6.003: Signals and Systems

Discrete-Time Frequency Representations

November 8, 2011

Mid-term Examination #3

Wednesday, November 16, 7:30-9:30pm, Walker (50-340)

No recitations on the day of the exam.

Coverage: Lectures 1–18 Recitations 1–16 Homeworks 1–10

Homework 10 will not be collected or graded. Solutions will be posted.

Closed book: 3 pages of notes $(8\frac{1}{2} \times 11 \text{ inches}; \text{ front and back}).$

No calculators, computers, cell phones, music players, or other aids.

Designed as 1-hour exam; two hours to complete.

Review session Monday at 3pm (36-112) and at open office hours.

Prior term midterm exams have been posted on the 6.003 website.

Conflict? Contact freeman@mit.edu before Friday, Nov. 11, 5pm.

Signal Processing: From CT to DT

Signal-processing problems first conceived & addressed in CT:

- audio
 - radio (noise/static reduction, automatic gain control, etc.)
 - telephone (equalizers, echo-suppression, etc.)
 - hi-fi (bass, treble, loudness, etc.)
- imaging
 - television (brightness, tint, etc.)
 - photography (image enhancement, gamma)
 - x-rays (noise reduction, contrast enhancement)
 - radar and sonar (noise reduction, object detection)

Such problems are increasingly solved with DT signal processing:

- MP3
- JPEG
- MPEG

Signal Processing: Acoustical

Mechano-acoustic components to optimize frequency response of loudspeakers: e.g., "bass-reflex" system.





Signal Processing: Acoustico-Mechanical

Passive radiator for improved low-frequency preformance.



Signal Processing: Electronic

Low-cost electronics \rightarrow new ways to overcome frequency limitations.



Small speakers (4 inch): eight facing wall, one facing listener.

Electronic "equalizer" compensated for limited frequency response.

Signal Processing

Modern audio systems process sounds digitally.

$$x(t) \longrightarrow A/D \xrightarrow{x[n]} DT \text{ filter} \xrightarrow{y[n]} D/A \longrightarrow y(t)$$

Signal Processing

Modern audio systems process sounds digitally.

Texas Instruments TAS3004

- 2 channels
- 24 bit ADC, 24 bit DAC
- 48 kHz sampling rate
- 100 MIPS
- \$9.63 (\$5.20 in bulk)



DT Fourier Series and Frequency Response

Today: frequency representations for DT signals and systems.

Review: Complex Geometric Sequences

Complex geometric sequences are eigenfunctions of DT LTI systems.

Find response of DT LTI system (h[n]) to input $x[n] = z^n$.

$$y[n] = (h * x)[n] = \sum_{k=-\infty}^{\infty} h[k] z^{n-k} = z^n \sum_{k=-\infty}^{\infty} h[k] z^{-k} = H(z) z^n.$$

Complex geometrics (DT): analogous to complex exponentials (CT)

$$z^{n} \longrightarrow h[n] \longrightarrow H(z) z^{n}$$
$$e^{st} \longrightarrow h(t) \longrightarrow H(s) e^{st}$$

Review: Rational System Functions

A system described by a linear difference equation with constant coefficients \rightarrow system function that is a ratio of polynomials in z.

Example:

$$y[n-2] + 3y[n-1] + 4y[n] = 2x[n-2] + 7x[n-1] + 8x[n]$$
$$H(z) = \frac{2z^{-2} + 7z^{-1} + 8}{z^{-2} + 3z^{-1} + 4} = \frac{2 + 7z + 8z^2}{1 + 3z + 4z^2} \equiv \frac{N(z)}{D(z)}$$

DT Vector Diagrams

Factor the numerator and denominator of the system function to make poles and zeros explicit.

$$H(z_0) = K \frac{(z_0 - q_0)(z_0 - q_1)(z_0 - q_2)\cdots}{(z_0 - p_0)(z_0 - p_1)(z_0 - p_2)\cdots}$$

Each factor in the numerator/denominator corresponds to a vector from a zero/pole (here q_0) to z_0 , the point of interest in the *z*-plane.

Vector diagrams for DT are similar to those for CT.

DT Vector Diagrams

Value of H(z) at $z = z_0$ can be determined by combining the contributions of the vectors associated with each of the poles and zeros.

$$H(z_0) = K \frac{(z_0 - q_0)(z_0 - q_1)(z_0 - q_2)\cdots}{(z_0 - p_0)(z_0 - p_1)(z_0 - p_2)\cdots}$$

The magnitude is determined by the product of the magnitudes.

$$|H(z_0)| = |K| \frac{|(z_0 - q_0)||(z_0 - q_1)||(z_0 - q_2)|\cdots}{|(z_0 - p_0)||(z_0 - p_1)||(z_0 - p_2)|\cdots}$$

The angle is determined by the sum of the angles.

$$\angle H(z_0) = \angle K + \angle (z_0 - q_0) + \angle (z_0 - q_1) + \dots - \angle (z_0 - p_0) - \angle (z_0 - p_1) - \dots$$

DT Frequency Response

Response to eternal sinusoids.

