

# Overview

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- Useful Image Processing Approaches
- Application of Image Processing to Major League Baseball Pitch-Tracking

# Basic Image Processing Tools

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- **Lighting Considerations**
- **Thresholding**
- **Morphological Filtering**
  - Basic operations
  - Size sorting
  - Skeletonization
- **Correlation**
  - Object detection in imagery
  - Time delay estimation for signals

# Lighting and Color

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- **Use good even illumination**
  - Imagery less noisy and thresholding is easier
- **Use of color for green screen or object tracking**
  - Use well-lit saturated color for robust extraction
  - Use of color gels can increase contrast

# Thresholding

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- Utilize 8-bit grayscale histogram to separate foreground objects from background
- Iterative algorithm for thresholding
  - Step 1: Scale image values to fill 8-bit dynamic range
  - Step 2: Choose an initial threshold  $T = T_0$
  - Step 3: Partition image using  $T$  into two regions – background and foreground (object)
  - Step 4: Compute mean gray values  $\mu_1$  and  $\mu_2$  of background and object regions respectively
  - Step 5: Compute new threshold  $T = (\mu_1 + \mu_2)/2$
  - Step 6: Repeat Steps 3 thru 5 until there is no significant change in  $T$

# Sobel Operator for Edge Detection

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- Operator uses two 3x3 kernels which are convolved with input image – one for horizontal derivative and one for vertical

$$G_x = \begin{bmatrix} -1 & 0 & +1 \\ -2 & 0 & +2 \\ -1 & 0 & +1 \end{bmatrix} * A \quad G_y = \begin{bmatrix} -1 & -2 & -1 \\ 0 & 0 & 0 \\ +1 & +2 & +1 \end{bmatrix} * A$$

$$G = \sqrt{G_x^2 + G_y^2}$$

# Sobel Example

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*Input Image*



*Sobel Gradient*

# Binary Morphology

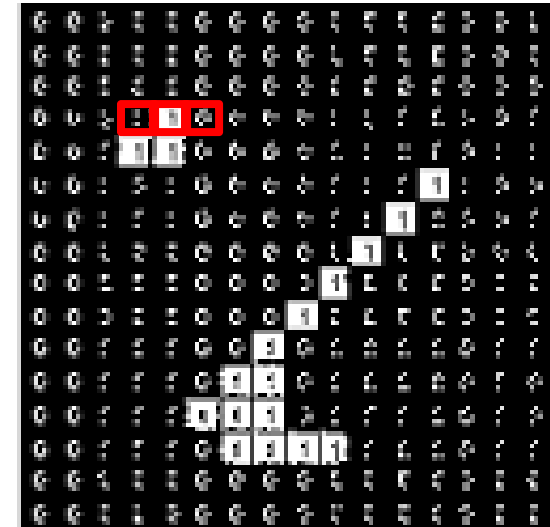
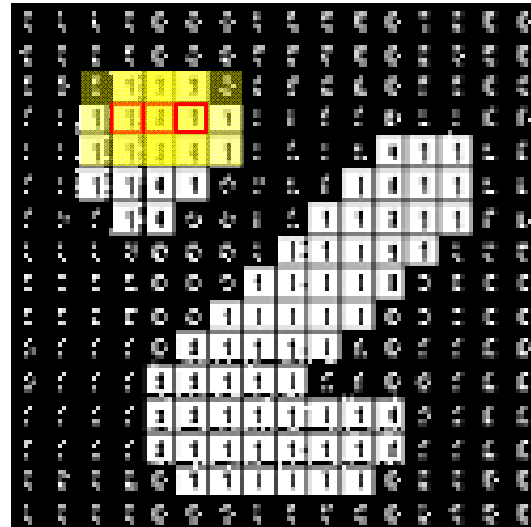
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- Basic idea is to probe an image with a simple, pre-defined shape (structuring element or kernel), drawing conclusions on how this shape fits or misses the shapes in the image
- Basic operators
  - Erosion  $A \ominus B = \bigcap_{b \in B} A_{-b}$
  - Dilation  $A \oplus B = \bigcup_{b \in B} A_b$
  - Opening  $A \circ B = (A \ominus B) \oplus B$
  - Closing  $A \bullet B = (A \oplus B) \ominus B$

# Examples of Erosion and Dilation

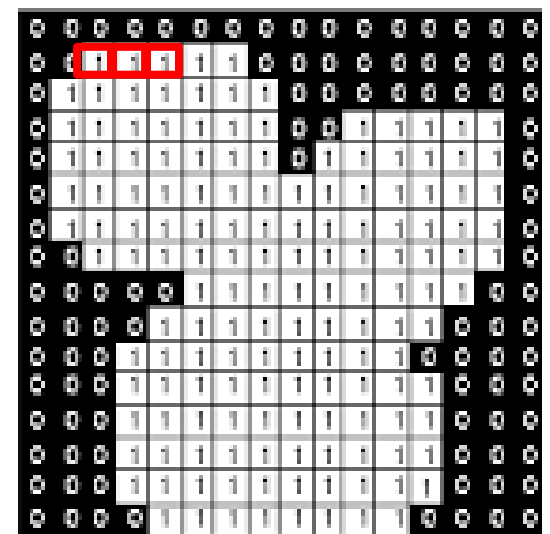
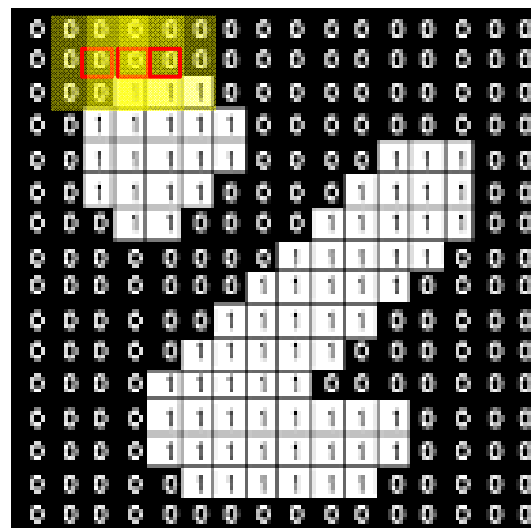
- Erosion

3x3 SE



- Dilation

3x3 SE





# Examples of Opening and Closing

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## ■ Opening

3x3 SE

0 0 0 0 0 0 0 0 0 0 0	→	0 0 0 0 0 0 0 0 0 0 0
0 0 0 0 1 0 0 1 1 0 0		0 0 0 0 0 0 0 0 0 0 0
0 0 0 1 0 0 0 1 1 1 0		0 0 0 0 0 0 0 0 0 0 0
0 0 0 1 1 1 0 0 0 0 0		0 0 0 1 1 1 0 0 0 0 0
0 0 0 1 1 1 0 0 0 0 0		0 0 0 1 1 1 0 0 0 0 0
0 0 0 1 1 1 0 0 0 0 0		0 0 0 1 1 1 0 0 0 0 0
0 0 0 0 0 0 0 0 0 0 0		0 0 0 0 0 0 0 0 0 0 0

