

Josephson Circuits I.

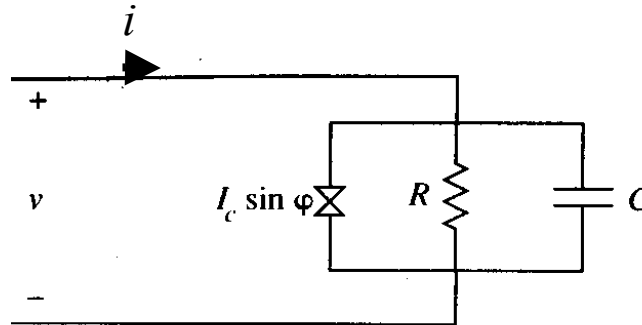
Outline

1. RCSJ Model Review
2. Response to DC and AC Drives
 - Voltage standard
3. The DC SQUID
4. Tunable Josephson Junction

October 21, 2003



JJ RCSJ Model as Circuit Element



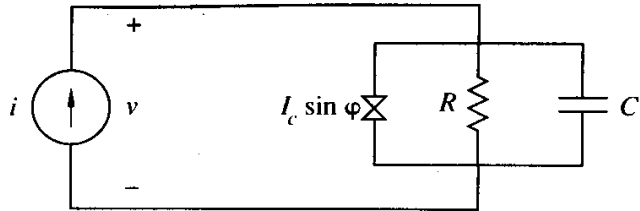
$$i = I_c \sin \varphi + \frac{v}{R} + C \frac{dv}{dt} \quad \text{and} \quad v = \frac{\Phi_o}{2\pi} \frac{d\varphi}{dt}$$

Therefore,

$$i = I_c \sin \varphi + \frac{\Phi_o}{2\pi R} \frac{d\varphi}{dt} + C \left(\frac{\Phi_o}{2\pi} \right)^2 \frac{d^2\varphi}{dt^2}$$



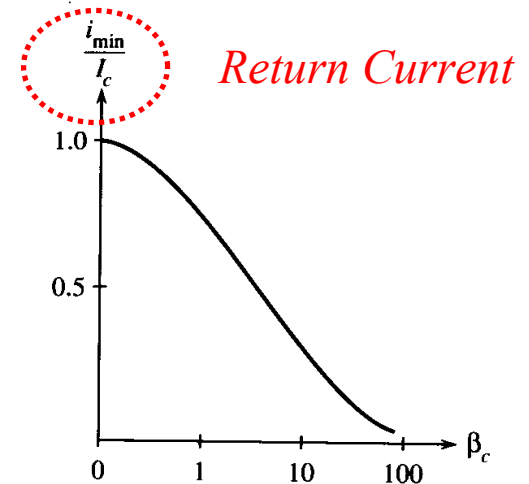
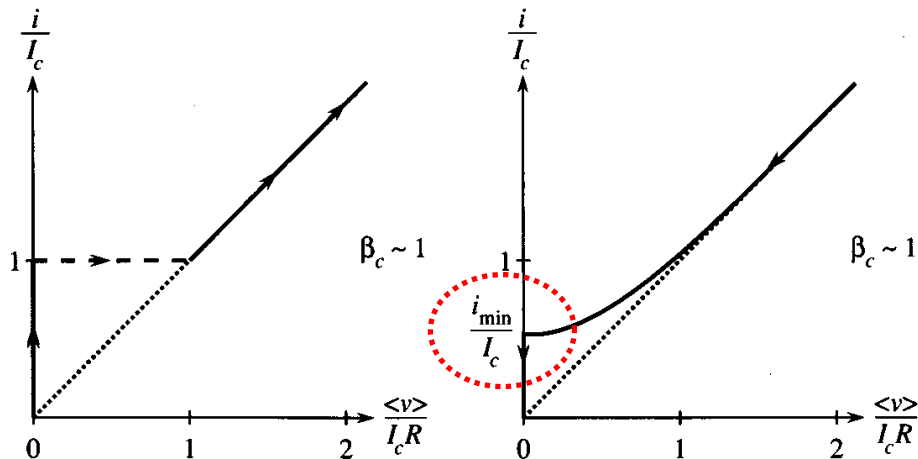
DC Current Drive



$$\beta_c = \frac{\tau_{RC}}{\tau_J} = \frac{R^2 C}{L_J} = \frac{2\pi I_c R^2 C}{\Phi_0}$$

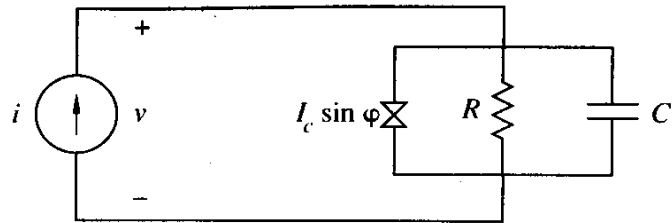
A. Static Solution: $\varphi = \sin^{-1} \frac{i}{I_c}$ for $i \leq I_c$

