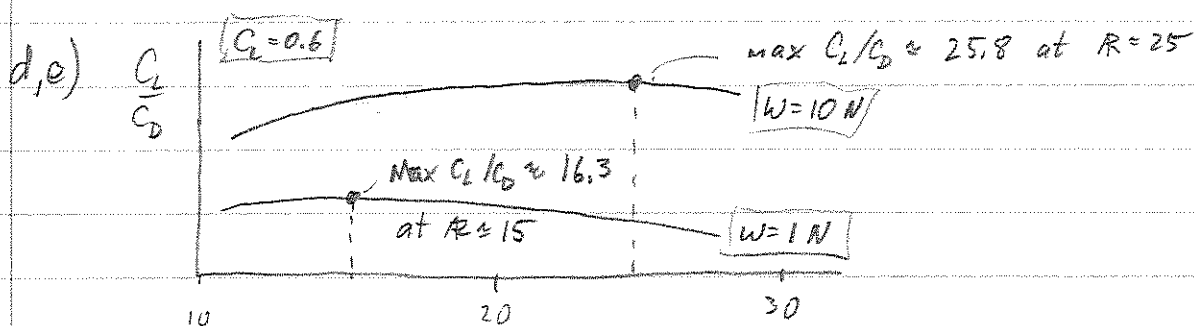


a) $b \cdot c_{avg} = S$, $b = \frac{S}{c_{avg}}$, $R = \frac{b^2}{S} = \frac{(S/c_{avg})^2}{S} \rightarrow \boxed{c_{avg} = \sqrt{S/R}}$

b) $W = L = \frac{1}{2} \rho v^2 S C_L \rightarrow v = \sqrt{\frac{2W}{S \rho C_L}}$, $\boxed{Re = \frac{v c_{avg}}{\nu} = \sqrt{\frac{2W}{S \rho C_L}} \cdot \sqrt{\frac{S}{R}} \frac{1}{\nu} = \frac{1}{\nu} \sqrt{\frac{2W}{\rho C_L R}}}$

c) $C_D = C_d + C_{Di} = 5.0 \left[\frac{1}{\nu} \left(\frac{2W}{\rho C_L R} \right)^{1/2} \right]^{-1/2} + \frac{C_L^2}{\pi R}$

$\boxed{C_D(C_L, R) = 5.0 \nu^{1/2} \left[\frac{\rho C_L R}{2W} \right]^{1/4} + \frac{C_L^2}{\pi R}}$



d) The statement "performance improves with larger R " addresses only C_{Di} and assumes that C_d is constant. In reality, a larger R implies a smaller c_{avg} and a smaller Re for a given S :



The smaller Re increases C_d , which eventually overcomes the decreasing C_{Di} . This is basically a Re effect.

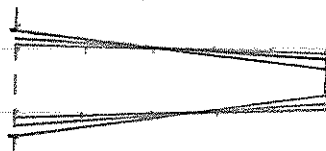
f) The heavier Albatross will have a larger optimum R because of the Re effect. Survival & evolution favors maximum efficiency for minimum energy consumption in flight. So each bird is likely to be closest to its optimum, hence $R_{Albatross} > R_{Tern}$

DE Fluids Problem 8 Solution

5'07

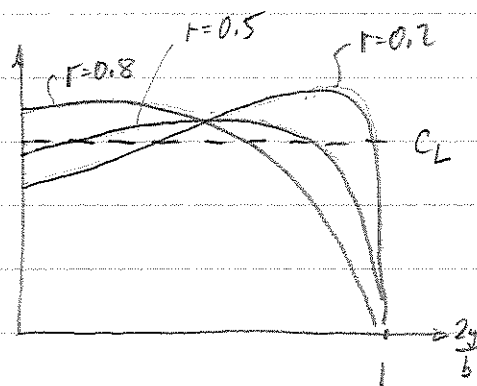
a) Linear interpolation between C_r and C_z :

$$C(y) = C_r + (C_z - C_r) \left| \frac{2y}{b} \right| = C_{avg} \cdot \frac{2}{1+r} \left[1 + (r-1) \left| \frac{2y}{b} \right| \right]$$



