

A causal, LTI system,  $G$ , has impulse response  $g(t)$ . The Laplace transform of  $g(t)$  is

$$G(s) = \frac{4}{s(s+2)^2}$$

1. What is the region of convergence of the Laplace transform? Explain.
2. Find  $g(t)$ .
3. Is the system BIBO stable or unstable?

1. Since  $G$  is causal, the R.O.C. is to the right of the rightmost pole, which is at  $s=0$ . Therefore, the R.O.C. is

$$\text{Re}[s] > 0$$

2. Expand  $G(s)$  by partial fraction expansion, using the coverup method:

$$G(s) = \frac{4}{s(s+2)^2} = \frac{1}{s} + \frac{a}{s+2} + \frac{-2}{(s+2)^2}$$

Note that  $a$  cannot be determined directly, since the pole at  $s=-2$  is 2nd order. Having found the other terms, solve:

## Problem 1

ID number (last four digits) SOLUTION

$$\begin{aligned}\frac{a}{s+2} &= \frac{4}{s(s+2)^2} - \frac{1}{s} + \frac{2}{(s+2)^2} \\ &= \frac{4 - (s+2)^2 + 2s}{s(s+2)^2} \\ &= \frac{-s^2 - 2s}{s(s+2)^2} = \frac{-1}{s+2}\end{aligned}$$

Therefore,

$$g(t) = \left( 1 - e^{-2t} - 2t e^{-2t} \right) \mathcal{U}(t)$$

3. Unstable, since the R.O.C. does not include  $\text{Re}[s] = 0$ .

Problem 2 (10%)

ID number (last four digits) SOLUTION

A causal, LTI system,  $G$ , has impulse response  $g(t)$  given by

$$g(t) = \frac{1}{1+t} \sigma(t)$$

Is the system BIBO stable? Explain.

$G$  is BIBO stable if and only if

$$M = \int_0^{\infty} |g(t)| dt < \infty$$

But

$$M = \int_0^{\infty} \frac{1}{1+t} dt = \ln(1+t) \Big|_0^{\infty} = \infty$$

So  $G$  is unstable.

