



2.29 Class Project | Thursday, May 16th

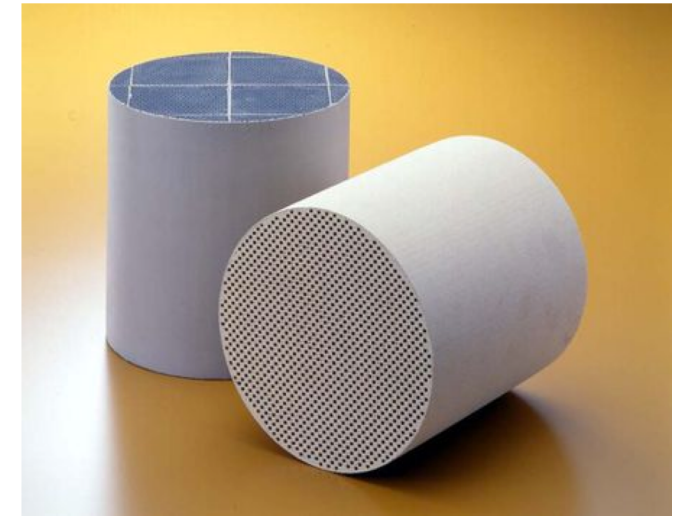
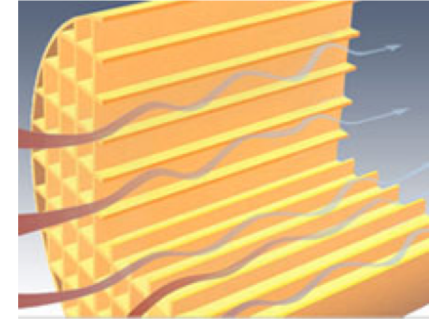
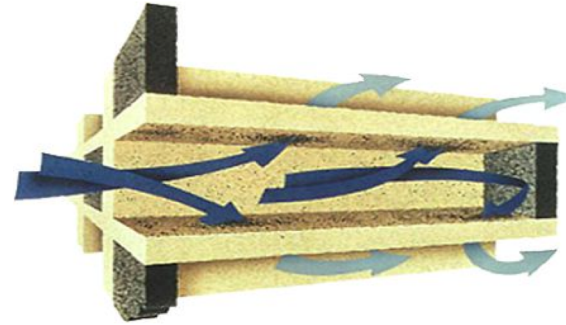
Solving Stiff Problems in Flow Thorough Catalysts

Flow through catalysts

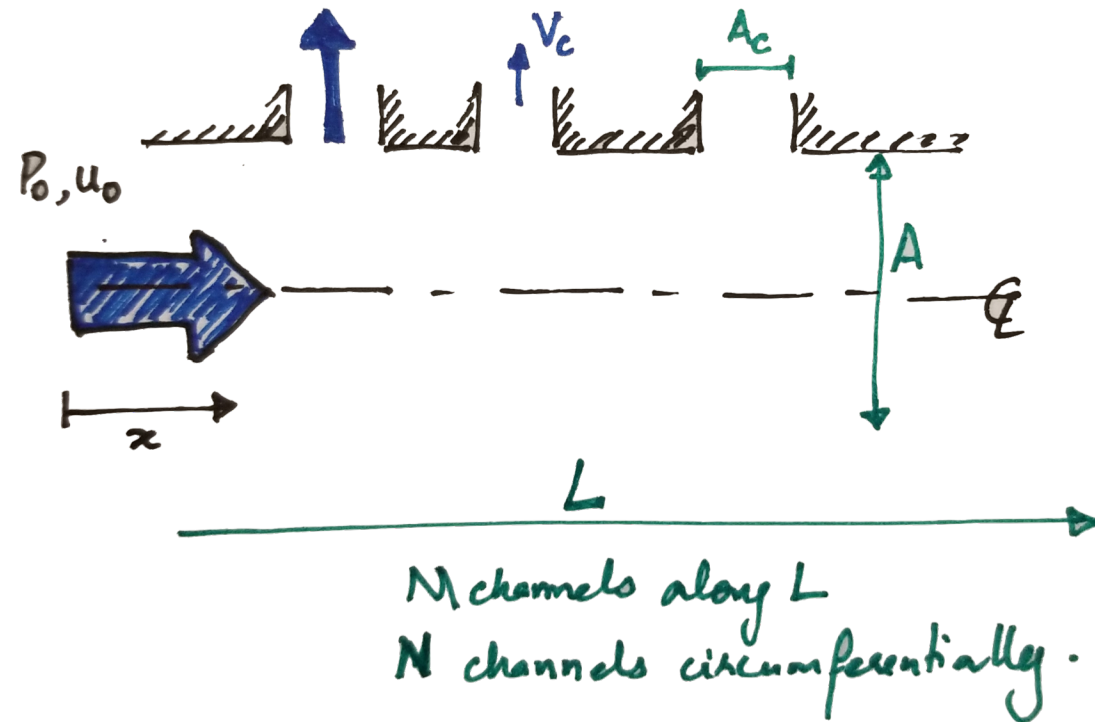
Selective Catalytic Reduction reduces NO_x emissions in diesel engines by 98%

Important to understand the flow in the catalyst to be able to:

- estimate the performance of the catalyst
- estimate the pressure drop induced by the catalyst