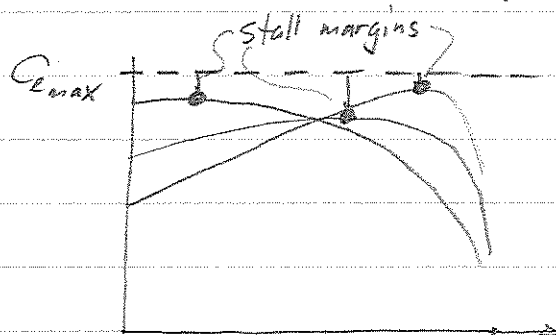
$$b) \Gamma(y) = \frac{1}{2} c V_{\infty} c_z, \quad c_z(y) = \frac{2\Gamma(y)}{c(y)V_{\infty}} = \frac{\Gamma_0}{C_{avg}V_{\infty}} (1+r) \frac{\sqrt{1 - (2y/b)^2}}{1 + (r-1) \left| \frac{2y}{b} \right|}$$

$$L = \frac{\pi}{4} \rho V_{\infty} \Gamma_0 b, \quad C_L = \frac{L}{\frac{1}{2} \rho V_{\infty}^2 b c_{avg}} = \frac{\pi}{2} \frac{\Gamma_0}{C_{avg} V_{\infty}}$$



c) Local stall will occur first at the peak $c_z(y)$ location.

Because the $r=0.5$ wing has the lowest C_z value at its peak, it will have the greatest stall margin.



UE Fluids Problem F9 Solution

S'07

a) $\frac{z}{b} = \cos \theta \rightarrow \Gamma = [0.05 - 0.02 \cos \theta] \sqrt{1 - \cos^2 \theta}$
 $= 0.05 \sin \theta - 0.02 \cos \theta \sin \theta$
 $\Gamma(\theta) = 0.05 \sin \theta - 0.01 \sin 2\theta$

b) $\Gamma = 2bV_\infty \sum A_n \sin n\theta$ ← same (*)

Could also use Fourier Analysis

Evaluate $\int_0^\pi (\psi) \sin \theta d\theta$

$\int_0^\pi (\psi) \sin 2\theta d\theta$

⋮

By inspection, we must have $2bV_\infty A_1 = 0.05$
 $2bV_\infty A_2 = -0.01$

Setting $V_\infty = 1, b = 2$.

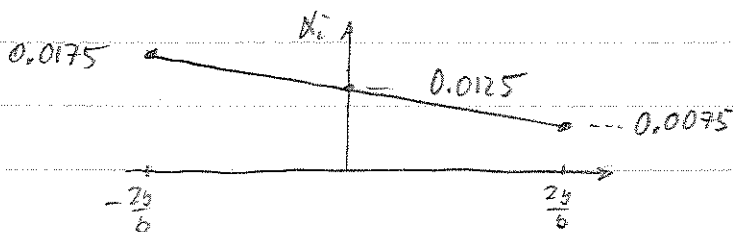
$A_1 = 0.0125, A_2 = -0.0025$

c) $L = \frac{\pi}{4} \rho V_\infty b A_1 = \frac{\pi}{4} \cdot 1 \cdot 1 \cdot 2 \cdot 0.0125 = 0.01963$
 $D_i = \pi b^2 \frac{1}{2} \rho V_\infty^2 [A_1^2 + 2A_2^2] = \pi \cdot 4 \cdot \frac{1}{2} \cdot [0.0125^2 + 2 \cdot 0.0025^2] = 0.00106$
 $e = [1 + 2(A_2/A_1)^2]^{-1} = [1 + 2 \cdot (0.0025/0.0125)^2]^{-1} = 0.9259$

d) $M_{roll} = \int_{-b/2}^{b/2} \rho V_\infty \Gamma y dy = \int_0^\pi \rho V_\infty \cdot 2bV_\infty [A_1 \sin \theta + A_2 \sin 2\theta] \left(\frac{b}{2} \cos \theta\right) \left(\frac{b}{2} \sin \theta d\theta\right)$
 $M_{roll} = \frac{1}{2} \rho V_\infty^2 b^3 \int_0^\pi [A_1 \sin \theta + A_2 \sin 2\theta] \frac{1}{2} \sin 2\theta d\theta$

$M_{roll} = \frac{1}{2} \rho V_\infty^2 b^3 \left[A_1 \cdot 0 + A_2 \frac{1}{2} \cdot \frac{\pi}{2} \right] = \frac{1}{2} \rho V_\infty^2 b^3 \cdot A_2 \cdot \frac{\pi}{4} = -0.00785$

e) $\alpha_i = A_1 \frac{\sin \theta}{\sin \theta} + A_2 \frac{\sin 2\theta}{\sin \theta} = A_1 + A_2 2 \cos \theta = A_1 + A_2 2 \left(\frac{z}{b}\right) = 0.0125 - 0.005 \left(\frac{z}{b}\right)$



Problem S2 (Signals and Systems) SOLUTION

A system has step response given by

$$g_s(t) = \begin{cases} 0, & t < 0 \\ 1 - e^{-t}, & t \geq 0 \end{cases}$$

Find and plot the response of the system to the input

$$u(t) = \begin{cases} 0, & t < 0 \\ 1 - e^{-2t}, & t \geq 0 \end{cases}$$

using Duhamel's integral.

