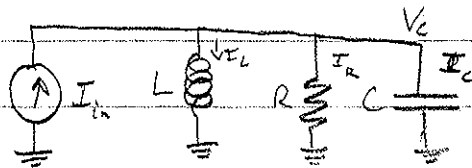


- ① Block Diagrams for Parallel LCR Circuits
- ② The Impulse Response of Second-Order Systems
- ③ Examples of Physical Second-Order Systems

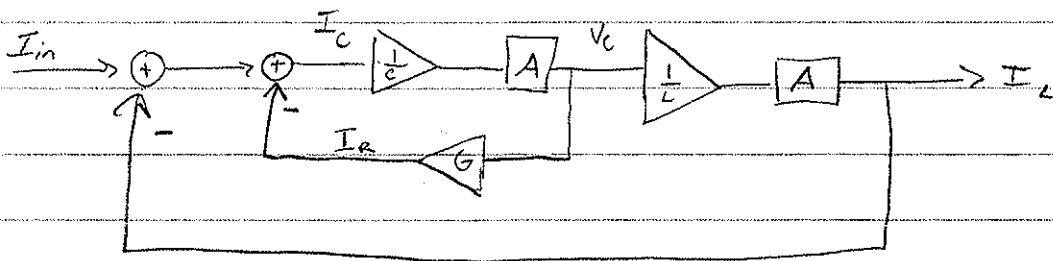


$$I_{in} = I_L + I_R + I_C$$

$$I_L = \frac{1}{L} \int V_c dt$$

$$I_R = \frac{V_c}{R}$$

$$I_C = C \frac{dV_c}{dt}$$



$$\frac{I_L}{I_{in}} = \frac{\left(\frac{\frac{A}{C}}{1 + \frac{A}{RC}} \right) \frac{A}{L}}{1 + \left(\frac{\frac{A}{C}}{1 + \frac{A}{RC}} \right) \frac{A}{L}}$$

$$\frac{I_R}{I_{in}} = \frac{1}{A} \left(\frac{L}{R} \right) \left(\frac{I_L}{I_{in}} \right)$$

$$\frac{I_C}{I_{in}} = \left(\frac{L}{A} \right) \left(\frac{C}{A} \right) \left(\frac{I_L}{I_{in}} \right)$$

$$\frac{I_L}{I_{in}} = \frac{\frac{\frac{A^2}{LC}}{1 + \frac{A}{RC}}}{1 + \frac{\frac{A^2}{LC}}{1 + \frac{A}{RC}}} = \frac{\frac{A^2}{LC}}{1 + \frac{A}{RC} + \frac{A^2}{LC}}$$

$$\omega_0^2 = \frac{1}{LC}$$

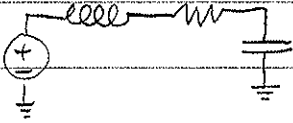
$$Q = \frac{R}{\sqrt{\frac{L}{C}}}$$

$$\boxed{\frac{I_L}{I_{in}} = \frac{\omega_0^2 A^2}{1 + \frac{\omega_0 A}{Q} + \omega_0^2 A^2}}$$

$$\frac{I_R}{I_{in}} = \frac{\frac{\omega_0 A}{Q}}{1 + \frac{\omega_0 A}{Q} + \omega_0^2 A^2}$$

$$\frac{I_C}{I_{in}} = \frac{1}{1 + \frac{\omega_0 A}{Q} + \omega_0^2 A^2}$$

Series



$$\omega_0^2 = \frac{1}{LC}$$

$$Q = \frac{\sqrt{L/C}}{R}$$

$$\frac{V_C}{V_{in}} = \frac{\omega_0^2 A^2}{1 + \frac{\omega_0 A}{Q} + \omega_0^2 A^2}$$

$$\frac{V_R}{V_{in}} = \frac{\frac{\omega_0 A}{Q}}{1 + \frac{\omega_0 A}{Q} + \omega_0^2 A^2}$$