B. Dynamical Solution



DC Voltage Drive

The voltage source is DC with $v=V_0$, so that



$$\varphi(t) = \varphi(0) + \frac{2\pi}{\Phi_0} V_0 t$$

The resulting current across the JJ is ac

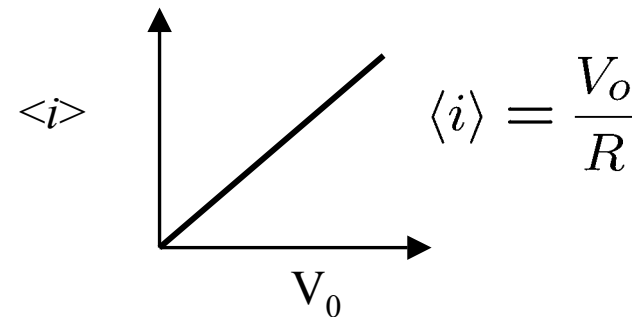
$$i_J = I_c \sin \left(\frac{2\pi}{\Phi_0} V_0 t + \varphi(0) \right)$$

The current across the resistor is dc

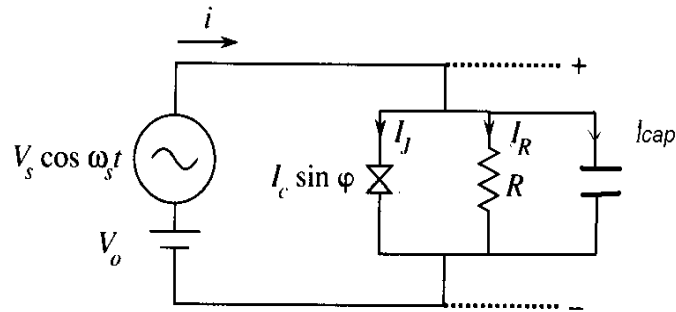
$$i_R = \frac{V_0}{R}$$

The total current is then

$$i = \frac{V_0}{R} + I_c \sin \left(\frac{2\pi}{\Phi_0} V_0 t + \varphi(0) \right)$$



AC Voltage Drive



The voltage source $v(t) = V_o + V_s \cos \omega_s t$

Then the gauge-invariant phase is

$$\varphi(t) = \varphi(0) + \frac{2\pi}{\Phi_o} V_o t + \frac{2\pi V_s}{\Phi_o \omega_s} \sin \omega_s t$$

The resulting current across the JJ is

$$i_J = I_c \sin \left(\varphi(0) + \frac{2\pi}{\Phi_o} V_o t + \frac{2\pi V_s}{\Phi_o \omega_s} \sin \omega_s t \right)$$

The current across the resistor is

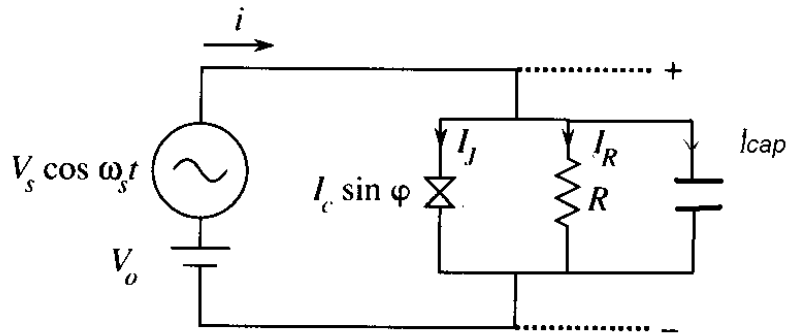
$$i_R(t) = \frac{V_o}{R} + \frac{V_s}{R} \cos \omega_s t$$

The current across the capacitor is $i_C(t) = -C V_s \omega_s \sin \omega_s t$

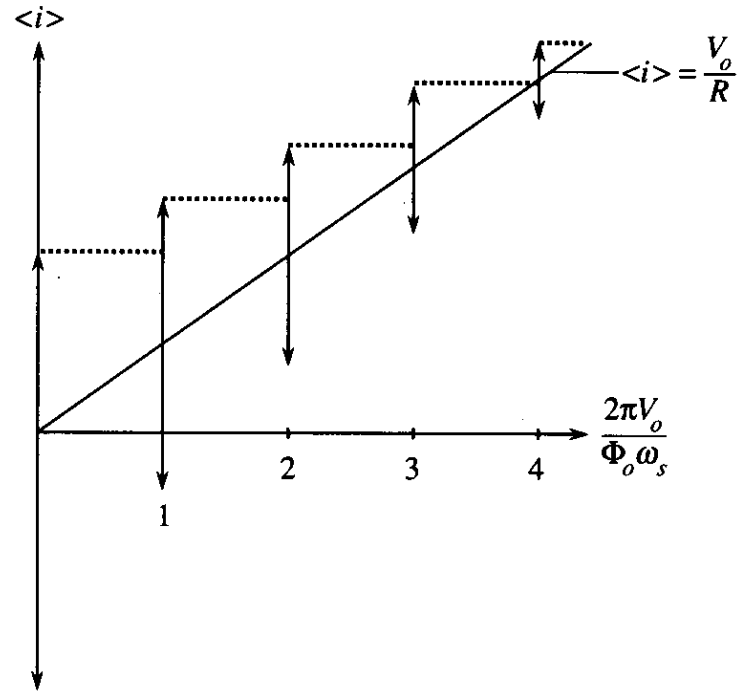
The total current is then $i(t) = i_R + i_J + i_C$



