

a) First assume isentropic flow (unchoked, no shock).

$$P_0 = P_r = P_e \left[1 + \frac{\gamma-1}{2} M_e^2 \right]^{\frac{\gamma}{\gamma-1}}, \quad M_e = \left\{ \frac{2}{\gamma-1} \left[\left(\frac{P_r}{P_e} \right)^{\frac{\gamma-1}{\gamma}} - 1 \right] \right\}^{1/2}$$

Using $\frac{P_r}{P_e} = \frac{100000}{80000} = 1.25$, $M_e = 0.5737$

For this M_e , $A^* = A_e M_e \left[\frac{2}{\gamma+1} \left(1 + \frac{\gamma-1}{2} M_e^2 \right) \right]^{\frac{-\gamma+1}{2(\gamma-1)}} = 0.819 A_e$

Since this nozzle has $A_t = \frac{A_t}{A_e} \cdot A_e = \frac{0.010}{0.014} A_e = 0.7143 A_e$
then $A^* > A_t$, so flow is choked.

Try again, using $A^* = A_t = 0.010 \text{ m}^2$ instead.

$$\dot{m} = \rho^* a^* A^* = \frac{\gamma P_r}{(\gamma-1) h_r} \left(1 + \frac{\gamma-1}{2} \right)^{\frac{-\gamma+1}{2(\gamma-1)}} \cdot A^* = \boxed{2.339 \text{ kg/s}}$$

b) Again assume isentropic flow

$\frac{P_r}{P_e} = \frac{100000}{90000} = 1.111$, $M_e = 0.3909$

$$A^* = A_e M_e \left[\frac{2}{\gamma+1} \left(1 + \frac{\gamma-1}{2} M_e^2 \right) \right]^{\frac{-\gamma+1}{2(\gamma-1)}} = 0.617 A_e < A_t \quad \underline{\text{unchoked}}$$

Using this $A^* = 0.617 A_e = 0.00864$

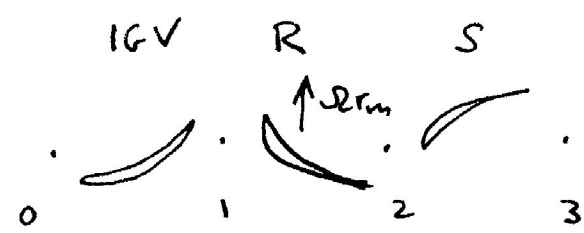
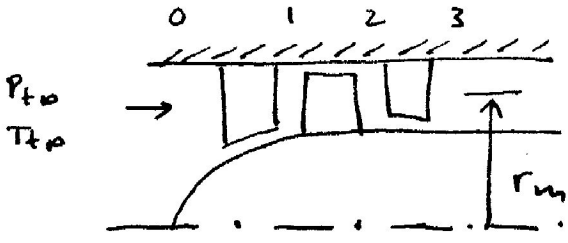
$$\dot{m} = \frac{\gamma P_r}{(\gamma-1) h_r} \left(1 + \frac{\gamma-1}{2} \right)^{\frac{-\gamma+1}{2(\gamma-1)}} A^* = \boxed{2.021 \text{ kg/s}}$$

c) For matched supersonic flow, no shocks, $(P_0)_e = P_r$

Also, M_e corresponds to $\frac{A_e}{A^*} = \frac{0.014}{0.010} = 1.4 \rightarrow M_e = 1.763$ (Appendix A)

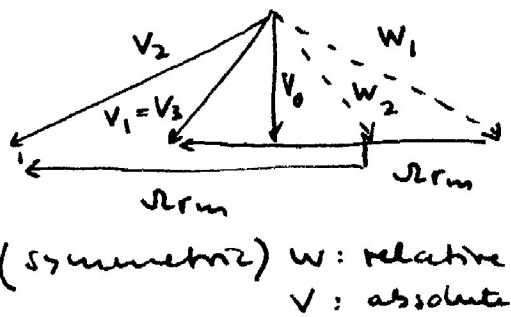
$$P_B = P_e = (P_{0e}) \left[1 + \frac{\gamma-1}{2} M_e^2 \right]^{\frac{-\gamma}{\gamma-1}} = \boxed{18415 \text{ Pa}}$$

