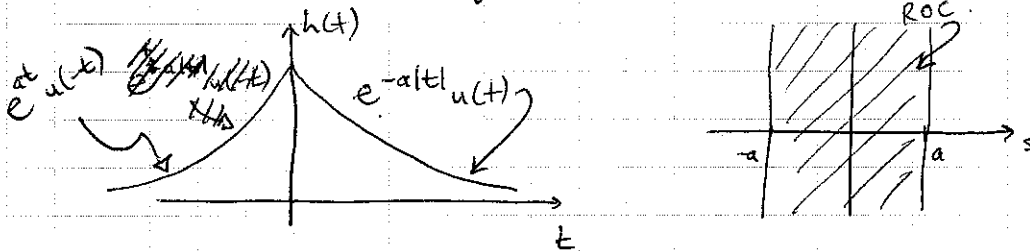


Today:

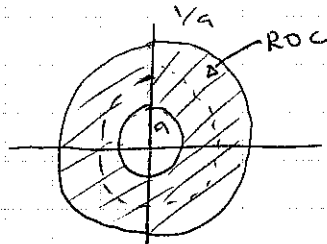
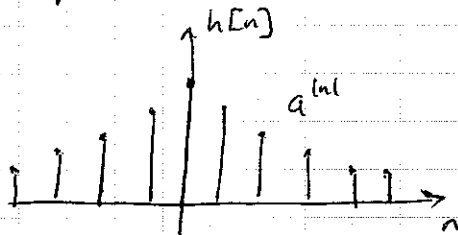
- (1) Simple example to review key issues in Laplace & z-transforms.
- (2) Second-order CT LCR circuits with Laplace transforms.
- (3) Second-order DT block with z-transforms.

① Review: suppose we are given a CT impulse resp.:



$$H(s) = \int_{-\infty}^{\infty} h(t)e^{-st} dt = \frac{1}{a-s} + \frac{1}{a+s} = \frac{2a}{a^2-s^2}$$

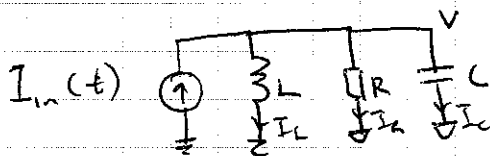
The equivalent DT IR is



$$H(z) = \sum_{n=-\infty}^{+\infty} h[n]z^{-n} = \frac{az}{1-az} + \frac{1}{1-az^{-1}} = \frac{1-a^2}{(1-az)(1-az^{-1})}$$

In the Laplace domain, note that integration $\rightarrow 1/s$, and differentiation $\rightarrow s$.

②

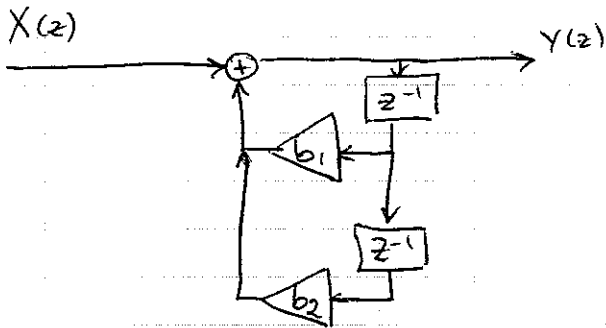


$$I_L = \frac{1}{L} \int v dt \Leftrightarrow I_L(s) = \frac{V(s)}{sL} \Rightarrow Z_L(s) = \frac{V_L(s)}{I_L(s)} = sL$$

$$I_R = \frac{V}{R} \Leftrightarrow I_R(s) = V_R(s)/R \Rightarrow Z_R(s) = R$$

$$I_C = C \frac{dv}{dt} \Leftrightarrow I_C(s) = sCV \Rightarrow Z_C(s) = \frac{V_C(s)}{I_C(s)} = \frac{1}{sC}$$

③ A canonical second-order DT system is represented by



$$\frac{Y(z)}{X(z)} = \frac{1}{1 - b_1 z^{-1} - b_2 z^{-2}}$$

$$r_1 r_2 \stackrel{\Delta}{=} -b_2$$

$$r_1 + r_2 \stackrel{\Delta}{=} b_1$$

Suppose $r_1 = r e^{+j\theta}$, $r_2 = r e^{-j\theta}$

Note, roots are complex conjugates.

$$\frac{Y(z)}{X(z)} = \frac{1}{(1 - r_1 z^{-1})(1 - r_2 z^{-1})}$$

The inverse z-transform is then $\frac{r_1 r_1^n u[n]}{r_1 - r_2} + \frac{r_2 r_2^n u[n]}{r_1 - r_2}$

$$= \frac{r^{n+1} e^{j\theta(n+1)}}{r e^{j\theta} - r e^{-j\theta}} - \frac{r^{n+1} e^{-j\theta(n+1)}}{r e^{j\theta} - r e^{-j\theta}} = \frac{r^n \sin[(n+1)\theta]}{\sin \theta}$$

Assume $r < 1$, so the impulse response is

