

What is a

"Point Group"?

# Point Group Definition

- A classification scheme for finite objects (molecules)
- Molecules having the same set of symmetry elements/operations “belong to” the same point group
- Point groups have labels we will learn
- We will use the Schoenflies notation (spectroscopy) rather than the Hermann-Mauguin notation (crystallography)

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# Types of Point Groups

Labels are the Schoenflies symbols: here are six limiting symmetry types

- High symmetry, multiple higher-order ( $n > 2$ ) rotation axes.  
Examples:  $T_d$ ,  $I_h$ ,  $O_h$
- Low symmetry, only the identity or that plus only a single mirror plane or an inversion center:  $C_1$ ,  $C_s$ ,  $C_i$
- Linear molecules:  $C_{\infty v}$ ,  $D_{\infty h}$
- C groups:  $C_{nv}$ ,  $C_{nh}$ ,  $C_n$
- D groups:  $D_{nd}$ ,  $D_{nh}$ ,  $D_n$
- S groups:  $S_4$ ,  $S_6$ ,  $S_8$ , etc.; only operations present are based upon  $S_n$

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# Types of Point Groups

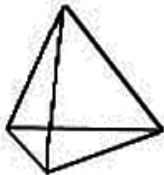
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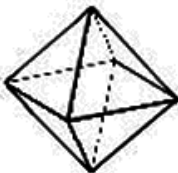


# The Platonic Solids: Polyhedra with Regular Polygon Faces

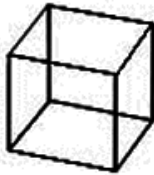
Symmetry lowered from the sphere, but still present are multiple higher-order axes



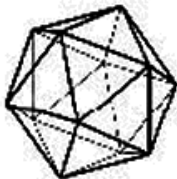
**Tetrahedron**



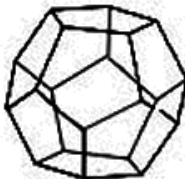
**Octahedron**



**Cube**



**Icosahedron**



**Dodecahedron**

# High Symmetry Groups

These have multiple higher order ( $n > 2$ ) rotation axes. Example:  $C_{60}$ , icosahedral

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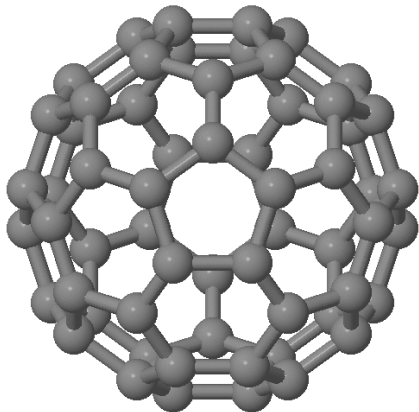
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Point Group =  $I_h$

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Element	Operation	Element	Operation
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Show All Proper

Show All Planes

Show All Improper

Inv ctr

$C_5$  axis

plane ( $\sigma$ )

$C_5$  axis

plane ( $\sigma$ )

$C_5$  axis

plane ( $\sigma$ )

$C_5$  axis

plane ( $\sigma$ )

$C_5$  axis

plane ( $\sigma$ )

$C_5$  axis

plane ( $\sigma$ )

$C_3$  axis

plane ( $\sigma$ )

$C_3$  axis

plane ( $\sigma$ )

$C_3$  axis

plane ( $\sigma$ )

$C_3$  axis

plane ( $\sigma$ )

$C_3$  axis

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plane ( $\sigma$ )

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$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

# High Symmetry Groups

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Home

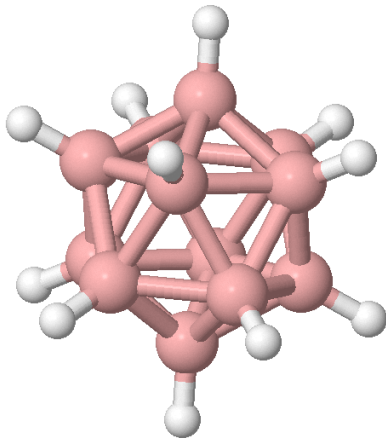
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Point Group =  $I_h$

