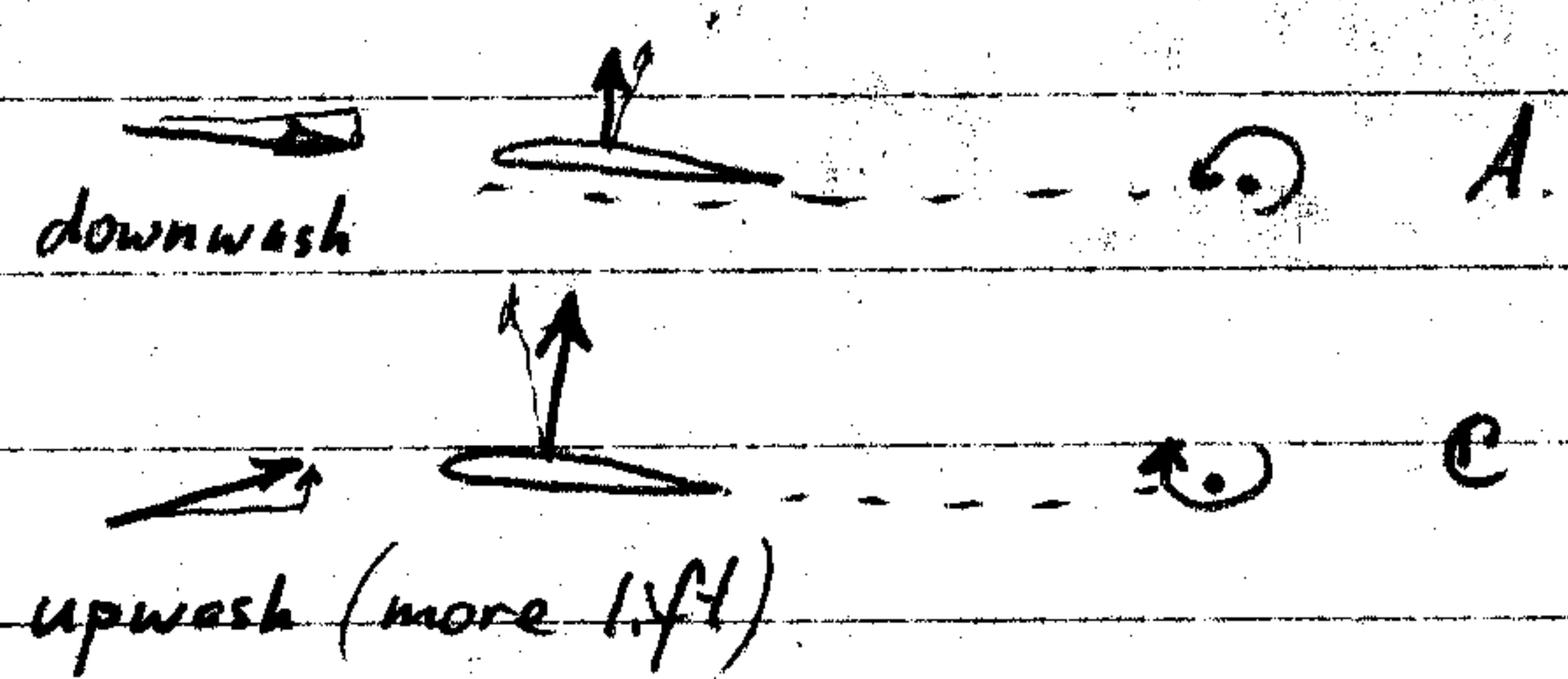
