## Second Midterm Review Solutions

Problem 1: Consider the matrix

$$A = \begin{bmatrix} 1 & 1\\ 0 & 1\\ -2 & 0 \end{bmatrix}.$$

and the vector

$$b = \begin{bmatrix} 1\\0\\1 \end{bmatrix}$$

(1) Find p = Ax that minimizes ||Ax - b||.

**Solution:** Note that the solution p minimizing the distance, is the orthogonal projection of b onto V = C(A) the column space of A.

The columns of A are linearly independent, so we can use this to compute the projection matrix  $P_V = A(A^T A)^{-1} A^T$ . Hence we can compute p as follows

$$p = A \begin{bmatrix} 5 & 1 \\ 1 & 2 \end{bmatrix}^{-1} \begin{bmatrix} 1 & 0 & -2 \\ 1 & 1 & 0 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} = A \frac{1}{9} \begin{bmatrix} 2 & -1 \\ -1 & 5 \end{bmatrix} \begin{bmatrix} -1 \\ 1 \end{bmatrix} = \begin{bmatrix} 1 & 1 \\ 0 & 1 \\ -2 & 0 \end{bmatrix} \frac{1}{3} \begin{bmatrix} -1 \\ 2 \end{bmatrix} = \frac{1}{3} \begin{bmatrix} 1 \\ 2 \\ 2 \end{bmatrix}$$

(2) Find x that minimizes ||Ax - b||.

**Solution:** Note that  $p = A((A^T A)^{-1} A^T b)$ , so we can use  $x = (A^T A)^{-1} A^T b$ . This is unique as the columns of A are linearly independent. Thus from the above computation

$$x = (A^T A)^{-1} A^T b = \frac{1}{3} \begin{bmatrix} -1\\2 \end{bmatrix}$$

Problem 2: Consider the matrix

$$A = \begin{bmatrix} 1 & 2\\ 1 & 2\\ -1 & -3\\ -1 & -3 \end{bmatrix}$$

(1) Use Gram-Schmidt to find the factorization A = QR.

**Solution:** Denote by  $v_1$  and  $v_2$  the 2 columns of A. First we rescale  $v_1$  to get:

$$q_1 = \frac{v_1}{\|v_1\|} = \frac{1}{2} \begin{bmatrix} 1\\ 1\\ -1\\ -1 \\ -1 \end{bmatrix}$$

Now we get an orthogonal vector to  $q_1$  by

$$q'_{2} = v_{2} - (q_{1} \cdot v_{2})q_{1} = v_{2} - 5q_{1} = \frac{1}{2} \begin{bmatrix} -1 \\ -1 \\ -1 \\ -1 \\ -1 \end{bmatrix}$$

Note this vector is already normalized, so  $q_2 = q'_2$ . These operations can be written as

$$Q = A \begin{bmatrix} 1/2 & 0\\ 0 & 1 \end{bmatrix} E_{12}^{(-5)}$$

So we can rewrite

$$A = QE_{12}^{(5)} \begin{bmatrix} 2 & 0 \\ 0 & 1 \end{bmatrix} = \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 1 & -1 \\ -1 & -1 \\ -1 & -1 \end{bmatrix} \begin{bmatrix} 2 & 5 \\ 0 & 1 \end{bmatrix}$$

(2) Check that the matrix in (1) satisfies  $Q^T Q = I$ 

Solution:

$$Q^{T}Q = \frac{1}{2} \begin{bmatrix} 1 & 1 & -1 & -1 \\ -1 & - & -1 & -1 \end{bmatrix} \frac{1}{2} \begin{bmatrix} 1 & -1 \\ 1 & -1 \\ -1 & -1 \\ -1 & -1 \end{bmatrix} = I$$

**Problem 3**: Consider the linear transformation

$$\phi: \mathbb{R}^3 \to \mathbb{R}^2$$

such that:

- $\phi(e_1) = 3e_1 + 1e_2$
- $\phi(e_2) = 2e_1$
- $\phi(e_3) = e_1 + e_2$

Here recall that we denote by  $e_i$  the standard basis.

(1) Find the matrix A of  $\phi$  with respect to the standard basis.

**Solution:** The above equations give us exactly the first second and third columns of the matrix A respectively, so we get

$$A = \begin{bmatrix} 3 & 2 & 1 \\ 1 & 0 & 1 \end{bmatrix}$$

(2) Let  $v_1 = \begin{bmatrix} 1\\0\\-1 \end{bmatrix}$ ,  $v_2 = \begin{bmatrix} 0\\1\\-1 \end{bmatrix}$  and  $v_3 = \begin{bmatrix} 1\\-1\\-1 \end{bmatrix}$  and let  $w_1 = \phi(v_1)$  and  $w_2 = \phi(v_2)$ . What is the matrix B of  $\phi$  with respect to the bases  $\{v_i\}$  and  $\{w_i\}$ .

Solution:

$$w_{1} = \phi(v_{1}) = Av_{1} = \begin{bmatrix} 3 & 2 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ 0 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 0 \end{bmatrix}$$
$$w_{2} = \phi(v_{2}) = Av_{2} = \begin{bmatrix} 3 & 2 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 0 \\ 1 \\ -1 \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix}$$

Further we compute

$$\phi(v_3) = Av_3 = \begin{bmatrix} 3 & 2 & 1 \\ 1 & 0 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -1 \\ -1 \end{bmatrix} = 0$$

Consider the change of basis formula  $B = W^{-1}AV$  for

$$V = \begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ -1 & -1 & -1 \end{bmatrix}$$
$$W = \begin{bmatrix} 2 & 1 \\ 0 & -1 \end{bmatrix}$$

So we compute

$$W^{-1} = \begin{bmatrix} 1/2 & 1/2 \\ 0 & -1 \end{bmatrix}$$

So we get

$$B = W^{-1}AV = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \end{bmatrix}$$

Note that this makes sense as  $\phi(v_1) = w_1$ ,  $\phi(v_2) = w_2$  and  $\phi(v_3) = 0$ .

