

**READING**

Nise Chapter 1, and  
Chapter 2.1-2.3

Department of Mechanical Engineering  
Massachusetts Institute of Technology  
2.010 Modeling, Dynamics and Control III  
Spring 2002

Problem Set #1

**DUE** Thursday, February 14, 2002

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Problem 1.

For each of the following systems , identify:

- a) The engineering or customer goal of the control system
- b) A measure of *good* performance
- c) The Output variable
- d) The Reference input
- e) The Plant and Actuator
- f) The Measurement
- g) The Disturbance(s)

If you don't know how the systems work, take an educated guess, keeping in mind the function of each part of the system.

- Water closet (the water tank on a toilet)
- A refrigerator in your kitchen
- Shower mixing valve
- An industrial robot carrying a spot weld gun working along a car assembly line
- The iris of your eye

Problem 2. Nise Problem 1.3

Problem 3. Nise Problem 1.5

## DIAGNOSTIC

### Problem 4.

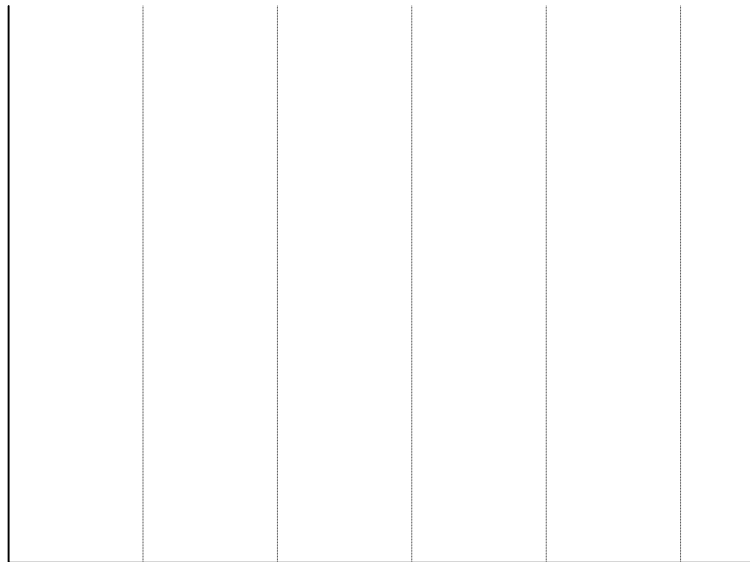
The next two problems are intended to be "diagnostic" and to assess your prior understanding of linear dynamic systems. They will not be graded, but they must be attempted. Please feel free to comment on what deficiencies you feel you have in trying to answer the questions.

Assume that the temperature of your room is related to the heat output from the radiator by the equation:

$$180 \frac{dT}{dt} + 3T = 10Q_{in}$$

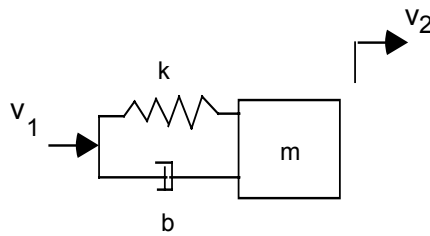
Where  $T$  is the temperature in deg. C. and  $Q_{in}$  is the heat input in Watts

- What is the time constant  $\tau$  of the system?
- What is the steady - state gain ( $K$ ) of the system?
- What is the Transfer Function  $T(s)/Q_{in}(s)$  for this system?
- Sketch a plot of how the temperature will change with time if the initial temperature  $T(0) = 0$  and  $Q_{in}$  is changed from 0 to 1 at  $t=0$  ( a step input) showing the exact output values at  $= 1\tau, 2\tau, 3\tau,$  and  $4\tau$ .



Problem 5.

The system shown below represents a simple model of a car suspension.



For this system:

a) Derive the equations of motion assuming the velocity  $v_1$  is the input, and velocity  $v_2$  is the output

b) Find the transfer function relating the input to the output:

$$G(s) = \frac{Y(s)}{U(s)}$$

c) For the following system parameter:

spring constant	$k = 400 \text{ N/m}$
mass	$m = 1 \text{ Kg}$
damping	$b = 300 \text{ N/m/sec}$

What is the natural frequency  $\omega_n$  of this system?