*Removes noise*

## ■ Closing

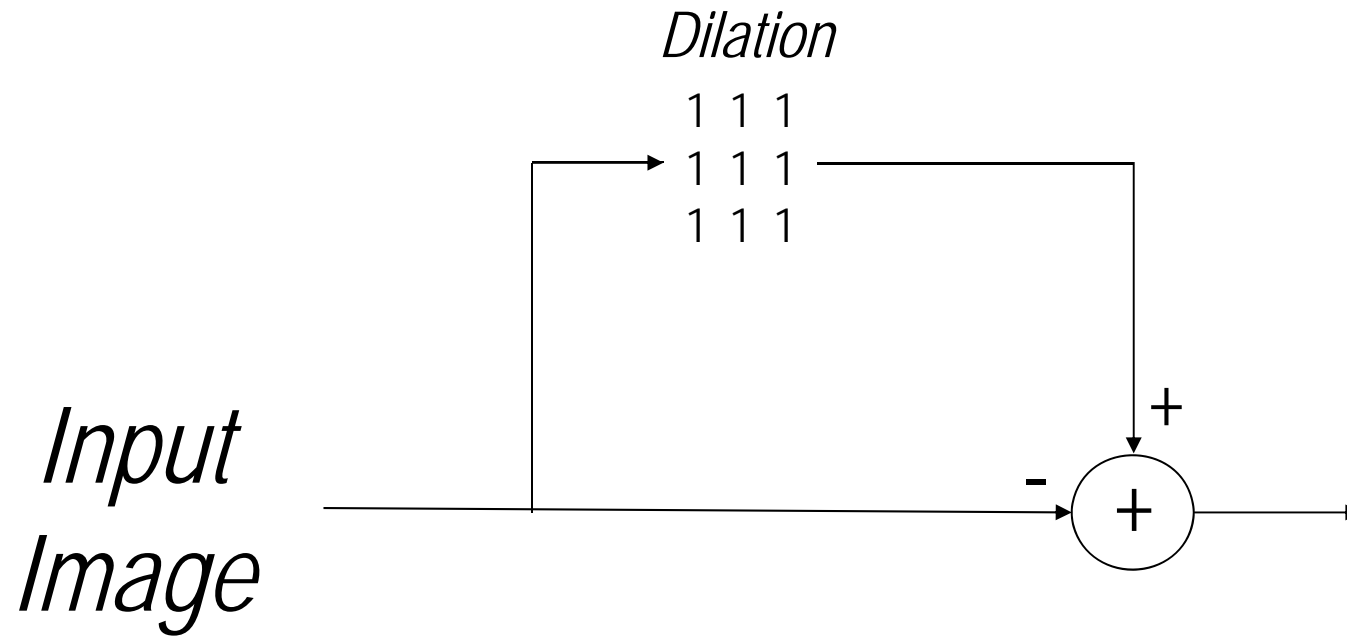
3x3 SE

0 0 0 0 0 0 0 0 0 0 0	→	0 0 0 0 0 0 0 0 0 0 0
0 0 0 1 1 1 1 1 0 0 0		0 0 0 1 1 1 1 1 0 0 0
0 0 0 1 0 0 0 1 0 0 0		0 0 0 1 1 1 1 1 0 0 0
0 0 0 1 1 1 0 1 0 0 0		0 0 0 1 1 1 1 1 0 0 0
0 0 0 1 1 1 1 1 0 0 0		0 0 0 1 1 1 1 1 0 0 0
0 0 0 1 1 1 1 1 0 0 0		0 0 0 1 1 1 1 1 0 0 0
0 0 0 0 0 0 0 0 0 0 0		0 0 0 0 0 0 0 0 0 0 0