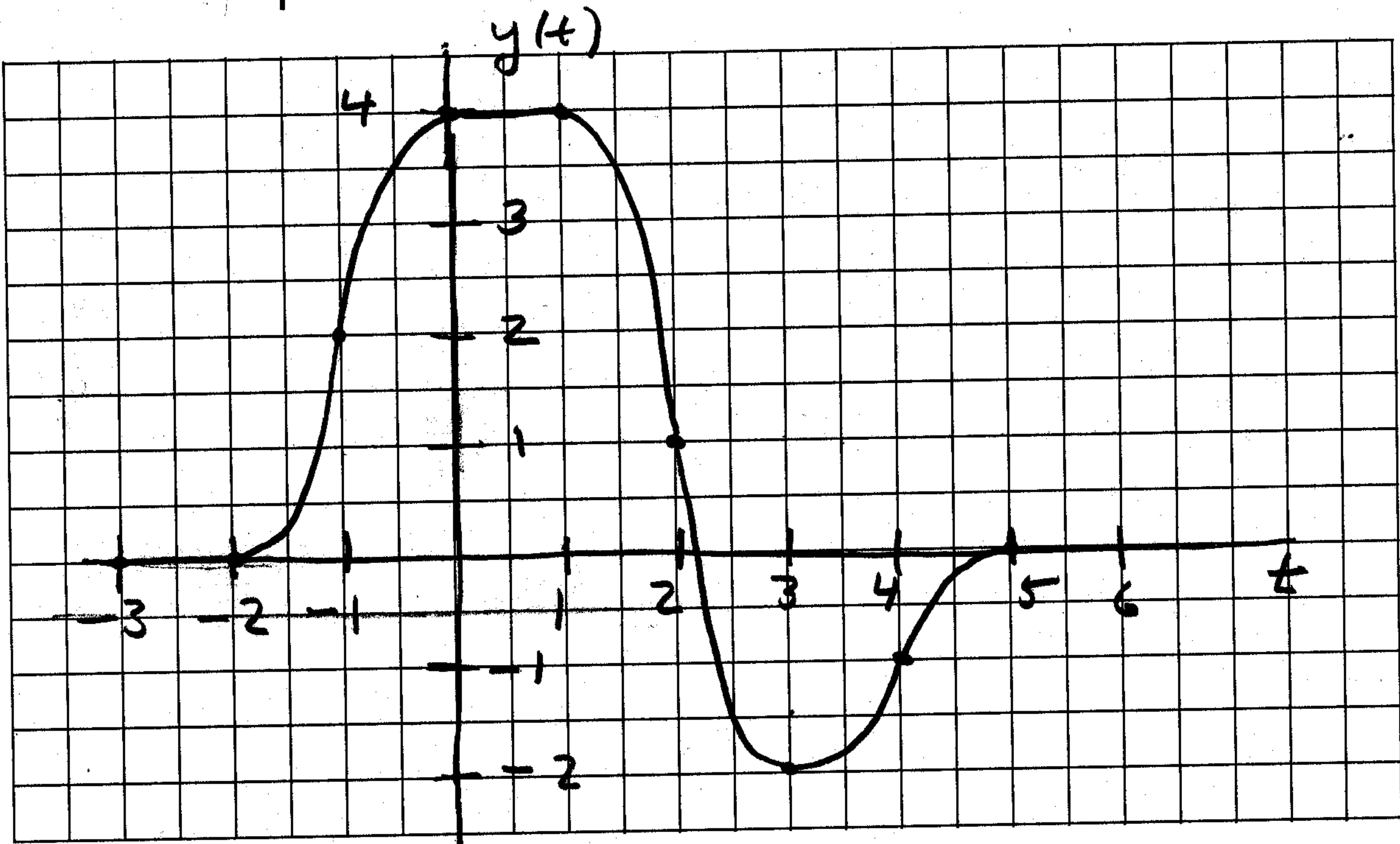