$$\frac{V_L}{V_{in}} = \frac{1}{1 + \frac{\omega_0 A}{Q} + \omega_0^2 A^2}$$

Impulse Response

$$\frac{I_L}{I_{in}} = \frac{\omega_0^2 A^2}{1 + \frac{\omega_0 A}{Q} + \omega_0^2 A^2} = \frac{\omega_0^2}{p_0 - p_1} \left[\frac{A}{1 - p_0 A} - \frac{A}{1 - p_1 A} \right]$$

roots p_0 & p_1 derived by solving for roots of quadratic

$$1 + \frac{\omega_0 A}{Q} + \omega_0^2 A^2 = 0$$

ie. I can factorize $(1 + \frac{\omega_0 A}{Q} + \omega_0^2 A^2) \Rightarrow (1 - p_0 A)(1 - p_1 A)$

Impulse Response: $\frac{\omega_0^2}{p_0 - p_1} [e^{p_0 t} - e^{p_1 t}] u(t)$

IF $Q > \frac{1}{2}$

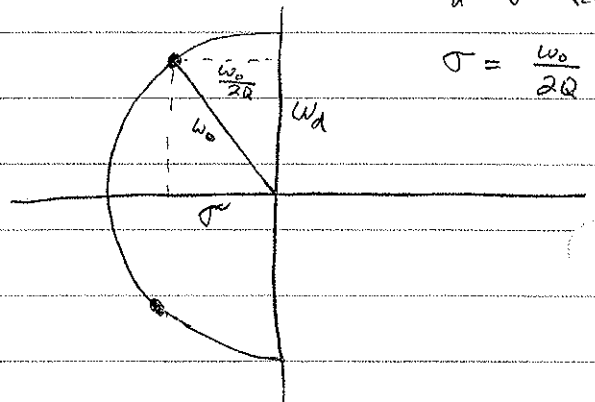
$$p_0 = \frac{-\omega_0}{2Q} + j \left(\sqrt{1 - \left(\frac{1}{2Q}\right)^2} \right) \omega_0$$

$$p_1 = \frac{-\omega_0}{2Q} - j \left(\sqrt{1 - \left(\frac{1}{2Q}\right)^2} \right) \omega_0$$

IF $Q < \frac{1}{2}$

$$p_0 = \frac{-\omega_0}{2Q} + \sqrt{1 - \left(\frac{1}{2Q}\right)^2} \omega_0$$

$$p_1 = \frac{-\omega_0}{2Q} - \sqrt{1 - \left(\frac{1}{2Q}\right)^2} \omega_0$$



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Impulse Response :

$$h(t) = \frac{\omega_0^2}{p_0 - p_1} [e^{p_0 t} - e^{p_1 t}] u(t)$$

$$\text{IF } Q < \frac{1}{2} : \frac{\omega_0^2}{\omega_d} [e^{p_1 t} - e^{p_2 t}] u(t)$$

$$\text{IF } Q > \frac{1}{2} : \frac{\omega_0}{\sqrt{1 - (\frac{1}{2Q})^2}} e^{-\frac{\omega_0}{2Q} t} \sin(\omega_0 \sqrt{1 - (\frac{1}{2Q})^2} \cdot t)$$

Derivation of Impulse Response for $Q > \frac{1}{2}$

$$\frac{\omega_0^2}{p_0 - p_1} [e^{p_1 t} - e^{p_2 t}]$$

$$\frac{\omega_0^2}{2j\omega_d} [e^{-\sigma t}] [e^{j\omega_d t} - e^{-j\omega_d t}]$$

$$\frac{\omega_0^2}{\omega_d} e^{-\sigma t} \left[\frac{e^{j\omega_d t} - e^{-j\omega_d t}}{2j} \right]$$

$$\frac{\omega_0^2}{\omega_d} e^{-\sigma t} \cdot \sin(\omega_d t)$$