Let $x[n] = \cos \Omega_0 n$ (for all time):

$$x[n] = \frac{1}{2} \left(e^{j\Omega_0 n} + e^{-j\Omega_0 n} \right) = \frac{1}{2} \left(z_0^n + z_1^n \right)$$

where $z_0 = e^{j\Omega_0}$ and $z_1 = e^{-j\Omega_0}$.

The response to a sum is the sum of the responses: $y[n] = \frac{1}{2} \left(H(z_0) z_0^n + H(z_1) z_1^n \right)$ $= \frac{1}{2} \left(H(e^{j\Omega_0}) e^{j\Omega_0 n} + H(e^{-j\Omega_0}) e^{-j\Omega_0 n} \right)$

Conjugate Symmetry

 $n = -\infty$

For physical systems, the complex conjugate of $H(e^{j\Omega})$ is $H(e^{-j\Omega})$.

The system function is the Z transform of the unit-sample response: $H(z) = \sum_{n=1}^{\infty} h[n] z^{-n}$

where h[n] is a real-valued function of n for physical systems.

$$H(e^{j\Omega}) = \sum_{n=-\infty}^{\infty} h[n]e^{-j\Omega n}$$
$$H(e^{-j\Omega}) = \sum_{n=-\infty}^{\infty} h[n]e^{j\Omega n} \equiv \left(H(e^{j\Omega})\right)^*$$

DT Frequency Response

Response to eternal sinusoids.

Let $x[n] = \cos \Omega_0 n$ (for all time), which can be written as $x[n] = \frac{1}{2} \left(e^{j\Omega_0 n} + e^{-j\Omega_0 n} \right)$.

Then

$$y[n] = \frac{1}{2} \left(H(e^{j\Omega_0})e^{j\Omega_0 n} + H(e^{-j\Omega_0})e^{-j\Omega_0 n} \right)$$

$$= \operatorname{Re} \left\{ H(e^{j\Omega_0})e^{j\Omega_0 n} \right\}$$

$$= \operatorname{Re} \left\{ |H(e^{j\Omega_0})|e^{j\angle H(e^{j\Omega_0})}e^{j\Omega_0 n} \right\}$$

$$= |H(e^{j\Omega_0})|\operatorname{Re} \left\{ e^{j\Omega_0 n + j\angle H(e^{j\Omega_0})} \right\}$$

$$y[n] = \left| H(e^{j\Omega_0}) \right| \cos \left(\Omega_0 n + \angle H(e^{j\Omega_0}) \right)$$

DT Frequency Response

The magnitude and phase of the response of a system to an eternal cosine signal is the magnitude and phase of the system function evaluated on the unit circle.

$$\cos(\Omega n) \longrightarrow H(z) \longrightarrow |H(e^{j\Omega})| \cos\left(\Omega n + \angle H(e^{j\Omega})\right)$$
$$H(e^{j\Omega}) = |H(z)|_{z=e^{j\Omega}}$$





















Comparision of CT and DT Frequency Responses

CT frequency response: H(s) on the imaginary axis, i.e., $s = j\omega$. DT frequency response: H(z) on the unit circle, i.e., $z = e^{j\Omega}$.



DT Periodicity

DT frequency responses are periodic functions of Ω , with period 2π .

If $\Omega_2 = \Omega_1 + 2\pi k$ where k is an integer then

$$H(e^{j\Omega_2}) = H(e^{j(\Omega_1 + 2\pi k)}) = H(e^{j\Omega_1}e^{j2\pi k}) = H(e^{j\Omega_1})$$

The periodicity of $H(e^{j\Omega})$ results because $H(e^{j\Omega})$ is a function of $e^{j\Omega}$, which is itself periodic in Ω . Thus DT complex exponentials have many "aliases."

$$e^{j\Omega_2} = e^{j(\Omega_1 + 2\pi k)} = e^{j\Omega_1}e^{j2\pi k} = e^{j\Omega_1}$$

Because of this aliasing, there is a "highest" DT frequency: $\Omega = \pi$.

Comparision of CT and DT Frequency Responses

CT frequency response: H(s) on the imaginary axis, i.e., $s = j\omega$. DT frequency response: H(z) on the unit circle, i.e., $z = e^{j\Omega}$.