JSmol

**Element Operation**

Show All Proper

Show All Improper

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_5$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

**Element Operation**

Show All Planes

inv ctr

plane ( $\sigma$ )

plane ( $\sigma$ )

plane ( $\sigma$ )

plane ( $\sigma$ )

plane ( $\sigma$ )

plane ( $\sigma$ )

plane ( $\sigma$ )

plane ( $\sigma$ )

plane ( $\sigma$ )

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plane ( $\sigma$ )

# High Symmetry Groups

The tetrahedron has four  $C_3$  axes but lacks inversion center

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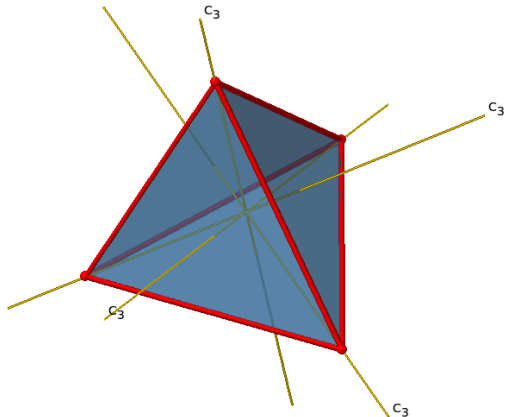
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## Element Operation

Show All Proper

$C_3$  axis

Rotate

$C_3$  axis

Rotate

$C_3$  axis

Rotate

$C_3$  axis

Rotate

$C_2$  axis

Rotate

$C_2$  axis

Rotate

$C_2$  axis

Rotate

$S_4$  axis

Rotate

$S_4$  axis

Rotate

$S_4$  axis

Rotate

## Element Operation

Show All Planes

plane ( $\sigma_d$ )

Reflect

plane ( $\sigma_d$ )

Reflect

plane ( $\sigma_d$ )

Reflect

plane ( $\sigma_d$ )

Reflect

plane ( $\sigma_d$ )

Reflect

plane ( $\sigma_d$ )

Reflect

Point Group =  $T_d$

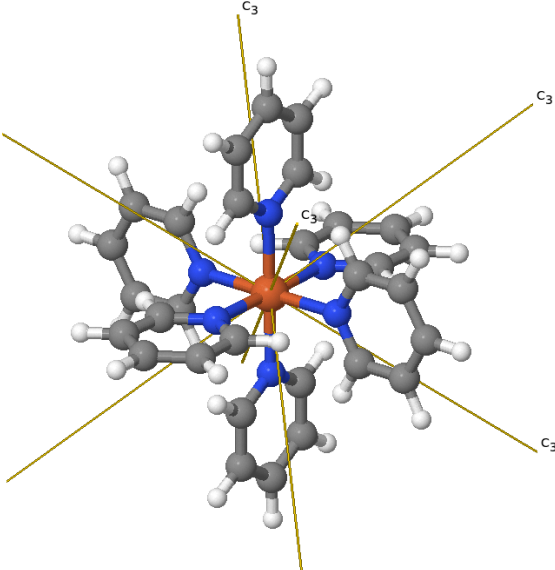
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# High Symmetry Groups

The group  $T_h$  has four  $C_3$  axes (through octahedral faces) and adds the inversion center

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Point Group =  $T_h$

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Element	Operation	Element	Operation
<input type="checkbox"/>	Show All Proper	<input type="checkbox"/>	Inv ctr <input type="button" value="Invert"/>
<input type="checkbox"/>	Show All Improper	<input type="checkbox"/>	plane ( $\sigma_h$ ) <input type="button" value="Reflect"/>
<input checked="" type="checkbox"/>	$C_3$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_h$ ) <input type="button" value="Reflect"/>
<input checked="" type="checkbox"/>	$C_3$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_h$ ) <input type="button" value="Reflect"/>
<input checked="" type="checkbox"/>	$C_3$ axis <input type="button" value="Rotate"/>		
<input checked="" type="checkbox"/>	$C_3$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$C_2$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$C_2$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$C_2$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$S_6$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$S_6$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$S_6$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$S_6$ axis <input type="button" value="Rotate"/>		