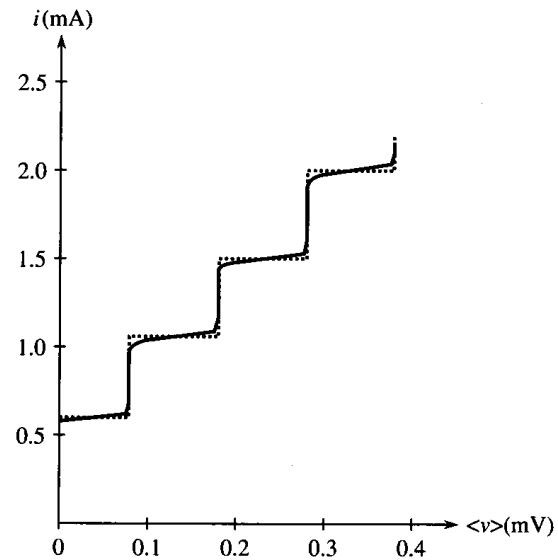
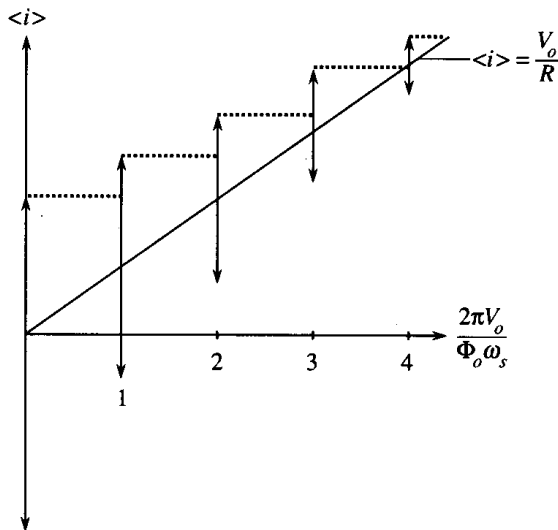
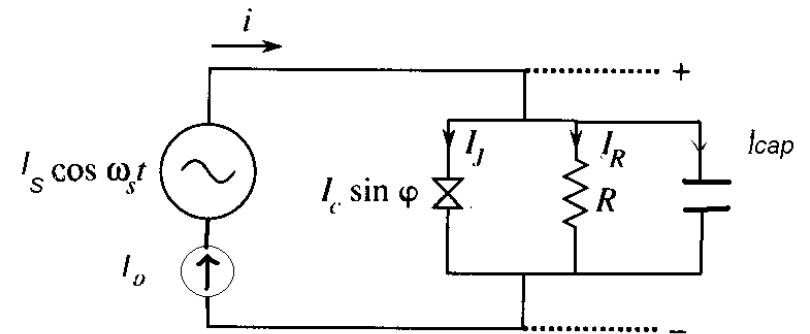
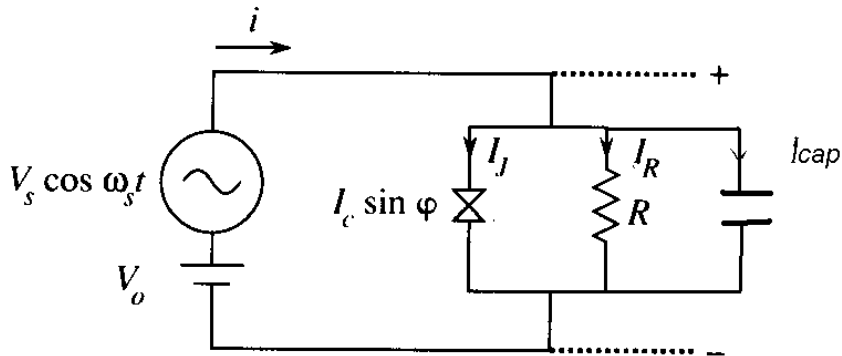
AC Voltage Drive



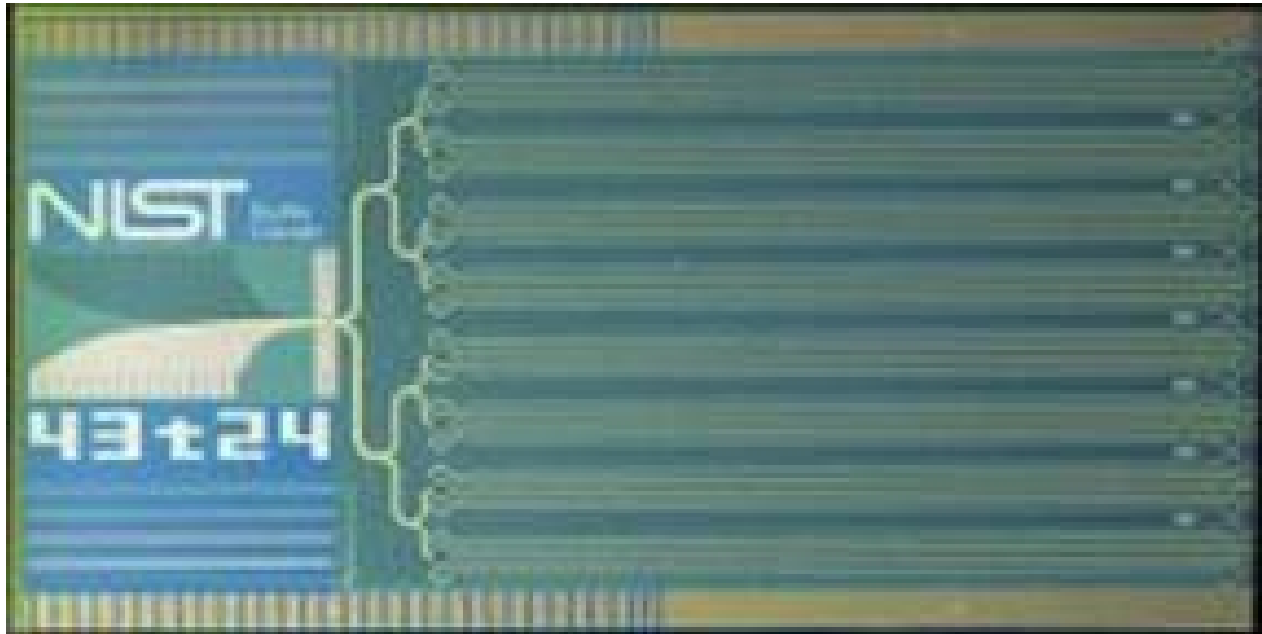
$$\langle i \rangle = \frac{V_o}{R} + I_c \sum_{n=-\infty}^{+\infty} (-1)^n J_n \left(\frac{2\pi V_s}{\Phi_o \omega_s} \right) \sin \varphi(0) \delta_{2\pi f_J, n\omega_s}$$