Consider 3 CT signals:

 $x_1(t) = \cos(3000t)$; $x_2(t) = \cos(4000t)$; $x_3(t) = \cos(5000t)$

Each of these is sampled so that

 $x_1[n] = x_1(nT)$; $x_2[n] = x_2(nT)$; $x_3[n] = x_3(nT)$ where T = 0.001.

Which list goes from lowest to highest DT frequency?

0.	$x_1[n]$	$x_2[n]$	$x_3[n]$	1.	$x_1[n]$	$x_3[n]$	$x_2[n]$
2.	$x_2[n]$	$x_1[n]$	$x_3[n]$	3.	$x_2[n]$	$x_3[n]$	$x_1[n]$
4.	$x_3[n]$	$x_1[n]$	$x_2[n]$	5.	$x_3[n]$	$x_2[n]$	$x_1[n]$

The discrete signals are

 $x_1[n] = \cos[3n]$ $x_2[n] = \cos[4n]$ $x_3[n] = \cos[5n]$

and the corresponding discrete frequencies are $\Omega=3,4$ and 5, represented below with \times marking $e^{j\Omega}$ and o marking $e^{-j\Omega}$).



 $\Omega=0.25$



 $\Omega = 0.5$















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Each of these is sampled so that

 $x_1[n] = x_1(nT)$; $x_2[n] = x_2(nT)$; $x_3[n] = x_3(nT)$ where T = 0.001.

Which list goes from lowest to highest DT frequency? 5

0.	$x_1[n]$	$x_2[n]$	$x_3[n]$	1.	$x_1[n]$	$x_3[n]$	$x_2[n]$
2.	$x_2[n]$	$x_1[n]$	$x_3[n]$	3.	$x_2[n]$	$x_3[n]$	$x_1[n]$
4.	$x_3[n]$	$x_1[n]$	$x_2[n]$	5.	$x_3[n]$	$x_2[n]$	$x_1[n]$





DT Fourier series represent DT signals in terms of the amplitudes and phases of harmonic components.

$$x[n] = \sum a_k e^{jk\Omega_0 n}$$

The period N of all harmonic components is the same (as in CT).

There are (only) N distinct complex exponentials with period N. (There were an infinite number in CT!)

If $y[n] = e^{j\Omega n}$ is periodic in N then

$$y[n] = e^{j\Omega n} = y[n+N] = e^{j\Omega(n+N)} = e^{j\Omega n}e^{j\Omega N}$$

and $e^{j\Omega N}$ must be 1, and $e^{j\Omega}$ must be one of the N^{th} roots of 1. Example: N = 8



There are N distinct complex exponentials with period N.

These can be combined via Fourier series to produce periodic time signals with N independent samples.



DT Fourier series represent DT signals in terms of the amplitudes and phases of harmonic components.

$$x[n] = x[n+N] = \sum_{k=0}^{N-1} a_k e^{jk\Omega_0 n} \quad ; \ \Omega_0 = \frac{2\pi}{N}$$

N equations (one for each point in time n) in N unknowns (a_k) .

Example:
$$N = 4$$

$$\begin{bmatrix} x[0] \\ x[1] \\ x[2] \\ x[3] \end{bmatrix} = \begin{bmatrix} e^{j\frac{2\pi}{N}0\cdot0} & e^{j\frac{2\pi}{N}1\cdot0} & e^{j\frac{2\pi}{N}2\cdot0} & e^{j\frac{2\pi}{N}3\cdot0} \\ e^{j\frac{2\pi}{N}0\cdot1} & e^{j\frac{2\pi}{N}1\cdot1} & e^{j\frac{2\pi}{N}2\cdot1} & e^{j\frac{2\pi}{N}3\cdot1} \\ e^{j\frac{2\pi}{N}0\cdot2} & e^{j\frac{2\pi}{N}1\cdot2} & e^{j\frac{2\pi}{N}2\cdot2} & e^{j\frac{2\pi}{N}3\cdot2} \\ e^{j\frac{2\pi}{N}0\cdot3} & e^{j\frac{2\pi}{N}1\cdot3} & e^{j\frac{2\pi}{N}2\cdot3} & e^{j\frac{2\pi}{N}3\cdot3} \end{bmatrix} \begin{bmatrix} a_0 \\ a_1 \\ a_2 \\ a_3 \end{bmatrix}$$

DT Fourier series represent DT signals in terms of the amplitudes and phases of harmonic components.

$$x[n] = x[n+N] = \sum_{k=0}^{N-1} a_k e^{jk\Omega_0 n} \quad ; \ \Omega_0 = \frac{2\pi}{N}$$

N equations (one for each point in time n) in N unknowns (a_k) .

