Massachusetts Institute of Technology 6.435 Theory of Learning and System Identification

Prof. Dahleh, Prof. Mitter	Homework 2
Out 2/25	Due F, $3/9$

1 [Generalized Glivenko-Cantelli] Consider the set of events characterized by:

$$A_{\alpha} = \{ z | L(z, \alpha) = 1 \}, \alpha \in \Lambda.$$

Show that the frequencies will converge to their probabilities *uniformly* over the set of events described above if and only if the set of functions $L(z, \alpha), \alpha \in \Lambda$ has a finite VC dimension.

2 [Markov Chains] Consider a discrete Markov chain of order n. Assume the chain has a single recurrent aperiodic class. Suppose we make the observations $x_1, x_2, \dots, x_{\ell}$.

- 1. Compute the ML estimate of the transition probability matrix.
- 2. What is the limiting behavior of such estimates? You don't need to prove your claim, just quote the appropriate results.
- 3. Define the KL distance between two chains with the same set of states and with probability functions P and Q, as:

$$D(P||Q) = \lim_{n \to \infty} \frac{1}{n} D(P_{X_1, \dots, X_n}||Q_{X_1, \dots, X_n}).$$

Show that $D(P||Q) = D(P_{X_i|X_{i-1}}||Q_{X_i|X_{i-1}})$, where the conditional KL distance is computed relative to the stationary distribution of the first chain. Recall the definition:

$$D(P_{Y|X}||Q_{Y|X}) = \mathbf{E}_{P_X P_{Y|X}} \left[\log \frac{P_{Y|X}}{Q_{Y|X}} \right].$$

[Hint: Use the chain rule $D(P_{X,Y}||Q_{X,Y}) = D(P_X||Q_X) + D(P_{Y|X}||Q_{Y|X})$.]

4. Show that if P_{α} is a parametrization of a class of transition probabilities, then the ML estimate from this class has the uniform convergence property. Show that the ML estimate converges to the min_{α} $D(P||P_{\alpha})$. [Hint: Imitate the lecture for the finite range case.]

3 [VC Dimension and Parametrization]

(a) Consider the class of one-dimensional functions:

$$y = \theta \left(\sum_{j=1}^{n} |a_j x^j| \cdot \operatorname{sgn}(x) + a_0 \right), \qquad a_j, x \in \mathbf{R}.$$

What is the VC dimension of this class? How does it relate to the number of parameters describing the function?

(b) Consider the class of functions:

$$y = \theta \Big(\sin(\beta x) \Big), \qquad \beta \in (0, \infty), \quad x \in (0, 2\pi).$$

Show that this one-parameter class of functions has infinite VC dimension.

4 [Convex Polytopes] Let C be the set of two-dimensional convex polygones with finite but arbitrary number of faces. Consider the class of two-dimensional functions defined as the interiors of polygones in C:

$$y = I_A(x)$$
 $x \in \mathbf{R}^2$, $A \in \mathcal{C}$.

- (a) Show that the VC dimension of this class is infinite.
- (b) Assume the true model is the interior of some $A \in C$. Consider the algorithm which starts with $S_0 = \emptyset$ and $\hat{A}_0 = \emptyset$, and computes the convex hull of positive samples:

$$S_k = \begin{cases} S_{k-1} \cup \{x_k\}, & \text{if } y_k = 1 \text{ and } x_k \notin \hat{A}_{k-1}, \\ S_{k-1}, & \text{otherwise}; \end{cases}$$
$$\hat{A}_k = \text{ConvexHull}(S_k).$$

Show that if the data is sampled uniformly in a rectangle containing A, then the algorithm converges:

$$\mathbf{P}(A \bigtriangleup \hat{A}_k) \to 0, \qquad k \to \infty,$$

where X riangle Y is the symmetric difference of X and Y, i.e. $X riangle Y = (X \cap Y^c) \cup (X^c \cap Y)$. (In this case, you can show that $\hat{A}_k \subset A$, and thus $A riangle \hat{A}_k = A \setminus \hat{A}_k$.)

(c) Is there a discrepancy between the implications of parts (a) and (b)? Justify your answer.

5 [optional] [Δ -Margin Separating Hyperplane]

Consider the class of N-dimensional functions:

$$y = \begin{cases} 1, & \text{if } w'x - b \ge \Delta, \\ 0, & \text{if } w'x - b \le -\Delta, \end{cases} \qquad w, b, x \in \mathbf{R}^N, \quad |w| = 1.$$

Note that the class defines hyperplanes separating the space into two halves, but has no specification for points lying within a margin Δ of each half-space. If we think of the function as a classifier, such points cannot be labeled, and are considered misclassified.

Show that, for N = 2, the VC dimension of the Δ -margin separating hyperplane is bounded from above by:

$$\min\left\{N, \frac{R^2}{\Delta^2}\right\} + 1,$$

where R is the radius of the smallest ball containing all the data points. (The result can be generalized to all N).