T15

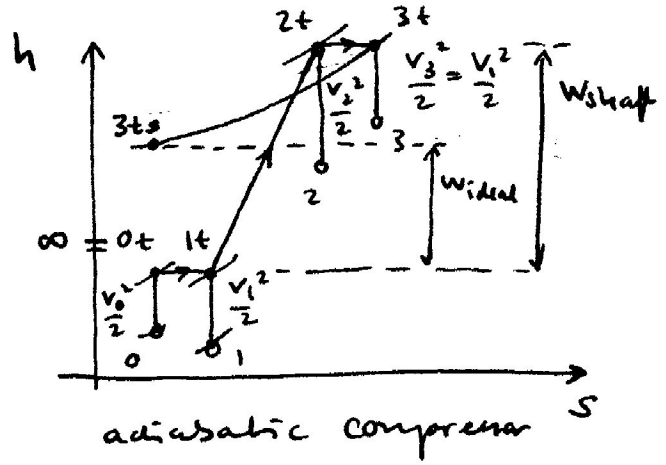


$R = r_H / r_T = 0.8$
 $\gamma_{ad} = 0.9$
 $P_{t0} = 1 \text{ bar}$ $T_{t0} = 293 \text{ K}$
 $c_p = 1604 \text{ J/kg K}$, $\gamma = 1.4$
 $v_x = 125 \text{ m/s}$ constant $r_m = 0.3 \text{ m}$
 abs.: $\alpha_0 = 0$ $\alpha_1 = 40^\circ$ $\alpha_2 = 60^\circ$ $\alpha_3 = 40^\circ$
 rel.: $\beta_1 = 60^\circ$ $\beta_2 = 40^\circ$

a)



b)



c) $V_0 = v_x$; $\Omega r_m = V_0 (\tan \alpha_1 + \tan \beta_1)$
 get $\Omega = 10,230 \text{ rpm}$

$\Omega = \frac{V_0}{r_m} (\tan \alpha_1 + \tan \beta_1)$

d) $\dot{m} = \int_0 A v_0$ $A = \pi (r_T^2 - r_H^2)$ $r_T = \frac{2r_m}{1+R} = 0.33 \text{ m}$, $r_H = r_T \cdot R = 0.27 \text{ m}$

$T_0 = T_{t0} - \frac{V_0^2}{2c_p} = 285 \text{ K}$ $M_0 = \frac{V_0}{\sqrt{\gamma R T_0}} = 0.37$ $P_0 = P_{t0} \left(1 + \frac{\gamma-1}{2} M_0^2\right)^{-\frac{\gamma}{\gamma-1}} = 0.91 \text{ bar}$ $\rho_0 = \frac{P_0}{R T_0} = 1.11 \frac{\text{kg}}{\text{m}^3}$

$\dot{m} = 15.7 \text{ kg/s}$

e) $h_{t3s} - h_{t0} = \Omega r_m (V_{02} - V_{01}) = \Omega r_m V_0 (\tan \alpha_2 - \tan \alpha_1) = 35.87 \text{ kJ/kg}$

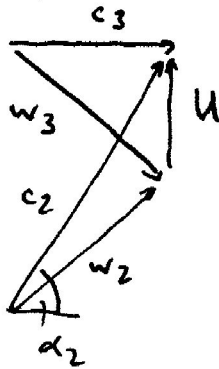
Note: since flow angles assumed to be blade metal angles (have ideal turning) and for this assume inviscid flow (no loss) the above is the ideal work input W_{ideal}

$\pi = \left(\frac{T_{t3s}}{T_{t0}}\right)^{\frac{\gamma}{\gamma-1}} = 1.5$

f) $\dot{W}_{shaft} = \frac{1}{\gamma_{ad}} \cdot \dot{m} W_{ideal} = 626 \text{ kW}$