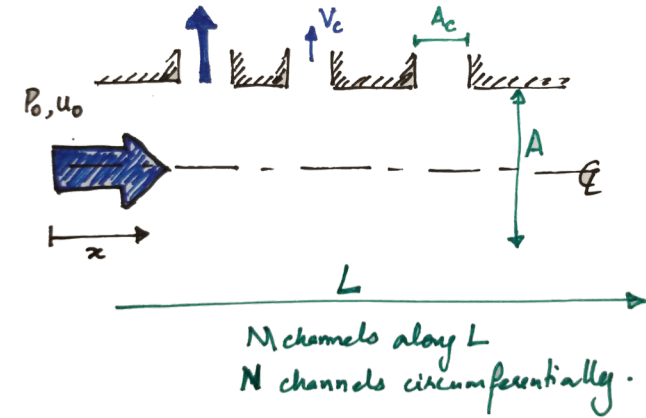
Simplified problem – “perforated pipe problem”



Derivation of equations

- Mass Conservation

$$v_c = \frac{-AL}{A_c NM} \frac{du}{dx}$$



- Momentum

$$\frac{1}{\rho} \frac{dP}{dx} + \frac{f_D}{2D_h} u^2 \left(1 - \frac{a_c M}{L} \right) + u \frac{du}{dx} (2 - \beta) = 0$$

- Reacting channels

$$P(x) - P_{amb} = \frac{1}{2} \rho \xi v_c^2$$

$$P(x) - P_{amb} = \frac{1}{2} \rho \xi \left(\frac{AL}{A_c NM} \right)^2 \left(\frac{du}{dx} \right)^2$$



Set-up governing equation

$$U = \frac{u}{u_0}$$

$$X = \frac{x}{L}$$

$$\bar{A} = \frac{A_c N M}{A}$$

$$B = \frac{2 - \beta}{\xi}$$

$$F = \frac{f_D L}{2 D_h \xi}$$


$$\bar{L} = 1 - \frac{a_c M}{L}$$

$$\xi \frac{A L}{A_c N M} \frac{du}{dx} \frac{d^2 u}{dx^2} + \frac{f_D}{2 D_h} u^2 \left(1 - \frac{a_c M}{L} \right) + u \frac{du}{dx} (2 - \beta) = 0$$

$$\frac{dU}{dX} \left(\frac{d^2 U}{dX^2} \right) + (B \bar{A}) U \frac{dU}{dX} + (F \bar{A} \bar{L}) U^2 = 0$$



Fixed Point iteration to solve the non-linear system



Non-linear solve using fixed point iteration

$$\frac{dU}{dX} \left(\frac{d^2U}{dX^2} \right) + (B\bar{A})U \frac{dU}{dX} + (F\bar{A}\bar{L})U^2 = 0$$

$$\frac{dU}{dX} = \frac{U_{i+1} - U_{i-1}}{2\Delta X} \qquad \frac{d^2U}{dX^2} = \frac{U_{i+1} - 2U_i + U_{i-1}}{(\Delta X)^2}$$



Non-linear solve using fixed point iteration

$$\frac{dU}{dX} \left(\frac{d^2U}{dX^2} \right) + (B\bar{A})U \frac{dU}{dX} + (F\bar{A}\bar{L})U^2 = 0$$

$$\vec{X} = \begin{bmatrix} U_1 \\ U_2 \\ \vdots \\ U_m \end{bmatrix}$$

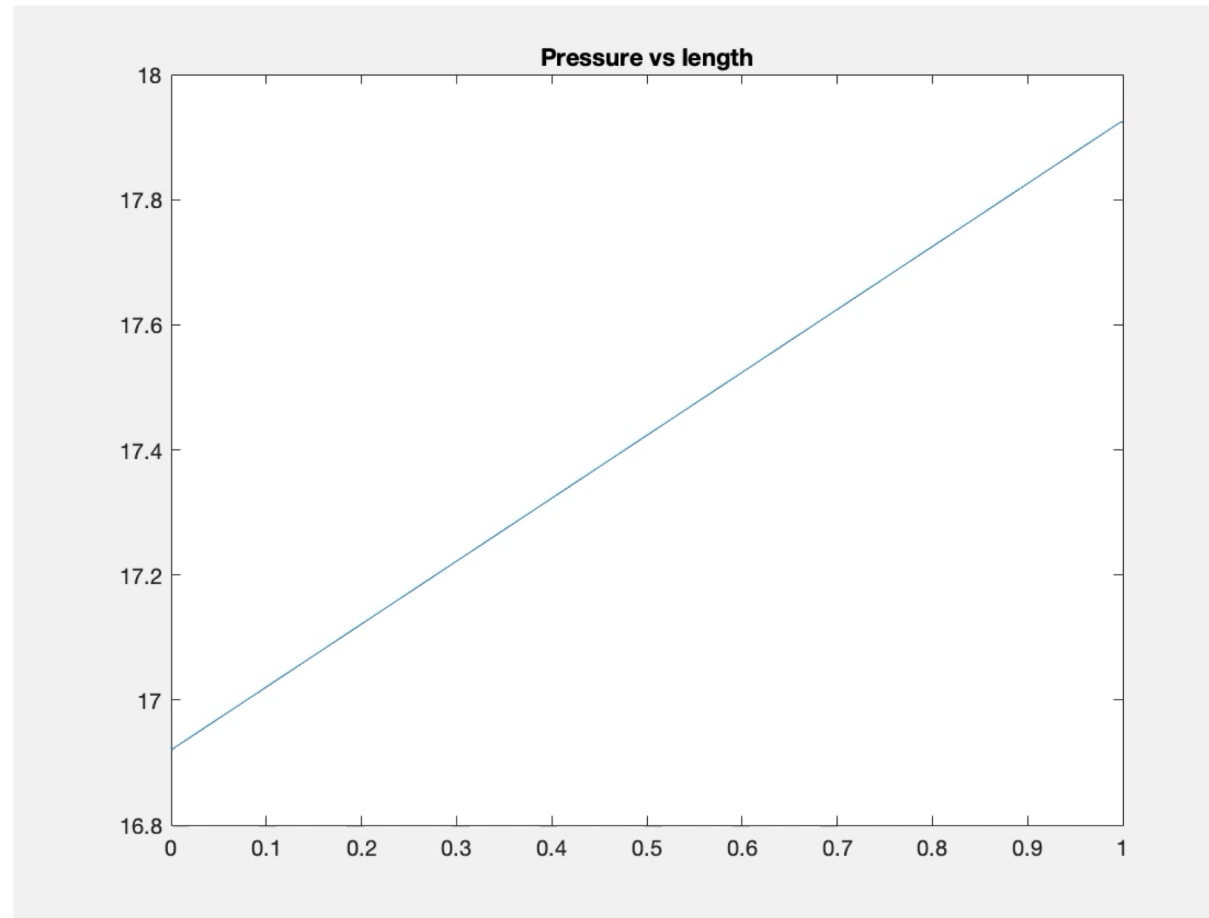
$$\vec{F}(X) = \begin{bmatrix} f_1 \\ f_2 \\ \vdots \\ f_m \end{bmatrix}$$

