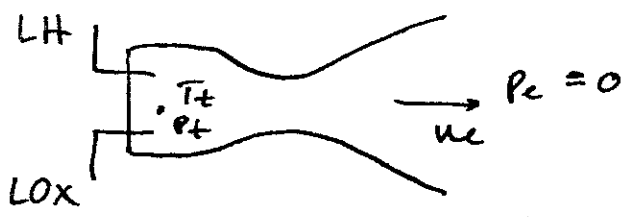


T17



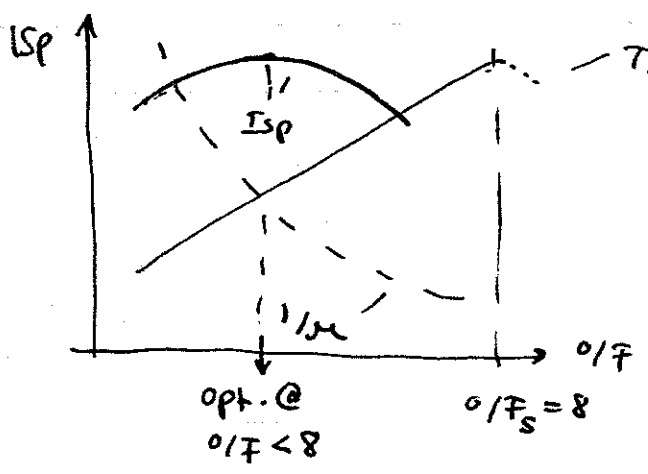
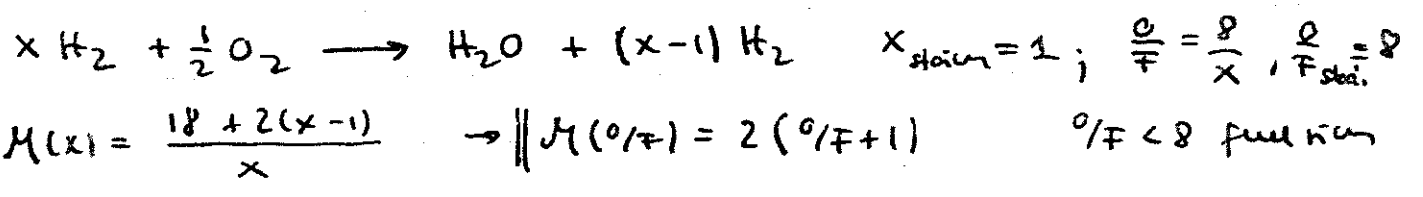
LH, LOX @ T=0K  
(cryogenic)  $t_{T=0}^{H_2} = 0$  kJ/mol  
 $t_{T=0}^{O_2} = 0$  kJ/mol

a)  $I_{sp} = \frac{u_e}{g}$ , 1st law:  $u_e^2 = 2c_p T_t \left(1 - \frac{T_c}{T_t}\right) \sim \frac{T_c}{T_t} = \left(\frac{P_c}{P_t}\right)^{\frac{\gamma-1}{\gamma}} = 0$   
 $c_p = \frac{\gamma}{\gamma-1} R$ ,  $R = \frac{R}{M}$  and  $M = \frac{\sum n_i M_i}{\sum n_i}$  combustion products

$I_{sp} = \frac{1}{g} \sqrt{\frac{2\gamma}{\gamma-1} \frac{R}{M} T_t}$

Note: M and Tt depend on oxidizer to fuel ratio O/F; assume  $\gamma$  constant (to simplify analysis)

|| Tt highest at stoichiometric conditions



$T_t \text{ No} \rightarrow$  run at fuel rich conditions! for optimum Isp

b) yes,  $O/F = 6$  is fuel rich  
 $\rightarrow$  to reduce  $M$  give low mass  $H_2$  more weight (relative to higher mass  $O_2$ )  
 $\rightarrow x = 4/3 > 1$

c) find adiabatic flame temp.  $T_f: \sum_{\text{Reactants}} n_i (t_f^{(i)} + \Delta h_{298 \rightarrow T}^{(i)}) = \sum_{\text{Products}} n_e (t_f^{(e)} + \Delta h_{298 \rightarrow T}^{(e)})$

so  $-x t_{298}^{H_2} - \frac{1}{2} t_{298}^{O_2} = t_f^{H_2O} + \bar{c}_{p,H_2O} (T_f - 298) + \bar{c}_{p,H_2} (T_f - 298)(x-1)$