# High Symmetry Groups

The group  $T$  is a pure rotation group with no mirror planes or inversion centers

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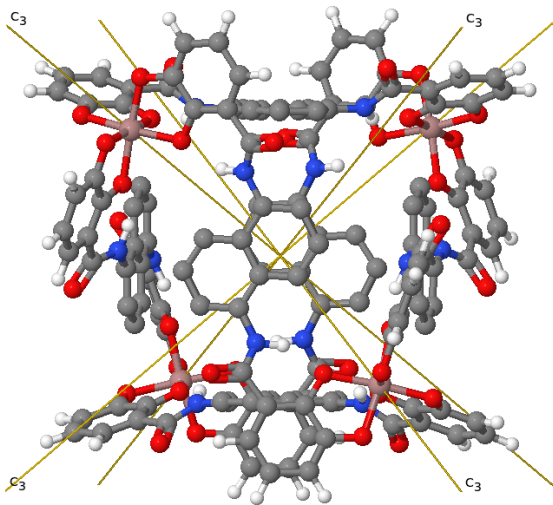
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## Element Operation

Show All Proper

$C_3$  axis

$C_3$  axis

$C_3$  axis

$C_3$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

Point Group =  $T$

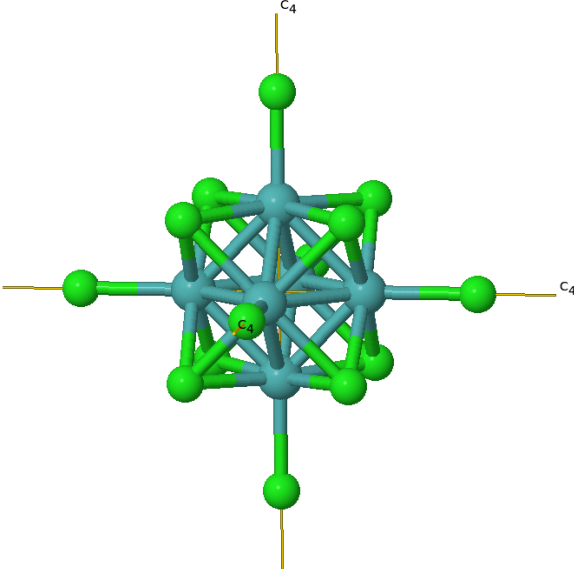
JSmol



# High Symmetry Groups

The group  $O_h$  has three  $C_4$  axes<sup>2</sup> and an inversion center:  $[\text{Mo}_6\text{Cl}_{14}]^{2-}$

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Point Group =  $O_h$

Element Operation

Element	Operation	Element	Operation
<input type="checkbox"/>	Show All Proper	<input type="checkbox"/>	Show All Planes
<input type="checkbox"/>	Show All Improper	<input type="checkbox"/>	inv ctr <input type="button" value="Invert"/>
<input checked="" type="checkbox"/>	$C_4$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_h$ ) <input type="button" value="Reflect"/>
<input checked="" type="checkbox"/>	$C_4$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_h$ ) <input type="button" value="Reflect"/>
<input checked="" type="checkbox"/>	$C_4$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_h$ ) <input type="button" value="Reflect"/>
<input type="checkbox"/>	$C_3$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_d$ ) <input type="button" value="Reflect"/>
<input type="checkbox"/>	$C_3$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_d$ ) <input type="button" value="Reflect"/>
<input type="checkbox"/>	$C_3$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_d$ ) <input type="button" value="Reflect"/>
<input type="checkbox"/>	$C_3$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_d$ ) <input type="button" value="Reflect"/>
<input type="checkbox"/>	$C_2$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_d$ ) <input type="button" value="Reflect"/>
<input type="checkbox"/>	$C_2$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_d$ ) <input type="button" value="Reflect"/>
<input type="checkbox"/>	$C_2$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_d$ ) <input type="button" value="Reflect"/>
<input type="checkbox"/>	$C_2$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_d$ ) <input type="button" value="Reflect"/>
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<input type="checkbox"/>	$C_2$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_d$ ) <input type="button" value="Reflect"/>
<input type="checkbox"/>	$C_2$ axis <input type="button" value="Rotate"/>	<input type="checkbox"/>	plane ( $\sigma_d$ ) <input type="button" value="Reflect"/>
<input type="checkbox"/>	$S_6$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$S_6$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$S_6$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$S_6$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$S_4$ axis <input type="button" value="Rotate"/>		
<input type="checkbox"/>	$S_4$ axis <input type="button" value="Rotate"/>		