*Fills in holes*

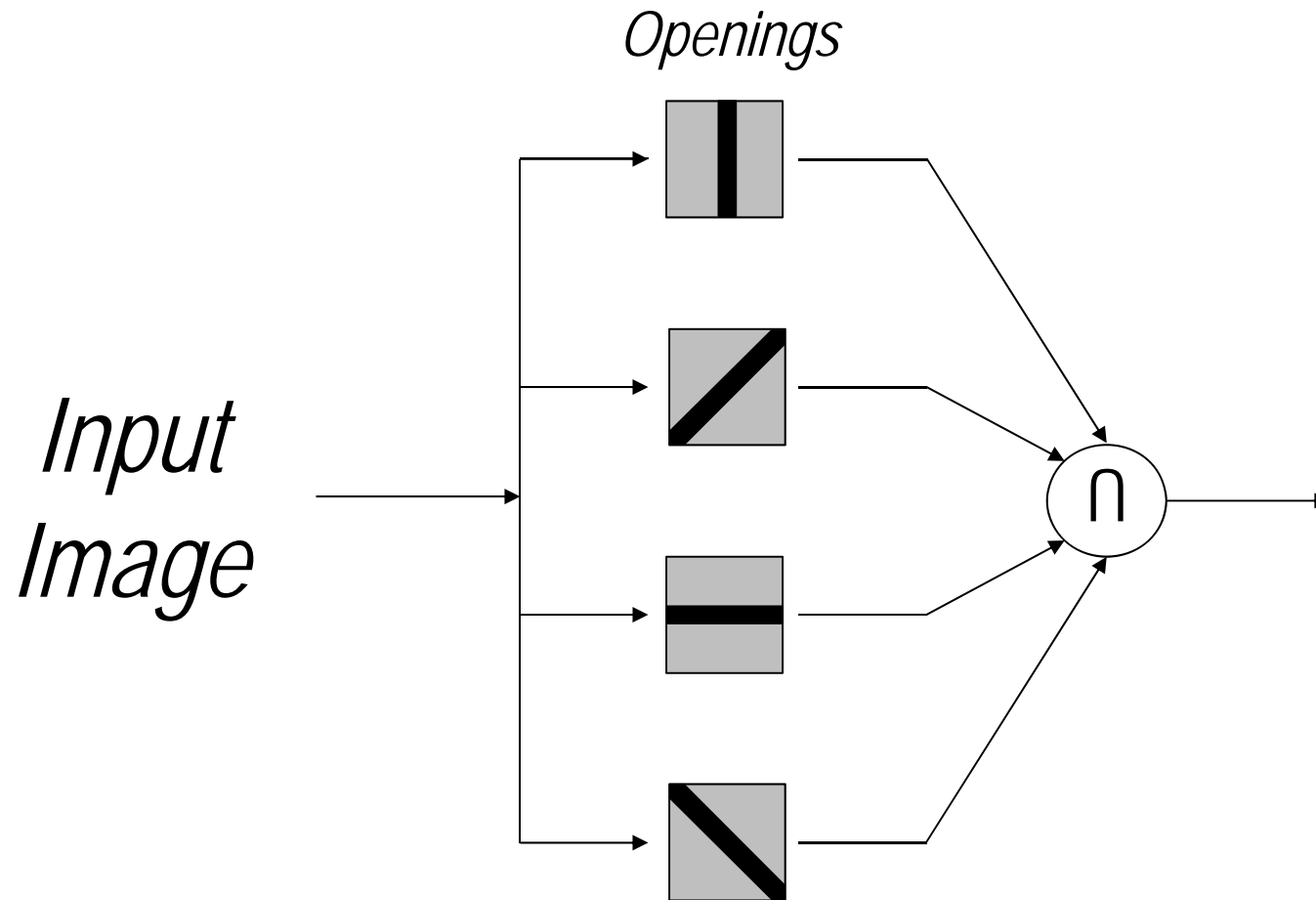
# Binary Edge Detection

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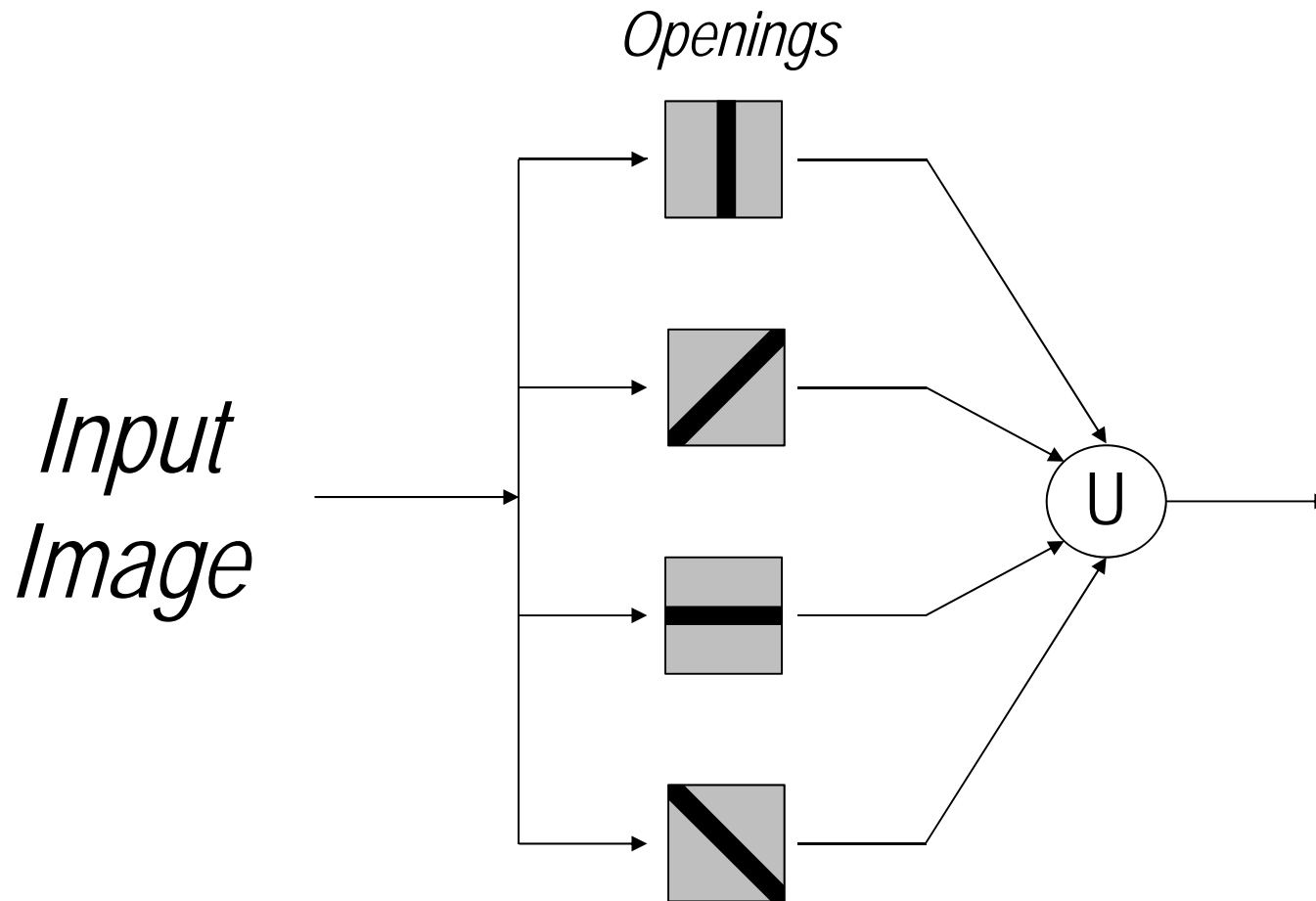
# Composite Filter for Removing Thin Lines & Noise

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# Composite Filter for Removing Compact Objects Smaller than Kernel

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# Taking Advantage of Geometric Structure

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- Objects of a known size
- Objects of a known width and length
- Lines at a particular orientation
- Shapes at a set orientation

# Hit or Miss Operator

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- If the foreground (1) and background (0) pixels in the structuring element *exactly match* foreground and background pixels in the image, then the image pixel underneath the origin of the structuring element is set to background (zero). Otherwise it is left unchanged

0	0	0
	1	
1	1	1

# Skeletonization

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- At each iteration, the image is first thinned by the left hand structuring element, and then by the right hand one, and then with the remaining six  $90^\circ$  rotations of the two elements. The process is repeated in cyclic fashion until none of the thinnings produces any further change.

0	0	0
	1	
1	1	1

	0	0
1	1	0
	1	

*Skeletonization Structuring Elements*





# Correlation for Object Detection

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- Use known shape of object to generate multiple reference instances at different orientations
- Use 2D correlation to detect objects in imagery

# Cross-Correlation Object Detection Example

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*Shape Templates*



# Signal Correlation for Time Delay Estimation

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- Source signal provides reference signal
- Cross-correlating reference signal to delayed signals generates time-offset delay
- Applications
  - EKG R-R interval (corresponds to heart rate)
  - Acoustic signals from microphone array

# Baseball Pitch Tracking

# Outline

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- **A little history**
- **Problem space**
  - Ball characteristics
  - Venues
- **Technical Approach**
  - Passive video
  - Efficient image processing for ball extraction
  - Camera model-based approach for 3-D position
  - Track estimation using 3-D ball positions
- **How MLB currently uses the system**
  - Training and grading umpires
  - Entertaining content for [www.mlb.com](http://www.mlb.com) "gameday"

What do these have in common?

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# A Little History

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## ■ Questec company

- Ex-Wall Street (Ed Plumacher) and an ex-Yankee pitcher (Ron Klimkowski) bought Northrup Grumman tracking technology
- Plan 1 – Sell system to teams
- Plan 2 – Sell data to broadcasters (Fox Sports)
- Plan 3 – Give data to broadcasters, sell advertisements to make money

## ■ Questec system problems

- Requires extensive setup and calibration (>2 hours using survey equipment)
- Requires operator queing of each pitch
- Used old Matrox board, and Questec bought up every board they could find
- Could only field a few systems in select ballparks

# A Little History (how we got involved)

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- **Had already demonstrated cool video processing and tracking technology in sports world**
  - Tracked wind (cat's paws) to help win 1992 America's Cup for Bill Koch
- **Serendipity**
  - We saw Fox Broadcast for MLB playoffs in 2001
  - Approached Questec, and convinced them that we could build a new and better system
  - They gave us three months to field a system for Fenway Park and they would do a bake-off between systems
  - When they saw how easy it was to setup and use and its accuracy, they ditched their system and the rest is history: Fox Sportsnet, Professional Tennis Tour, MLB pitch tracking system (replaced in 2009 by Zone Evaluation system when Questec failed as a business concern)