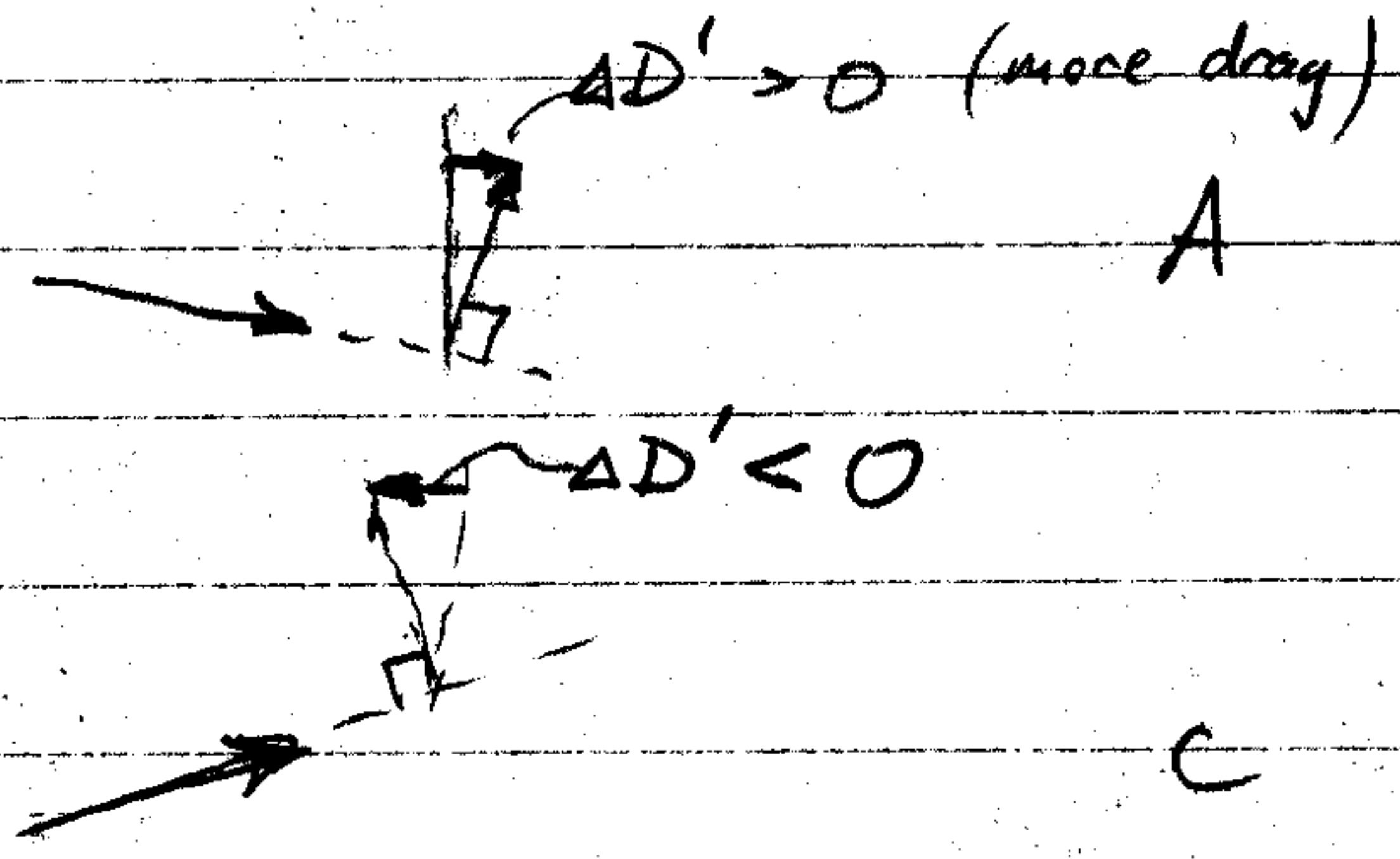