$$\vec{G}(\vec{X}) = \vec{X} + \vec{F}(\vec{X})$$

$$\vec{G}(\vec{X}_e) = \vec{X}_e$$



BUT....



Stiff Problem – Stiff ODE solver

*“A stiff equation is a differential equation for which certain numerical methods for solving the equation are **numerically unstable**, unless the **step size** is taken to be **extremely small**. It has proven difficult to formulate a precise definition of stiffness, but the main idea is that the equation includes **some terms** that can lead to **rapid variation in the solution**.”*



Stiff Problem – Stiff ODE solver

Commonly seen in chemistry – different reaction rates for different species involves many different time scales and this makes the problem stiff.

E.g. Global Chemistry – Transport models (GEOSChem) have very fast (~min) to very slow (~months) reactions. Packages like KPP (**Kinetic PreProcessor**) are used to solve them.

Stiff solvers use the Jacobian matrix to estimate the function behavior



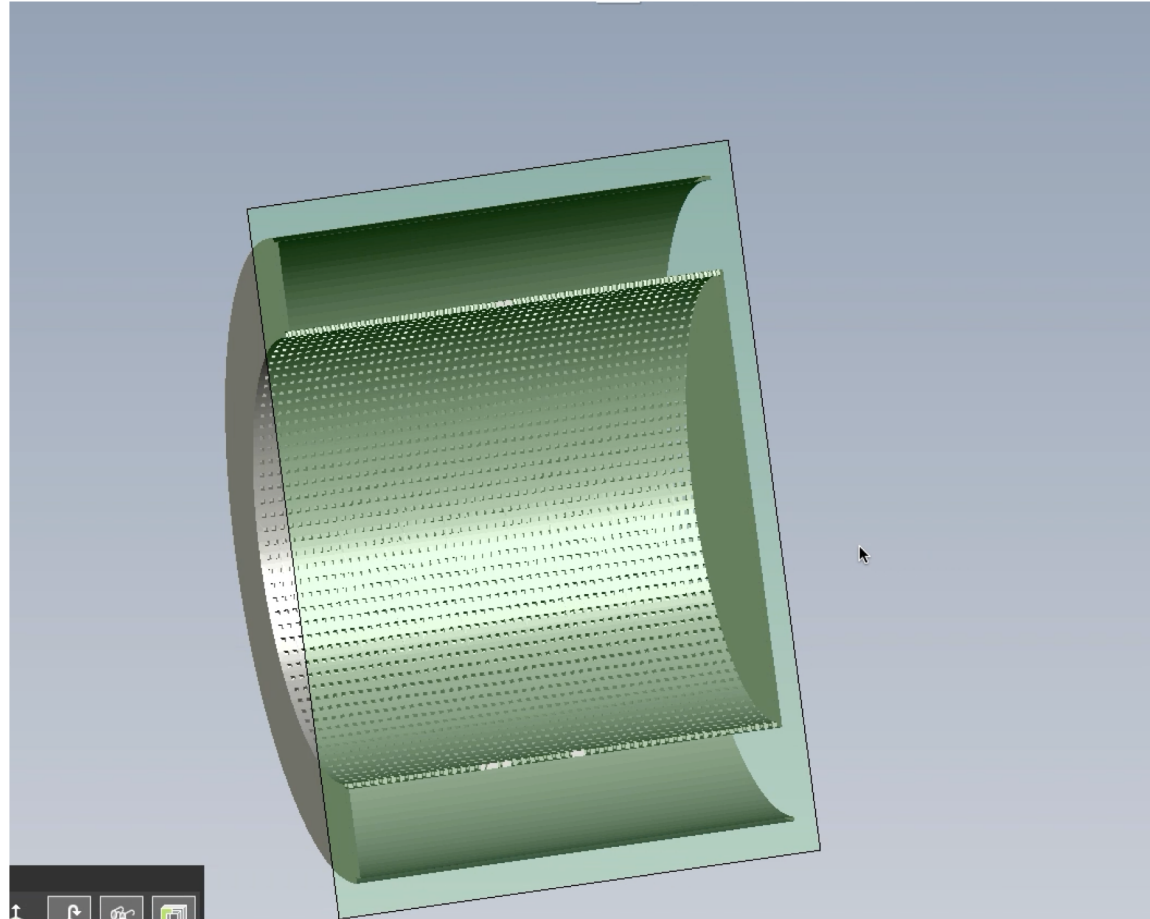
ANSYS Fluent

Use a CFD package to solve – ANSYS fluent

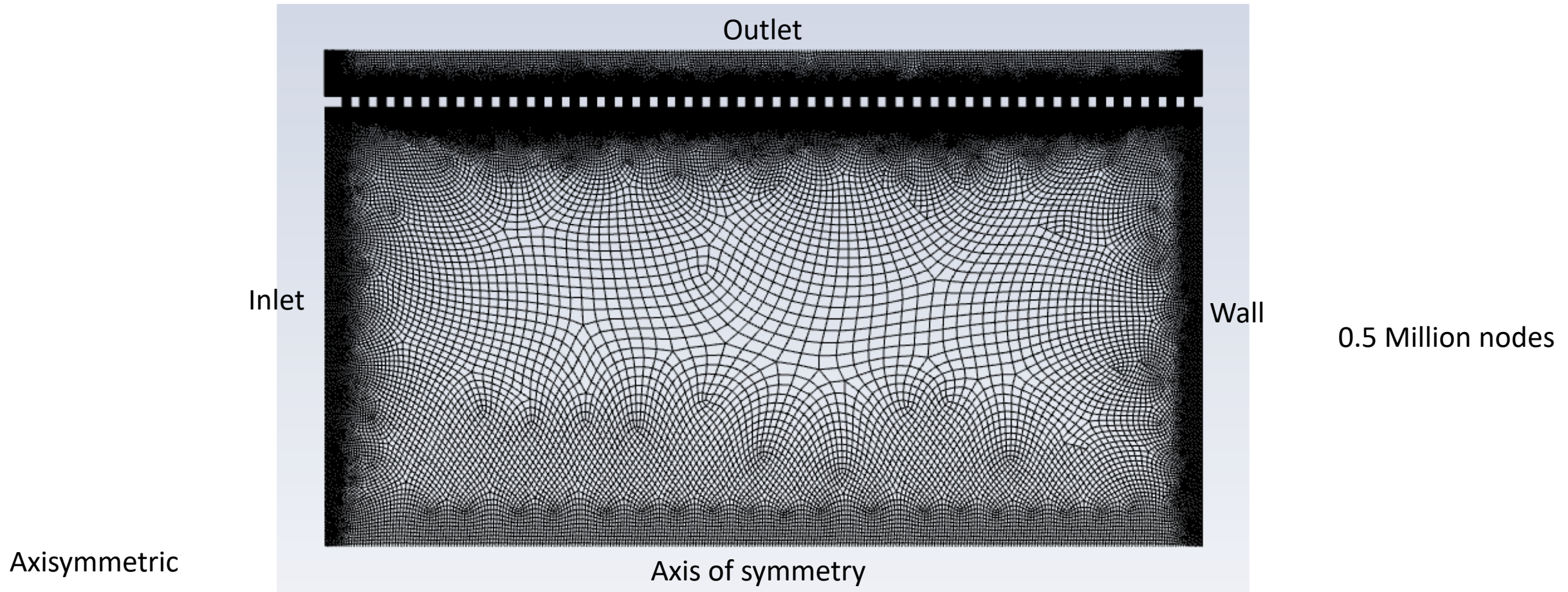
- Pressure based solver used
 - Energy Equation, S-A turbulence model
- Velocity formulation
 - Relative velocity formulation used since most of the fluid is moving
- PISO vs Coupled algorithm
 - PISO – segregated algorithm (similar to the pressure correction methods we saw in class)
 - Coupled – solves both momentum and continuity together (faster convergence)