# Problem Space

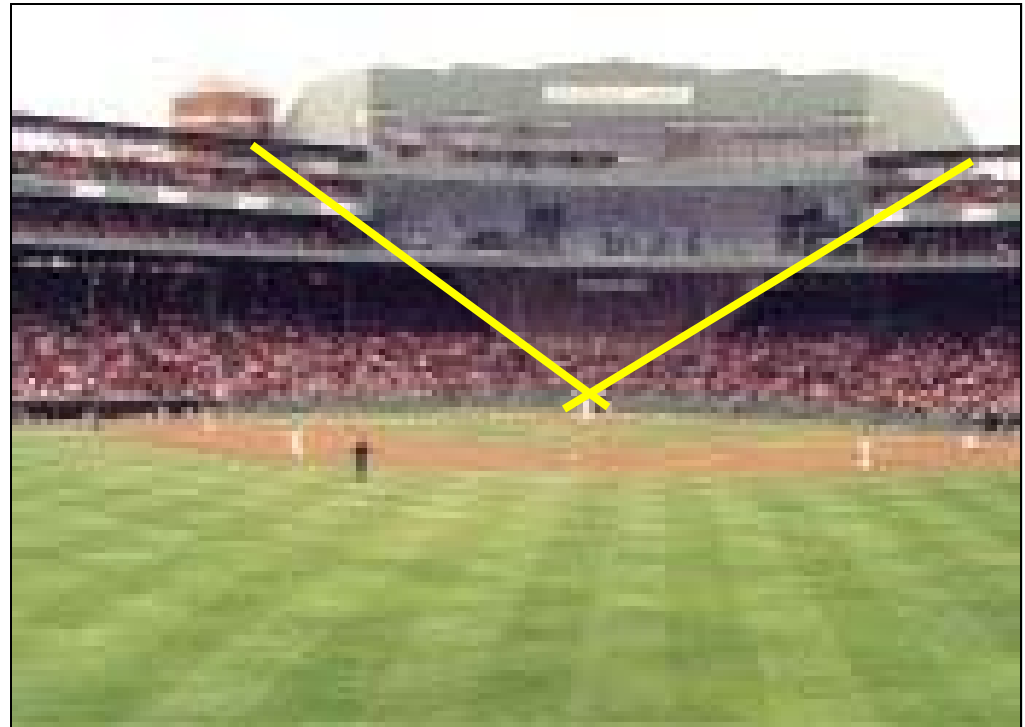
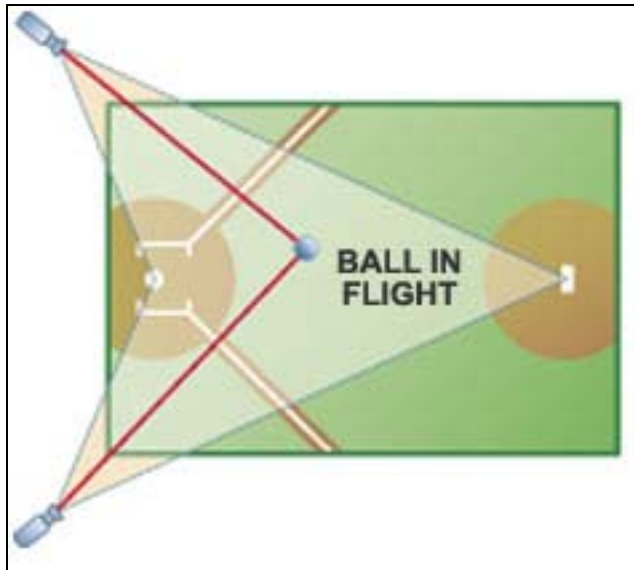
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- **Ball**
  - Known size, color
  - Background, variable (sun shadow, debris, rain, snow, birds, players)
- **Venue**
  - MLB Ballparks
- **Equipment**
  - Inexpensive cameras
  - PCs
  - Digitizing board
  - Analog video mixer
  - Timebase (written to sound track)



# Camera Placement

- Two cameras to solve for ball  $(x,y,z,t)$
- High placement to see the pitching corridor



# Camera Placements

- Attached to ceiling girders



# Field Cameras

- Cameras to collect lefty/righty batter strike zone views





# Center Field Broadcast Camera

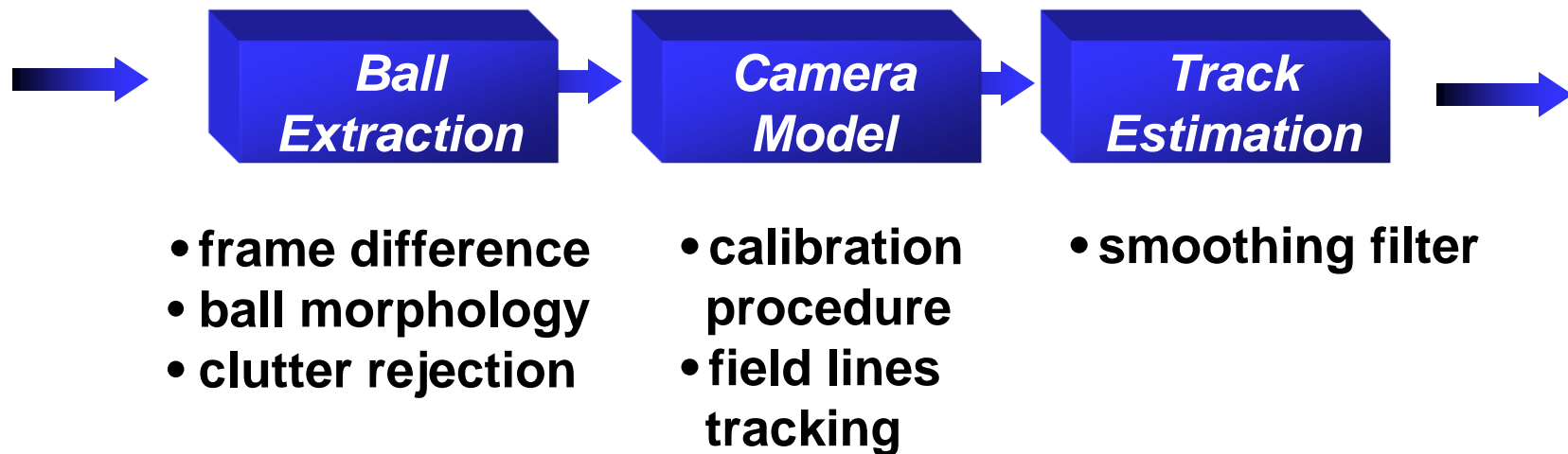
- Broadcast feed to provide movie snippet of pitch for umpire review



# Overall Approach

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- Relies on fast ball extraction
- Calibrated camera model, in-game updates
- Track filter suitable for ball trajectories



# Simultaneous Camera Feeds

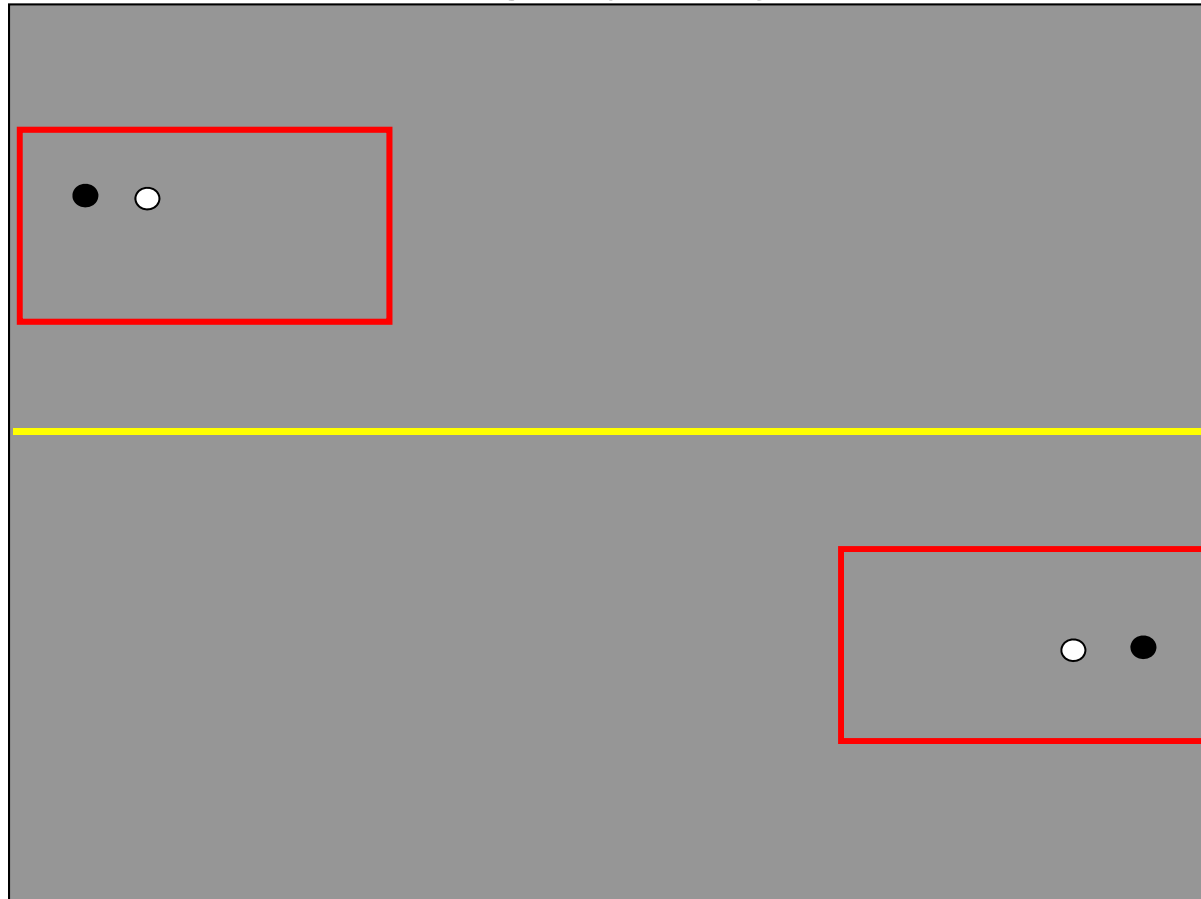
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- Video Mixer allows single frame-grabber card, cameras externally sync'ed
- Pitch appears simultaneously in both images (L to R) (R to L)