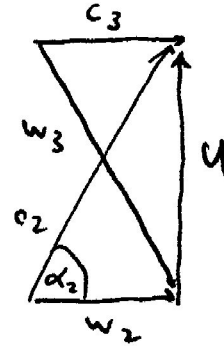
T16

Impulse Turbine



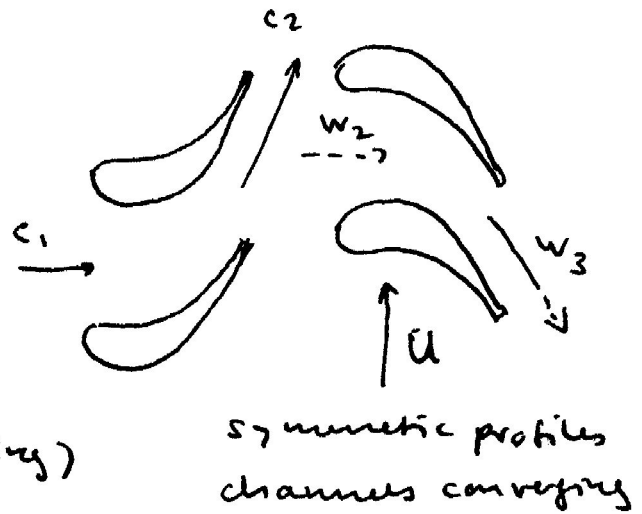
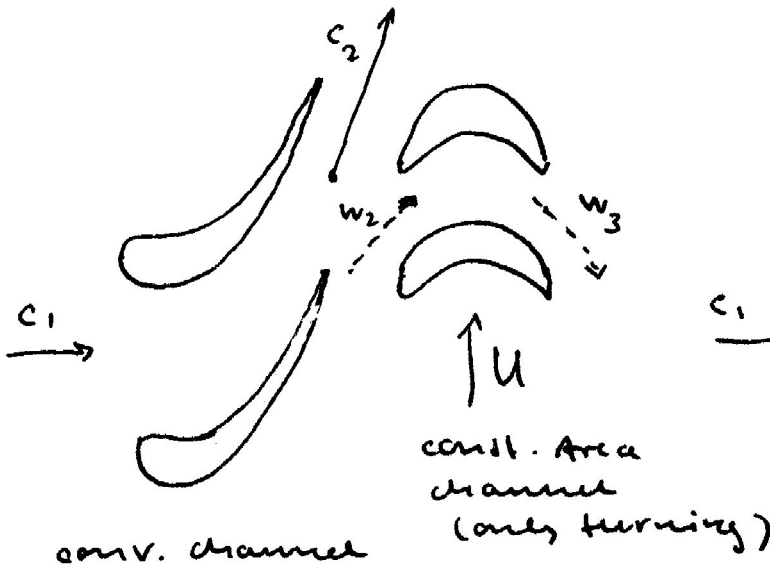
c : abs
 w : rel.
 u : wheel
 $c_p = (1000) \text{ J/kg K}$

Reaction Turbine



$\alpha_2 = 70^\circ$
 $c_2 = 400 \text{ m/s}$
 $T_{t2} = 1100 \text{ K}$

a)



b) $2u = c_2 \sin \alpha_2$

$u = 188 \text{ m/s}$

$u = c_2 \sin \alpha_2$

$u = 376 \text{ m/s}$

c) $w_{\text{shaft}} = u(c_{\theta 3} - c_{\theta 2})$

$w_{\text{shaft}} = -u c_2 \sin \alpha_2 = -2u^2 = 70.7 \frac{\text{m}^3}{\text{kg}}$

$w_{\text{shaft}} = u(c_{\theta 3} - c_{\theta 2})$

$w_{\text{shaft}} = -u^2 = -141.4 \frac{\text{m}^3}{\text{kg}}$

Note: work output!

d) $\Delta T_t = \frac{2u^2}{c_p} = 70.7 \text{ K}$

$\Delta T_t = \frac{u^2}{c_p} = 141.4 \text{ K}$

e) $\Delta T = \Delta T_t = \frac{c_2^2}{2c_p} + \frac{c_3^2}{2c_p}$

$c_3 = c_2 \cos \alpha_2 = 137 \text{ m/s}$

$\Delta T = 0 \text{ K}$ (impulse turbine!)

ditto:

$\Delta T = \Delta T_t - \frac{c_2^2}{2c_p} + \frac{c_3^2}{2c_p}$

$\Delta T = 70.7 \text{ K}$

Problem S11 (Signals and Systems)

1. From the problem statement,

$$\omega_n = \sqrt{2} \frac{9.82 \text{ m/s}^2}{129 \text{ m/s}} = 0.1077 \text{ r/s}$$

$$\zeta = \frac{1}{\sqrt{2}(L_0/D_0)} = \frac{1}{\sqrt{2} \cdot 15} = 0.0471$$

Therefore,

$$\bar{G}(s) = \frac{1}{s(s^2 + 0.01015s + 0.0116)}$$

The roots of the denominator are at $s = 0$, and

$$s = \frac{-0.01015 \pm \sqrt{0.01015^2 - 4 \cdot 0.0116}}{2}$$

$$= -0.005075 \pm 0.1075j$$

So

$$\bar{G}(s) = \frac{1}{s(s - [-0.005075 + 0.1075j])(s - [-0.005075 - 0.1075j])}$$

