Massachusetts Institute of Technology Department of Electrical Engineering and Computer Science 6.111 - Introductory Digital Systems Laboratory

Final Project Check Off Sheet

Project Title: Super I/O
Student Name: Ross Glashon, James Wnorowski
TA Name: Chris Forker
TA Signature/Date:
<u>Design</u>
State transition diagrams, Block Diagrams, Code. (Ross)
State transition diagrams, Block Diagrams, Code. (James)
Functionality
☐ I2C interface communicates between different modules using internal bus.
Different module functionality: Digital I/O, motor, servo, LCD, analog input, shaft encoder.
Demonstrate controlling a robot using the Super I/O.
Discussion
How is the interface between modules controlled? What limits the number of modules that can be implemented?