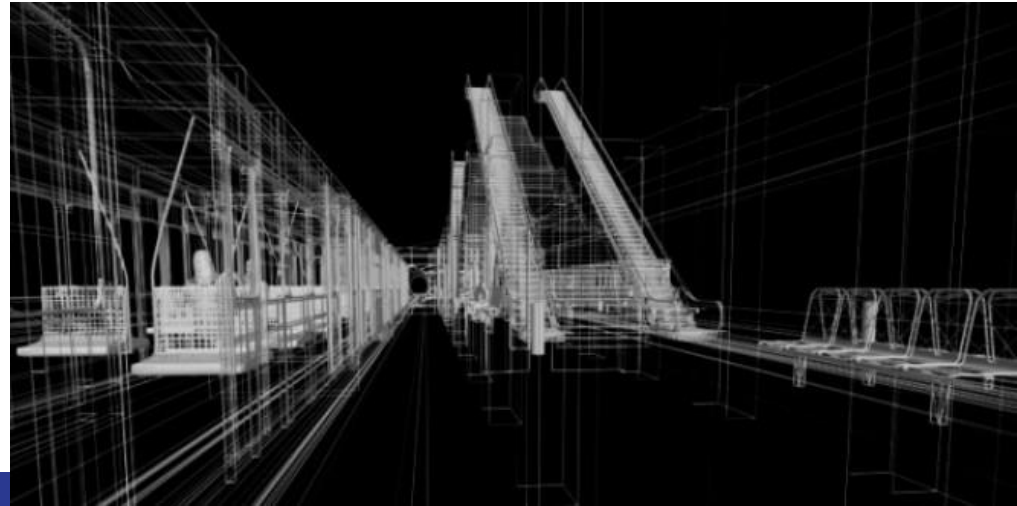


Immersive 3D World


Christine Konicki and Mikhail Rudoy
6.111 Fall 2015

Project Overview

- **3D world for exploration (actual game as reach objective)**
- **Game controller for walking around**
- **Headphones with gyroscope for looking around**
- **Footstep sound through headphones**
- **FPGA controls game FSM, hardware logic, audio generation, etc.**

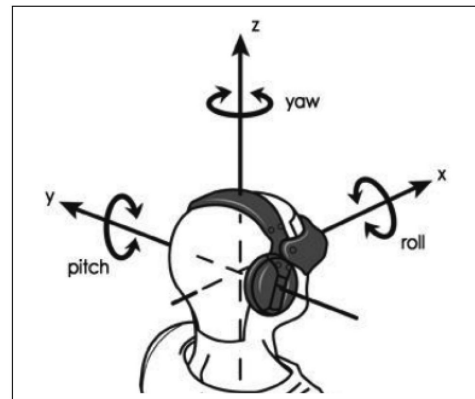


3D Graphics Module

- **Static World with changing perspective**
 - **Virtual “camera” position and orientation as inputs**
 - **VGA output to screen**
 - **Triangle (Polygon) Graphics**
 - **Triangles compute in parallel while pixels compute in series**
 - **Each triangle module involves a change of coordinates, interior testing, and depth interpolation**
- 