Solution: Duhamel's integral is

$$y(t) = u(0)g_s(t) + \int_0^\infty g_s(t - \tau)u'(\tau) d\tau$$

For $\tau \geq 0$, we can write

$$u'(\tau) = 2e^{-2\tau}$$

Also, note that $u(0) = 0$. Therefore, for $t \geq 0$,

$$\begin{aligned} y(t) &= \int_0^t (1 - e^{-(t-\tau)}) 2e^{-2\tau} d\tau \\ &= 2 \int_0^t (e^{-2\tau} - e^{-t-\tau}) d\tau \\ &= 2 \int_0^t e^{-2\tau} d\tau - 2e^{-t} \int_0^t e^{-\tau} d\tau \end{aligned}$$

Note that the upper limit of the integral is t , since g_s is causal, and therefore $g_s(t-\tau) = 0$ for $\tau > t$. Evaluating the integrals, we have

$$\begin{aligned} y(t) &= (1 - e^{-2t}) - 2e^{-t}(1 - e^{-t}) \\ &= 1 - e^{-2t} - 2e^{-t} + 2e^{-2t} \\ &= 1 - 2e^{-t} + e^{-2t} \end{aligned}$$

For $t < 0$, $y(t) = 0$, since there is no overlap between $g_s(t - \tau)$ and $u(\tau)$. Therefore,

$$y(t) = (1 - 2e^{-t} + e^{-2t}) \sigma(t)$$

Problem S3 (Signals and Systems) SOLUTION

SOLUTION: The step response of the airfoil (to unit change in angle of attack) is

$$g_s(t) = 2\pi\psi(\bar{t})$$

where $\bar{t} = 2Ut/c$ is the dimensionless time, and $\psi(\bar{t})$ is the Küssner function. The Küssner function can be approximated as

$$\psi(\bar{t}) = \begin{cases} 0, & \bar{t} < 0 \\ 1 - \frac{1}{2}e^{-0.13\bar{t}} - \frac{1}{2}e^{-\bar{t}}, & \bar{t} \geq 0 \end{cases}$$

The problem statement gives the following conditions:

$$\begin{aligned} c &= 1 \text{ m} \\ U &= 1 \text{ m/s} \end{aligned}$$

Therefore, $\bar{t} = 2t$, and the step response is then

$$g_s(t) = 2\pi \left(1 - \frac{1}{2}e^{-0.26t} - \frac{1}{2}e^{-2t} \right) \sigma(t)$$

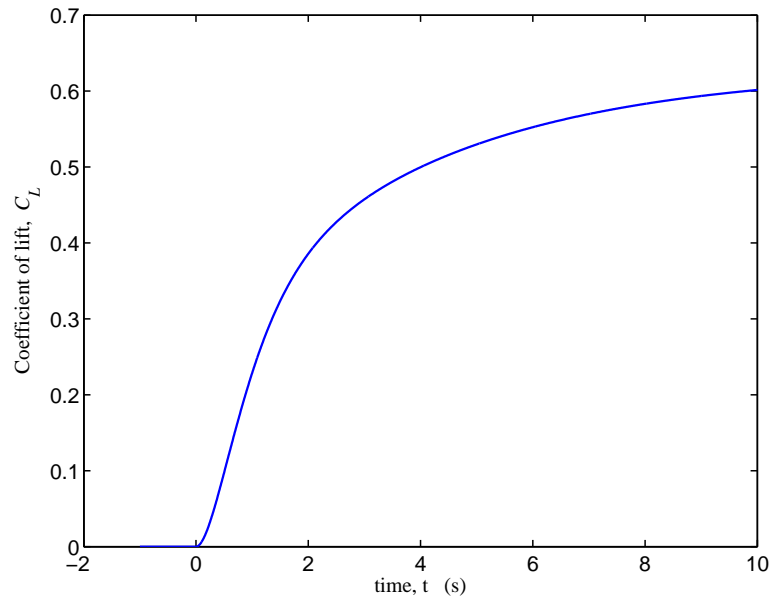
The angle of attack is

$$\begin{aligned} \alpha(t) &= w(t)/U \\ &= 0.1 \cdot (1 - e^{-2t}) \sigma(t) \\ &= u(t) \end{aligned}$$