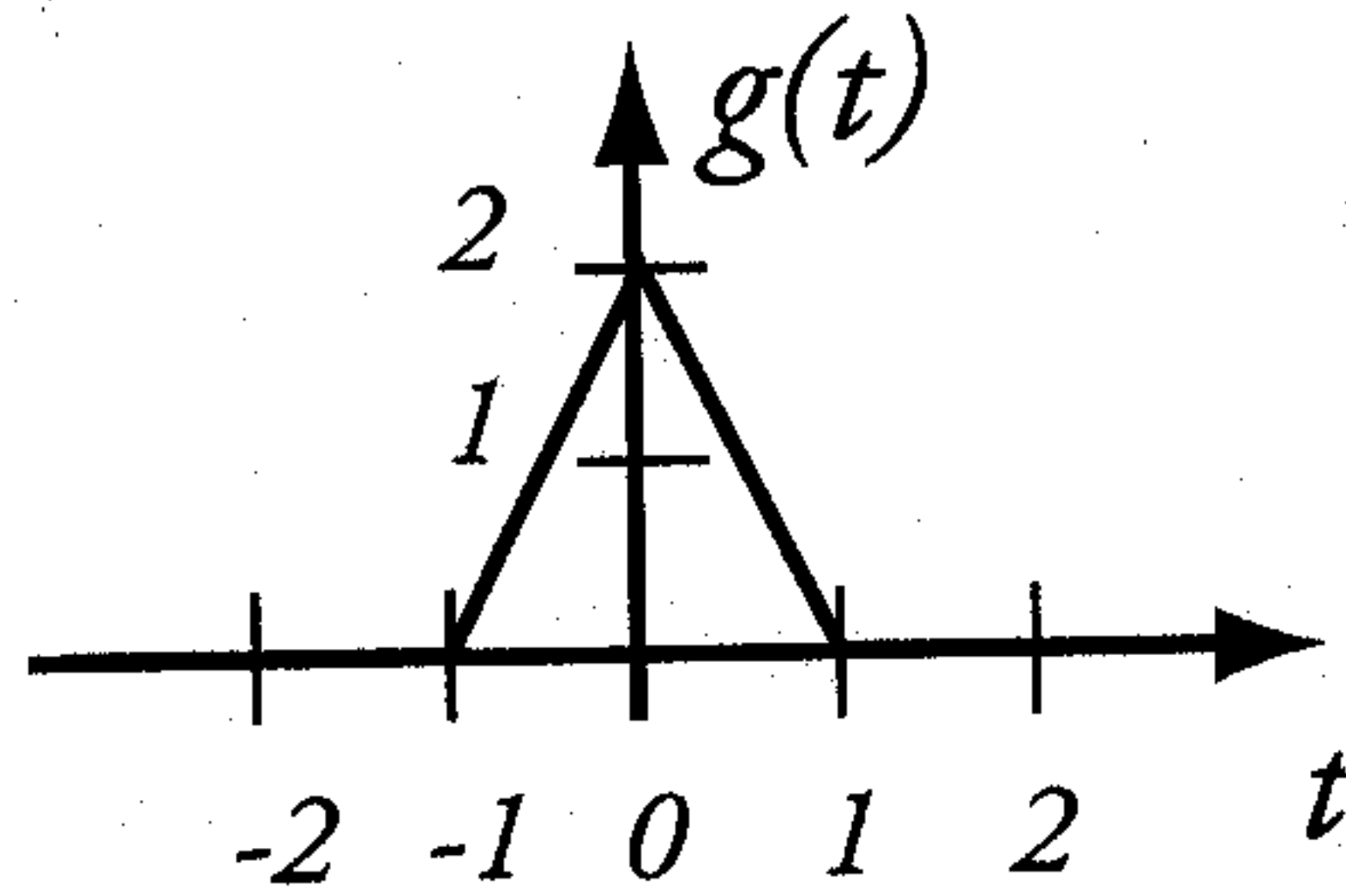
