

# FPGA Radar Guidance: Checklist

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## 1. Main FPGA

### (a) Ultrasound

- Commitment:** Can calculate distance to an object with 1 ultrasound
- Commitment:** Can calculate angle to object from 6 ultrasounds
- The Goal:** Can calculate angle and distance as the median of multiple results to improve accuracy

### (b) Orientation and Path Calculation

- The Goal:** Can calculate calculate orientation based on two distance measurements and a bunch of angle calculations
- Stretch Goal:** Can calculate the distance and angle of rotation of the path to a target location
- Stretch Goal:** Can use feedback based controls to get the rover to the desired location

### (c) IR Transmit

- The Goal:** Can send IR commands on my custom protocol to the “Rover”

### (d) VGA Display

- Commitment:** Simple interface show the location of the “Rover”
- The Goal:** Display a more sophisticated display with a basic target pattern in the background
- The Goal:** Display the location of the “Rover” and the target with Alpha blending
- The Goal:** Display the orientation of the “Rover”
- Stretch Goal:** Advance the sophistication of the display (e.g., scaling)
- Stretch Goal:** Add the path to the display

## 2. “Rover”

### (a) IR Receiver

- The Goal:** Can receive IR commands on my custom protocol from the Main FPGA

### (b) Motor Controls

- The Goal:** Can cause the rover to move forward
- Stretch Goal:** Can cause the rover to turn at a desired angle
- Stretch Goal:** Can cause the rover to move a desired distance

## 3. Other

### (a) Reports

- Proposal Draft — *November 2nd*
- Proposal Final — *November 13th*
- Reflection — *November 23rd*
- Final Report — *December 9th*

### (b) Presentations

- Abstract Meeting
- Block Diagram Conference — *Week of November 2nd*
- Practice Presentation — *November 4th*
- Actual Presentation — *November 9th*
- Checklist Meeting — *November 20th*
- Status Update — *November 30th*
- Checkoff — *December 7th*
- Project Demos — *December 8th*