AC Voltage vs Current Drives



Voltage Standard



10 V conventional Josephson voltage standard chip. The chip is 1 cm x 2 cm and contains 20,208 series connected Nb-AlO_x-Nb junctions.

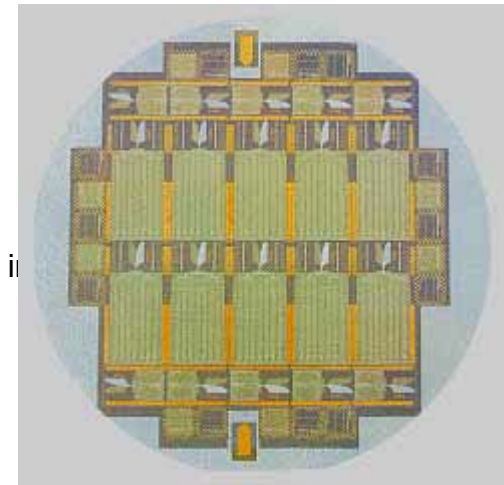
<http://www.boulder.nist.gov/div814/div814/whatwedo/volt/dc/JVS.html>

HYPRES: Voltage Standard Chip

HYPRES is the only commercial manufacturer of the superconducting integrated circuit used in Primary Voltage Standard Systems. HYPRES chips are used in the primary voltage standards in national laboratories around the world including Italy, France, United Kingdom, Australia, China, Malaysia, Japan, England, Canada, Norway, United States, Netherlands and Mexico. The HYPRES Josephson Junction Array Voltage Standard circuits provide the ultimate accuracy for realizing and maintaining the SI Volt.

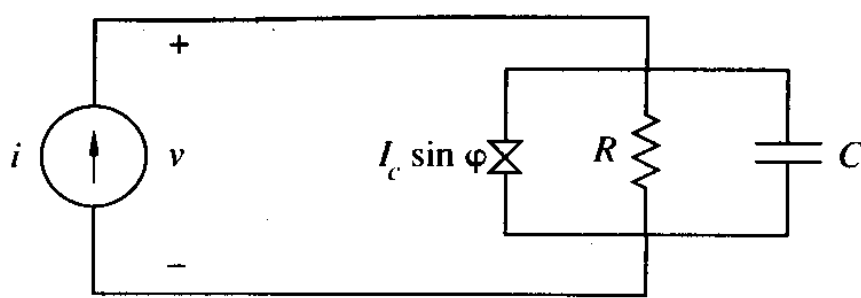
Features/Specifications

- Niobium/Aluminum Oxide/Niobium, SiO₂ dielectric, Niobium wiring technology.
- All Niobium technology. Refractory. Impervious to moisture and thermal cycling.
- 20,208 Josephson junctions (10 V chip) 3,660 Josephson junctions (1 V chip)
- 18 x 38 micrometers junction area.
- Installed in a FR-4 epoxy glass mount.
- RF input WR-12 waveguide flange.
- RF Distribution - 16 way parallel x 1263 cells in series (10 V) - 4 way parallel x 915 cells in series (1 V)
- Designed for a frequency range of 72-78 GHz
- Operating temperature of 4.2 K
- Common DC terminal resistance is < 1 Ohm - typical
- Approximately 10 mW operating power at the input flange for 10 V chip (2 mW for 1 V)
- -11V to +11 V range for 10 V chip.
- -2.5 V to + 2.5 V range for 1 V chip.
- Stability time is typically 1 hour for the 10 V chip, 5 hours for the 1V chip
- 0.005 PPM accuracy at 10 V (10 V chip)
- 0.05 PPM accuracy at 1V (1V chip)
- Calibration certificate supplied with each chip.
- Two (2) year warranty



<http://www.hypres.com/>

Parametric Inductor



$$i(t) = I_c \sin \varphi(t) + \frac{v(t)}{R} + C \frac{d}{dt} v(t)$$

Take the time derivative of the currents, and for the Josephson term:

$$\frac{d}{dt} i_J(t) = \left[\frac{2\pi I_c}{\Phi_0} \cos \varphi(t) \right] v(t)$$

The parametric (time-dependent) inductance can be defined as

$$L_J = \frac{\Phi_0}{2\pi I_c \cos \varphi(t)}$$

*On the zero-voltage branch, for $I_s \ll I_0$ and $I_0 + I_s \ll I_c$, then $I_0 \sim I_c \sin \phi$, so that

