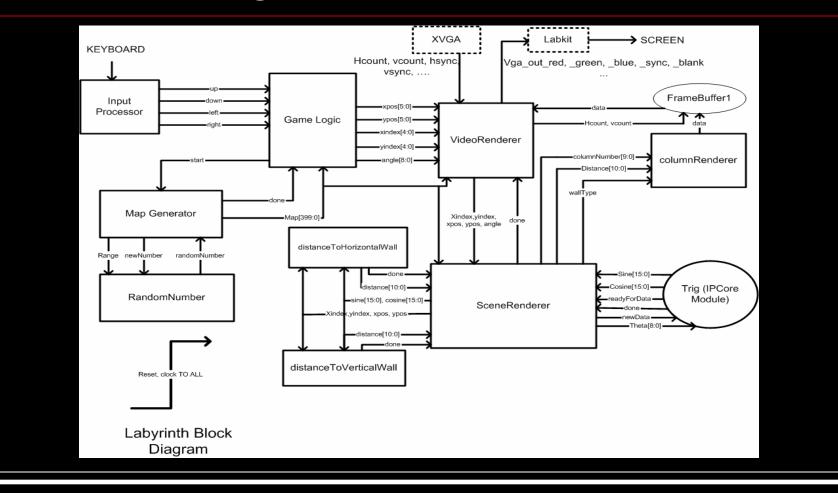


6.111 Final Project Laplie Anderson and Mihalis Papalampros

Description

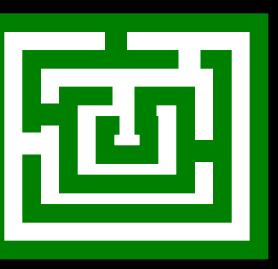
- Players are trapped inside a maze and must navigate to the center
- Players can only see what is in front of them (in a 3D view) and a mini-map showing their general location
- Players can move forward/back and turn left/right

Block Diagram



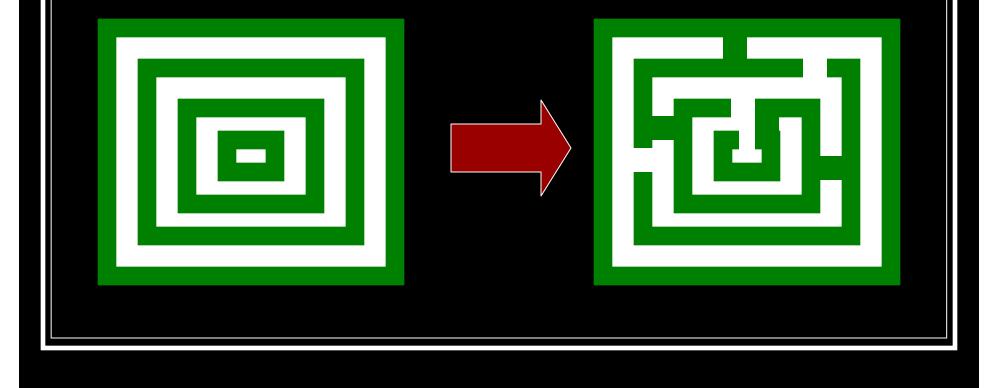
Maps are Randomly Generated

- A new random map is generated for every new game
 - Players are presented with a new challenge every time they play
 - Another layer of complexity