Problem 4: Consider the matrix

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$$

(1) Find the determinant using the cofactor formula along the first row.

Solution: We compute the required cofactors first

$$C_{11} = (-1)^2 det(M_{11}) = det([d]) = d$$
$$C_{12} = (-1)^3 det(M_{12}) = det([c]) = -c$$

So the cofactor formula becomes

$$det(A) = aC_{11} + bC_{12} = ad - bc$$

(2) Find the determinant using the cofactor formula along the second row.

Solution: We compute the required cofactors first

$$C_{21} = (-1)^3 det(M_{11}) = det([b]) = -b$$

$$C_{22} = (-1)^4 det(M_{22}) = det([a]) = a$$

So the cofactor formula becomes

$$det(A) = cC_{21} + aC_{22} = -bc + ad$$

(3) Use Cramer's rule to find the inverse of the above matrix.

Solution: Note that from the above computations we have computed all cofactors, so we can put them in the cofactor matrix

$$X = \begin{bmatrix} C_{11} & C_{21} \\ C_{12} & C_{22} \end{bmatrix} = \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

Thus we get the inverse is given by

$$A^{-1} = \frac{1}{det(A)}X = \frac{1}{ad - bc} \begin{bmatrix} d & -b \\ -c & a \end{bmatrix}$$

**Problem 5**: Consider the matrix

$$\begin{bmatrix} 0 & 1 & 2 \\ 1 & 2 & 1 \\ 3 & 5 & 7 \end{bmatrix}$$

(1) Use the cofactor formula to compute the determinant.

Solution: We expand along th first row as this has a zero. We hence have

$$det(A) = 0 * C_{11} + 1 * C_{12} + 2 * C_{13} = -(7-3) + 2(5-6) = -6$$

(2) Use row operations to compute the determinant.

Solution: We first do Gaussian elimination. Note that to start we need to swap the first 2 rows, so

$$A \rightsquigarrow \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 2 \\ 3 & 5 & 7 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 2 \\ 0 & -1 & 4 \end{bmatrix} \rightsquigarrow \begin{bmatrix} 1 & 2 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 6 \end{bmatrix}$$

Note that here we have only swapped rows once, so we get

$$det(A) = -det\begin{pmatrix} 1 & 2 & 1 \\ 0 & 1 & 2 \\ 0 & 0 & 6 \end{bmatrix}) = -6$$

Here we use the determinant of upper triangular matrices is the product of diagonal entries

(3) Use the large 3! formula to compute the determinant.

Solution: We write all the terms of the formula to get

$$det(A) = 0 * 2 * 7 + 1 * 1 * 3 + 2 * 1 * 5 - 0 * 1 * 5 - 1 * 1 * 7 - 2 * 2 * 3 = 0 + 3 + 10 - 0 - 7 - 12 = -6$$

**Problem 6** Consider the matrix

$$A = \begin{bmatrix} 1 & 0 & 0 \\ 2 & -1 & 0 \\ -1 & -1 & 3 \end{bmatrix}$$

(1) Compute the eigenvalues of the matrix.

**Solution:** Recall that to consider the eigenvalues we need to consider the zeroes of  $det(A - \lambda I)$ , so we compute

$$det(A - \lambda I) = det(\begin{bmatrix} 1 - \lambda & 0 & 0\\ 2 & -1 - \lambda & 0\\ -1 & -1 & 3 - \lambda \end{bmatrix}) = (1 - \lambda)(-1 - \lambda)(3 - \lambda)$$

Here again we use the determinant of a lower triangular matrix is the product of the diagonal entries.

Thus from the above we see that the zeroes of the above are given by  $\lambda_1 = 1$ ,  $\lambda_2 = -1$  and  $\lambda_3 = 3$ 

(2) Compute eigenvectors for the above eigenvalues. Is there an eigenvector that is particularly easy?

**Solution:** First we compute the eigenvector of  $\lambda_1 = 1$ , ie we need to find elements in the nullspace of

$$A - I = \begin{bmatrix} 0 & 0 & 0 \\ 2 & -2 & 0 \\ -1 & -1 & 2 \end{bmatrix}$$

Note that the sum of the rows are 0, so we get an eigenvector  $\begin{bmatrix} 1\\1\\1 \end{bmatrix}$ .

Now we compute the eigenvector of  $\lambda_2 = -1$ , so we need to find elements in the nullspace of

$$A + I = \begin{bmatrix} 2 & 0 & 0 \\ 2 & 0 & 0 \\ -1 & -1 & 4 \end{bmatrix}$$

Here we can get an eigenvector  $\begin{bmatrix} 0\\4\\1 \end{bmatrix}$ . Finally we compute the eigenvector of  $\lambda_3 = 3$ , so we need to find elements in the nullspace of

$$A - 3I = \begin{bmatrix} -2 & 0 & 0\\ 2 & -4 & 0\\ -1 & -1 & 0 \end{bmatrix}$$

Note that the last colomn is 0, so we get an eigenvector  $\begin{bmatrix} 0\\0\\1 \end{bmatrix}$ . Note that this eigenvector always works for a lower triangular matrix.