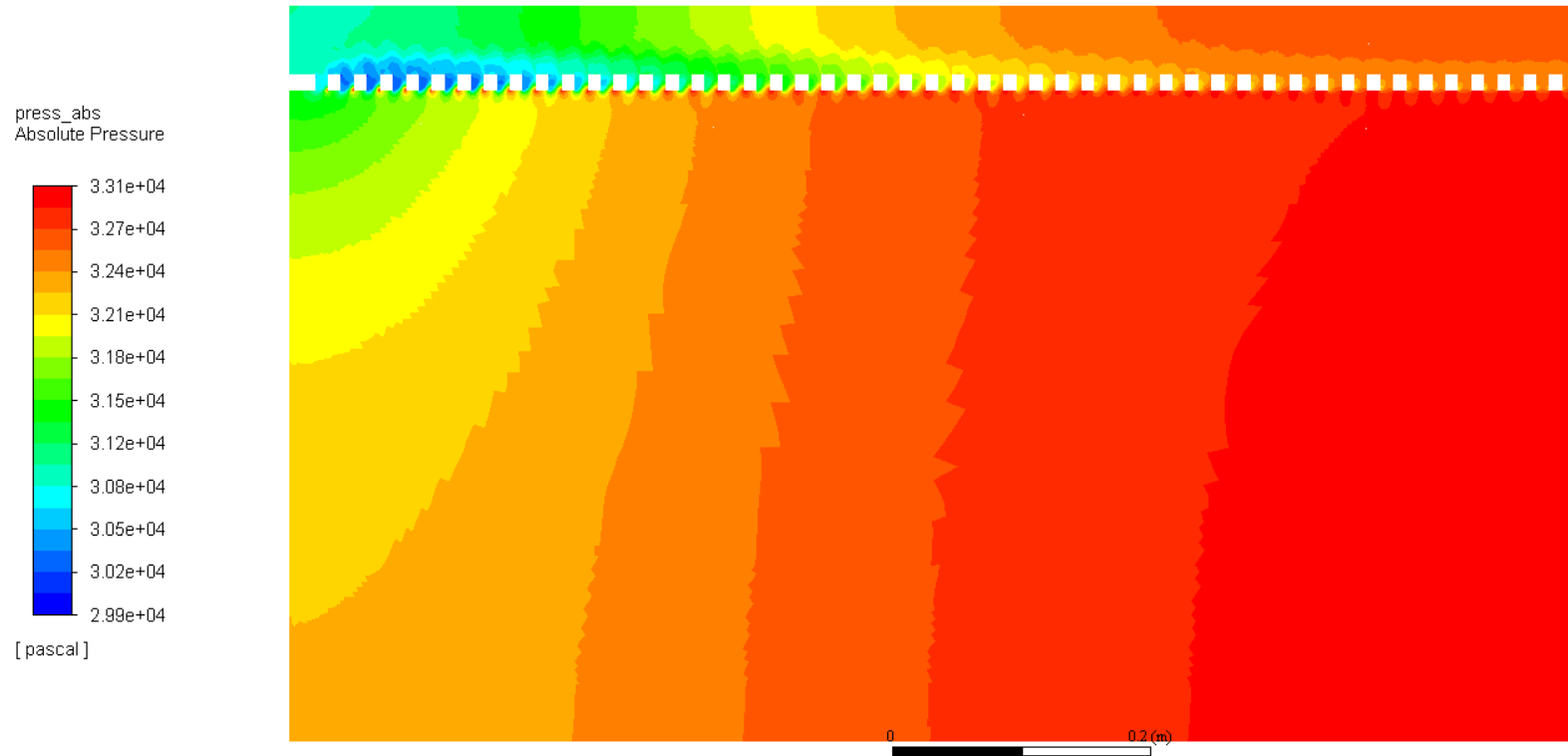
Catalyst 3D geometry



Simplified 2D geometry



Simplified 2D geometry