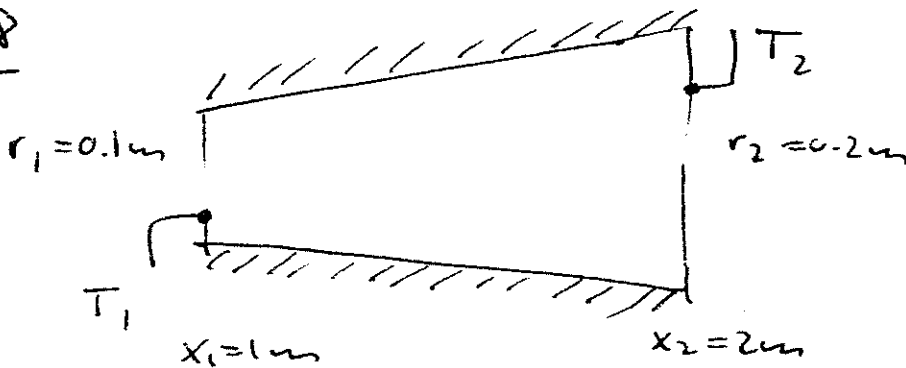
(assume avg-cp over temperature range and constant  $\gamma = \frac{\bar{c}_{p,H_2O}}{\bar{c}_{p,H_2}} \approx 1.17$ )

$T_f = T_f = 298 - \frac{x t_{298}^{H_2} + \frac{1}{2} t_{298}^{O_2} + t_f^{H_2O}}{x \bar{c}_{p,H_2} + \bar{c}_{p,H_2O} - \bar{c}_{p,H_2}}$   $\lambda x = 8/(O/F)$

for a):  $T_f = 4337K$ ,  $u_e = 5250 \text{ m/s}$   
 $I_{sp} = 535 \text{ s}$

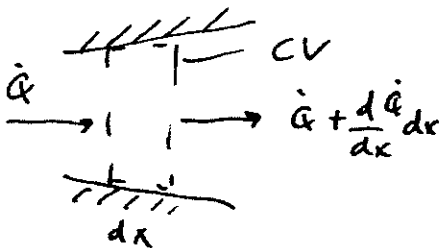
for b):  $T_f = 3555K$ ,  $u_e = 5389 \text{ m/s}$   
 $\lambda = 1.19$   $I_{sp} = 549 \text{ s}$

TIP



Assume 1-D  
heat x-fer

a)



1st law:  $0 = \dot{Q} - (\dot{Q} + \frac{d\dot{Q}}{dx} dx)$

$\frac{d\dot{Q}}{dx} = 0$  or  $\dot{Q} = \text{const}$

b)

$\dot{Q} = A(x) \dot{q}(x)$       $A = \pi r^2(x) = 0.01\pi x^2$

$\frac{d}{dx}(A\dot{q}) = 0$ ;      $\frac{d\dot{q}}{dx} + \left(\frac{1}{A} \frac{dA}{dx}\right) \dot{q} = 0$       $\frac{dA}{dx} = 0.02\pi x$

c) Fourier:  $\dot{q} = -k \frac{dT}{dx}$  solve for  $\dot{q}$  first, then for  $T(x)$

$\frac{d\dot{q}}{dx} + \frac{2}{x} \dot{q} = 0 \rightarrow \frac{d\dot{q}}{\dot{q}} = -\frac{2dx}{x}$ ;      $\ln \dot{q} = -2 \ln x + \ln \tilde{C}_1$

$\dot{q} = \frac{\tilde{C}_1}{x^2}$  then  $\frac{dT}{dx} = \frac{-C_1}{x^2}$  and  $T(x) = \frac{C_1}{x} + C_2$

B.C.:  $T(1) = T_1$  :  $T_1 = C_1 + C_2$

$T(2) = T_2$  :  $T_2 = \frac{C_1}{2} + C_2$

$T(x) = \frac{2(T_1 - T_2)}{x} + 2T_2 - T_1$

d)