Use the coverup method to obtain the partial fraction expansion

$$\bar{G}(s) = \frac{86.283}{s} + \frac{-43.142 + 2.036j}{s - [-0.005075 + 0.1075j]}$$

$$+ \frac{-43.142 - 2.036j}{s - [-0.005075 - 0.1075j]}$$

Taking the inverse Laplace transform (assuming that $\bar{g}(t)$ is causal), we have

$$\bar{g}(t) = 86.283\sigma(t)$$

$$+ (-43.142 + 2.036j)e^{(-0.005075+0.1075j)t}$$

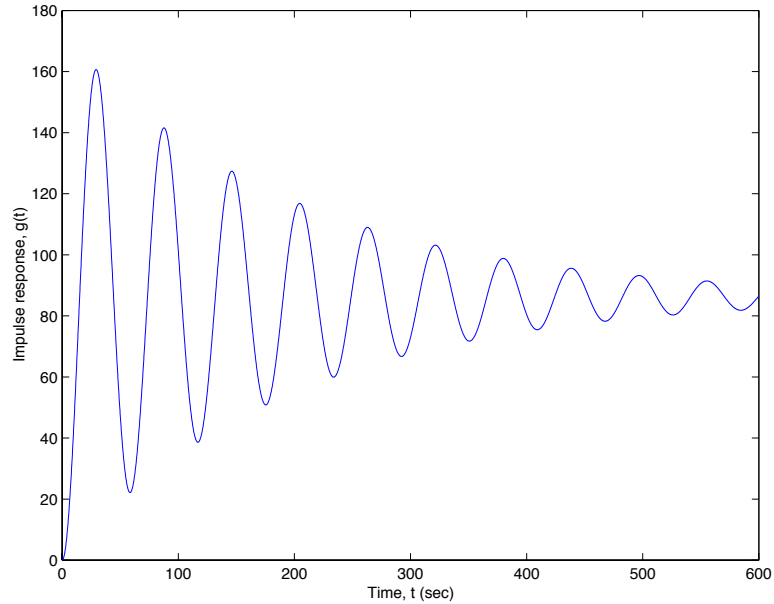
$$+ (-43.142 - 2.036j)e^{(-0.005075-0.1075j)t}$$

Therefore,

$$\bar{g}(t) = \sigma(t) [86.283 + 2e^{-0.005075t} (-43.142 \cos \omega_d t - 2.036 \sin \omega_d t)]$$

$$= \sigma(t) [86.283 + (-86.284 \cos \omega_d t - 4.072 \sin \omega_d t) e^{-0.005075t}]$$

where $\omega_d = 0.1075$ r/s. See below for the impulse response.