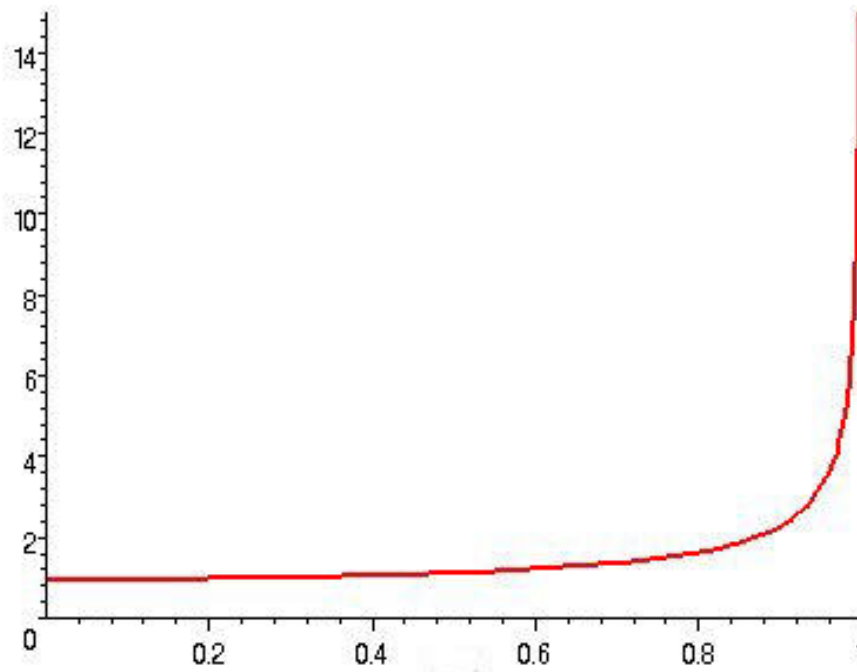
$$L_J \approx \frac{\Phi_0}{2\pi I_c \sqrt{1 - (I_0/I_c)^2}}$$



Inductance along $V=0$ branch

$$L_J \approx \frac{\Phi_o}{2\pi I_c \sqrt{1 - (I_o/I_c)^2}}$$

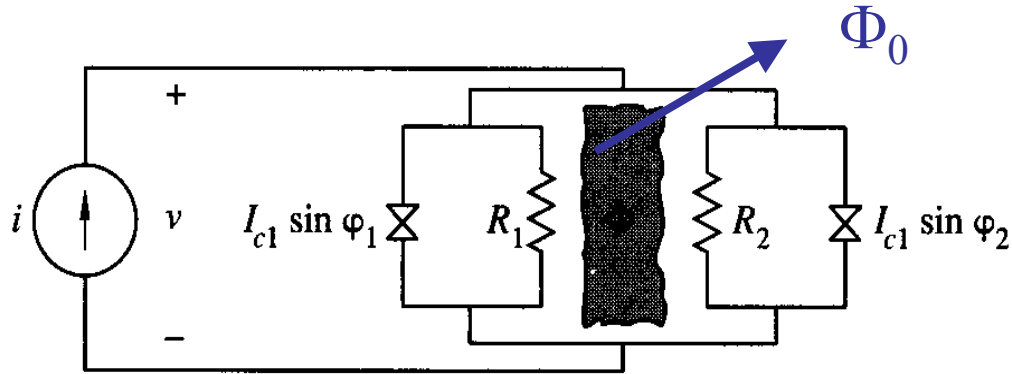
$$L\left[\frac{\Phi_o}{2\pi I_c}\right]$$



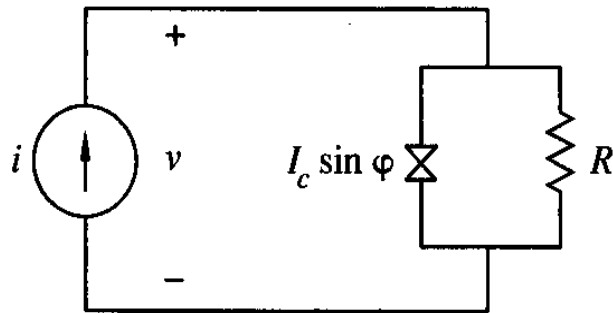
I/I_c



The DC SQUID (damped)



(a)

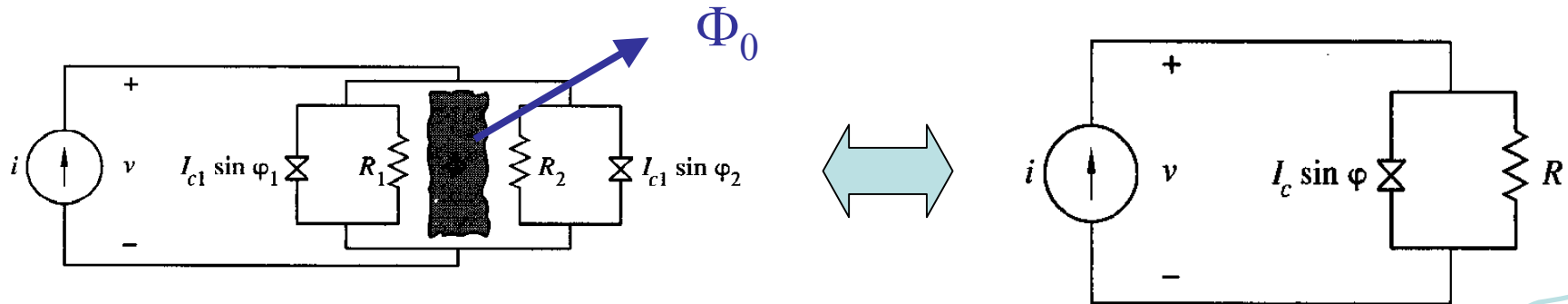


(b)

Our goal is to show that the DC SQUID circuit in (a) is equivalent to the circuit for a single junction with an effective I_c and an effective resistance. The inductance of the SQUID loop in (a) is considered negligible.