# Ball Extraction

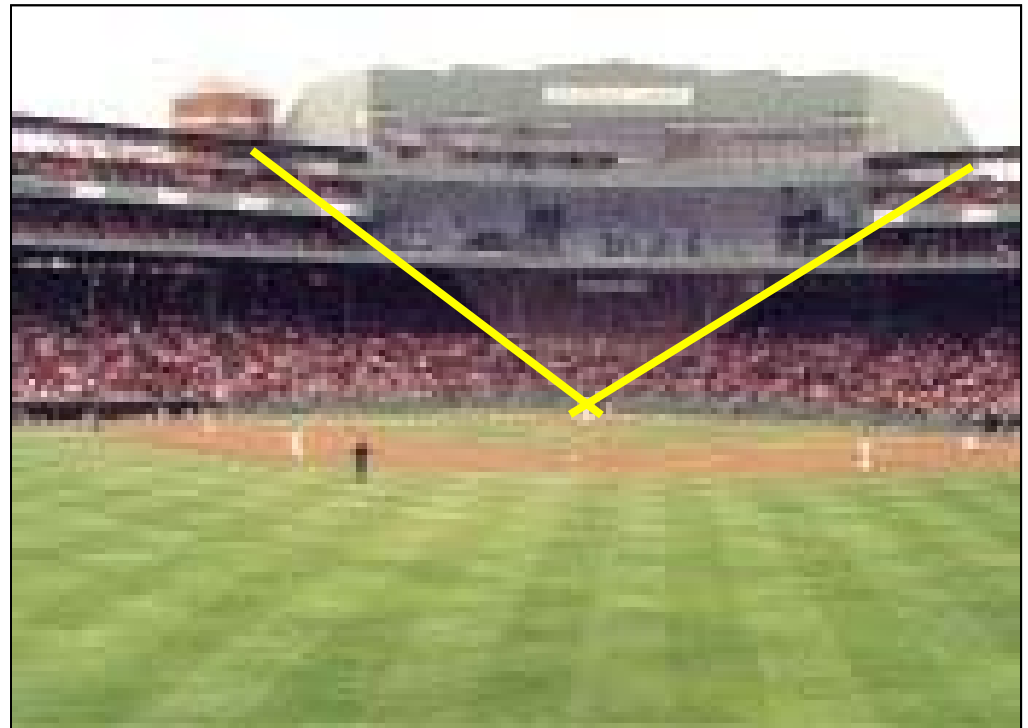
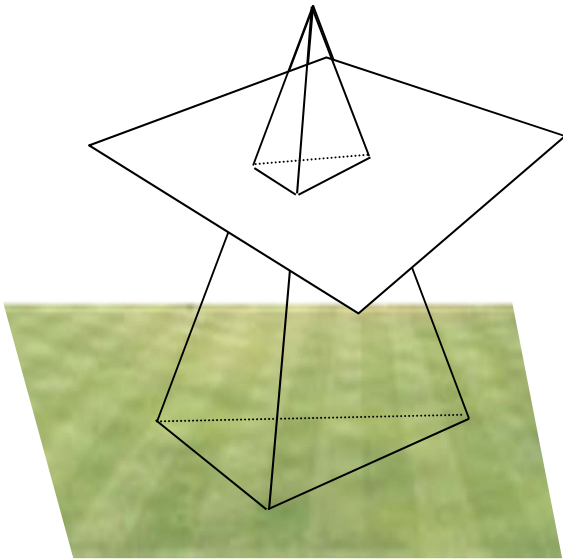
- Frame differencing
- Focused processing for valid pitch
- Two valid detections along trajectory before pitch declared





# Calibration Approach

- Each camera done independently
- Use calibration pattern placed on field
- Photogrammetry solution: Church's method of space resection
- Ideal camera model
- Known focal length



# Calibration Targets

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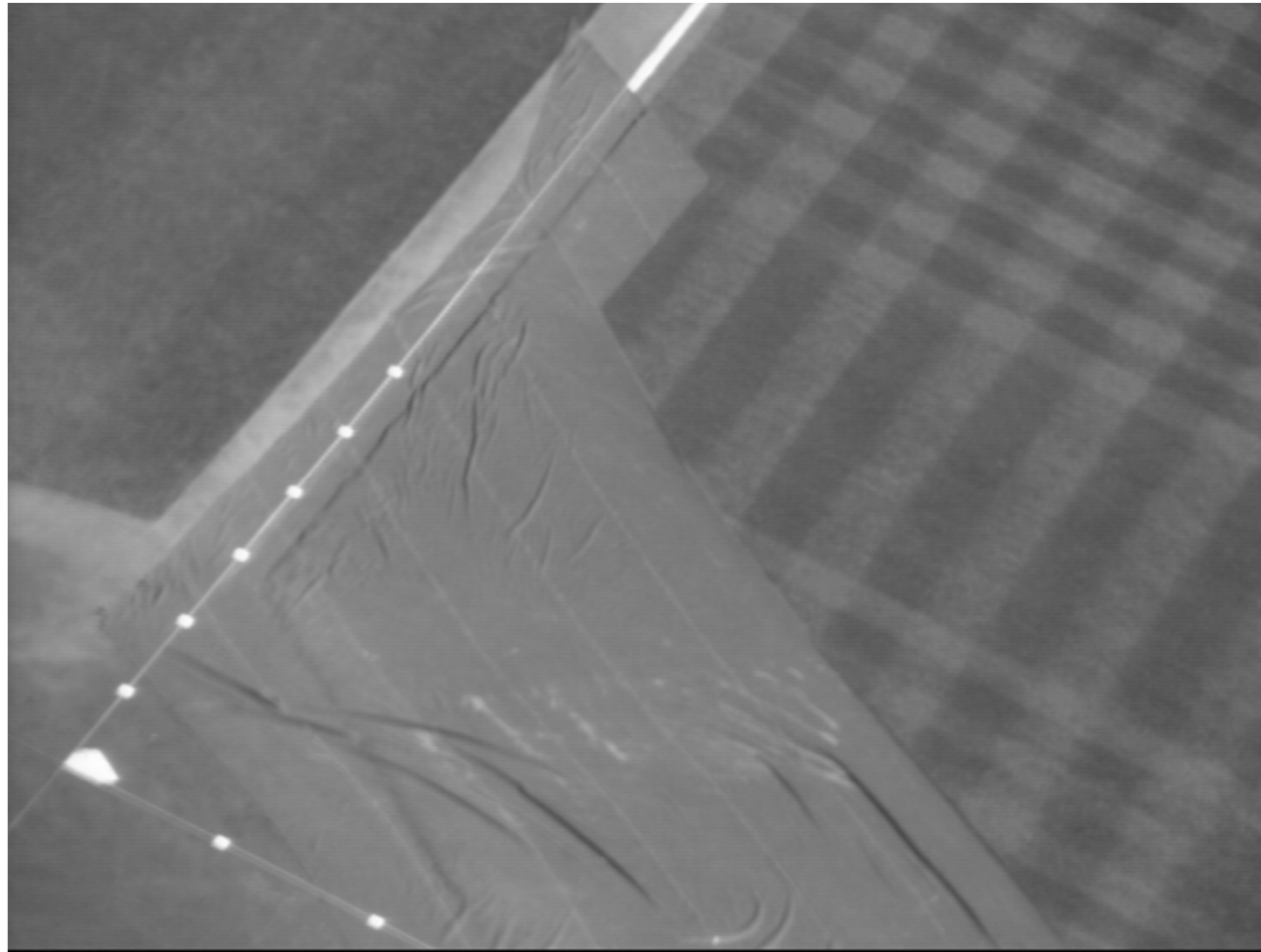
- Field disks plus ball array