The lift coefficient can then be found from Duhamel's integral. Since $u(0) = 0$, we have

$$\begin{aligned} y(t) = C_L(t) &= \int_0^t g_s(t - \tau)u'(\tau) d\tau \\ &= \int_0^t 2\pi \left(1 - \frac{1}{2}e^{-0.26(t-\tau)} - \frac{1}{2}e^{-2(t-\tau)} \right) 0.2e^{-2\tau} d\tau \\ &= 0.4\pi \int_0^t \left(e^{-2\tau} - \frac{1}{2}e^{-0.26t-1.74\tau} - \frac{1}{2}e^{-2t} \right) d\tau \\ &= 0.4\pi \left[\frac{1}{2}(1 - e^{-2t}) - \frac{1}{2 \cdot 1.74}e^{-0.26t}(1 - e^{-1.74t}) - \frac{1}{2}te^{-2t} \right] \\ &= \pi (0.2 - 0.08506e^{-2t} - 0.1149e^{-0.26t} - 0.2te^{-2t}) \\ &= 0.62832 - 0.26722e^{-2t} - 0.3611e^{-0.26t} - 0.62832te^{-2t} \end{aligned}$$

A plot of the response is shown below:



Problem S4 Solution (Signals and Systems)

1. Find the step response of the system

$$\frac{d^2}{dt^2}y(t) + 3\frac{d}{dt}y(t) + 2y(t) = u(t)$$

Solution. First, find the homogeneous solution, that is, the solution to

$$\frac{d^2}{dt^2}y(t) + 3\frac{d}{dt}y(t) + 2y(t) = 0$$

If we assume an exponential solution of the form $y(t) = e^{st}$, then the characteristic equation becomes

$$s^2 + 3s + 2 = 0$$

The roots are $s_1 = -1$, $s_2 = -2$. The general homogeneous solution is then

$$y_h(t) = c_1e^{-t} + c_2e^{-2t}$$

Next, we find the particular solution, for the input $u(t) = 1$, $t > 0$. Guess that the solution is a constant, $y(t) = c$. Plugging into the d.e. yields

$$2c = 1$$

and therefore $c = 1/2$. Therefore, the total solution is

$$y(t) = y_h(t) + y_p(t) = \frac{1}{2} + c_1e^{-t} + c_2e^{-2t}$$

The initial conditions are $y(0) = y'(0) = 0$. Solving for the constants, $c_1 = -1$, $c_2 = 1/2$. Therefore,

$$g_s(t) = \left(\frac{1}{2} - e^{-t} + \frac{1}{2}e^{-2t}\right)\sigma(t)$$

2. Take the derivative of the step response to find the impulse response.

Solution. Take the derivative using the chain rule for multiplication

$$\begin{aligned} g(t) &= \frac{d}{dt} \left[\left(\frac{1}{2} - e^{-t} + \frac{1}{2}e^{-2t}\right)\sigma(t) \right] \\ &= (e^{-t} - e^{-2t})\sigma(t) + \left(\frac{1}{2} - e^{-t} + \frac{1}{2}e^{-2t}\right)\delta(t) \end{aligned}$$

Since $\frac{1}{2} - e^{-t} + \frac{1}{2}e^{-2t} = 0$ at $t = 0$,

$$g(t) = (e^{-t} - e^{-2t})\sigma(t)$$

3. Now assume that the input is given by

$$u(t) = e^{-2t}\sigma(t)$$

Before doing part (4), try to find the particular solution by the usual method, that is, by intelligent guessing. Be careful — it may not be what you expect!

Solution. The obvious thing to do is to guess that

$$y_p(t) = ce^{-2t}$$

But we already know that e^{-2t} is a solution to the homogeneous equations. It can't be a particular solution! So instead, guess that

$$y_p(t) = ct e^{-2t}$$

Plugging into the differential equation gives

$$\begin{aligned} \frac{d^2}{dt^2} y_p(t) + 3 \frac{d}{dt} y_p(t) + 2y_p(t) &= -c e^{-2t} \\ &= u(t) = e^{-2t} \end{aligned}$$

Therefore, $c = -1$, and

$$y_p(t) = -t e^{-2t}$$

4. Now find $y(t)$ using the superposition integral. Is the particular solution what you expected?

Solution. Perform the convolution integral,

$$y(t) = \int_{-\infty}^{\infty} g(t - \tau) u(\tau) d\tau$$

The result is

$$\begin{aligned} y(t) &= \int_0^t \left(e^{-(t-\tau)} - e^{-2(t-\tau)} \right) e^{-2\tau} d\tau \\ &= (e^{-t} - e^{-2t} - t e^{-2t}) \sigma(t) \end{aligned}$$

Note that the correct particular solution is in the final result.