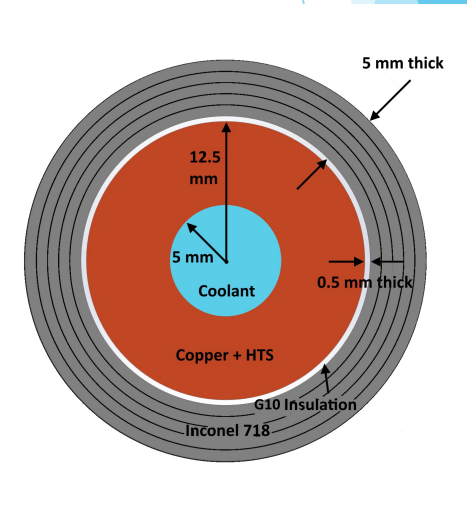
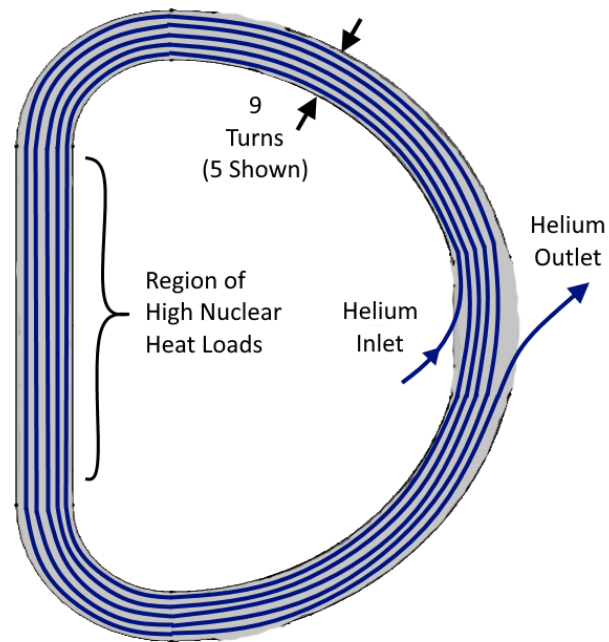
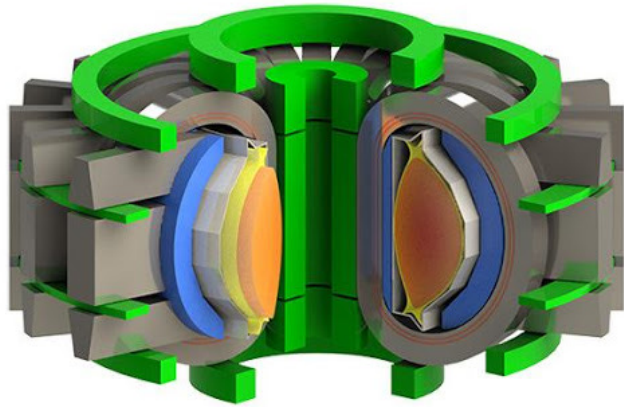
The background features abstract, overlapping geometric shapes in various shades of blue, ranging from light sky blue to deep navy blue. These shapes are primarily located on the left and right sides of the slide, framing the central white area where the text is placed.

Investigation into Numerical Stability for the simulation of supercritical helium flows in superconducting magnets

Ben Hamilton

What and Why

- ▶ Supercritical helium is used to maintain superconducting magnets cold enough to sustain large electrical currents without loss
- ▶ Fusion systems require these magnets to confine their plasma



Supercritical Fluid

▶ Ideal Gas

- ▶ Simple, algebraic equation of state
- ▶ Compressible flow
- ▶ Constant transport properties
- ▶ Coupling of energy, momentum, mass equations that may be non-linear but are entirely algebraic

▶ Incompressible Fluid

- ▶ No change in density
- ▶ Divergence-free velocity field
- ▶ Energy equations decoupled from momentum equations

▶ Supercritical fluid

- ▶ Equation of state complicated
- ▶ Large relative changes in properties with temperature
- ▶ Full coupling of energy, momentum and mass equations with possibly non-algebraic relations (worse than non-linear!)