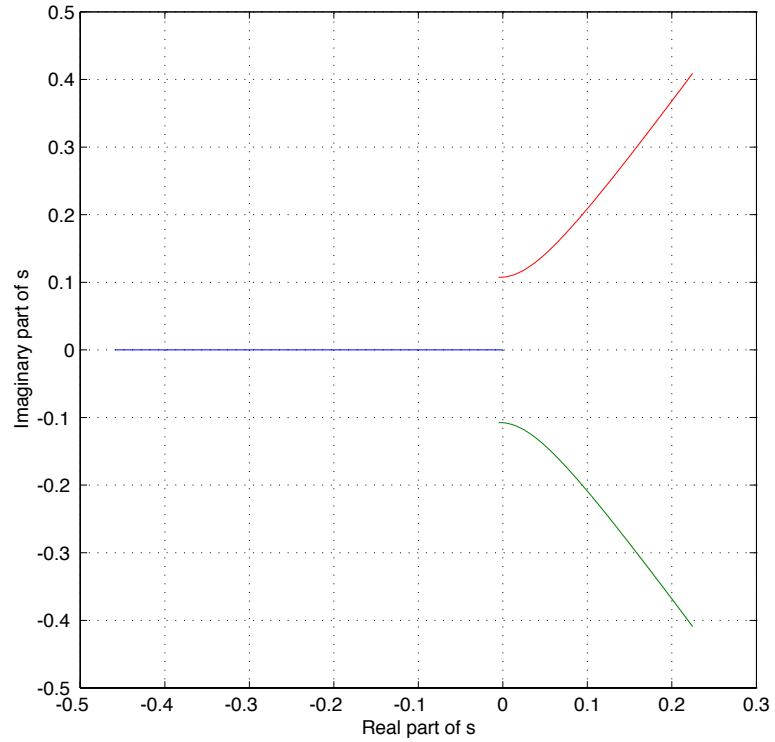
2. From the problem statement,

$$\begin{aligned}
 \frac{H(s)}{R(s)} &= \frac{k\bar{G}(s)}{1 + k\bar{G}(s)} \\
 &= \frac{k \frac{1}{s(s^2 + 2\zeta\omega_n s + \omega_n^2)}}{1 + k \frac{1}{s(s^2 + 2\zeta\omega_n s + \omega_n^2)}} \\
 &= \frac{k}{s^3 + 2\zeta\omega_n s^2 + \omega_n^2 s + k}
 \end{aligned}$$

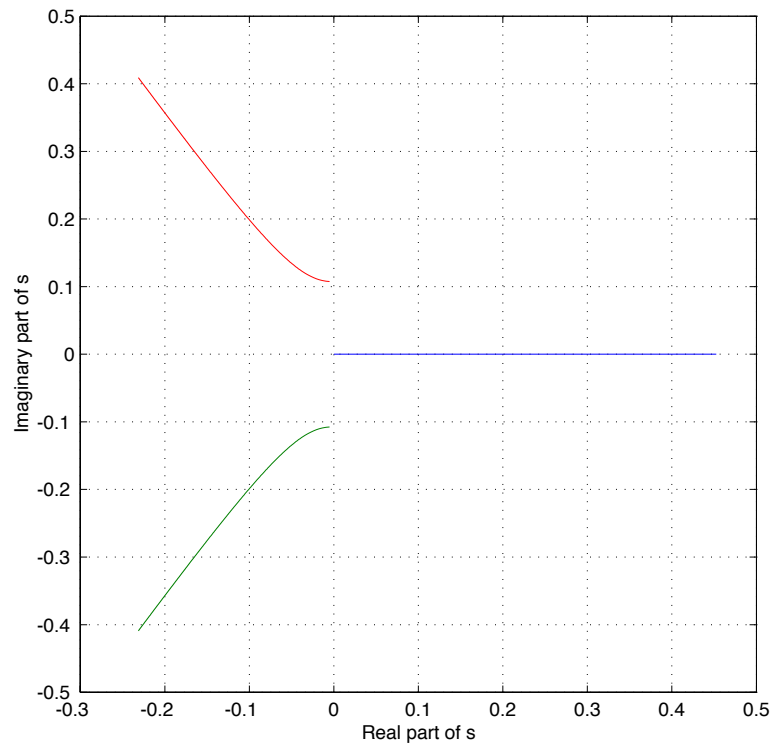
So the poles of the system are the roots of the denominator polynomial,

$$\phi(s) = s^3 + 2\zeta\omega_n s^2 + \omega_n^2 s + k = 0$$

The roots can be found using Matlab, a programmable calculator, etc. The plot of the roots (the “root locus”) is shown below. Note that the oscillatory poles go unstable at a gain of only $k = 0.000118$.



3. The roots locus for negative gains can be plotted in a similar way, as below. Note that the real pole is unstable for all negative k .



Problem S12 (Signals and Systems)

1. $g(t) = \sin(at)\sigma(-t)$. To do this problem, expand the sinusoid as complex exponentials, so that

$$g(t) = \left[\frac{e^{ajt} - e^{-ajt}}{2j} \right] \sigma(-t)$$

Therefore, the LT is given by

$$G(s) = \int_{-\infty}^0 \left[\frac{e^{ajt} - e^{-ajt}}{2j} \right] e^{-st} dt$$

For the LT to converge, the integrand must go to zero as t goes to $-\infty$. Therefore, the integral converges only for $\text{Re}[s] < 0$. The integral is then

$$\begin{aligned} G(s) &= \int_{-\infty}^0 \left[\frac{e^{ajt} - e^{-ajt}}{2j} \right] e^{-st} dt \\ &= \frac{1}{2j} \left[\frac{1}{-s + aj} e^{(aj-s)t} \Big|_{-\infty}^0 - \frac{1}{-s - aj} e^{(-aj-s)t} \Big|_{-\infty}^0 \right] \\ &= \frac{1}{2j} \left[\frac{1}{-s + aj} - \frac{1}{-s - aj} \right] \\ &= \frac{-a}{s^2 + a^2}, \quad \text{Re}[s] < 0 \end{aligned}$$