In fact, we will also show later that there is an equivalent statement even for the underdamped case.

DC SQUID Equivalent Circuit

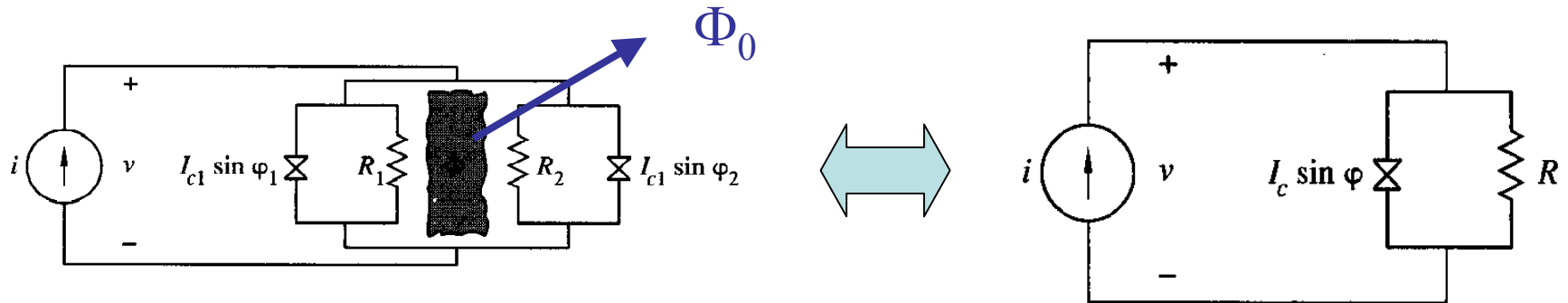


$$\begin{aligned}
 i &= i_{J_1} + i_{J_2} + i_{R_1} + i_{R_2} \\
 &= I_{c1} \sin \varphi_1 + I_{c1} \sin \varphi_2 + \frac{v}{R_1} + \frac{v}{R_2}
 \end{aligned}$$

Use flux quantization, $\varphi_2 - \varphi_1 = \frac{2\pi\Phi}{\Phi_0}$ and the fact that the junctions are identical

$$i = \underbrace{2I_{c1} \cos\left(\frac{\pi\Phi_{\text{ext}}}{\Phi_0}\right)}_{I_c} \sin\left(\underbrace{\varphi_1 + \frac{\pi\Phi_{\text{ext}}}{\Phi_0}}_{\varphi}\right) + \underbrace{\left(\frac{1}{R_1} + \frac{1}{R_2}\right)}_{1/R} \underbrace{v(t)}_{\frac{\Phi_0}{2\pi} \frac{d}{dt} \varphi}$$

DC SQUID Equivalent Circuit



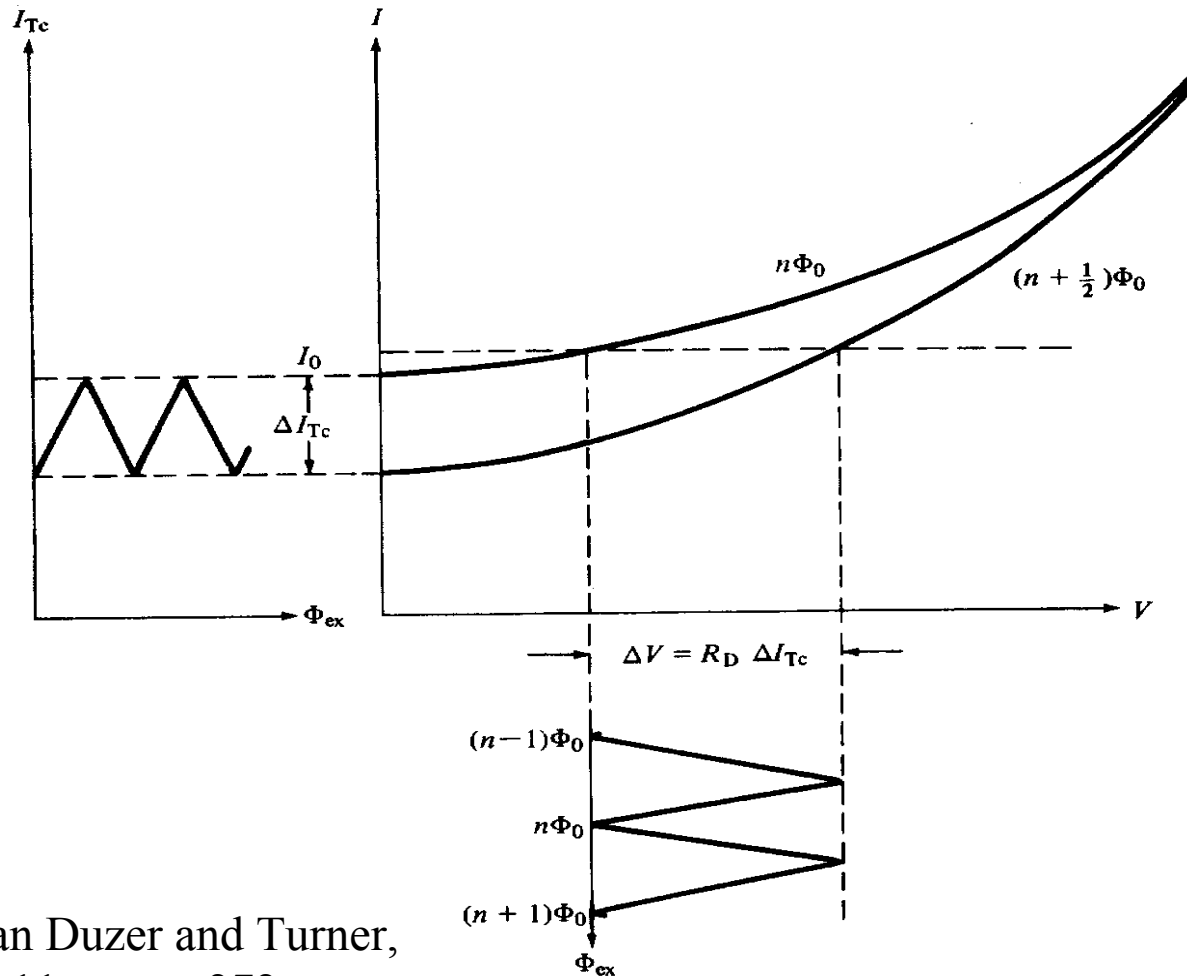
$$i = I_c \sin \varphi + \frac{1}{R} \frac{\Phi_o}{2\pi} \frac{d\varphi}{dt} \quad \text{with} \quad I_c = 2I_{c1} \cos \left(\frac{\pi \Phi_{\text{ext}}}{\Phi_o} \right)$$