$\dot{Q} = -k 0.01\pi \frac{dT}{dx} \Big|_{x=1} = 0.02\pi k (T_1 - T_2)$

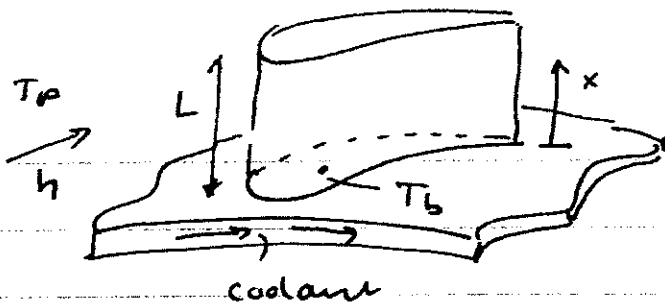
$R = \frac{T_1 - T_2}{\dot{Q}}$  so  $R = \frac{1}{0.02\pi k}$

e)

$\dot{q} = -k \frac{dT}{dx} = 2k \frac{T_1 - T_2}{x^2}$

$\dot{q}(x) = 2k \frac{T_1 - T_2}{x^2}$

T19



Spring 2007, 2SP

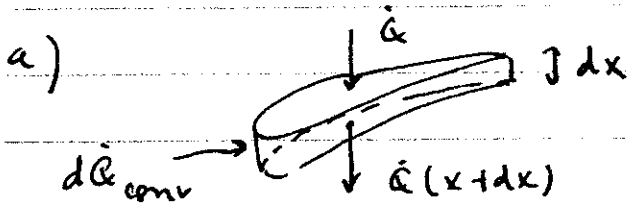
$$T_\infty = 1200^\circ\text{C} \quad h = 250 \text{ W/m}^2\text{K}$$

$$k = 20 \text{ W/mK} \quad L = 50 \text{ mm}$$

$$A_c = 6 \cdot 10^{-4} \text{ m}^2 \quad P = 110 \text{ mm}$$

$$T_b = 300^\circ\text{C}$$

Assume: blade top adiabatic



1st law:

$$0 = \dot{Q}(x) - \dot{Q}(x+dx) + d\dot{Q}_{conv}$$

$$d\dot{Q}_{conv} = h(T_\infty - T(x))P dx$$

$$\dot{Q}(x) = -kA_c \frac{dT}{dx} \quad \text{and} \quad \dot{Q}(x+dx) = \dot{Q}(x) + \frac{d\dot{Q}}{dx} dx$$

get this

$$\frac{d^2T}{dx^2} + \frac{hP}{kA_c} (T_\infty - T) = 0$$

b) B.C.:  $x=0: T(0) = T_b$ ,  $x=L: \dot{Q}(x=L) = 0$   $\left. \frac{dT}{dx} \right|_L = 0$

c) Use  $\Theta = T - T_\infty$  }  $\left. \begin{array}{l} \frac{d^2\Theta}{dx^2} - c^2 \Theta = 0 \\ c^2 = \frac{hP}{kA_c} \end{array} \right\} \left. \begin{array}{l} \Theta(0) = T_b - T_\infty \\ \frac{d\Theta}{dx}(L) = 0 \end{array} \right\}$

$$\Theta = \tilde{C}_1 e^{-Cx} + \tilde{C}_2 e^{Cx}; \quad \tilde{C}_1 = \tilde{C}_2 e^{2cL}, \quad \tilde{C}_2 = \frac{T_b - T_\infty}{1 + e^{2cL}}$$