1.

ii) $L'_A < L'_B < L'_C$



iii) $D'_A > D'_B > D'_C$



$$\frac{x}{c} = \frac{1}{2}(1 - \cos\theta)$$

$$1 - 2\frac{x}{c} = \cos\theta$$

$$2. \quad \frac{dz_A}{dx} = 4\frac{h}{c}(1 - 2\frac{x}{c})$$
$$= 4\frac{h}{c}\cos\theta$$

$$\frac{dz_B}{dx} = -2\frac{h}{c}\frac{x}{c}$$
$$= \frac{h}{c}(\cos\theta - 1)$$

$$A_0 = \frac{1}{\pi} \int_0^\pi \left(x - \frac{dz_A}{dx} \right) d\theta$$

$$A_0 = \frac{1}{\pi} \int_0^\pi \left(x - \frac{dz_B}{dx} \right) d\theta$$

$$A_0 = \frac{1}{\pi} \int_0^\pi -4\frac{h}{c}\cos\theta d\theta = 0$$

$$A_0 = \frac{1}{\pi} \int_0^\pi \frac{h}{c}(1 - \cos\theta) d\theta = \frac{h}{c}$$

$$A_1 = \frac{2}{\pi} \int_0^\pi \frac{dz_A}{dx} \cos\theta d\theta$$

$$A_1 = \frac{2}{\pi} \int_0^\pi \frac{dz_B}{dx} \cos\theta d\theta$$

$$A_1 = \frac{2}{\pi} \int_0^\pi 4\frac{h}{c}\cos^2\theta d\theta = 4\frac{h}{c}$$

$$A_1 = \frac{2}{\pi} \int_0^\pi \frac{h}{c}(\cos^2\theta - \cos\theta) d\theta = \frac{h}{c}$$