Therefore, for this overdamped equivalent circuit, for $i > I_c$

$$\langle v(t) \rangle = iR \sqrt{1 - \left[\frac{2I_{c1}}{i} \cos \left(\frac{\pi \Phi_{\text{ext}}}{\Phi_o} \right) \right]^2}$$

$$\langle v(t) \rangle = iR \sqrt{1 - \left(\frac{i_{\text{max}}}{i} \right)^2}$$

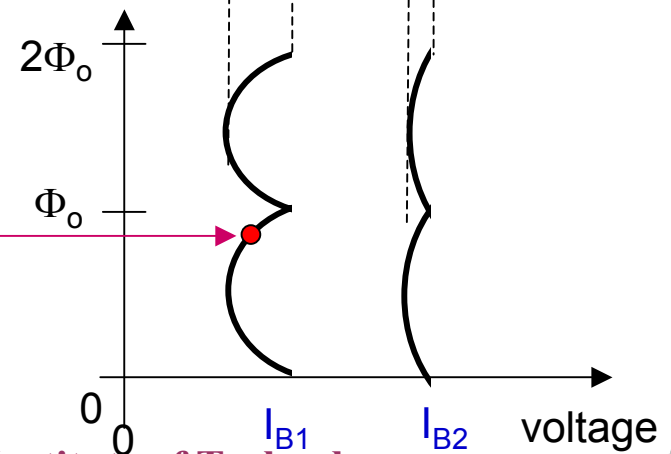
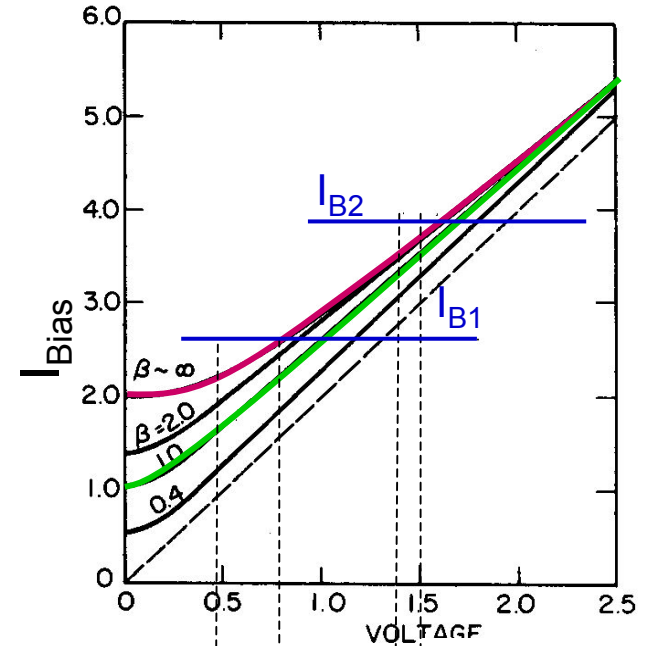
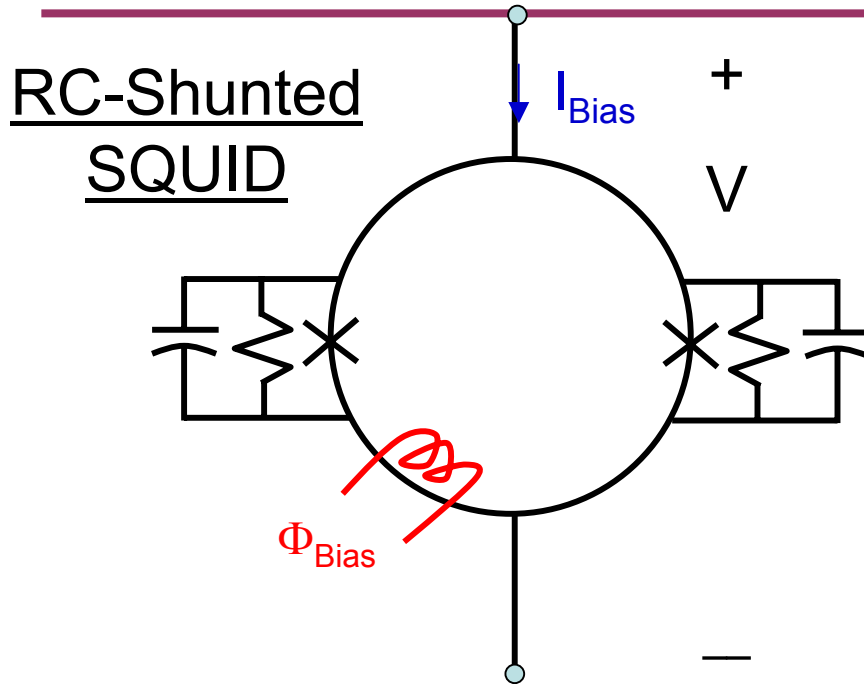
DC SQUID Voltage Modulation