What is the damping ratio  $\zeta$ ?

What is the *approximate* 2% settling time to a step input?

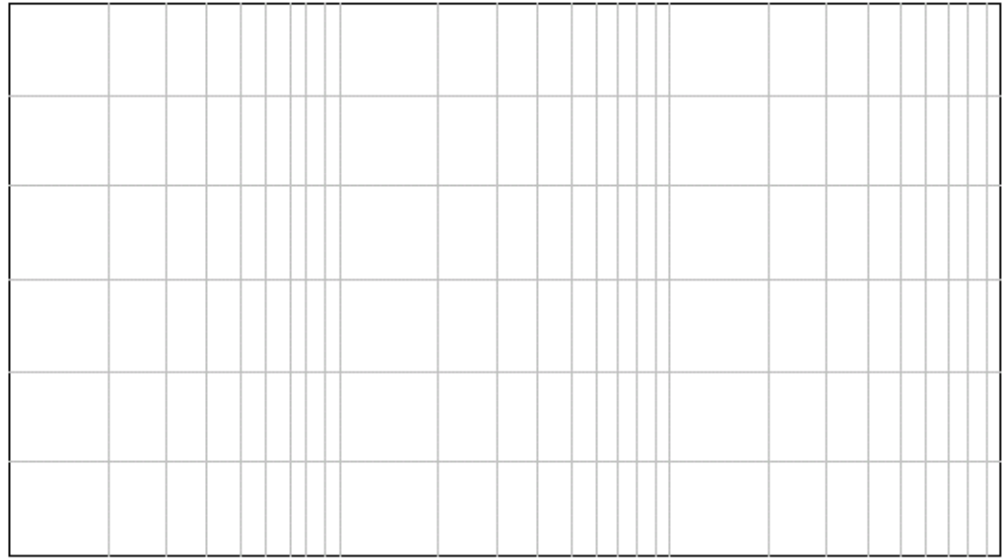
d) Sketch the step response of the system.

e) On an s-plane, plot the poles and zeros of  $G(s)$ .

f) Sketch a Bode Diagram for  $G(j\omega)$  on the attached paper

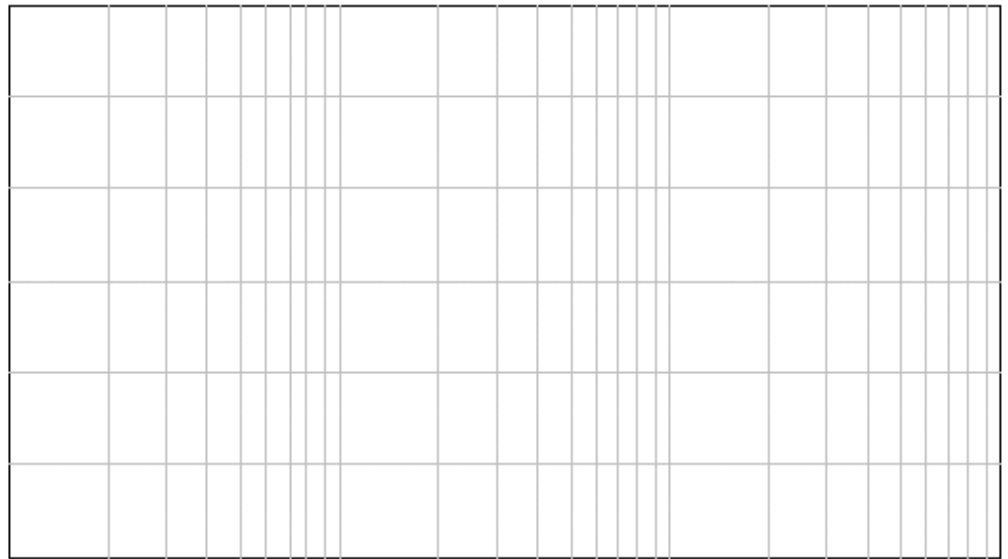
h) What is the resonant frequency?

Magnitude



Frequency

Phase



Frequency