$$A_2 = 0$$

$$A_2 = 0$$

$$A_3 = 0$$

$$A_3 = 0$$

$$a) \quad C_L = \pi(2A_0 + A_1) = 4\pi\frac{h}{c}$$

$$C_L = \pi(2A_0 + A_1) = 3\pi\frac{h}{c}$$

$$\frac{dC_L}{d(h/c)} = 4\pi$$

$$\frac{dC_L}{d(h/c)} = 3\pi$$

$$b) \quad C_{m,c/4} = \frac{\pi}{4}(A_2 - A_1) = -\pi\frac{h}{c}$$

$$C_{m,c/4} = \frac{\pi}{4}(A_2 - A_1) = -\frac{\pi}{4}\frac{h}{c}$$

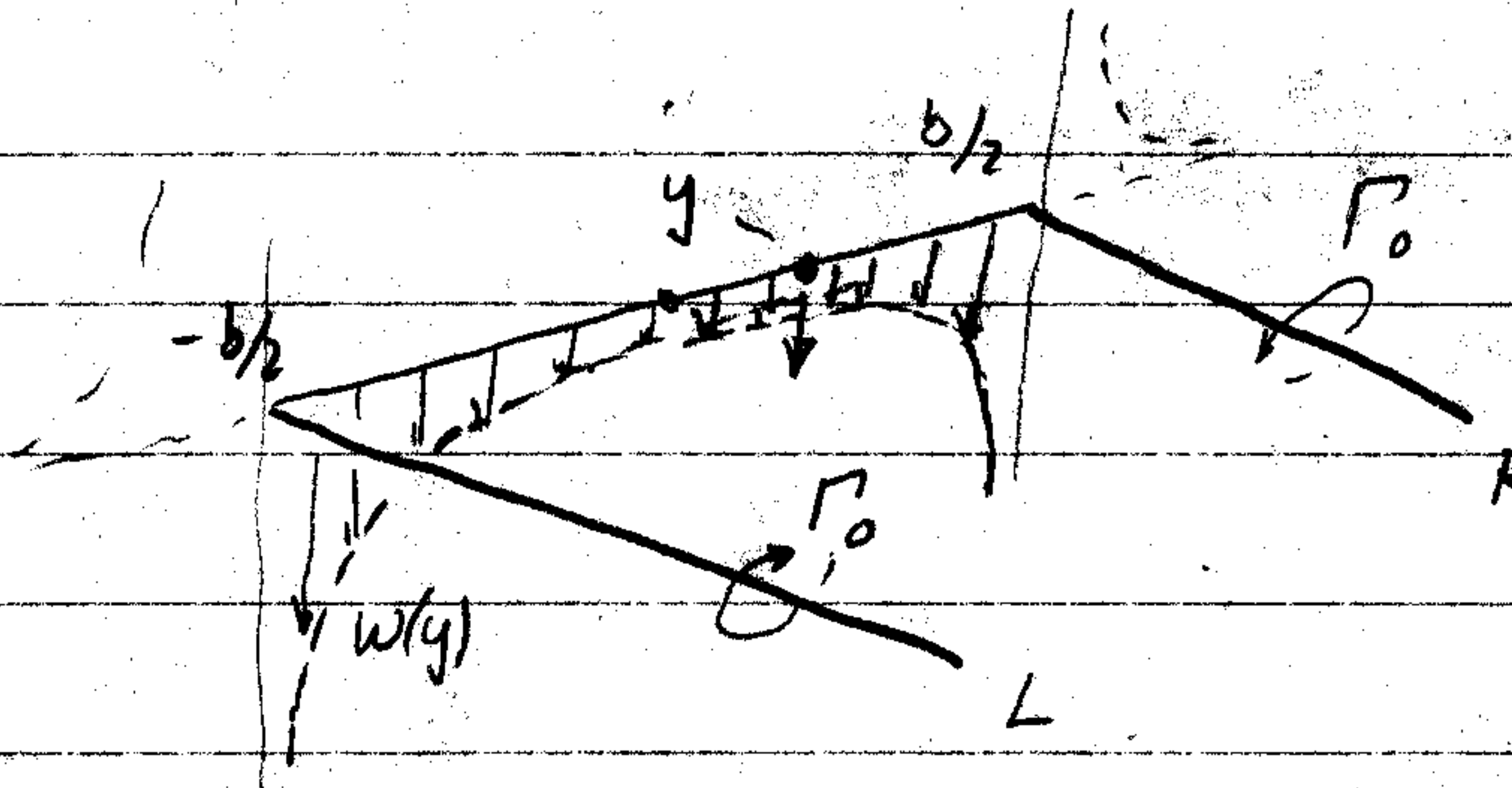
$$\frac{dC_{m,c/4}}{d(h/c)} = -\pi$$

$$\frac{dC_{m,c/4}}{d(h/c)} = -\frac{\pi}{4}$$

A. has $\frac{4}{3} \times$ larger control power, but $4 \times$ larger torque.

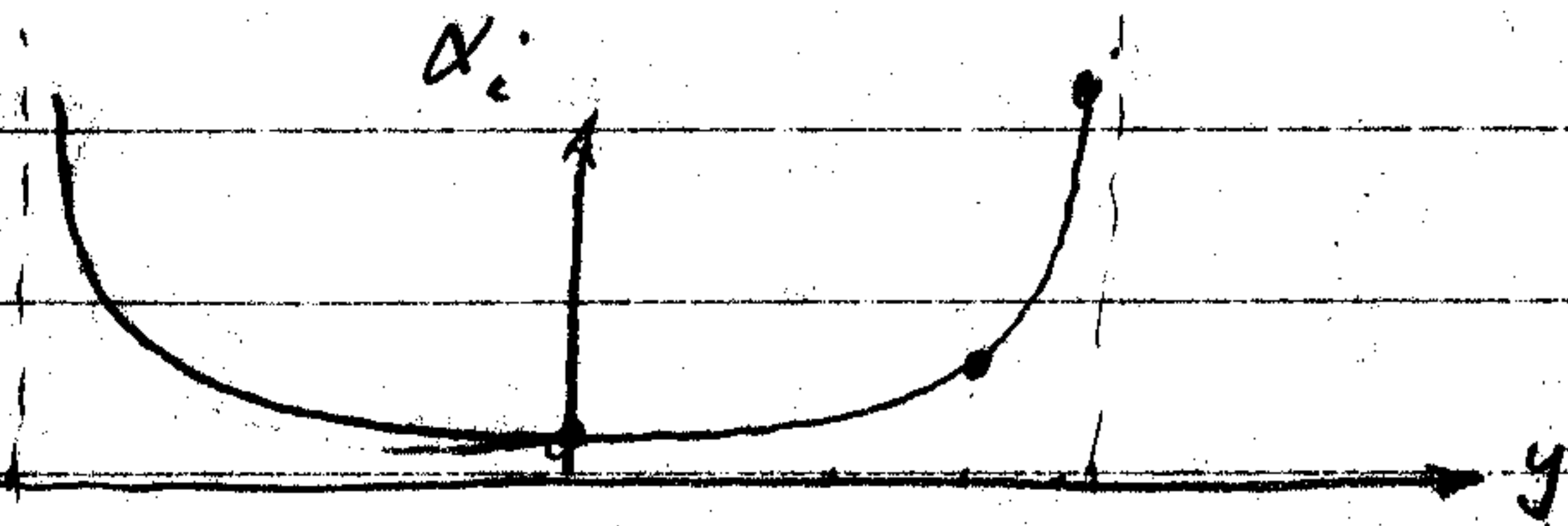
3.

a) $w(y)$ is from trailing legs of the horseshoe vortex



$$w(y) = \frac{-\Gamma_0}{4\pi} \frac{1}{b/2-y} - \frac{\Gamma_0}{4\pi} \frac{1}{b/2+y}$$

$$w(y) = \frac{-\Gamma_0}{4\pi} \left[\frac{1}{b/2-y} + \frac{1}{b/2+y} \right]$$



y	w
0	$-\frac{0.5}{4\pi} [1+1] = -\frac{1}{4\pi} = -0.08$
0.75	$-\frac{0.5}{4\pi} \left[\frac{1}{0.25} + \frac{1}{1.75} \right] = -\frac{2.3}{4\pi} = -0.18$