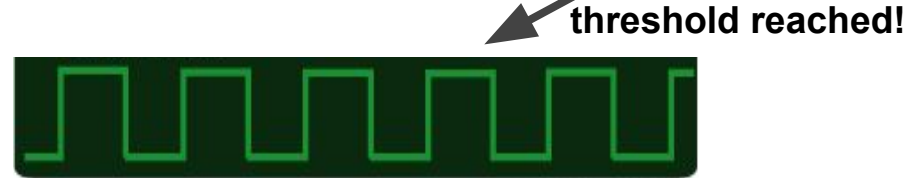
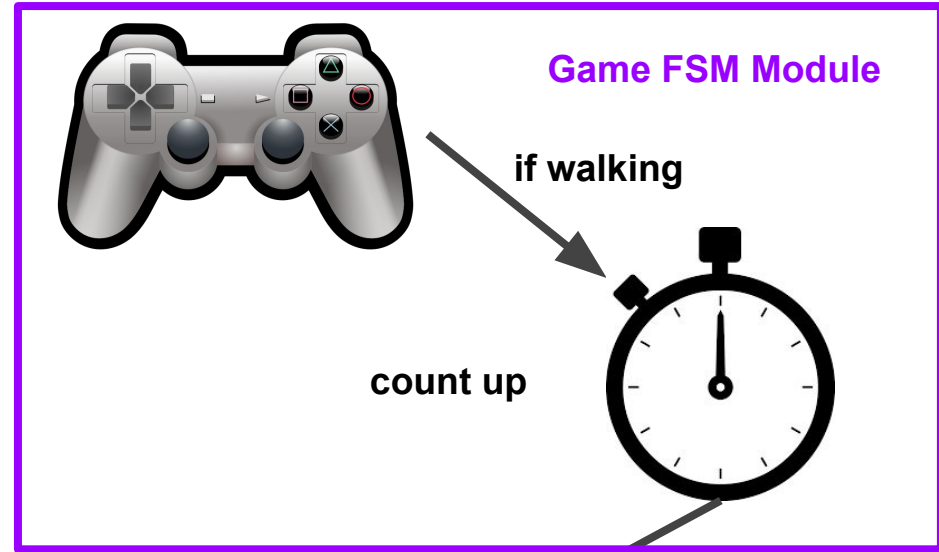
Gyroscope Coordinate Transform Module

- Gyroscope outputs three rotation values
- We only want two of them, but for the user's head, not for the gyroscope itself
- So we use a change of coordinates
- The parameters for this change of coordinates depend on gyroscope readings at fixed reference points at configuration time
- Robust against different use conditions




Audio Module

- **Footstep -> bass square wave**
- **Sound is triggered by enable signal from FSM module**
- **In FSM:**
 - **Compute distance traveled each clock cycle**
 - **Increment counter by computed distance**
 - **At certain threshold, trigger audio module and reset counter**




