

OverviewLaplace transform

$$x(t) = \int_{\sigma - j\infty}^{\sigma + j\infty} \underline{X}(s) e^{st} \frac{ds}{2\pi j}$$

$$\underline{X}(s) = \int_{-\infty}^{\infty} e^{-st} x(t) dt$$

Fourier transform

$$x(t) = \int_{-\infty}^{\infty} \underline{X}(j\omega) e^{j\omega t} \frac{d\omega}{2\pi}$$

$$\underline{X}(j\omega) = \int_{-\infty}^{\infty} e^{-j\omega t} x(t) dt$$

Fourier series for periodic signals

$$x(t) = \sum_k a_k e^{j \frac{2\pi}{T} kt}$$

$$a_k = \frac{1}{T} \int_T e^{-j \frac{2\pi}{T} kt} x(t) dt$$

Z-transform

$$x[n] = \oint \bar{X}(z) z^{n-1} \frac{dz}{2\pi j}$$

$$\bar{X}(z) = \sum_{n=-\infty}^{\infty} z^{-n} x[n]$$

Discrete time Fourier transform

$$x[n] = \int_{2\pi} \bar{X}(e^{j\Omega}) e^{j\Omega n} \frac{d\Omega}{2\pi}$$

$$\bar{X}(e^{j\Omega}) = \sum_{n=-\infty}^{\infty} e^{-j\Omega n} x[n]$$

Periodic discrete time series

$$x[n] = \sum_{k=0}^{N-1} a_k e^{j \frac{2\pi}{N} kn}$$

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} e^{-j \frac{2\pi}{N} kn} x[n]$$

Numerical differentiation using FFT

Start with expansion of $x(t)$

$$x(t) = \int_{-\infty}^{\infty} \overline{X}(j\omega) e^{j\omega t} \frac{d\omega}{2\pi}$$

Note that taking derivatives in time is equivalent to multiplication by $(j\omega)$ factors in frequency

$$\frac{dx}{dt} = \int_{-\infty}^{\infty} [j\omega \overline{X}(j\omega)] e^{j\omega t} \frac{d\omega}{2\pi}$$

$$\frac{d^2x}{dt^2} = \int_{-\infty}^{\infty} [j\omega^2 \overline{X}(j\omega)] e^{j\omega t} \frac{d\omega}{2\pi}$$

Approach:

Use mapping between t and n

$$t = nT \longleftrightarrow n$$

$$\frac{dx}{dt} = \frac{dn}{dt} \frac{dx}{dn} = \frac{1}{T} \frac{dx}{dn}$$

$$\frac{d^2x}{dt^2} = \frac{1}{T^2} \frac{d^2x}{dn^2}$$

Algorithm

(1) Discretize using $\tilde{x}[n] = x(nT)$

(2) Compute

$$a_k = \frac{1}{N} \sum_{n=0}^{N-1} e^{-j\left(\frac{2\pi}{N}\right)kn} \tilde{x}[n] \quad \text{using FFT}$$

(3) Compute

$$\frac{d\tilde{x}}{dn} = \sum_{k=0}^{N-1} \left(j \frac{2\pi}{N} k\right) a_k e^{j\left(\frac{2\pi}{N}\right)kn} \quad \text{using FFT}$$

$$\frac{d^2\tilde{x}}{dn^2} = \sum_{k=0}^{N-1} \left(j \frac{2\pi}{N} k\right)^2 a_k e^{j\left(\frac{2\pi}{N}\right)kn} \quad \text{using FFT}$$

(4) Reconstruct continuous time points

$$\left(\frac{dx}{dt}\right)_{t=nT} \approx \frac{1}{T} \left(\frac{d\tilde{x}}{dn}\right)_n$$

$$\left(\frac{d^2x}{dt^2}\right)_{t=nT} \approx \frac{1}{T^2} \left(\frac{d^2\tilde{x}}{dn^2}\right)_n$$

Thinking about numerical error

The FFT allows us to evaluate $\frac{d^2 x}{dt^2}$ and $\frac{d^2 z}{dt^2}$ seemingly without error (but there will be round-off error).

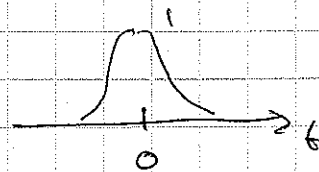
The only question then is how good of an approximation is $\tilde{x}(t)$ to ~~$x(t)$~~ $x(t)$ (as a continuous function of t) in the vicinity of $x(t)$ to $x(t)$.

