Kristen Anderson & Kat Kononov 6.111 Checkoff List

	Drive car via remote forward backward
	turns
	When driven into an object, car turns to avoid it and attempts to turn in the previous direction
	When Enter is pushed during the correction phase the car stops trying to correct.
	When driving alongside an object, the car won't allow the driver to turn into the object.
	When 1 is pushed the car is allowed to drive into wall (crash avoidance off)
	When 1 is pushed again the car avoidance is on.
	When the car is in one place it will move forward if an object approaches it from the side.
	When the car is in one place it will move forward if an object approaches it from the back.
	When the car is in one place it will move backward if an object approaches it from the front.
If time permits	
	When 2 is pushed, the car parallel parks itself without crashing.
	Video
	Where the car is
	Where the car has gone
	What objects it saw