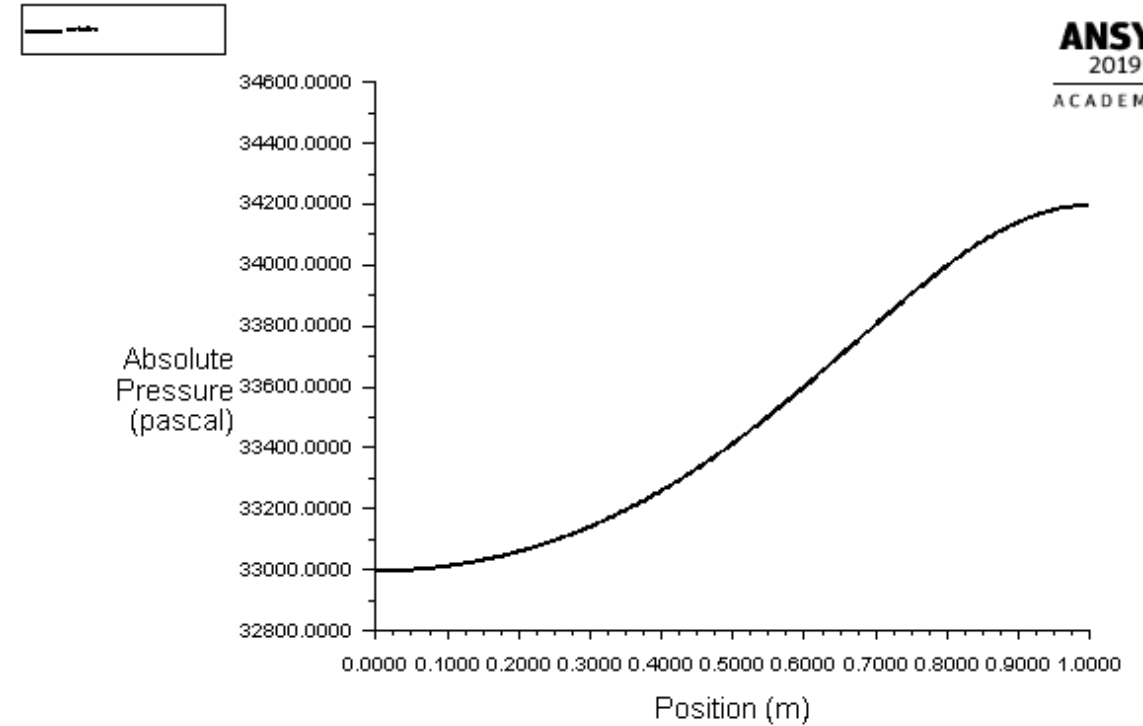
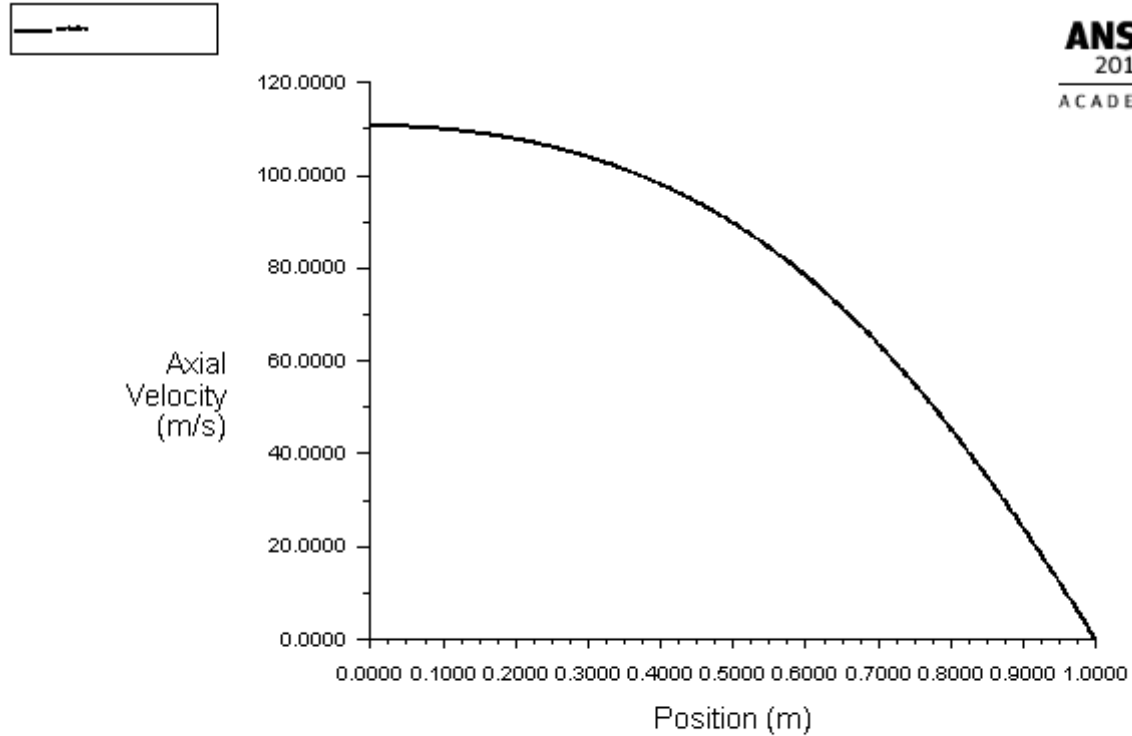
ANSYS
2019 R1
ACADEMIC