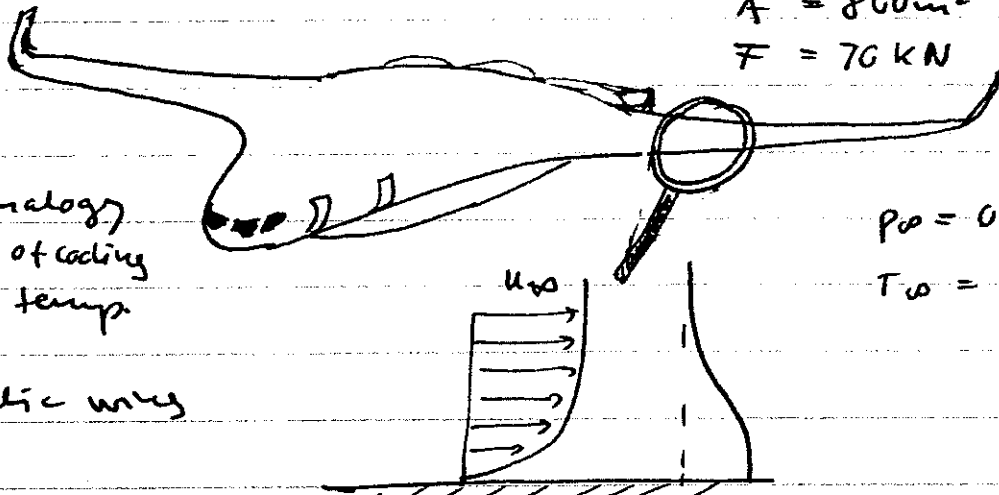
$$\text{so } \frac{T - T_\infty}{T_b - T_\infty} = \frac{e^{\sqrt{\frac{hP}{kA_c}}(2L-x)} + e^{\sqrt{\frac{hP}{kA_c}}x}}{1 + e^{2\sqrt{\frac{hP}{kA_c}}L}} = \frac{\cosh\left(L\sqrt{\frac{hP}{kA_c}}\left(1 - \frac{x}{L}\right)\right)}{\cosh\left(L\sqrt{\frac{hP}{kA_c}}\right)}$$

Plug in numbers get  $T(L) = 1037^\circ\text{C} \rightarrow$  yes, scheme is satisfactory

$$\text{d) } \dot{Q} = -kA_c \left. \frac{dT}{dx} \right|_{x=0} \quad \frac{dT}{dx} = \frac{d\Theta}{dx} = c(T_b - T_\infty) \frac{1 - e^{2cL}}{1 + e^{2cL}} = c(T_b - T_\infty) \tanh(cL)$$

$$\dot{Q} = \sqrt{hPkA_c} (T_\infty - T_b) \tanh\left(\sqrt{\frac{hP}{kA_c}} L\right) \quad \dot{Q} = 508 \text{ W}$$

$M_\infty = 0.8$   
 $A = 800 \text{ m}^2$      $A_{LE} = 20 \text{ m}^2$   
 $F = 70 \text{ kN}$



Concepts:

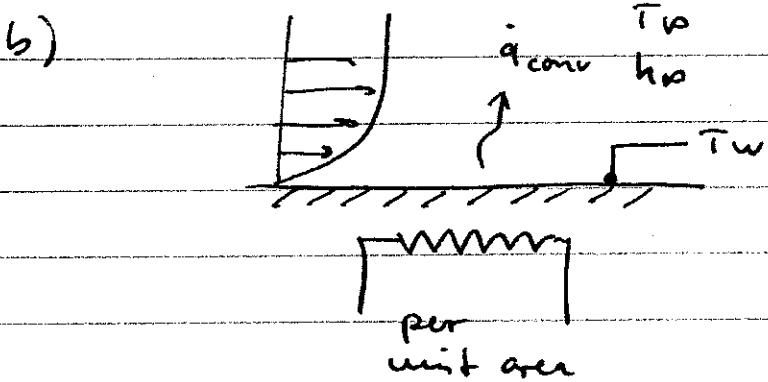
- Reynolds Analogy
- Newton's law of cooling
- Adiabatic wall temp

$p_\infty = 0.187 \text{ bar}$   
 $T_\infty = 217 \text{ K}$

a) adiabatic wing

$T_{wall} = T_{tr} = \left(1 + \frac{\gamma-1}{2} M_\infty^2\right) T_\infty$

$T_{wall} = 245 \text{ K} \rightarrow -28^\circ \text{C}$  need surface heating



level flight:

$F = D = \frac{1}{2} \rho_\infty u_\infty^2 A C_D$

$C_D = \frac{F R T_\infty}{\frac{1}{2} \rho_\infty u_\infty^2 A}$

$u_\infty^2 = M_\infty^2 \gamma R T_\infty$

$C_D = \frac{2F}{\rho_\infty M_\infty^2 A} = 0.01$

Reynolds analogy     $St = \frac{C_D}{2} = \frac{h_p}{\rho_\infty u_\infty c_p} \rightarrow h_p = 372 \text{ W/m}^2$