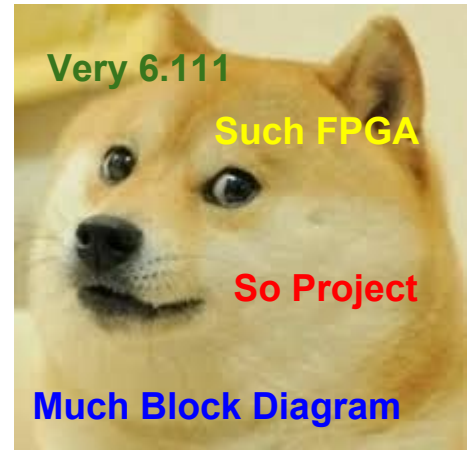
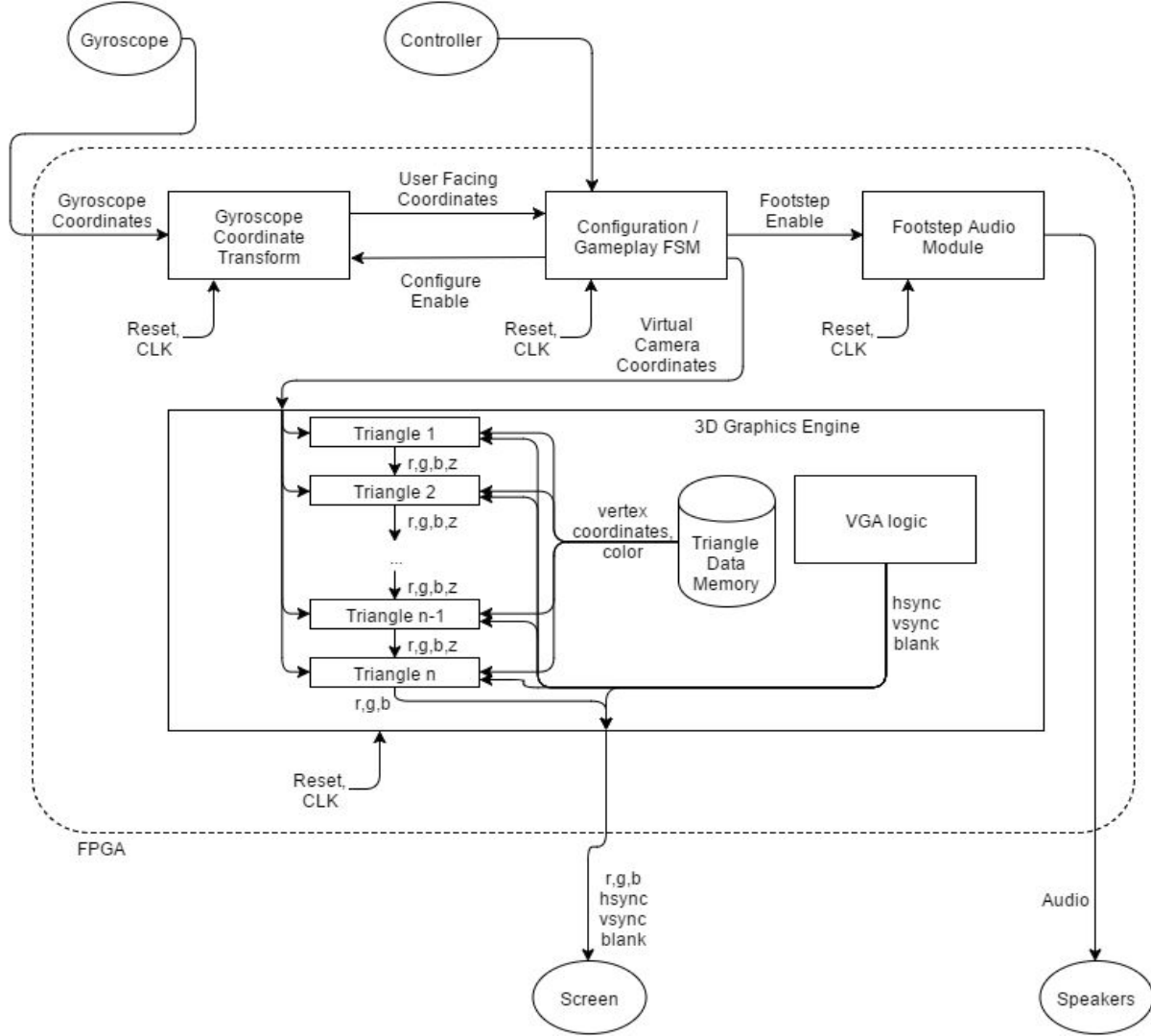
play sound
through FPGA

Game FSM Module

- **Tie everything together**
 - **Configure gyroscope coordinate transform module**
 - **Store user coordinates in registers; update using input from controller**
 - **Combine transformed gyroscope coordinates with user coordinates to get virtual camera coordinates for the graphics module**
 - **Trigger footstep sound**
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Hardware Interface

- **Several necessary parts outside of the labkit**
 - **VGA out and headphone out: part of the labkit**
 - **Gyroscope: external IC, interfaced with ADCs; attached physically to the headphones**
 - **Controller: external component; synchronized in labkit**
- 



Project Completion Timeline	Week of 11/2	Week of 11/9	Week of 11/16	Week of 11/23	Week of 11/30	Week of 12/7
1. Graphics and VGA interface, order parts	Red	Red	White	White	White	White
2. Gyroscope and controller game logic	White	Green	Green	White	White	White
3. Audio module SW	White	White	Blue	White	White	White
4. Interface gyroscope and controller HW	White	White	Blue	Blue	White	White
5. Test integration of modules	White	White	White	Green	Green	White
6. Buffer week for testing and/or catch up	White	White	White	White	Green	White
7. Demo and Checkoff	White	White	White	White	Green	Green