# Massachusetts Institute of Technology

Department of Electrical Engineering and Computer Science

6.242, Fall 2004: MODEL REDUCTION \*

# Problem set 3 solution<sup>1</sup>

# Problem 3.1

Hankel singular numbers of a stable causal LTI system  ${\cal G}$  of very large order are given by

 $\sigma_k(G) = 2^{-m}$  for  $k = 2^m + 1, \dots, 2^{m+1}$ ,  $(m = 0, 1, \dots)$ ,  $\sigma_1(G) = 2$ .

(a) Suggest a good a-priori lower bound for the quality  $||G - \hat{G}||_{\infty}$  of approximating G by a system  $\hat{G}$  of order 8.

The available lower bound is  $\sigma_9(G) = 1/8$ .

(b) Suggest a good a-priori upper bound for the quality  $||G - \hat{G}_{btr}||_{\infty}$  of approximating G by a system  $\hat{G}_{btr}$  of order 8 using the method of balanced truncation.

The available upper bound equals the double sum of *different* singular values  $\sigma_k(G)$  with k > 8, which yields

$$2(2^{-3} + 2^{-4} + 2^{-5} + \dots) = 2 \cdot 2^{-2} = 1/2.$$

<sup>\*©</sup>A. Megretski, 2004

<sup>&</sup>lt;sup>1</sup>Version of October 26, 2004.

(c) What are the Hankel singular numbers of  $\hat{G}_{btr}$  from (b)?

As it is proven in the lecture notes, Hankel sinular numbers of the 8-th order reduced system are the first eight Hankel numbers of G:

2, 1, 1/2, 1/2, 1/4, 1/4, 1/4, 1/4.

#### Problem 3.2

Give an explicit description of the set of all possible n-vectors

 $[\sigma_1(G), \sigma_2(G), \ldots, \sigma_n(G)],$ 

FORMED BY THE HANKEL SINGULAR VALUES  $\sigma_k(G)$  OF ALL STABLE "ALL PASS" TRANS-FER FUNCTIONS G OF ORDER n (I.E. SUCH THAT  $|G(j\omega)| = 1$  FOR ALL  $\omega$ ).

(a) DESIGN A NUMERICAL EXPERIMENT, UTILIZING MATLAB FUNCTIONS lyap, chol, AND eig, TO COLLECT DATA ON THE TOPIC. (DO NOT USE sysbal AND SIMILAR "FULL SERVICE" MODEL REDUCTION FUNCTIONS.)

Function hsvd\_6242.m provides calculation of Hankel singular values for stable systems of moderate order. (It can also produce a reduced order system, when necessary.)

```
function H=hsvd_6242(G,m)
% function H=hsvd_6242(G,m)
%
% Hankel svd for CT stable system G
    with one argument: H is the ordered vector of Hankel singular values
%
%
    with two arguments: H is the m-th order btr reduced system
               % a test example
if nargin<1,
    G=ss(diag(-(1:30)),ones(30,1),ones(1,30),0);
    m=3;
end
[A,B,C,d] = ssdata(G);
Wc=lyap(A,B*B');
Wo=lyap(A',C'*C);
[V,D]=eig(Wc*Wo);
```

```
V=real(V);
[W,I]=sort(-sqrt(abs(diag(D))));
V=V(:,I);
W = -W;
if nargin==1,
    H=W;
else
    V=V(:,1:m);
    U=(V'*Wo*V)\setminus(V'*Wo);
    H=ss(U*A*V,U*B,C*V,d);
end
if nargin~=1,
    w=linspace(0,100,1000);
    g=squeeze(freqresp(G,w));
    g1=squeeze(freqresp(H,w));
    close(gcf)
    subplot(2,1,1);plot(w,real(g),w,real(g1)); grid
```

end

Function  $ps32_6242_2004.m$  generates random all-pass systems and calculates their Hankel singular numbers, utilizing  $hsvd_6242.m$ .

subplot(2,1,2);plot(w,imag(g),w,imag(g1)); grid

```
function ps32_6242_2004(n,m)
% function ps32_6242_2004(n,m)
%
% solves Problem 3.2a by generating a random all-pass
% stable transfer function G of order n+2m (n real poles, 2n complex poles)
% and finding its Hankel singular values
%
% uses hsvd_6242.m
if nargin<1, n=5; end
if nargin<2, m=5; end
p=rand(n); % -p are real poles
a=rand(m); % -a are real parts of complex poles</pre>
```

```
b=rand(m); % b are imaginary parts of complex poles
s=tf('s');
G=1;
for k=1:n,
    G=G*((s-p(k))/(s+p(k)));
end
for k=1:m,
    G=G*((s^2-2*a(k)*s+a(k)^2+b(k)^2)/(s^2+2*a(k)*s+a(k)^2+b(k)^2));
end
hsvd_6242(G)
```

(b) FORMULATE A HYPOTHESES ON WHAT THE ANSWER IS.