Would expect it to have an accuracy comparable to what we would get from N -point Lagrange interpolation and then analytic integration (which becomes very good if lots of points are used).

Basically, if you undersample so that you don't have enough points to get a good approximation to the continuous function, the accuracy will be poor (5)

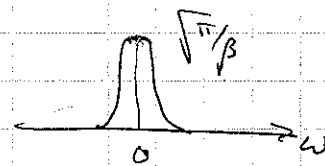
Example

$$\text{let } x(t) = e^{-\beta t^2}$$

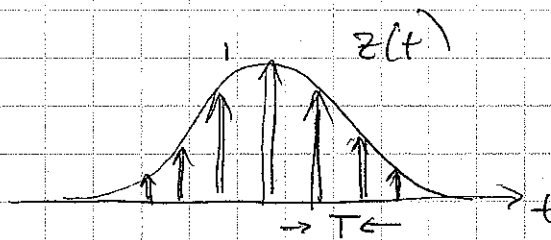


$$X(j\omega) = \int_{-\infty}^{\infty} e^{-j\omega t} x(t) dt$$

$$= \int_{-\infty}^{\infty} e^{-j\omega t} e^{-\beta t^2} dt = \sqrt{\frac{\pi}{\beta}} e^{-\omega^2/4\beta}$$



Consider



$$z(t) = e^{-\beta t^2} \sum_n \delta(t - nT)$$

Product in time implies convolution in frequency

$$x(t) = e^{-\beta t^2} \longleftrightarrow X(j\omega) = \sqrt{\frac{\pi}{\beta}} e^{-\omega^2/4\beta}$$

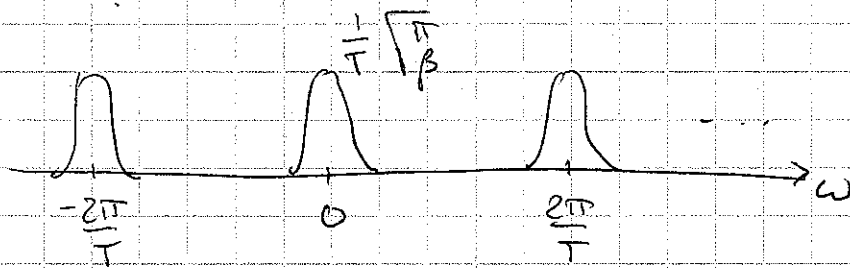
$$y(t) = \sum_n \delta(t - nT) \longleftrightarrow Y(j\omega) = \sum_k \frac{2\pi}{T} \delta(\omega - \frac{2\pi k}{T})$$

$$Z(t) = x(t) y(t)$$

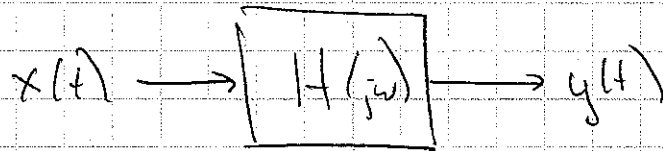
$$Z(j\omega) = \frac{1}{2\pi} X(j\omega) * Y(j\omega)$$

$$Z(j\omega) = \frac{1}{2\pi} \sum_k \sqrt{\frac{\pi}{\beta}} \frac{2\pi}{T} e^{-\left(\omega - \frac{2\pi k}{T}\right)^2 / 4\beta}$$

$$= \frac{1}{T} \sqrt{\frac{\pi}{\beta}} \sum_k e^{-\left(\omega - \frac{2\pi k}{T}\right)^2 / 4\beta}$$



Thinking about filters



Four different cases

CT
signal

$$y(t) = \int_{-\infty}^{\infty} H(j\omega) \bar{X}(j\omega) e^{j\omega t} \frac{d\omega}{2\pi}$$

$$= \int_{-\infty}^{\infty} \left[\int_{-\infty}^{\infty} e^{-j\omega t'} h(t') dt' \right] \left[\int_{-\infty}^{\infty} e^{-j\omega t''} x(t'') dt'' \right]$$

$$= \int_{-\infty}^{\infty} dt' \int_{-\infty}^{\infty} dt'' h(t') x(t'') \underbrace{\int_{-\infty}^{\infty} e^{j\omega(t-t'-t'')} \frac{d\omega}{2\pi}}_{\delta(t-t'-t'')}$$

$$= \int_{-\infty}^{\infty} h(t') x(t-t') dt$$

$$\boxed{y(t) = (h * x)(t)}$$

Periodic CT signal

$$x(t) = \sum_k a_k e^{j \frac{2\pi}{T} k t}$$

$$e^{j \frac{2\pi}{T} k t} \longrightarrow \boxed{H(j\omega)} \longrightarrow H(j \frac{2\pi}{T} k) e^{j \frac{2\pi}{T} k t}$$