Map Generation

Start every map with concentric squares
Add/Remove walls to create maze

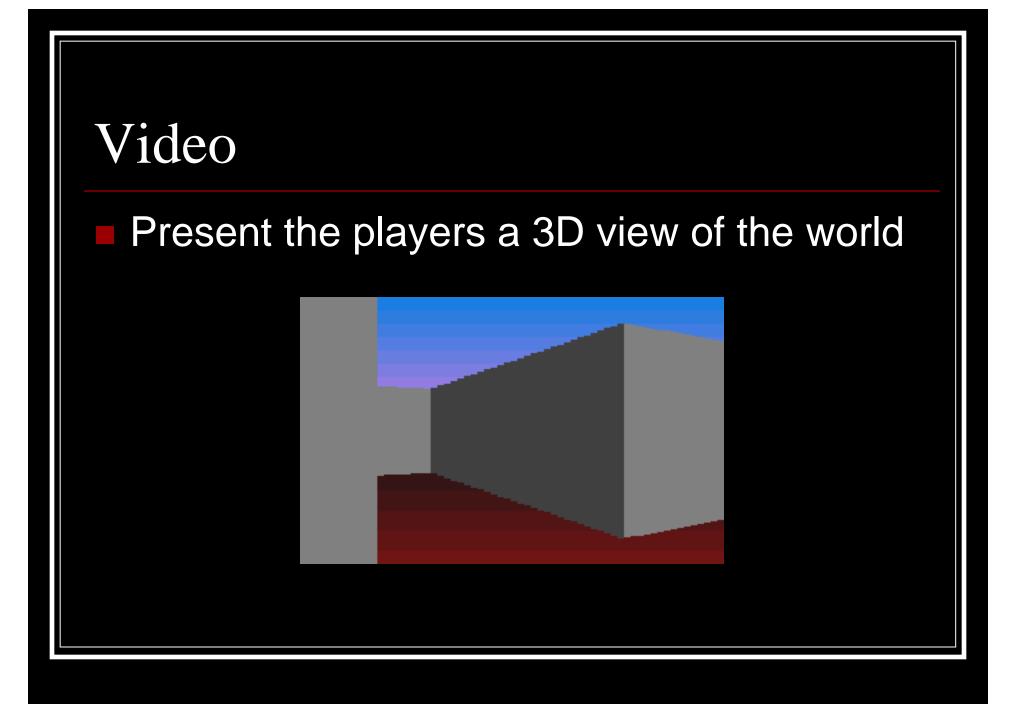


Map Generation

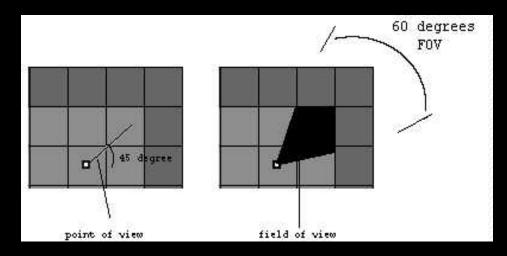
- Use random number generator module to choose which walls to add or remove
- After adding a wall make sure some set of invariants are never broken
 - At least 1 path to everywhere on the map
 - Limited number of paths to center of map

Game Logic

- Take as input up/down/left/right keys
- Update position if the move is possible according to the map (prevent player from walking through walls)
- Output the current position of the player and the player's viewing angle



Ray Casting to Simulate 3D



- For every angle, find out how far the nearest wall is, and scale based on that distance
- Currently, each player has a 60 degree field of view, but depending on speed after testing, this might be adjusted

Writing Columns to Memory

SceneRenderer outputs a distance and column number to ColumnRenderer
ColumnRenderer scales the specified column and writes it to the video buffer

Double Buffering

The monitor shows one buffer while the other buffer is being written

Once SceneRenderer says a new frame is ready, the video switches to the other buffer

Timeline

Sun	Mon	Tue	Wed	Thu	Fri	Sat
			1	2	3	4
5	6	7	8	9	10	11
12	13	\bigstar^{14}	15	16	17	18
19	*20	21	22	23	24	25
26	★ ²⁷	28	29	30		

Sur	ı	Mon	Tue	Wed	Thu	Fri	Sat
						1	2
	3	* 4	5	6	7	*8	9
1	0	11	12	13	14	15	16
1	7	18	19	20	21	22	23
24	51	25	26	27	28	29	30

November 20th

- SceneRenderer outputting correct distance for every angle
- Random Number Generator and initial map generator complete
- November 27th
 - ColumnGenerator writing columns to memory
 - MapGenerator complete
 - Initial Collision Detection
- December 4th
 - All subsystems working separately
- December 8th
 - Everything working together

Any Questions?