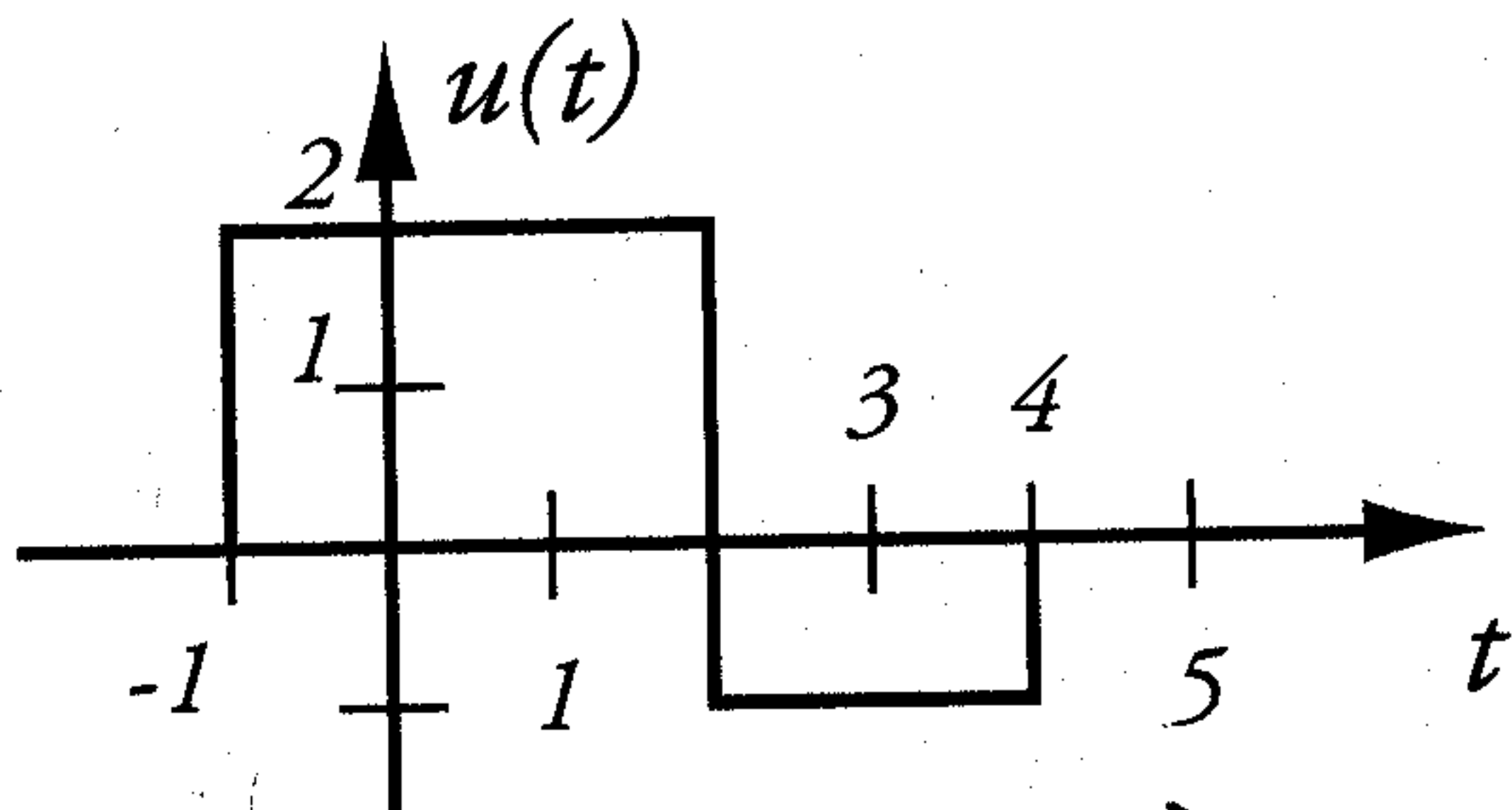
Problem 3