Governing Equations for a 1-D flow

▶ Mass

$$-\frac{\partial \rho}{\partial t} = \rho \frac{\partial v}{\partial x} + v \frac{\partial \rho}{\partial x}$$

▶ Momentum

$$\frac{\partial v}{\partial t} = -v \frac{\partial v}{\partial x} - \frac{1}{\rho} \frac{\partial p}{\partial x} - \frac{fv|v|}{2D_h}$$

▶ Energy

$$\frac{\partial h}{\partial t} = -v \frac{\partial h}{\partial x} - \frac{3v^2}{2} \frac{\partial v}{\partial x} - \frac{v^3}{2\rho} \frac{\partial \rho}{\partial x} + \frac{1}{\rho A} \frac{\partial q}{\partial x}$$

▶ Also

$$p = p(h, \rho) \quad \frac{\partial q}{\partial x} = g(T, \rho, v, \mu, \text{Pr})$$
$$T = T(h, \rho) \quad f = f(\rho, v, \mu, D_h)$$

Boundary Conditions:

$$p(0, t) = p_0$$

$$\begin{cases} T(0, t) = T_0 & v(0, t) > 0 \\ \frac{\partial T}{\partial x(0, t)} = 0 & v(0, t) < 0 \end{cases}$$

$$p(L, t) = p_e$$

$$\frac{\partial T}{\partial x(L, t)} = 0$$

Initial Conditions:

$$T(x, 0) = T_0$$

$$p(x, 0) = \frac{x}{L} p_e + \left(1 - \frac{x}{L}\right) p_0$$

Original Solution Method

- ▶ All spatial derivatives are 2nd order centered space (except at boundaries)
- ▶ FTCS method for the advection equation are unstable without adequate diffusion, so need at least semi-implicit method:
 - ▶ System is non-linear, and not all equations are known algebraic functions. So we need an iterative method
 - ▶ Jacobi's method with modified SUR for implicit time scheme (1st order convergence)
- ▶ Check the CFL condition

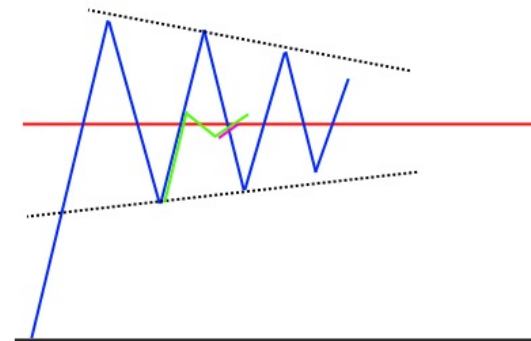
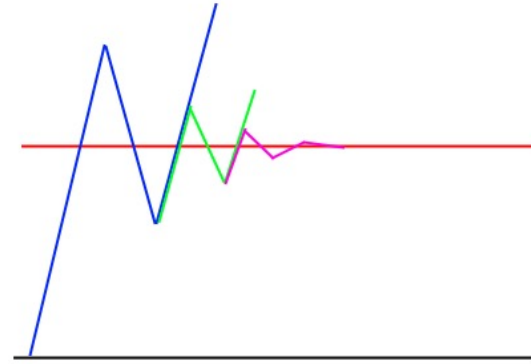
$$\frac{v_{\max} \Delta t}{\Delta x} = \frac{20 \cdot 0.001}{0.2} = 0.1$$