0.95	$-\frac{0.5}{4\pi} \left[\frac{1}{0.05} + \frac{1}{1.95} \right] = -\frac{10.2}{4\pi} = -0.82$

$$\alpha_i(y) = -w(y)/V_\infty \quad \alpha_i(0) = 0.9^\circ$$

$$\alpha_i(0.75) = 2.1^\circ$$

$$\alpha_i(0.95) = 9.3^\circ$$

b) $\Gamma = \frac{1}{2} V_\infty C C_L$, $\Gamma = \Gamma_0 = 0.5 \text{ m/s}$, $C = C_0 = 0.2 \text{ m}$

$$\rightarrow C_L = \frac{2\Gamma}{V_\infty C} = \frac{2 \cdot 0.5}{5 \cdot 0.2} = 1.0 \quad \text{constant } C_L$$

$$C_L = 2\pi \left[\cancel{\alpha} + \alpha_{\text{geom}} - \cancel{\alpha_{\text{tip}}} - \alpha_i \right]$$

$$\alpha_{\text{geom}}(y) = \frac{C_L}{2\pi} + \alpha_i = \frac{1}{2\pi} + \frac{\Gamma_0}{4\pi V_\infty} \left[\frac{1}{b/2-y} + \frac{1}{b/2+y} \right], \quad \frac{\Gamma_0}{2V_\infty} = 0.05 \text{ m}$$

$$\rightarrow \alpha_{\text{geom}}(y) = \frac{1}{2\pi} \left\{ 1 + 0.05 \left[\frac{1}{1-y} + \frac{1}{1+y} \right] \right\} \quad \text{radians}$$

c) $\alpha_{\text{geom}}(y)$ gets very large (infinite!) as we approach each tip at $y = \pm b/2$. Wing requires lots of washin.