ID number (last four digits) SOLUTION

Given the signals  $g(t)$  and  $u(t)$  as plotted below, find the signal  $y(t)$  given by

$$y(t) = g(t) * u(t)$$

Sketch the result in the grid below, as accurately as possible. Explain your reasoning on the page that follows. The grid squares *do not* have to represent 1 unit — you can choose the units as appropriate to plot the result. Be sure to label the axes of the grid.

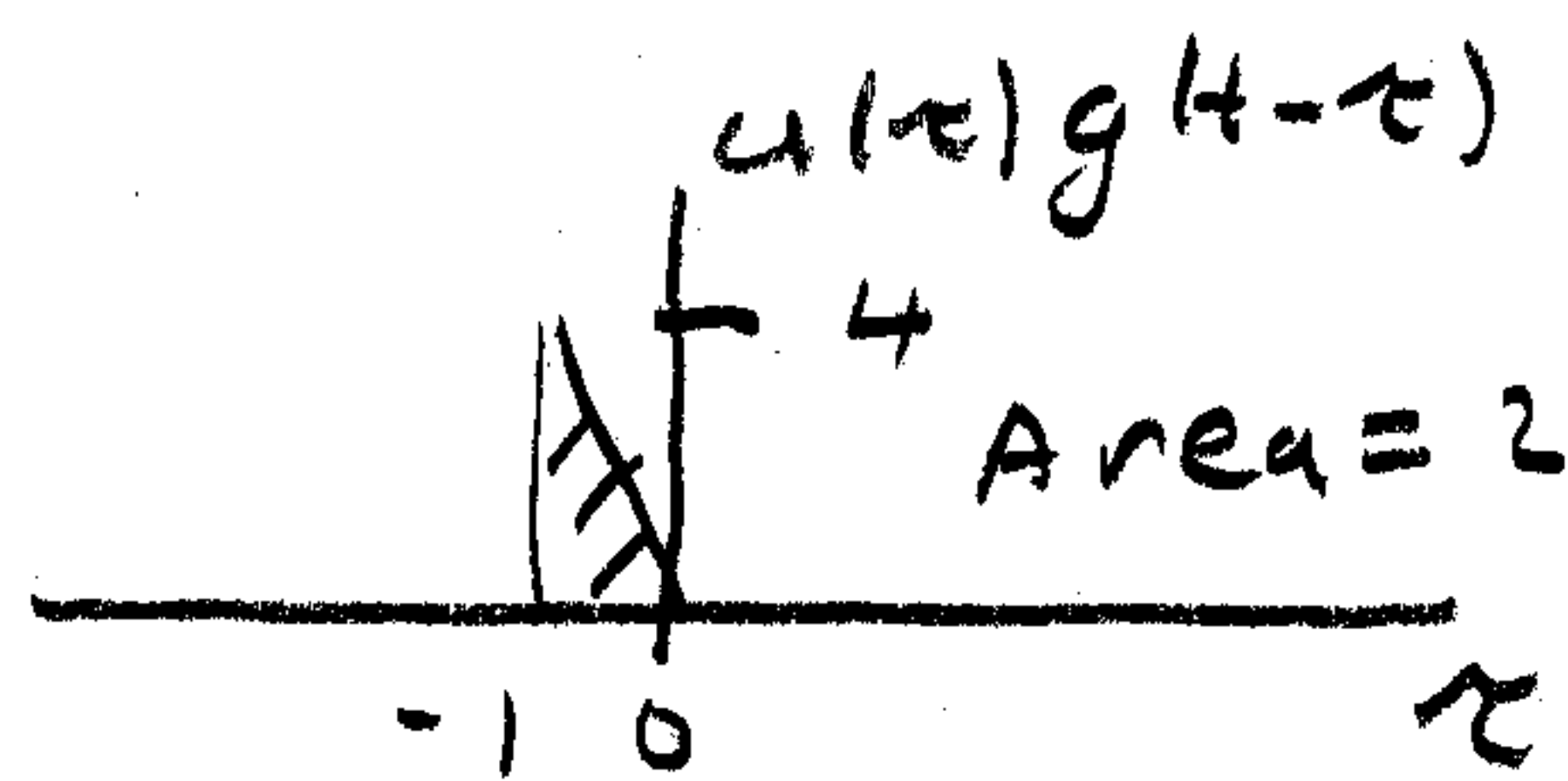
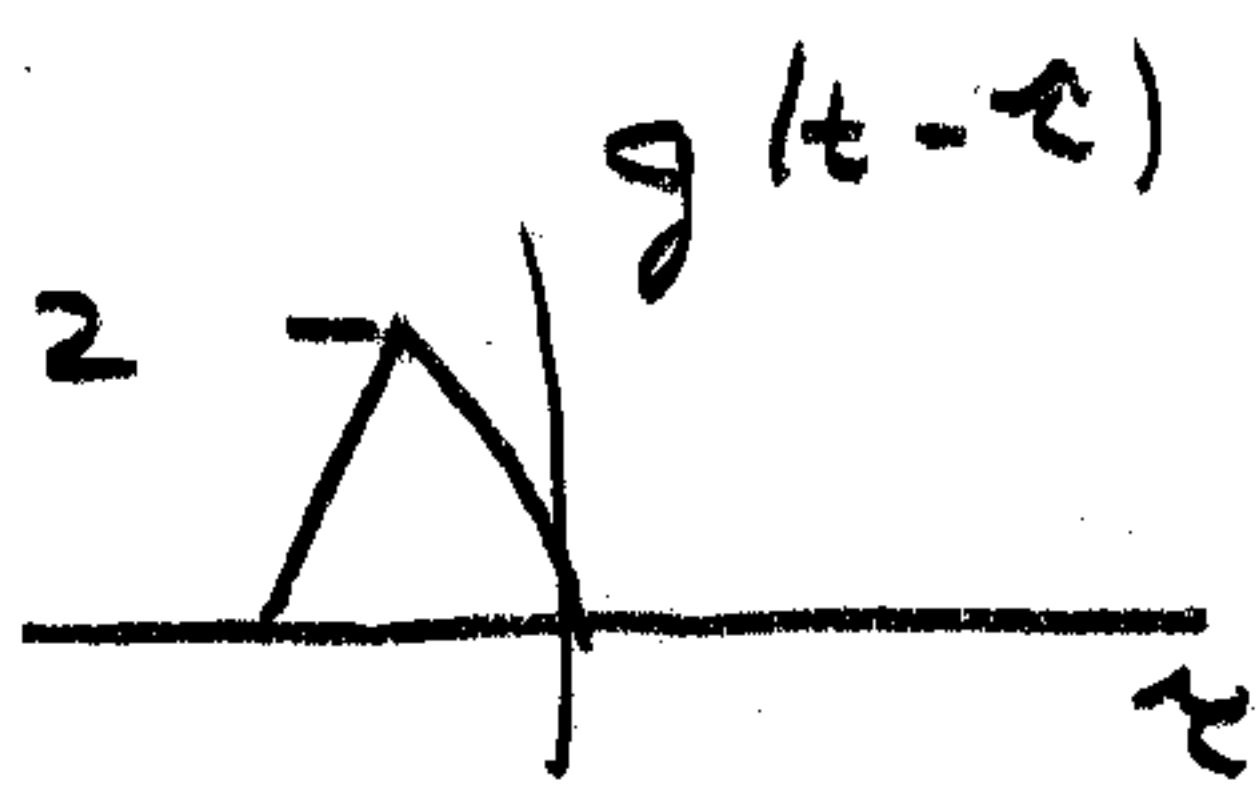
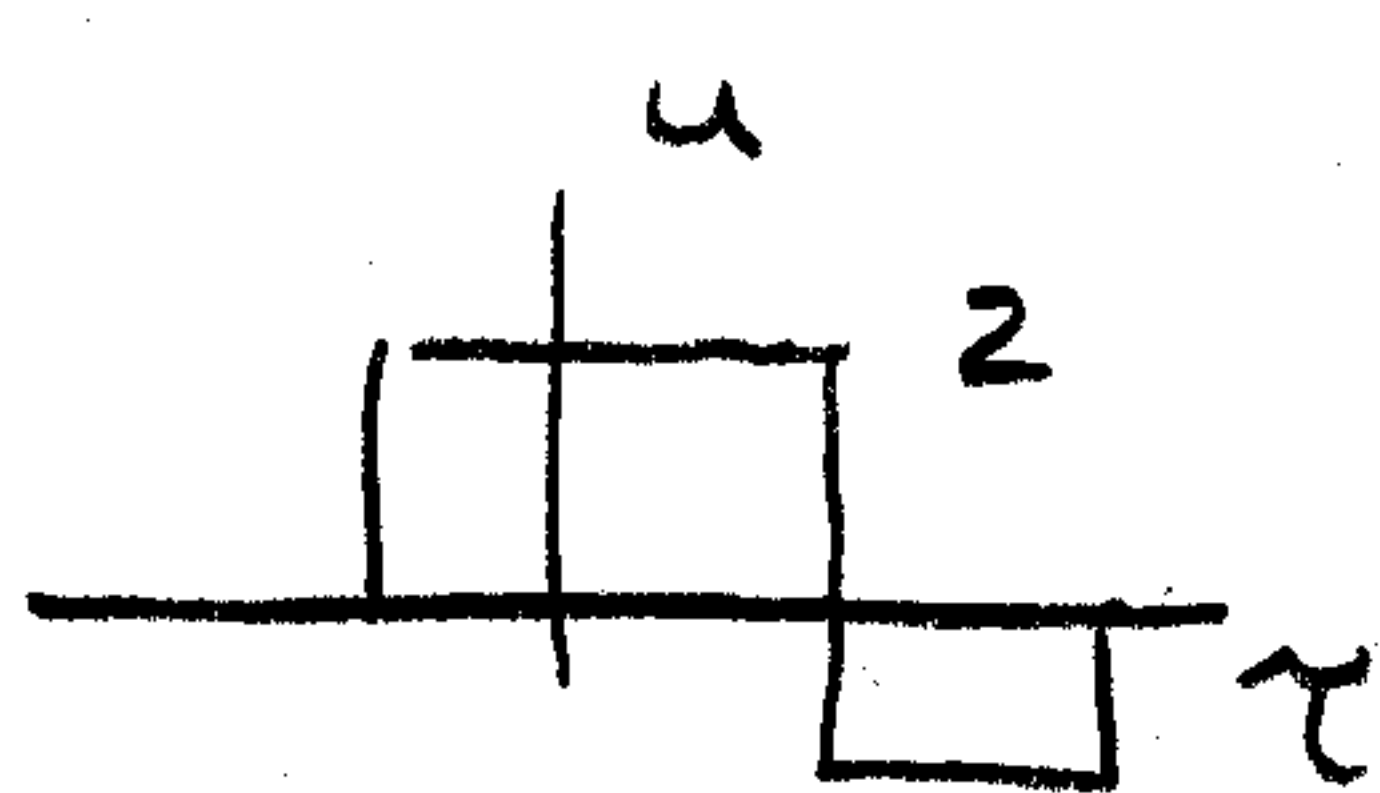