1st Law:

$\dot{W}_{el} = A_{LE} h_p (T_w - T_\infty) \quad \wedge \quad T_w = 5^\circ \text{C}$

$\dot{W}_{el} = 453 \text{ W}$

Problem S13 (Signals and Systems) SOLUTION

1. The LT is

$$G(s) = \frac{3s^2 + 3s - 10}{s^2 - 4}, \quad -2 < \text{Re}[s] < 2$$

Because the numerator is the same order as the denominator, the partial fraction expansion will have a constant term:

$$\begin{aligned} G(s) &= \frac{3s^2 + 3s - 10}{s^2 - 4} \\ &= \frac{3s^2 + 3s - 10}{(s - 2)(s + 2)} \\ &= a + \frac{b}{s - 2} + \frac{c}{s + 2} \end{aligned}$$

To find  $a$ ,  $b$ , and  $c$ , use coverup method:

$$\begin{aligned} a &= G(s)|_{s=\infty} = 3 \\ b &= \left. \frac{3s^2 + 3s - 10}{s + 2} \right|_{s=2} = 2 \\ c &= \left. \frac{3s^2 + 3s - 10}{s - 2} \right|_{s=-2} = 1 \end{aligned}$$

So

$$G(s) = 3 + \frac{2}{s - 2} + \frac{1}{s + 2}, \quad -2 < \text{Re}[s] < 2$$

We can take the inverse LT by simple pattern matching, taking note of the fact that the pole at  $s = 2$  must be anticausal, since it is to the right of the ROC. The result is that

$$g(t) = 3\delta(t) - 2e^{2t}\sigma(-t) + e^{-2t}\sigma(t)$$

2. The LT is

$$G(s) = \frac{3s^2 + 3s - 10}{s^2 - 4}, \quad \text{Re}[s] < -2$$

that is, the same as in part (1) except for the ROC. Therefore,

$$G(s) = 3 + \frac{2}{s - 2} + \frac{1}{s + 2}, \quad \text{Re}[s] < -2$$

The inverse LT is then

$$g(t) = 3\delta(t) - 2e^{2t}\sigma(-t) - e^{-2t}\sigma(-t)$$

3. The LT is given by

$$G(s) = \frac{6s^2 + 26s + 26}{(s + 1)(s + 2)(s + 3)}, \quad -2 < \text{Re}[s] < -1$$

The partial fraction expansion is

$$\begin{aligned} G(s) &= \frac{6s^2 + 26s + 26}{(s+1)(s+2)(s+3)} \\ &= \frac{a}{s+1} + \frac{b}{s+2} + \frac{c}{s+3} \end{aligned}$$

where

$$\begin{aligned} a &= \left. \frac{6s^2 + 26s + 26}{(s+2)(s+3)} \right|_{s=-1} = 3 \\ b &= \left. \frac{6s^2 + 26s + 26}{(s+1)(s+3)} \right|_{s=-2} = 2 \\ c &= \left. \frac{6s^2 + 26s + 26}{(s+1)(s+2)} \right|_{s=-3} = 1 \end{aligned}$$

So

$$G(s) = \frac{3}{s+1} + \frac{2}{s+2} + \frac{1}{s+3}, \quad -2 < \operatorname{Re}[s] < -1$$

The inverse LT is given by

$$g(t) = (e^{-3t} + 2e^{-2t}) \sigma(t) - 3e^{-t} \sigma(-t)$$

4. The LT is

$$G(s) = \frac{6s^2 + 26s + 26}{(s+1)(s+2)(s+3)}, \quad -3 < \operatorname{Re}[s] < -2$$

This is the same as in part (3), except for the ROC. Therefore, the partial fraction expansion is

$$G(s) = \frac{3}{s+1} + \frac{2}{s+2} + \frac{1}{s+3}, \quad -3 < \operatorname{Re}[s] < -2$$

and the inverse LT is

$$g(t) = e^{-3t} \sigma(t) - (2e^{-2t} + 3e^{-t}) \sigma(-t)$$

5. The LT is

$$G(s) = \frac{4s^2 + 11s + 9}{(s+1)^2(s+2)}, \quad -2 < \operatorname{Re}[s] < -1$$