Contours of Absolute Pressure (pascal) (Time=3.0010e+00)

May 16, 2019
ANSYS Fluent 2019 R1 (axi, dp, pbns, S-A, transient)



Centerline velocity and pressure



Using a stiff solver

Solving the governing equations using a Stiff Solver

- MATLAB ode15s
- Convert eqns to system of first order ODEs

$$\frac{dU}{dX} \left(\frac{d^2U}{dX^2} \right) + (B\bar{A})U \frac{dU}{dX} + (F\bar{A}\bar{L})U^2 = 0$$

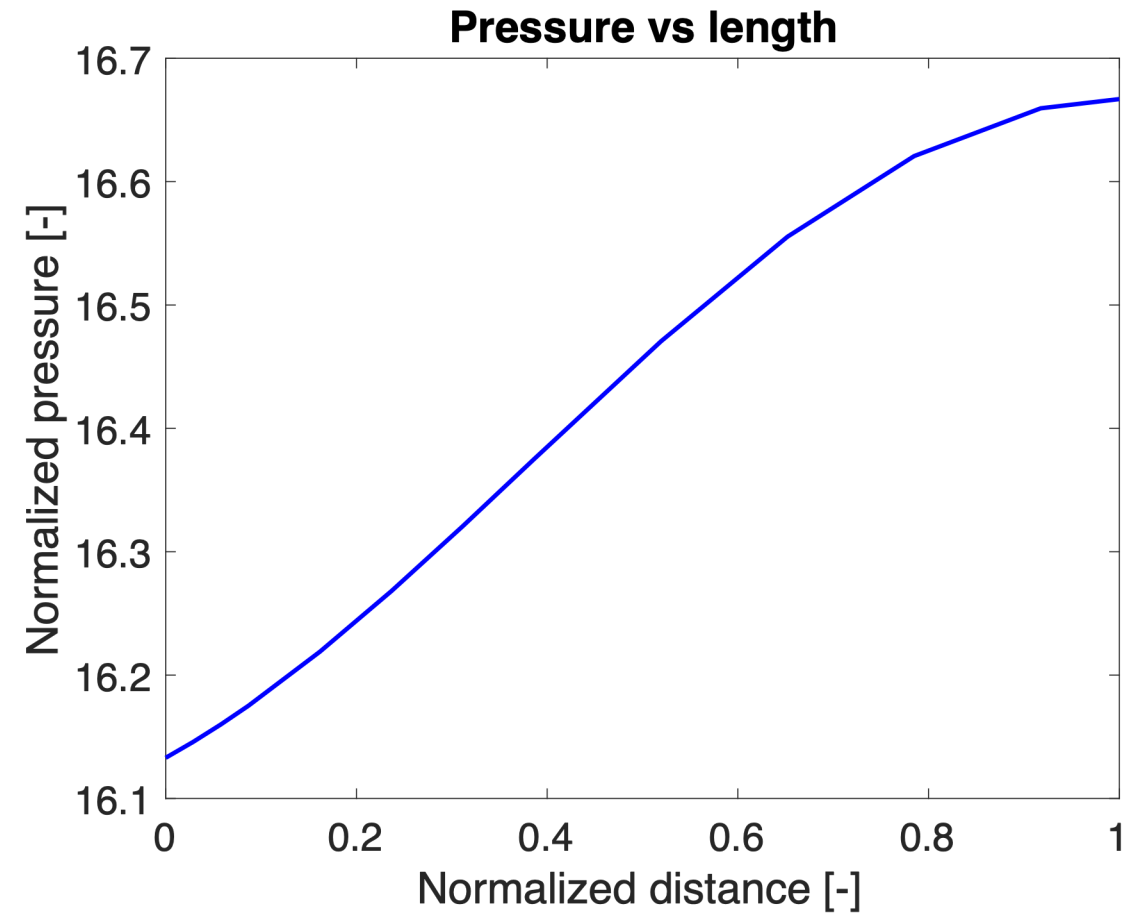
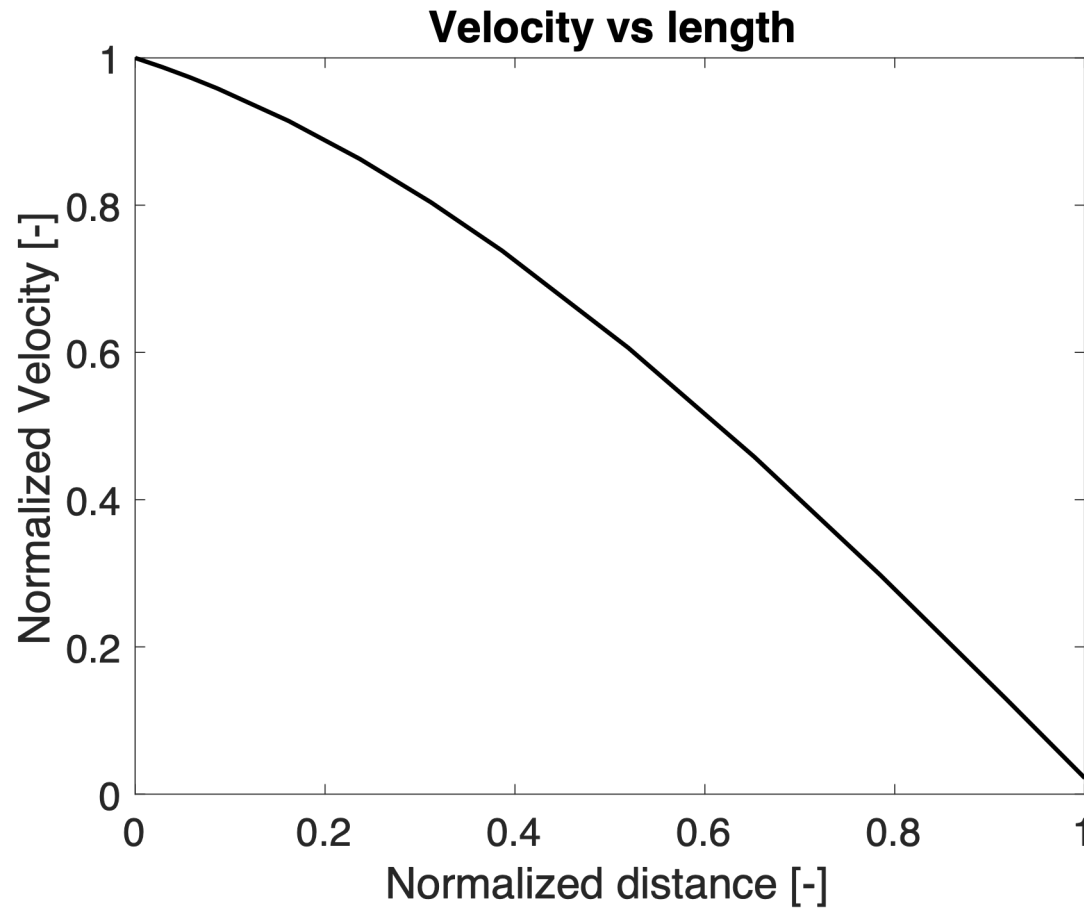
Let $y_1 = U$