# Calibration Targets

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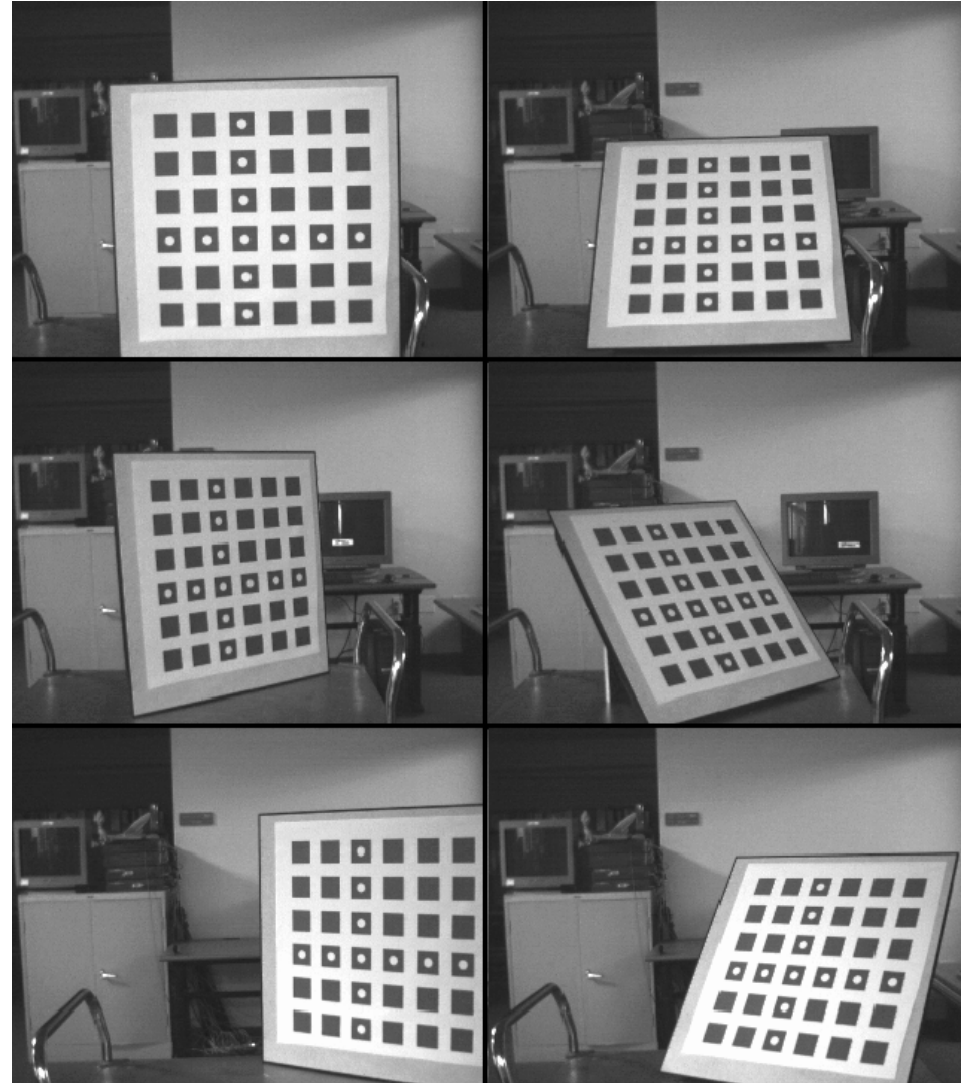
- Linear arrays



# Much Better Calibration Method

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- Zhang's method using multiple views of a calibrated array moving through the field of view
- Would solve for Extrinsic (6 DOF for camera position and pointing) and Intrinsic (Focal length and distortion)



# Tracking Pitches



# Practical Issues

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- **Movements of cameras**
  - Wind vibration, fan stomping
  - Slow heating of steel girders
- **Changing light conditions (stadium shadow)**
- **Snow, rain**
- **Birds and other intervening objects (thrown by fans)**

# Trajectory Smoothing

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- Smoothing done after all 4-D samples extracted
- Piecewise polynomial smoothing (7 points)
  - Pedro's fastball could have as few as 7 samples
  - Wakefield's knuckleball could have as many as 11
- Last polynomial used to extrapolate over the plate
- Measured ball locations to estimates of ball locations at back plane (apex of home plate) confirmed 1-sigma accuracy