This one is a little tricky — there is a second order pole at  $s = -1$ . So the partial fraction expansion is

$$G(s) = \frac{4s^2 + 11s + 9}{(s+1)^2(s+2)} = \frac{a}{s+1} + \frac{b}{(s+1)^2} + \frac{c}{s+2}$$

We can find  $b$  and  $c$  by the coverup method:

$$\begin{aligned} b &= \left. \frac{4s^2 + 11s + 9}{s+2} \right|_{s=-1} = 2 \\ c &= \left. \frac{4s^2 + 11s + 9}{(s+1)^2} \right|_{s=-2} = 3 \end{aligned}$$

So

$$G(s) = \frac{a}{s+1} + \frac{2}{(s+1)^2} + \frac{3}{s+2}$$

To find  $a$ , pick a value of  $s$ , and plug into the equation above. The easiest value to pick is  $s = 0$ . Then

$$G(0) = \frac{a}{1} + \frac{2}{(1)^2} + \frac{3}{2} = \frac{9}{2}$$

Solving, we have

$$a = 1$$

Therefore,

$$G(s) = \frac{1}{s+1} + \frac{2}{(s+1)^2} + \frac{3}{s+2}, \quad -2 < \operatorname{Re}[s] < -1$$

The inverse LT is then

$$g(t) = 3e^{-2t}\sigma(t) - (e^{-t} + 2te^{-t})\sigma(-t)$$

6. The LT is

$$G(s) = \frac{4s^2 + 11s + 9}{(s+1)^2(s+2)}, \quad \operatorname{Re}[s] < -2$$

This problem is similar to above. The partial fraction expansion is

$$G(s) = \frac{1}{s+1} + \frac{2}{(s+1)^2} + \frac{3}{s+2}, \quad \operatorname{Re}[s] < -2$$

The inverse LT is then

$$g(t) = -(e^{-t} + 2te^{-t} + 3e^{-2t})\sigma(-t)$$

7. The LT is

$$G(s) = \frac{4s^3 + 11s^2 + 5s + 2}{s^2(s+1)^2}, \quad -1 < \operatorname{Re}[s] < 0$$

We can find  $b$  and  $d$  by the coverup method

$$b = \left. \frac{4s^3 + 11s^2 + 5s + 2}{(s+1)^2} \right|_{s=0} = 2$$
$$d = \left. \frac{4s^3 + 11s^2 + 5s + 2}{s^2} \right|_{s=-1} = 4$$

So

$$G(s) = \frac{4s^3 + 11s^2 + 5s + 2}{s^2(s+1)^2} = \frac{a}{s} + \frac{2}{s^2} + \frac{c}{s+1} + \frac{4}{(s+1)^2}$$

To find  $a$  and  $c$ , pick two values of  $s$ , say,  $s = 1$  and  $s = 2$ . Then

$$G(1) = \frac{4 + 11 + 5 + 2}{1^2(1+1)^2} = \frac{a}{1} + \frac{2}{1^2} + \frac{c}{1+1} + \frac{4}{(1+1)^2}$$
$$G(2) = \frac{4 \cdot 2^3 + 11 \cdot 2^2 + 5 \cdot 2 + 2}{2^2(2+1)^2} = \frac{a}{2} + \frac{2}{2^2} + \frac{c}{2+1} + \frac{4}{(2+1)^2}$$

Simplifying, we have that

$$\begin{aligned} a + \frac{c}{2} &= \frac{5}{2} \\ \frac{a}{2} + \frac{c}{3} &= \frac{3}{2} \end{aligned}$$

Solving for  $a$  and  $c$ , we have that

$$\begin{aligned} a &= 1 \\ c &= 3 \end{aligned}$$

So

$$G(s) = \frac{1}{s} + \frac{2}{s^2} + \frac{3}{s+1} + \frac{4}{(s+1)^2}, \quad -1 < \operatorname{Re}[s] < 0$$