So

$$y(t) = \sum_k H(j \frac{2\pi}{T} k) a_k e^{j \frac{2\pi}{T} k t}$$

Would like to see this lead to a convolution

$$\begin{aligned} &= \sum_k \int_{-\infty}^{\infty} e^{-j \frac{2\pi}{T} k t'} h(t') dt' \frac{1}{T} \int_{-\infty}^{\infty} e^{-j \frac{2\pi}{T} k t''} x(t'') dt'' e^{j \frac{2\pi}{T} k t} \\ &= \int_{-\infty}^{\infty} dt' \frac{1}{T} \int_{-\infty}^{\infty} dt'' h(t') x(t'') \sum_k e^{j \frac{2\pi}{T} k (t+t'-t'')} \end{aligned}$$

Thinking about ~~sum~~ summation

$$\sum_k \frac{1}{T} e^{j \frac{2\pi}{T} k (t+t'-t'')} = \sum_n \delta(t-t'-t''-nT)$$

$$y(t) = \int_{-\infty}^{\infty} dt' \left(\int_T dt'' h(t') x(t'') \right) \sum_n \delta(t-t'-t''-nT)$$

Can understand result most easily if we integrate over t'' .

$$y(t) = \sum_n \int_T x(t'') h(t-t''-nT) dt''$$

This is interesting...

$$= \int_T x(t') h(t-t') dt'$$

$$+ \int_T x(t') h(t-t'-T) dt'$$

$$+ \dots \text{ other responses}$$

$$= \int_{-\infty}^{\infty} x(t') h(t-t') dt'$$

$$= (x * h)(t)$$

Discrete time case

$$x[n] = \int_{2\pi} \overline{X}(e^{j\omega}) e^{j\omega n} \frac{d\omega}{2\pi}$$

$$e^{j\omega n} \rightarrow \boxed{H(e^{j\omega})} \rightarrow H(e^{j\omega}) e^{j\omega n}$$

$$y[n] = \int_{2\pi} H(e^{j\omega}) \overline{X}(e^{j\omega}) e^{j\omega n} \frac{d\omega}{2\pi}$$

$$= \int_{2\pi} \left[\sum_{n'} e^{j\omega n'} h[n'] \right] \left[\sum_{n''} e^{j\omega n''} x[n''] \right] e^{j\omega n} \frac{d\omega}{2\pi}$$

$$= \sum_{n'} \sum_{n''} h[n'] x[n''] \int_{2\pi} \underbrace{e^{j\omega(n-n'-n'')}}_{\delta[n-n'-n'']} \frac{d\omega}{2\pi}$$

$$= \sum_{n'} h[n'] x[n-n']$$

$$= (h * x)[n]$$

Periodic discrete time case

$$x[n] = \sum_{k=0}^{N-1} a_k e^{i \frac{2\pi}{N} kn}$$

$$e^{i \frac{2\pi}{N} kn} \rightarrow \boxed{H(z)} \rightarrow H(e^{i \frac{2\pi}{N} k}) e^{i \frac{2\pi}{N} kn}$$

$$y[n] = \sum_{k=0}^{N-1} H(e^{i \frac{2\pi}{N} k}) a_k e^{i \frac{2\pi}{N} kn}$$

Once again, we would like to get convolution rule

$$\begin{aligned}
 &= \sum_{k=0}^{N-1} \left[\sum_{n'=-\infty}^{\infty} e^{-i \frac{2\pi}{N} kn'} h[n'] \right] \left[\frac{1}{N} \sum_{n''=0}^{N-1} e^{-i \frac{2\pi}{N} kn''} x[n''] \right] e^{i \frac{2\pi}{N} kn} \\
 &= \sum_{n'=-\infty}^{\infty} \sum_{n''=0}^{N-1} h[n'] x[n''] \underbrace{\frac{1}{N} \sum_{k=0}^{N-1} e^{i \frac{2\pi}{N} k(n-n'-n'')}}_{\sum_m \delta[n-n'-n''-mN]} \\
 &= \sum_{m=-\infty}^{\infty} \sum_{n''=0}^{N-1} x[n''] h[n-n''-mN]
 \end{aligned}$$

interesting...

$$= \sum_{n''=-\infty}^{\infty} x[n''] h[n-n''] = (x * h)[n]$$