Use graphical convolution. Note that this problem is a little like the smoothing problem —  $g(t)$  looks a little like the smoother from class, but has area 2.

Also, because  $u$  has step discontinuities only, and  $g$  is continuous,  $y(t)$  will be continuous and have continuous slope. In fact, because  $u$  is piecewise constant, and  $g$  is piecewise linear,  $y$  will be piecewise quadratic, i.e., little segments of parabolas.

$t \leq -2$ : For  $t \leq -2$ ,  $g(t-\tau)$  and  $u(\tau)$  don't overlap, so  $y(t) = 0$ .

$t = -1$ :



$$\Rightarrow y(-1) = 2$$

This process can be continued for each  $t$ .

I got the following table:

$t$	$y(t)$
-2	0
-1	2
0	4
1	4
2	1
3	-2
4	-1
5	0

which, together with remarks above, gives  $y(t)$  plotted on 1st page.

Consider an LTI system  $G$  with input signal  $u(t)$  and output signal  $y(t)$ .

1. What is the definition of the transfer function,  $G(s)$ ?
2. Explain why the transfer function is the Laplace transform of the impulse response.

1. For an LTI system, an exponential input  $u(t) = e^{st}$  should produce an exponential output,  $y(t) = G(s) e^{st}$ .

The amplitude of the output,  $G(s)$ , is the transfer function.