Smol

# High Symmetry Groups

The group  $O_h$  has three  $C_4$  axes and an inversion center:  $SF_6$

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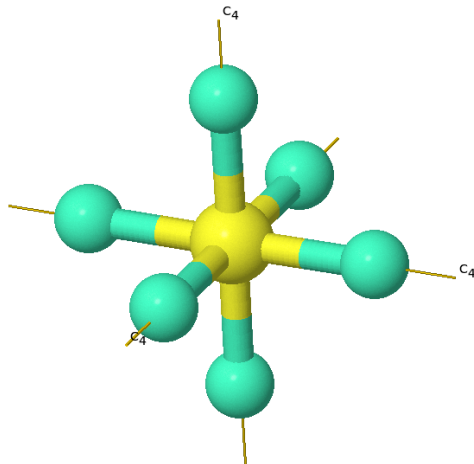
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Point Group =  $O_h$

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Element	Operation	Element	Operation
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Show All Proper

Show All Improper

$C_4$  axis

$C_4$  axis

$C_4$  axis

$C_3$  axis

$C_3$  axis

$C_3$  axis

$C_3$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

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$C_2$  axis

$C_2$  axis

$C_2$  axis

$C_2$  axis

$S_6$  axis

$S_6$  axis

$S_6$  axis

$S_6$  axis

$S_4$  axis

$S_4$  axis

Show All Planes

Inv ctr

plane ( $\sigma_h$ )

plane ( $\sigma_h$ )

plane ( $\sigma_h$ )

plane ( $\sigma_d$ )

plane ( $\sigma_d$ )

plane ( $\sigma_d$ )

plane ( $\sigma_d$ )

plane ( $\sigma_d$ )

plane ( $\sigma_d$ )

plane ( $\sigma_d$ )

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# Groups of Low Symmetry

The identity alone, or together with one mirror or an inversion center

- The identity only,  $C_1$
- The identity plus one mirror plane:  $C_s$
- The identity plus an inversion center:  $C_i$

# Groups of Low Symmetry

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# Groups of Low Symmetry

The identity alone, or together with one mirror or an inversion center

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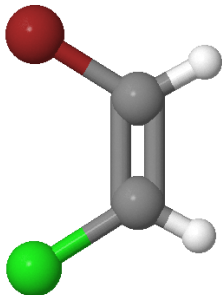
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Element Operation

plane ( $\sigma$ ) [Reflect](#)



Point Group =  $C_s$

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# Groups of Low Symmetry

The identity alone, or together with one mirror or an inversion center

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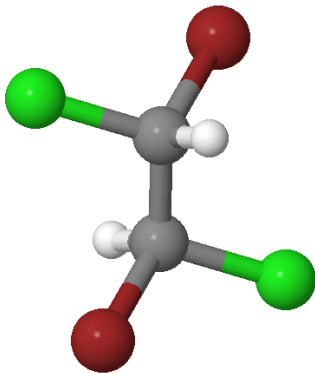
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Element Operation

inv ctr



Point Group =  $C_1$

JSmol



# Linear Molecules

Distinguish based upon presence or absence of  $\perp C_2$  axes

- A linear molecule has a  $C_\infty$  axis of rotation
- Nitrous oxide,  $N_2O$ ,  $N=N=O$ , the two ends are different so no  $C_2 \perp$  to the  $C_\infty$ , the point group assignment is  $C_{\infty v}$
- Carbon dioxide,  $CO_2$ ,  $O=C=O$ , the two ends are “symmetry related” and exchangeable by  $\perp C_2$  or by  $\sigma_h$  so the point group assignment is  $D_{\infty h}$
- In general,  $D$  groups have  $nC_2$  axes  $\perp$  to the  $C_n$  (single principal rotation axis)