The inverse LT is then

$$g(t) = (3e^{-t} + 4te^{-t})\sigma(t) - (1 + 2t)\sigma(-t)$$

8. The LT is

$$G(s) = \frac{4s^3 + 11s^2 + 5s + 2}{s^2(s+1)^2}, \quad \operatorname{Re}[s] < -1$$

From above, the PFE is

$$G(s) = \frac{1}{s} + \frac{2}{s^2} + \frac{3}{s+1} + \frac{4}{(s+1)^2}, \quad \operatorname{Re}[s] < -1$$

The inverse LT is then

$$g(t) = -(3e^{-t} + 4te^{-t} + 1 + 2t)\sigma(-t)$$

9. The LT is

$$G(s) = \frac{s^3 + 3s^2 + 9s + 12}{(s^2 + 4)(s^2 + 9)}, \quad \operatorname{Re}[s] < 0$$

$G(s)$  can be expanded as

$$\begin{aligned} G(s) &= \frac{s^3 + 3s^2 + 9s + 12}{(s^2 + 4)(s^2 + 9)} \\ &= \frac{s^3 + 3s^2 + 9s + 12}{(s + 2j)(s - 2j)(s + 3j)(s - 3j)} \\ &= \frac{a}{s + 2j} + \frac{b}{s - 2j} + \frac{c}{s + 3j} + \frac{d}{s - 3j} \end{aligned}$$

The coefficients can be found by the coverup method:

$$\begin{aligned} a &= \left. \frac{s^3 + 3s^2 + 9s + 12}{(s - 2j)(s + 3j)(s - 3j)} \right|_{s=-2j} = 0.5 \\ b &= \left. \frac{s^3 + 3s^2 + 9s + 12}{(s + 2j)(s + 3j)(s - 3j)} \right|_{s=+2j} = 0.5 \\ c &= \left. \frac{s^3 + 3s^2 + 9s + 12}{(s + 2j)(s - 2j)(s - 3j)} \right|_{s=-3j} = 0.5j \\ d &= \left. \frac{s^3 + 3s^2 + 9s + 12}{(s + 2j)(s - 2j)(s + 3j)} \right|_{s=+3j} = -0.5j \end{aligned}$$



Therefore

$$G(s) = \frac{0.5}{s+2j} + \frac{0.5}{s-2j} + \frac{0.5j}{s+3j} + \frac{-0.5j}{s-3j}, \quad \text{Re}[s] < 0$$

and the inverse LT is

$$g(t) = -0.5 (e^{-2jt} + e^{2jt} + je^{-3jt} - je^{3jt}) \sigma(-t)$$

This can be expanded using Euler's formula, which states that

$$e^{ajt} = \cos at + j \sin at$$

Applying Euler's formula yields

$$g(t) = -(\cos 2t + \sin 3t) \sigma(-t)$$

## Problem S14 (Signals and Systems) SOLUTION

The transfer functions needed in this problem are the (noncausal) smoother,

$$G_1(s) = \frac{-a^2}{(s-a)(s+a)}$$

and a similar (causal) low-pass filter

$$G_2(s) = \frac{a^2}{(s+a)^2}$$

The input is assumed to be

$$u(t) = \cos \omega t$$

1. Find the transfer function,  $G_1(j\omega)$ , as a function of frequency,  $\omega$ . **Solution:** Simply replacing  $s$  by  $j\omega$ , we have

$$G_1(j\omega) = \frac{-a^2}{(j\omega - a)(j\omega + a)} = \frac{a^2}{\omega^2 + a^2}$$

Note that even though  $j\omega$  is complex,  $G_1(j\omega)$  is real for all  $\omega$ .

2. Since the transfer function is complex, it can be represented as

$$G_1(j\omega) = A_1(\omega)e^{j\phi_1(\omega)}$$

where the amplitude of the transfer function is  $A_1(\omega)$ , and the phase of the transfer function is  $\phi_1(\omega)$ . Find  $A_1(\omega)$  and  $\phi_1(\omega)$ . **Solution:** The expression above can be expanded as

$$G_1(j\omega) = A_1(\omega) (\cos(\phi_1(\omega)) + j \sin(\phi_1(\omega)))$$

and hence

$$\phi_1 = \tan^{-1} \left( \frac{\text{Im}(G_1)}{\text{Re}(G_1)} \right)$$

$$A_1 = \text{abs}(G_1)$$

Since in the present case,  $G_1(j\omega)$  is real, we must have that the phase  $\phi_1 = 0$ , and therefore