Modified SUR

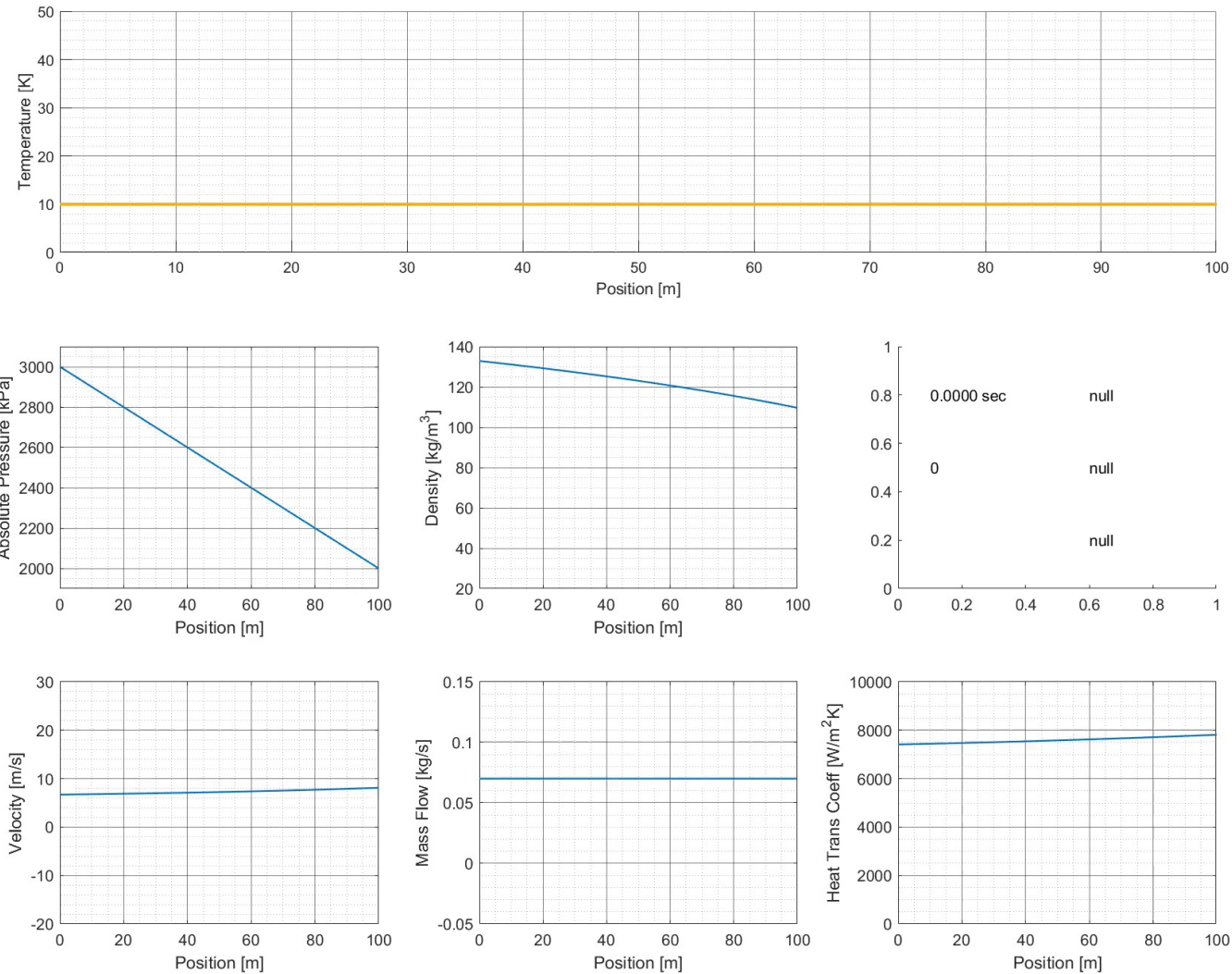
- ▶ Goal of successive relaxation is to reduce spectral radius of B (reduce impact of minor variations blowing up) with the parameter w
 - ▶ $w \sim 1$: Nearly a full step, but spectral radius of B may be too large and solution blows up
 - ▶ w small: Slight increment to final solution, many iterations, long solution time.
 - ▶ How can we balance the two?

Modified SUR

- ▶ Start with $w \sim 1$
 - ▶ If the solution starts to get worse, cut w by a factor (0.5)
 - ▶ Slowly increase w by another factor each step (about 1.05) to help rate of convergence
- ▶ If solution converging slowly (i.e. due to oscillations)
 - ▶ Cut w by a factor (0.5)
- ▶ Algorithm may get too aggressive in reducing w , so stop when w reaches a certain min value and call it a loss
 - ▶ Goal is to tune these parameters to achieve convergence at almost all time steps