2. For an arbitrary input,  $u(t)$ , the response is

$$y(t) = g(t) * u(t) = u(t) * g(t)$$

For the exponential input,

$$y(t) = e^{st} * g(t)$$

$$= \int_{-\infty}^{\infty} e^{s(t-\tau)} g(\tau) d\tau$$

$$= e^{st} \int_{-\infty}^{\infty} e^{-s\tau} g(\tau) d\tau$$

$$\equiv \mathcal{L}[g(t)]$$

So the output is

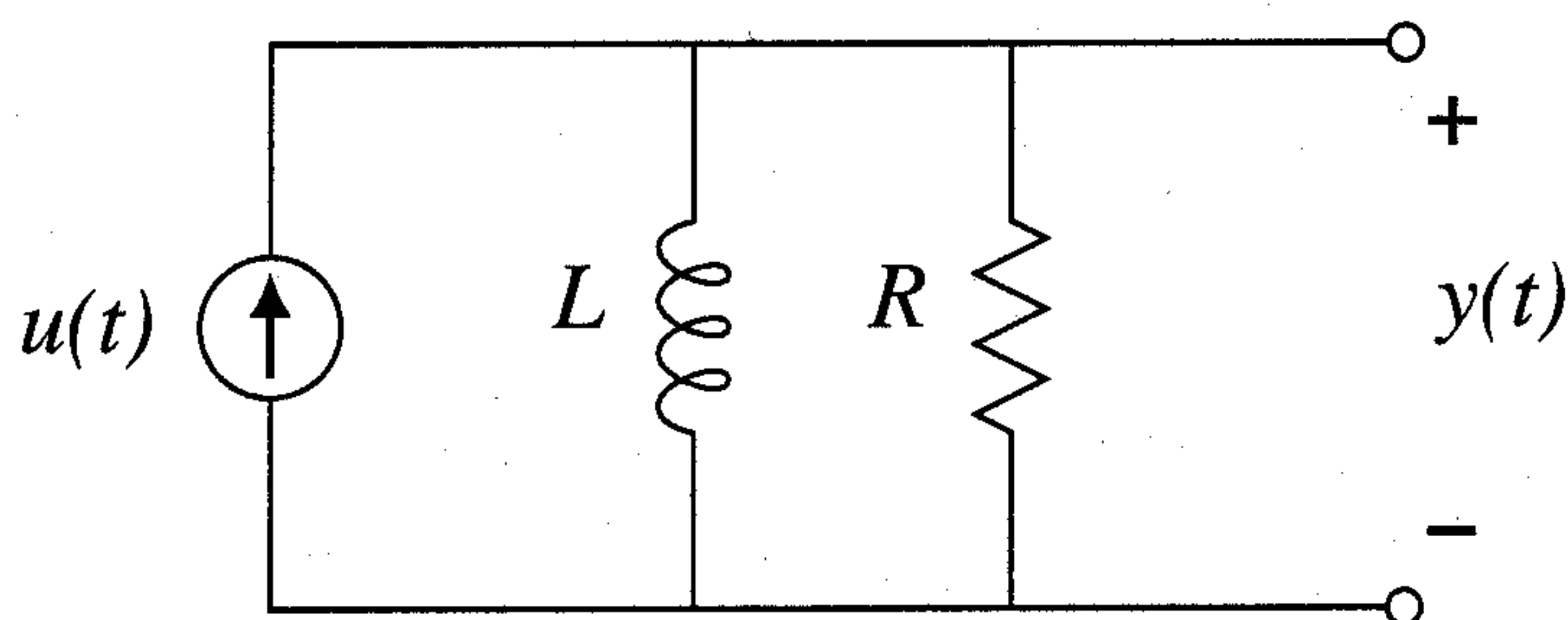
$$y(t) = \mathcal{L}[g(t)] e^{st}$$

Comparing this result and the definition, we must have that the transfer function is

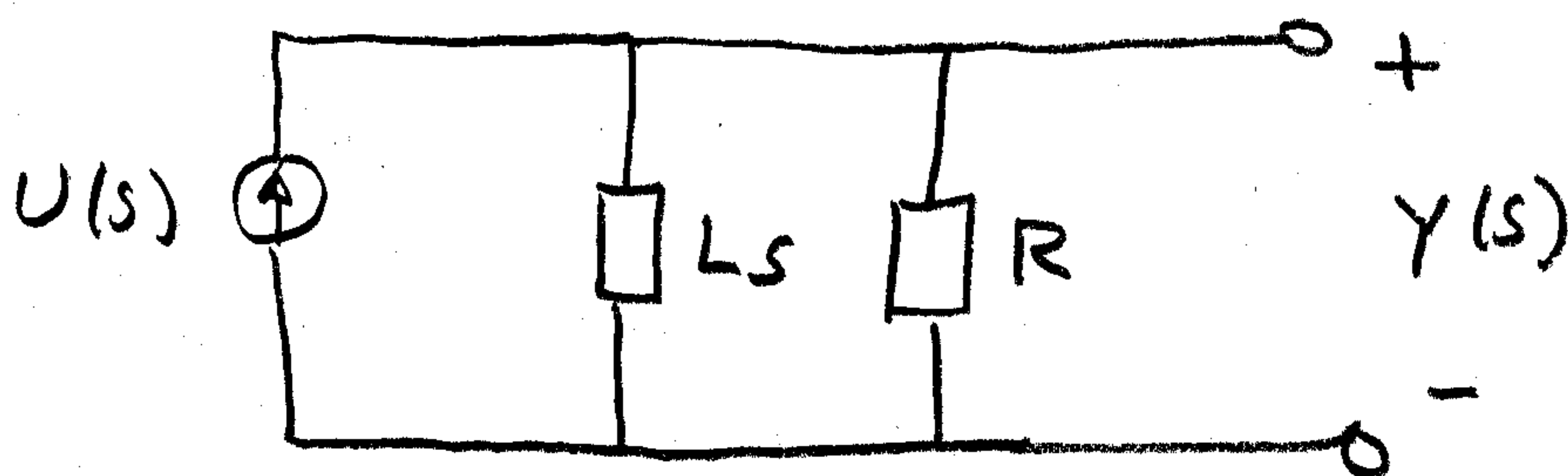
$$G(s) = \mathcal{L}[g(t)]$$



Find the step response of the circuit below. The component values are  $R = 4\Omega$ ,  $L = 2\text{ H}$ .



Using impedance methods, we can reduce the circuit to



which we then treat as a static circuit. The inductor and resistor are in parallel, with equivalent impedance

$$Ls \parallel R = \frac{LsR}{Ls + R} = \frac{8s}{2s + 4} = \frac{4s}{s + 2}$$

For this simple circuit, all the current  $U(s)$  goes through this single impedance, so

$$Y(s) = \frac{4s}{s+2} U(s)$$

(This is just  $v = iR$ ). For a step input,

$$U(s) = \frac{1}{s}, \quad \text{Re}(s) > 0. \quad \text{Also, the circuit}$$

is causal, so the transfer function is valid for  $\text{Re}(s) > -2$ . Therefore,

$$Y(s) = \frac{4s}{s+2} \cdot \frac{1}{s} = \frac{4}{s+2}, \quad \text{Re}(s) > -2$$

(Note cancellation of factor  $s$ ) Therefore,

$$y(t) = g_s(t) = 4e^{-2t} \sigma(t)$$