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# Examples of $C$ groups

A single  $C_n$  plus  $n$  vertical mirror planes

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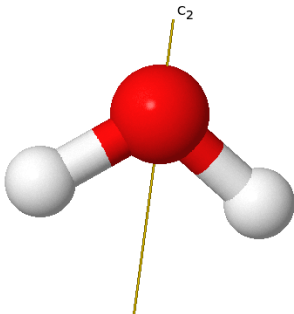
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Element Operation

$C_2$  axis

Rotate

Element Operation

plane ( $\sigma_{xz}$ )

Reflect

plane ( $\sigma_{yz}$ )

Reflect

Point Group =  $C_{2v}$

JSmol



# Examples of $C_n$ groups

A single  $C_n$  plus  $n$  vertical mirror planes

Home

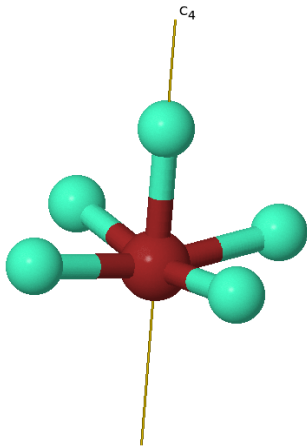
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**Element**   **Operation**

$C_4$  axis   [Rotate](#)

$C_2$  axis   [Rotate](#)

**Element**   **Operation**

Show All Planes

plane ( $\sigma_v$ )   [Reflect](#)

plane ( $\sigma_v$ )   [Reflect](#)

plane ( $\sigma_d$ )   [Reflect](#)

plane ( $\sigma_d$ )   [Reflect](#)

Point Group =  $C_{4v}$

JSmol



# Examples of $C$ groups

A single  $C_n$  plus a horizontal mirror plane

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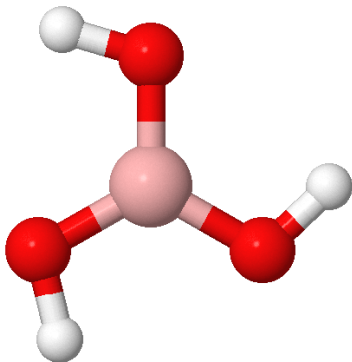
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**Element**   **Operation**

$C_3$  axis

Rotate

**Element**   **Operation**

plane ( $\sigma_h$ )

Reflect

$S_3$  axis

Rotate

Point Group =  $C_{3h}$

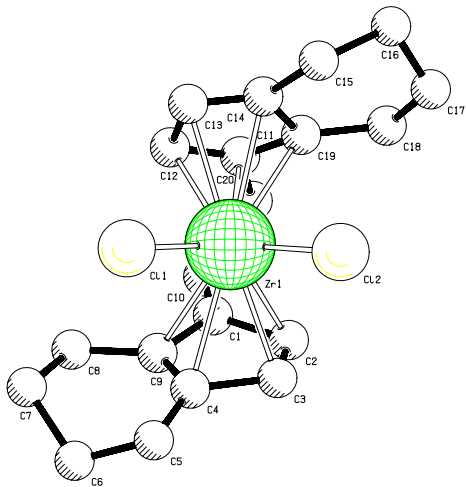
JSmol





# Examples of $C$ groups

A single  $C_2$  with no mirror planes: *ansa* metallocene example of point group  $C_2$