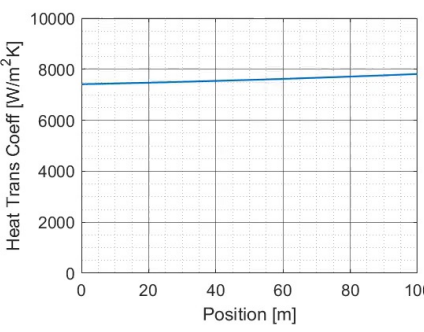
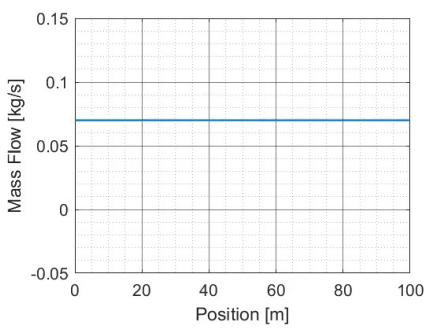
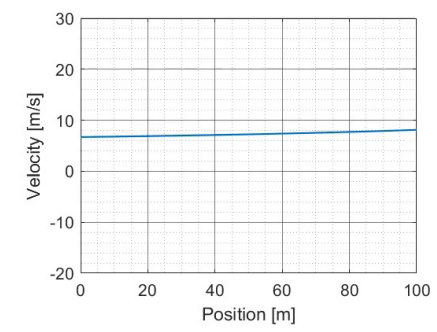
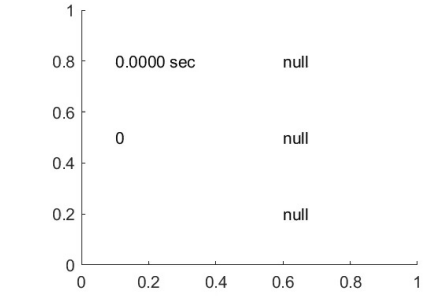
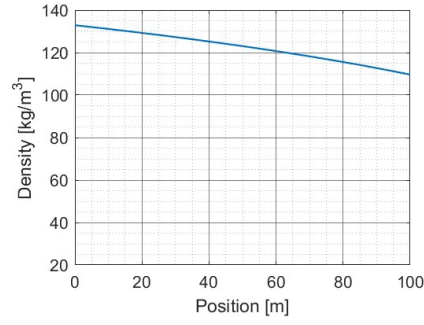
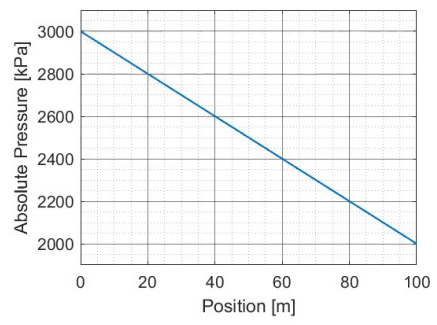
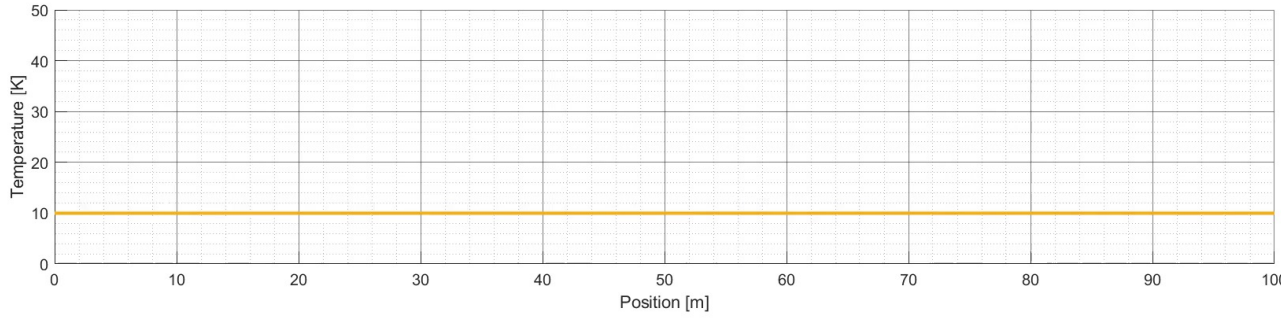
Original Solution



Improved Scheme: C-N

- ▶ The solution method is an iterative implicit method, so we get knowledge of the time derivatives at step k as well as at step $k+1$ without any additional computation.
- ▶ Implement the C-N scheme for 2nd order time accuracy
 - ▶ Is it stable? The equations are non-linear so von-Neumann analysis makes no promises
 - ▶ Unfortunately, it is not stable enough
 - ▶ Bug in code or simply need the diffusion from the purely implicit method

C-N Implementation



Final Thoughts

- ▶ Highly coupled non-linear system of PDEs, even in 1 spatial dimension, is difficult to solve
 - ▶ Needed implicit method for advection instability
 - ▶ Needed small time steps to ensure stability from non-linear terms
- ▶ Use Jacobi's method with a modified relaxation method to solve
 - ▶ Why not a root-finding algorithm? Time. The jacobian matrix (or even its estimate using FD) was neither sparse nor small.
 - ▶ Ease of handling changing boundary conditions
 - ▶ SUR method tunable to get best chance of stability
- ▶ Future work
 - ▶ Implement faster convergence method
 - ▶ Improve the C-N scheme so that it is stable

Questions?