The numerical experiment indicates clearly that all Hankel singular numbers of an all-pass system equal 1.

(c) PROVE THE HYPOTHESES (AT LEAST FOR THE CASE n = 2).

Let

$$G(s) = C(sI - A)^{-1}B + D$$

be an all-pass stable transfer function. Without loss of generality, assume that A is an *n*-by-*n* Hurwitz matrix, the pair (A, B) is controllable, and the pair (C, A) is observable.

The most important step of the proof is to establish existence of a matrix P = P' such that

$$2\bar{x}'P(A\bar{x}+B\bar{f}) = |\bar{f}|^2 - |C\bar{x}+D\bar{f}|^2 \quad \forall \ \bar{f} \in \mathbf{R}, \ \bar{x} \in \mathbf{R}^n,$$
(3.1)

which is a special case of the KYP (Kalman-Yakubovich-Popov) Lemma.

To prove (3.1) independently, define P as the observability Gramian  $P = W_o$ . By assumption,

$$|G(j\omega)|^2 - 1 = 0 \quad \forall \ \omega \in \mathbf{R}.$$

Hence

$$\int_{-\infty}^{\infty} (|\tilde{y}(j\omega)|^2 - |\tilde{f}(j\omega)|^2) d\omega = 0,$$

where  $\tilde{f}$  is the Fourier transform of a square integrable function f = f(t) defined for  $t \ge 0$ , and  $\tilde{y}(j\omega) = G(j\omega)\tilde{f}(j\omega)$ . According to the Parceval identity, this means that

$$\int_{0}^{\infty} (|Cx(t) + Df(t)|^{2} - |f(t)|^{2})dt = 0$$

for the solution x = x(t) of

$$\dot{x}(t) = Ax(t) + Bf(t), \quad x(0) = 0.$$
 (3.2)

Since

$$\int_{T}^{\infty} (|Cx(t) + Df(t)|^2 - |f(t)|^2) dt = x(T)' W_o x(T)$$

whenever  $f(t) \equiv 0$  for  $t \geq T$ , we have

$$x(T)'W_o x(T) + \int_0^T (|Cx(t) + Df(t)|^2 - |f(t)|^2) dt \equiv 0$$

for every solution of (3.2). Differentiating this with respect to T yields

$$2x(T)'W_o(Ax(T) + f(T)) + |Cx(T) + Df(T)|^2 - |f(T)|^2 \equiv 0$$

Since the pair (A, B) is controllable, x(T) can be an arbitrary vector from  $\mathbb{R}^n$ . Since f(T) can also be chosen arbitrarily (and independently of x(T)), identity (3.1) holds for  $P = W_o$ .

Once (3.1) is established, comparing the coefficients at fx on both sides of the identity yields

$$B'P + DC = 0.$$

In addition, comparing the coefficients at  $f^2$  yields  $D^2 = 1$ . Substituting  $C = -D^{-1}B'W_o$  into the Lyapunov equation

$$W_o A + A' W_o = -C'C$$

and multiplying by  $W_o^{-1}$  on both sides yields

$$AW_o^{-1} + W_o^{-1}A' = -BB'.$$

Hence  $W_c = W_o^{-1}$ , and the Hankel singular values of G, as square roots of the eigenvalues of  $W_o W_c = I_n$ , are all equal to 1.

# Problem 3.3

Use the method of balanced truncation to find a 10th order reduced model for the system described in Problem 2.3, with M = 1, B = 0.2, K = 4, and n = 50. (Do not use sysbal and similar "full service" model reduction functions.)

The task is performed by  $ps33_6242_2004.m$ . Applying balanced truncation in the case M = 1, B = 0.2, K = 4, n = 50 fails miserably, which can explained by the fact that there are no 10th order approximations which are good "accross the spectrum" in this case. On the other hand, for a larger dissipation factor B = 20, balanced truncation performs much better than the moments matching methods from problem set 2.

```
function ps33_6242_2004(n,m,M,R,K)
% function ps33_6242_2004(n,m,M,R,K)
%
% Solves Problem 3.3
if nargin<1, n=50; end
if nargin<2, m=10; end
if nargin<3, M=1; end
if nargin<4, R=0.2; end
if nargin<5, K=4; end
g=(2*(n^2)*K/M)*toeplitz([ 2 -1 zeros(1,2*n-1)]);
In=eye(2*n+1);
On=zeros(2*n+1);
b=[1;zeros(2*n,1)];
c=[zeros(1,n) 1 zeros(1,n)];
A=[On In; -g - (R/M)*In];
B=[zeros(2*n+1,1);b];
C=[c zeros(1,2*n+1)];
G=ss(A,B,C,0);
H=hsvd_6242(G,m);
```