# Examples of $D$ groups

$D_{nh}$  has  $n$   $C_2 \perp$  to the  $C_n$ , plus a  $\sigma_h$

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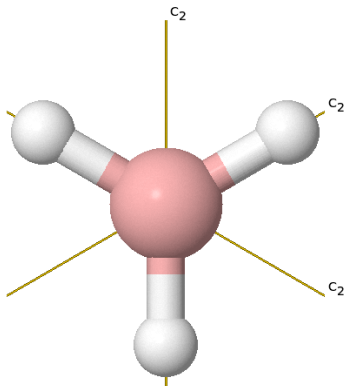
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**Element** **Operation**

Show All Proper

$C_3$  axis

Rotate

$C_2$ ' axis

Rotate

$C_2$ ' axis

Rotate

$C_2$ ' axis

Rotate

$S_3$  axis

Rotate

**Element** **Operation**

Show All Planes

plane ( $\sigma_h$ )

Reflect

plane ( $\sigma_v$ )

Reflect

plane ( $\sigma_v$ )

Reflect

plane ( $\sigma_v$ )

Reflect

Point Group =  $D_{3h}$

JSmol



# Examples of $D$ groups

$D_{nh}$  has  $n$   $C_2 \perp$  to the  $C_n$ , plus a  $\sigma_h$

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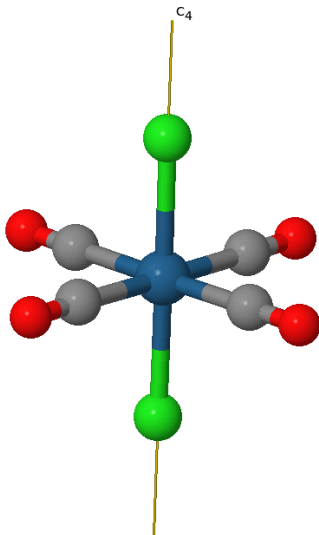
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**Element** **Operation**

Show All Proper

$C_4$  axis

$C_2$  axis

$C_2'$  axis

$C_2''$  axis

$C_2'''$  axis

$C_2''''$  axis

$S_4$  axis

**Element** **Operation**

Show All Planes

inv ctr

plane ( $\sigma_h$ )

plane ( $\sigma_v$ )

plane ( $\sigma_v'$ )

plane ( $\sigma_d$ )

plane ( $\sigma_d'$ )

Point Group =  $D_{4h}$

JSmol



# Examples of $D$ groups

$D_{nd}$  has  $n$   $C_2 \perp$  to the  $C_n$ , plus  $n\sigma_d$  but no  $\sigma_h$ ; example is  $S_4N_4$

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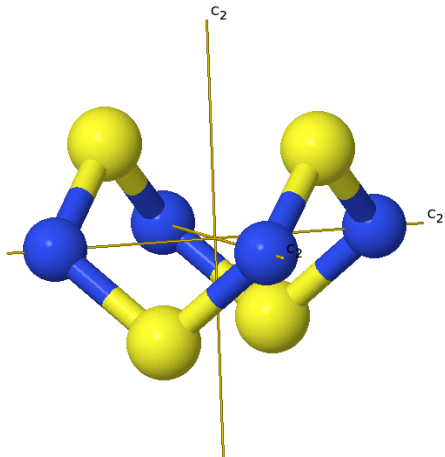
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Element	Operation	Element	Operation
<input checked="" type="checkbox"/> $C_2$ axis	<input type="button" value="Rotate"/>	<input type="checkbox"/> plane ( $\sigma_d$ )	<input type="button" value="Reflect"/>
<input checked="" type="checkbox"/> $C_2'$ axis	<input type="button" value="Rotate"/>	<input type="checkbox"/> plane ( $\sigma_d$ )	<input type="button" value="Reflect"/>
<input checked="" type="checkbox"/> $C_2''$ axis	<input type="button" value="Rotate"/>		
<input type="checkbox"/> $S_4$ axis	<input type="button" value="Rotate"/>		

