

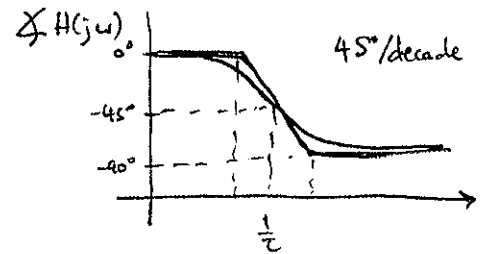
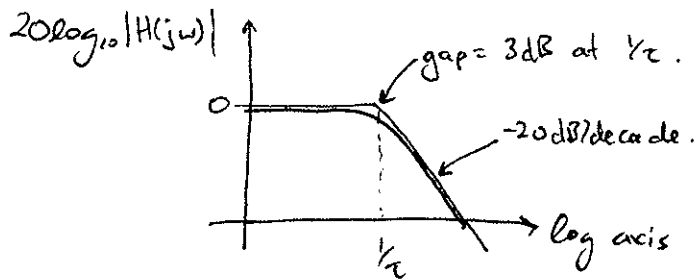
1.

▷ Today:

- ① Bode plot of a single-pole first-order system
- ② " " " " two-pole second-order system.
- ③ Bode plot example.

①

$x(t) \rightarrow \boxed{h(t) = \frac{1}{\tau} e^{-t/\tau}} \rightarrow y(t)$
 $H(j\omega) = \frac{1}{\tau j\omega + 1}$, $|H(j\omega)| = \frac{1}{\sqrt{1 + \omega^2 \tau^2}}$, $\angle H(j\omega) = -\tan^{-1}(\omega\tau)$



②

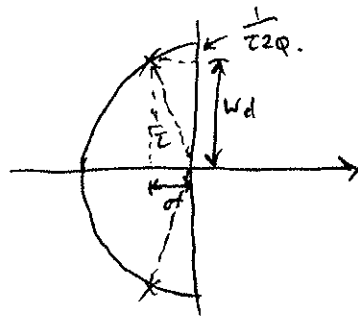
$x(t) \rightarrow \boxed{h(t) = \frac{\omega_0^2}{\omega \tau} e^{-\sigma t} \sin(\omega_d t) u(t)}$
 $\rightarrow y(t)$

$X(s) \rightarrow \boxed{H(s) = \frac{1}{\tau^2 s^2 + \frac{\tau s}{\phi} + 1}} \rightarrow Y(s)$

$\omega_0 = 1/\tau$

$\omega_d = \omega_0 \sqrt{1 - \frac{1}{4\phi^2}}$

$\sigma = \frac{\omega_0}{2\phi}$

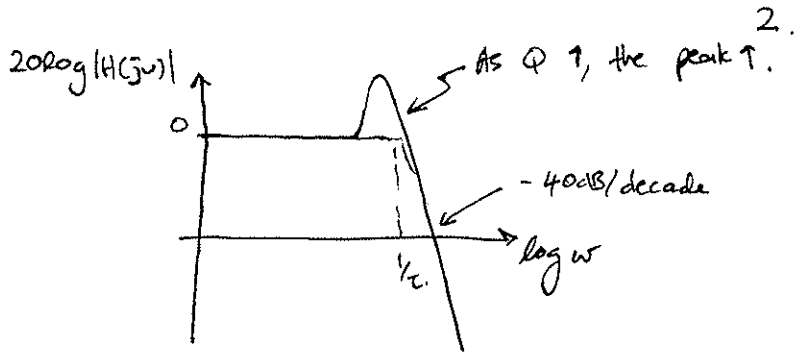


$H(j\omega) = \frac{1}{1 - \omega^2 \tau^2 + \frac{j\omega \tau}{\phi}}$

If $Q > 1/2$, the step response is underdamped (complex poles).

$|H(j\omega)| = \frac{1}{\sqrt{(1 - \omega^2 \tau^2)^2 + \frac{\omega^2 \tau^2}{\phi^2}}}$

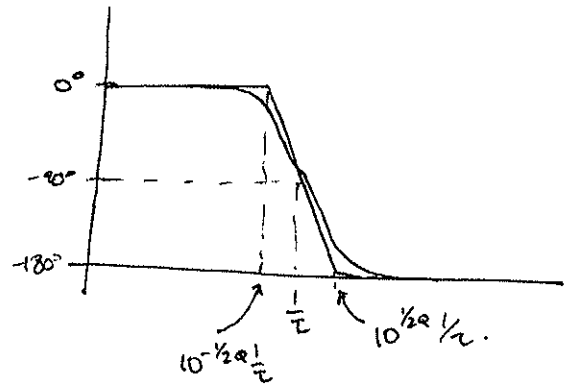
$\angle H(j\omega) = -\tan^{-1} \left(\frac{\omega \tau / \phi}{1 - \omega^2 \tau^2} \right)$



$$\omega_{\text{peak}} = \omega_0 \sqrt{1 - \frac{1}{2Q^2}}$$

$$H_{\text{peak}} = \frac{Q}{\sqrt{1 - \frac{1}{2Q^2}}}$$

A peak only occurs if $Q > \frac{1}{\sqrt{2}}$.



As $Q \rightarrow \infty$, $10^{-\frac{1}{2}Q}$, $10^{\frac{1}{2}Q} \rightarrow 1$, and the phase transition becomes infinitely sharp.

③ $H(s) = \frac{10^6}{(s+1)(10^{-5}s+1)(10^{-14}s^2 + \frac{10^{-7}s}{100} + 1)}$

$$20 \log |H(j\omega)| = 120 - 20 \log |j\omega + 1| - 20 \log |10^{-5}j\omega + 1| - 20 \log |10^{-14}j^2\omega^2 + \frac{10^{-7}j\omega}{100} + 1|$$

$$\angle H(j\omega) = -\tan^{-1}(\omega) - \tan^{-1}(10^5\omega) - \tan^{-1}\left(\frac{10^{-7}\omega}{100} / (1 - \omega^2 10^{-14})\right)$$