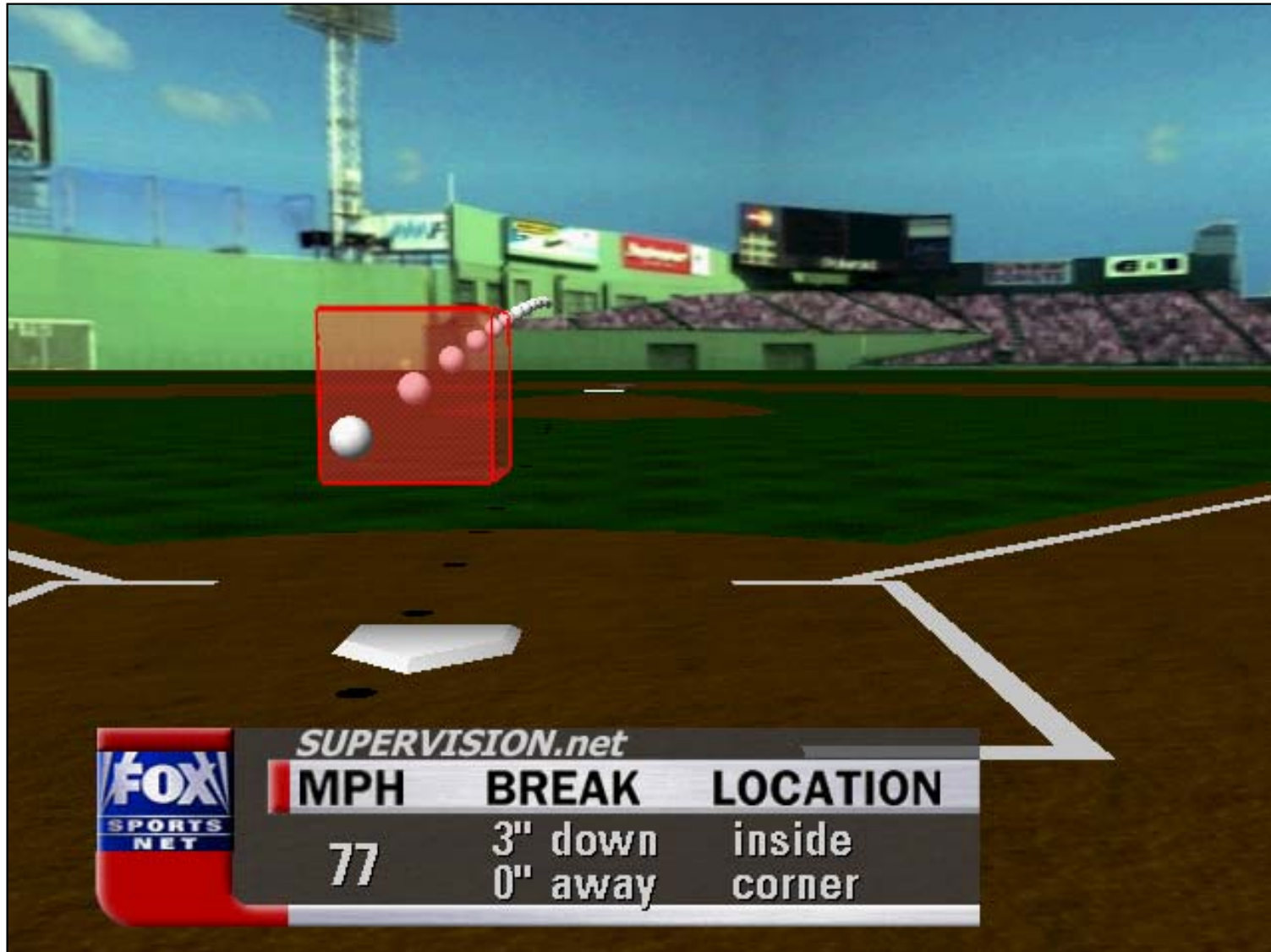
# Accuracy

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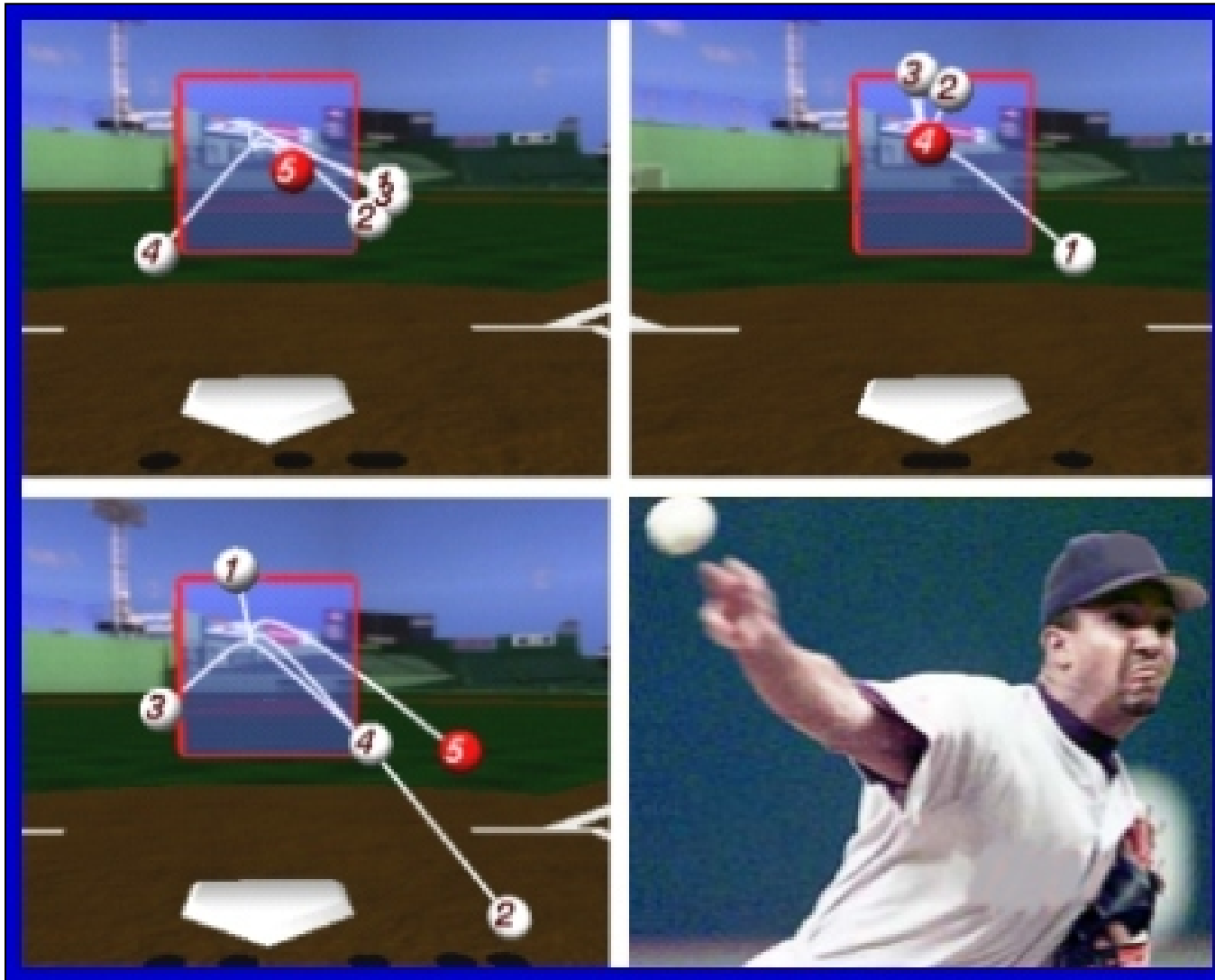
- **Broadcast system: 1.5"**
  - Wider field of view, cheap surveillance cameras, trajectories from mound to plate
- **Umpire Information System: 0.5"**
  - Emphasizing area near plate, higher resolution cameras\*
  - Not worrying about trajectories all the way back to the mound