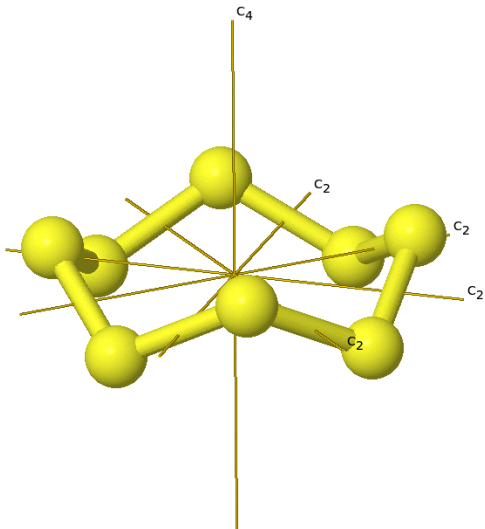
Point Group =  $D_{2d}$

JSmol



# Examples of $D$ groups

$D_{nd}$  has  $n$   $C_2 \perp$  to the  $C_n$ , plus  $n\sigma_d$  but no  $\sigma_h$ ; example is  $S_8$

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JSmol



# Examples of $D$ groups

$D_n$  has  $n$   $C_2$   $\perp$  to the  $C_n$ , but no mirror planes; example is  $[\text{Fe}(\text{C}_2\text{O}_4)_3]^{3-}$

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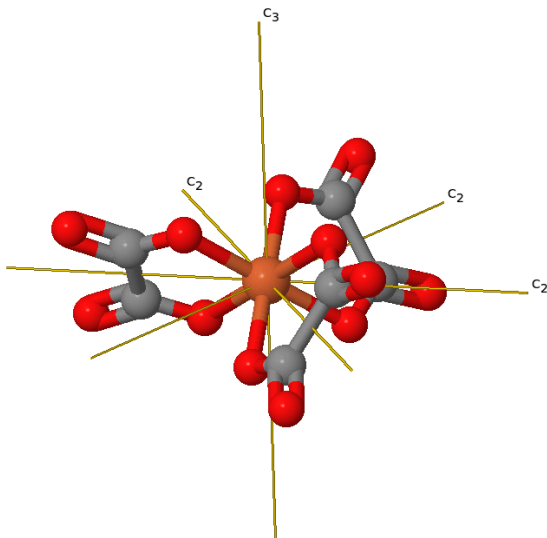
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## Element Operation

Show All Proper

$C_3$  axis

$C_2'$  axis

$C_2'$  axis

$C_2'$  axis

Point Group =  $D_3$

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# Example of $S_n$ groups

$S_n$  only for  $n = 2, 4, 6, \dots$  but note,  $S_2 =$  inversion so that is  $C_i$

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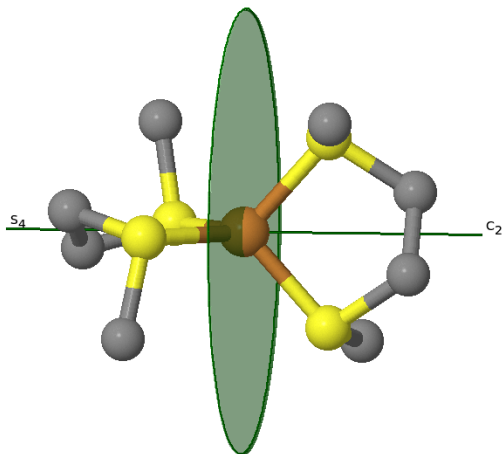
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Element Operation

$C_2$  axis

$S_4$  axis

Point Group =  $S_4$

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# Types of Point Groups

Labels are the Schoenflies symbols: here are six limiting symmetry types

- High symmetry, multiple higher-order ( $n > 2$ ) rotation axes.  
Examples:  $T_d$ ,  $I_h$ ,  $O_h$
- Low symmetry, only the identity or that plus only a single mirror plane or an inversion center:  $C_1$ ,  $C_s$ ,  $C_i$
- Linear molecules:  $C_{\infty v}$ ,  $D_{\infty h}$
- C groups:  $C_{nv}$ ,  $C_{nh}$ ,  $C_n$
- D groups:  $D_{nd}$ ,  $D_{nh}$ ,  $D_n$
- S groups:  $S_4$ ,  $S_6$ ,  $S_8$ , etc.; only operations present are based upon  $S_n$



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