$$y_1' = y_2$$

$$y_2' = -(BA)y_1 - (FAL)y_1^2/y_2$$

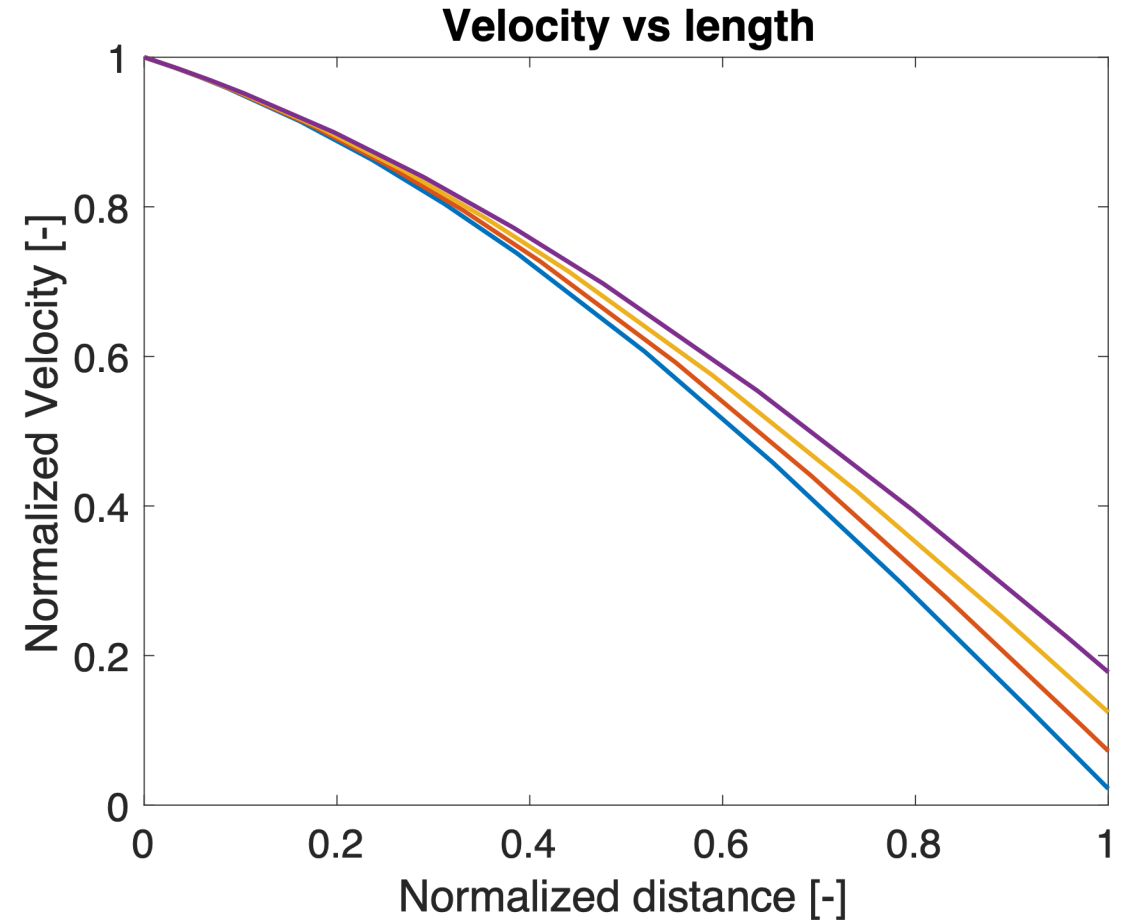
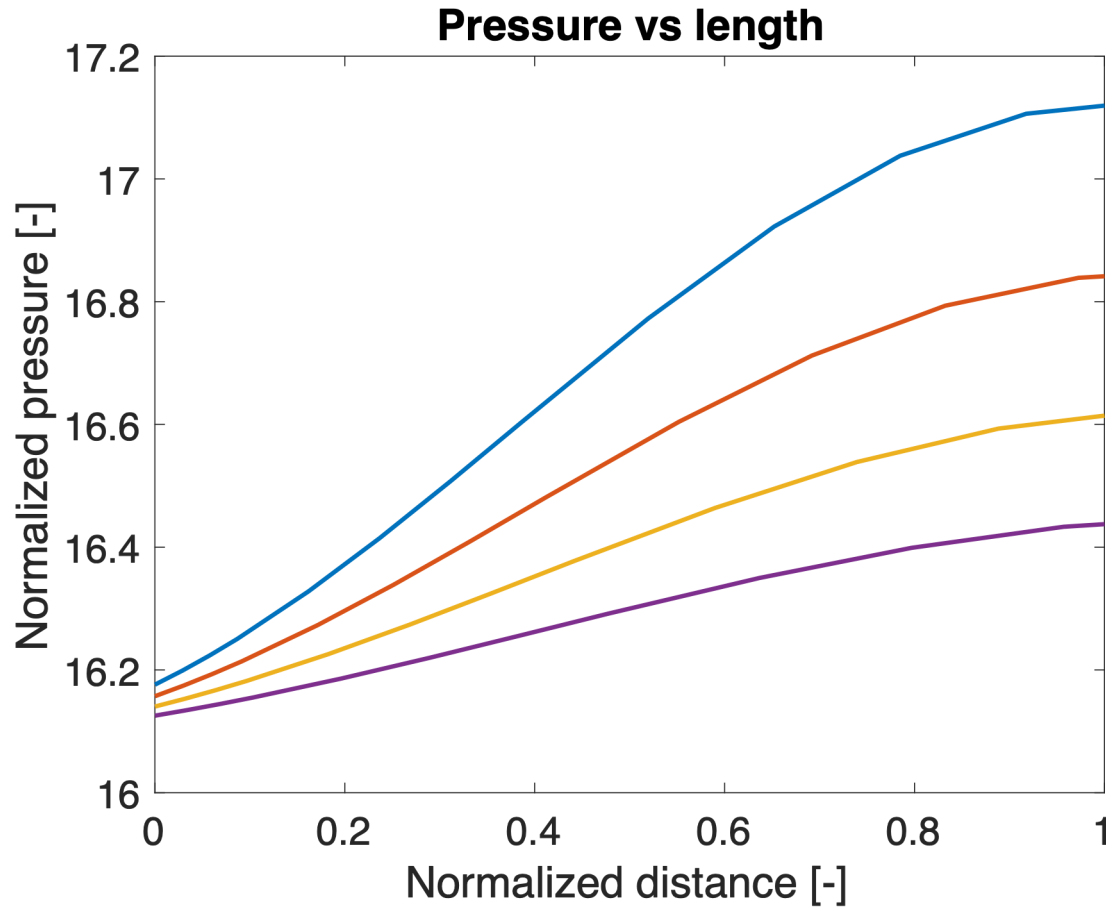


Velocity and Pressure along centerline



Can be used to study effects of different design choices:

E.g : Varying effective exit area



Questions