$$A_1(\omega) = \frac{a^2}{\omega^2 + a^2}$$

$$\phi_1\omega = 0$$

3. Find the transfer function,  $G_2(j\omega)$ , as a function of frequency,  $\omega$ , as well as  $A_2(\omega)$  and  $\phi_2(\omega)$ . **Solution:** Express  $G_2$  as

$$G_2(j\omega) = \frac{a^2}{(j\omega + a)^2}$$

Since the magnitude of a product is the product of the magnitudes,

$$\begin{aligned} A_2(\omega) &= \frac{a^2}{\text{abs}(j\omega + a)^2} \\ &= \frac{a^2}{\left(\sqrt{\omega^2 + a^2}\right)^2} \\ &= \frac{a^2}{\omega^2 + a^2} \end{aligned}$$

That is,  $A_2(\omega)$  and  $A_1(\omega)$  are exactly the same!

Next, find  $\phi_2$ :

$$\phi_2(\omega) = -2 \tan^{-1}(\omega/a)$$

The minus sign is because the term  $j\omega + a$  is in the denominator of  $G_2(j\omega)$ ; the factor of 2 is because there are two such terms. So the phases of the transfer functions are different, even though the amplitudes are the same.

4. For the input  $u(t)$  above, show that the output of the system  $G_1$  is

$$y_1(t) = A_1(\omega) \cos(\omega t + \phi_1(\omega))$$

and do likewise for system  $G_2$ . **Solution:** It's enough to show the results for  $y_1(t)$ , since the result for the case  $y_2(t)$  results just by changing subscripts. Since the input is

$$u(t) = \cos(\omega t) = \frac{e^{j\omega t} + e^{-j\omega t}}{2}$$

the output is given by

$$\begin{aligned} y_1(t) &= \frac{G_1(j\omega)e^{j\omega t} + G_1(-j\omega)e^{-j\omega t}}{2} \\ &= \frac{A_1(\omega)e^{j\phi_1(\omega)}e^{j\omega t} + A_1(-\omega)e^{j\phi_1(-\omega)}e^{-j\omega t}}{2} \end{aligned}$$

But  $A_1(-\omega) = A_1(\omega)$ , and  $\phi_1(-\omega) = -\phi_1(\omega)$ . This result is in fact valid for any transfer function  $G(j\omega)$  that results from a real impulse response  $g(t)$ . Therefore,

$$\begin{aligned} y_1(t) &= \frac{A_1(\omega)e^{j\phi_1(\omega)}e^{j\omega t} + A_1(\omega)e^{-j\phi_1(\omega)}e^{-j\omega t}}{2} \\ &= A_1(\omega) \frac{e^{j\phi_1(\omega)}e^{j\omega t} + e^{-j\phi_1(\omega)}e^{-j\omega t}}{2} \\ &= A_1(\omega) \cos(\omega t + \phi_1(\omega)) \end{aligned}$$

as required.

5.  $A_1$  and  $A_2$  determine how much the magnitude of the input cosine wave is affected by each filter. Ideally,  $A_1$  and  $A_2$  would be 1, meaning that the filters don't change the magnitude of the input sine at all. Which filter (if either) changes the magnitude the least? **Solution:**  $A_1(\omega) = A_2(\omega)$ , so the two filters have exactly the same magnitude response — neither is better in that regard.

6.  $\phi_1$  and  $\phi_2$  determine how much the phase of the input cosine wave is affected by each filter. Non-zero values of  $\phi$  correspond to a shifting left or right (i.e., advancing or delaying) the sine wave. Ideally,  $\phi_1$  and  $\phi_2$  would be zero, meaning that the filters don't change the phase of the input sine at all. Which filter (if either) produces the least phase shift? **Solution:**  $\phi_1(\omega) = 0$  for all  $\omega$ , so it has the least phase shift.
7. Explain why the non-causal filter is preferred in signal processing applications where it can be applied. **Solution:** For many signal processing applications, the noncausal filter would be preferred, since it produces no change in the phase of the signal from input to output. Conversely, real-time filters almost always unavoidably change the phase from input to output.