2. $g(t) = e^{at}\sigma(-t)$. The LT is given by

$$G(s) = \int_{-\infty}^0 e^{at} e^{-st} dt = \int_{-\infty}^0 e^{(a-s)t} dt$$

For the LT to converge, the integrand must go to zero as t goes to $-\infty$. Therefore, the integral converges only for $\text{Re}[s] < a$. Then

$$\begin{aligned} G(s) &= \int_{-\infty}^0 e^{(a-s)t} dt \\ &= \frac{1}{a-s} e^{(a-s)t} \Big|_{-\infty}^0 \\ &= 0 - \frac{1}{a-s} \\ &= -\frac{1}{s-a}, \quad \text{Re}[s] < a \end{aligned}$$

3. $g(t) = te^{at}\sigma(-t)$. The LT is given by

$$G(s) = \int_{-\infty}^0 te^{at} e^{-st} dt = \int_{-\infty}^0 te^{(a-s)t} dt$$

For the LT to converge, the integrand must go to zero as t goes to $-\infty$. Therefore, the integral converges only for $\text{Re}[s] < a$. To find the integral, integrate by parts:

$$\begin{aligned}
 G(s) &= \int_{-\infty}^0 t e^{(a-s)t} dt \\
 &= t \frac{1}{a-s} e^{(a-s)t} \Big|_{-\infty}^0 - \frac{1}{a-s} \int_{-\infty}^0 e^{(a-s)t} dt \\
 &= 0 - \frac{1}{a-s} \int_{-\infty}^0 e^{(a-s)t} dt \\
 &= -\frac{1}{(a-s)^2} e^{(a-s)t} \Big|_{-\infty}^0 \\
 &= -\frac{1}{(s-a)^2}, \quad \text{Re}[s] < a
 \end{aligned}$$

4. $g(t) = \cos(\omega_0 t) e^{-a|t|}$, for all t . The LT is given by

$$G(s) = \int_{-\infty}^{\infty} \cos(\omega_0 t) e^{-a|t|} e^{-st} dt$$

For the LT to converge, the integrand must go to zero as t goes to $-\infty$ and ∞ . Therefore, the integral converges only for $-a < \text{Re}[s] < a$. The integral is given by

$$\begin{aligned}
 G(s) &= \int_{-\infty}^{\infty} \cos(\omega_0 t) e^{-a|t|} e^{-st} dt \\
 &= \int_{-\infty}^0 \cos(\omega_0 t) e^{at} e^{-st} dt + \int_0^{\infty} \cos(\omega_0 t) e^{-at} e^{-st} dt
 \end{aligned}$$

Expanding the cosine term as

$$\cos(\omega_0 t) = \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2}$$

yields

$$\begin{aligned}
 G(s) &= \int_{-\infty}^0 \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2} e^{at} e^{-st} dt + \int_0^{\infty} \frac{e^{j\omega_0 t} + e^{-j\omega_0 t}}{2} e^{-at} e^{-st} dt \\
 &= \int_{-\infty}^0 \frac{e^{(j\omega_0 + a - s)t} + e^{(-j\omega_0 + a - s)t}}{2} dt + \int_0^{\infty} \frac{e^{(j\omega_0 - a - s)t} + e^{(-j\omega_0 - a - s)t}}{2} dt \\
 &= \frac{1}{2} \left[\frac{1}{j\omega_0 + a - s} + \frac{1}{-j\omega_0 + a - s} - \frac{1}{j\omega_0 - a - s} - \frac{1}{-j\omega_0 - a - s} \right] \\
 &= \frac{-s}{s^2 - 2as + a^2 + \omega_0^2} + \frac{s}{s^2 + 2as + a^2 + \omega_0^2}, \quad -a < \text{Re}[s] < a
 \end{aligned}$$

5. $g(t) = e^{2t}\sigma(t) - e^{-t}\sigma(-t)$. The LT of $e^{2t}\sigma(t)$ is given by

$$\frac{1}{s-2}, \quad \text{Re}[s] > 2$$

The LT of $-e^{-t}\sigma(-t)$ is given by

$$\frac{-1}{s+1}, \quad \text{Re}[s] < -1$$

For the LT of $g(t)$ to converge, both parts of the integral must converge, so the r.o.c. is the *intersection* of the two r.o.c.'s above. Since the intersection is empty, there is no LT for any value of s .