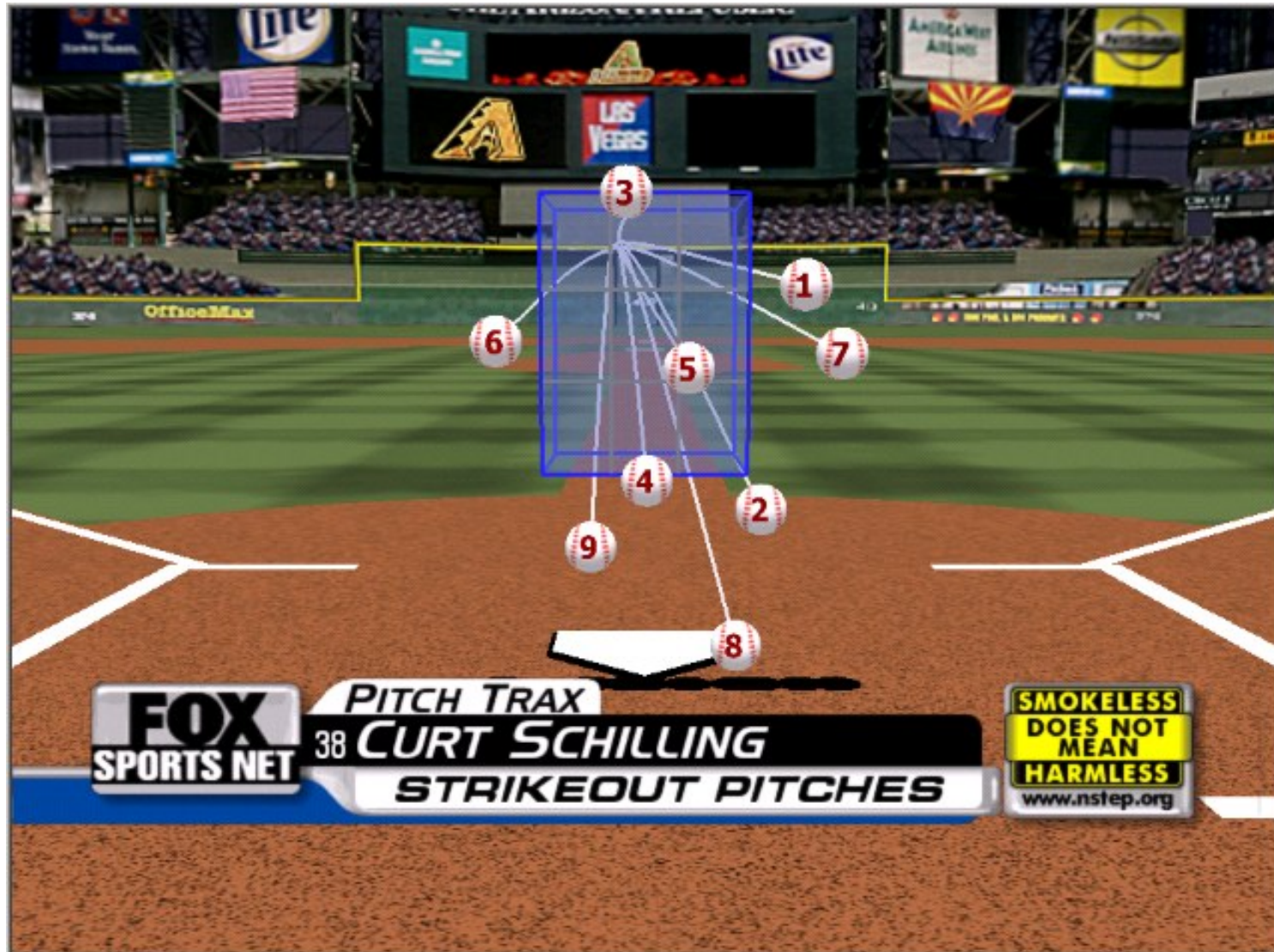
# Fox Broadcast Samples



# Fox Broadcast Samples



# Fox Broadcast Samples



# Vertical Strike Zone Determination

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# Umpire Information System

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# Game Day on MLB.com 2007




(0-0)

## Boston 4, Tampa Bay 1

Top 6th: Live



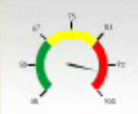
(0-0)




**Josh Beckett** - #19 RHP  
0-0, 1.69 ERA  
75 Pitches - 49 Strikes, 26 Balls

[Collapse](#)

Out pitch: **Four-seam**  
Average fastball: **94.0 mph**  
Steady velocity on **Four-seam FB**



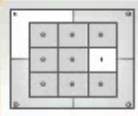


**Carlos Pena** - #23 1B  
.000 AVG, 0 HR, 0 RBI  
0-for-2  
Strikeout (2)

[Collapse](#)

Loves to face: **Four-seam**  
Hates to face: **Four-seam**


	AVG	HR	RBI
vs Beckett:	.000	0	0



On Deck: **Pat Burrell** .000  
In Hole: **Matt Joyce** .000


[Expand](#)

Fenway Park, Boston, MA

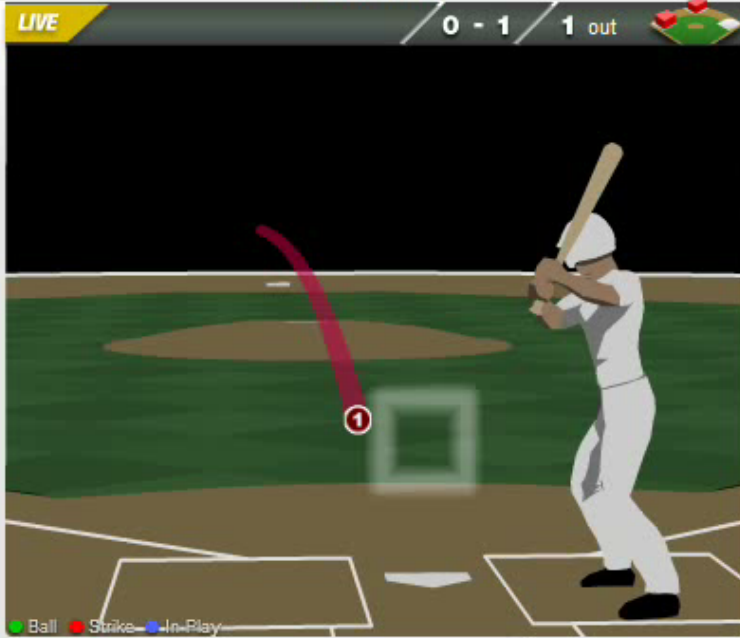


**Runners On:**  
1B:  
2B: C. Crawford  
3B: A. Iwamura

Currently Cloudy

 **44° F** wind 19 mph W  
more info at [weather.com](#)

**LIVE**
0 - 1
1 out



● Ball
● Strike
● In-Play

Pitch-By-Pitch
**Play-By-Play**
Scoring Plays

1
2
3
4
6
7
8
9

2. Carl Crawford doubles (1) on a line drive to left fielder Jason Bay. Akinori Iwamura to 3rd. None out.

3. Evan Longoria pops out to catcher Jason Varitek in foul territory. One out.

4. Pitcher  
**J. Beckett**

SPD	BRK	PFX	PITCH	RESULT
1	90	8"	10"	Fastball

Batter  
**C. Pena**


Swinging Strike

Video
**Boxscore**
Lineups/Bench


	1	2	3	4	5	6	7	8	9	R	H	E
<b>Tampa Bay</b>	0	0	1	0	0					1	2	0
<b>Boston</b>	1	0	3	0	0					4	8	0

Outfield assists: Crawford (Youkilis at 3rd base).  
DP: (Longoria-Pena, C).

Boston	AB	R	H	RBI	BB	SO	LOB	AVG
Ellsbury, CF	3	0	0	0	0	1	0	.000
Pedroia, 2B	2	2	1	1	1	0	0	.500
Ortiz, DH	3	0	1	0	0	0	1	.333
Youkilis, 1B	3	1	2	0	0	0	1	.667
Drew, RF	2	0	1	1	1	0	1	.500
Bay, LF	2	1	1	1	1	0	2	.500
Lowell, 3B	3	0	1	1	0	0	5	.333
Lowrie, SS	2	0	1	0	0	0	0	.500
Varitek, C	2	0	0	0	0	0	2	.000



Sell your extra tickets



# MLB.com App on Ipad 2015