Example: N = 4

$$\begin{bmatrix} x[0]\\ x[1]\\ x[2]\\ x[3] \end{bmatrix} = \begin{bmatrix} 1 & 1 & 1 & 1\\ 1 & j & -1 & -j\\ 1 & -1 & 1 & -1\\ 1 & -j & -1 & j \end{bmatrix} \begin{bmatrix} a_0\\ a_1\\ a_2\\ a_3 \end{bmatrix}$$

Orthogonality

DT harmonics are orthogonal to each other (as were CT harmonics).

$$\sum_{n=0}^{N-1} e^{j\Omega_0 kn} e^{-j\Omega_0 ln} = \sum_{n=0}^{N-1} e^{j\Omega_0 (k-l)n}$$
(N) ; $k = l$

$$= \begin{cases} \frac{1-e^{j\Omega_0(k-l)N}}{1-e^{j\Omega_0(k-l)}} = \frac{1-e^{j\frac{2\pi}{N}(k-l)N}}{1-e^{j\frac{2\pi}{N}(k-l)}} = 0 \quad ; \ k \neq l \end{cases}$$

$$= N\delta[k-l]$$

Sifting

Use orthogonality property of harmonics to sift out FS coefficients.

Assume
$$x[n] = \sum_{k=0}^{N-1} a_k e^{jk\Omega_0 n}$$

Multiply both sides by the complex conjugate of the l^{th} harmonic, and sum over time.

$$\sum_{n=0}^{N-1} x[n] e^{-jl\Omega_0 n} = \sum_{n=0}^{N-1} \sum_{k=0}^{N-1} a_k e^{jk\Omega_0 n} e^{-jl\Omega_0 n} = \sum_{k=0}^{N-1} a_k \sum_{n=0}^{N-1} e^{jk\Omega_0 n} e^{-jl\Omega_0 n}$$
$$= \sum_{k=0}^{N-1} a_k N \delta[k-l] = N a_l$$

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} x[n] e^{-jk\Omega_0 n}$$

Since both x[n] and a_k are periodic in N, the sums can be taken over any N successive indices.

Notation. If f[n] is periodic in N, then

$$\sum_{n=0}^{N-1} f[n] = \sum_{n=1}^{N} f[n] = \sum_{n=2}^{N+1} f[n] = \dots = \sum_{n=} f[n]$$

DT Fourier Series

$$a_k = a_{k+N} = \frac{1}{N} \sum_{n = \langle N \rangle} x[n] e^{-jk\Omega_0 n} \quad ; \ \Omega_0 = \frac{2\pi}{N} \qquad (\text{``analysis'' equation'})$$

$$x[n] = x[n+N] = \sum_{k=\langle N \rangle} a_k e^{jk\Omega_0 n}$$

("synthesis" equation)

DT Fourier series have simple matrix interpretations.

$$\begin{split} x[n] &= x[n+4] = \sum_{k=<4>} a_k e^{jk\Omega_0 n} = \sum_{k=<4>} a_k e^{jk\frac{2\pi}{4}n} = \sum_{k=<4>} a_k j^{kn} \\ \begin{bmatrix} x[0]\\ x[1]\\ x[2]\\ x[3] \end{bmatrix} &= \begin{bmatrix} 1 & 1 & 1 & 1\\ 1 & j & -1 & -j\\ 1 & -j & -1 & j \end{bmatrix} \begin{bmatrix} a_0\\ a_1\\ a_2\\ a_3 \end{bmatrix} \\ a_k &= a_{k+4} = \frac{1}{4} \sum_{n=<4>} x[n] e^{-jk\Omega_0 n} = \frac{1}{4} \sum_{n=<4>} e^{-jk\frac{2\pi}{N}n} = \frac{1}{4} \sum_{n=<4>} x[n] j^{-kn} \\ \begin{bmatrix} a_0\\ a_1\\ a_2\\ a_3 \end{bmatrix} \\ &= \frac{1}{4} \begin{bmatrix} 1 & 1 & 1 & 1\\ 1 & -j & -1 & j\\ 1 & -1 & 1 & -1\\ 1 & j & -1 & -j \end{bmatrix} \begin{bmatrix} x[0]\\ x[1]\\ x[2]\\ x[3] \end{bmatrix} \end{split}$$

These matrices are inverses of each other.

Discrete-Time Frequency Representations

Similarities and differences between CT and DT.

DT frequency response

- vector diagrams (similar to CT)
- frequency response on unit circle in z-plane ($j\omega$ axis in CT)

DT Fourier series

- represent signal as sum of harmonics (similar to CT)
- finite number of periodic harmonics (unlike CT)
- finite sum (unlike CT)

The finite length of DT Fourier series make them especially useful for signal processing! (more on this next time)