From Van Duzer and Turner,
Figure 5.11a, page 272



DC SQUID Voltage Modulation



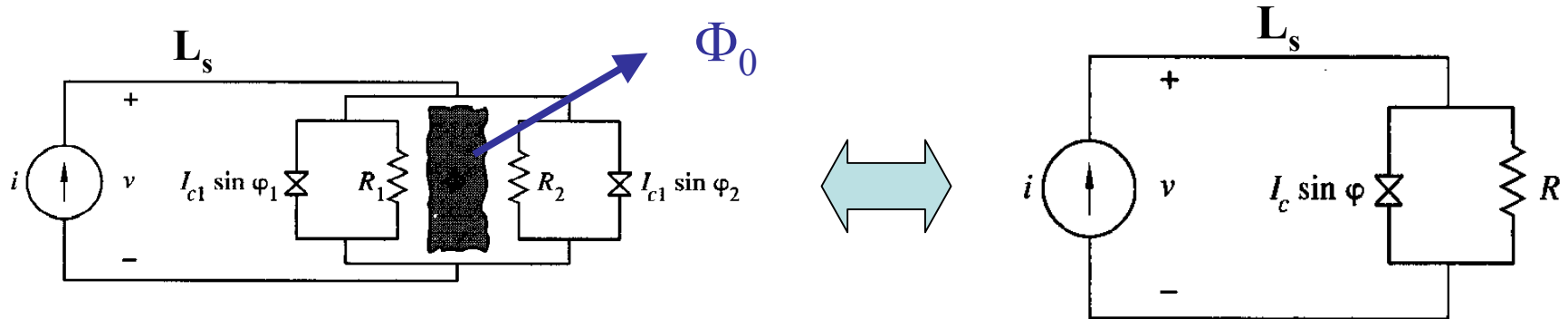
I_{bias} kept slightly above I_C

$\Phi_{bias} = 0.75\Phi_0$ for sensitivity

Goal is to maximize: $\frac{dV}{d\Phi} \approx \frac{R}{L}$



DC SQUID Sensitivity



Assume that $L_s > L_J = \Phi_0 / 2\pi I_c(\Phi_{\text{ext}})$, then the range of modulation of the current is about

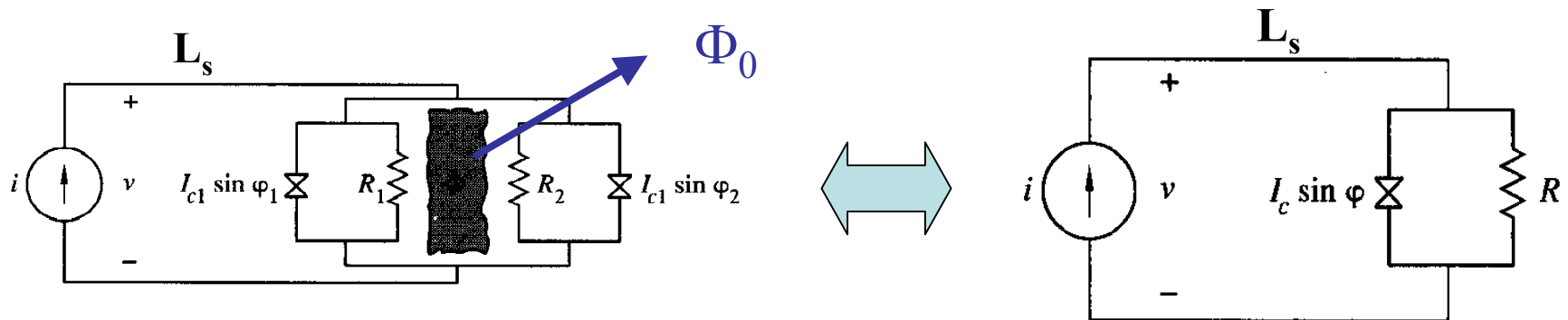
$$\delta i = i_{\text{max}}^+ - i_{\text{max}}^- \approx \Phi_0 / L$$

The sensitivity of the output voltage to the input flux is

$$\frac{\delta \langle v \rangle}{\delta \Phi_{\text{ext}}} \approx \frac{R_D \delta i}{\frac{1}{2} \Phi_0} = \frac{2R_D}{L}$$

With $R_D \sim R = 1 \text{ Ohm}$ and $L \sim 1 \text{ nH}$, then the sensitivity is about one microvolt per flux quantum, so that small fractions of a flux quantum can be measured.

DC SQUID and Thermal Noise



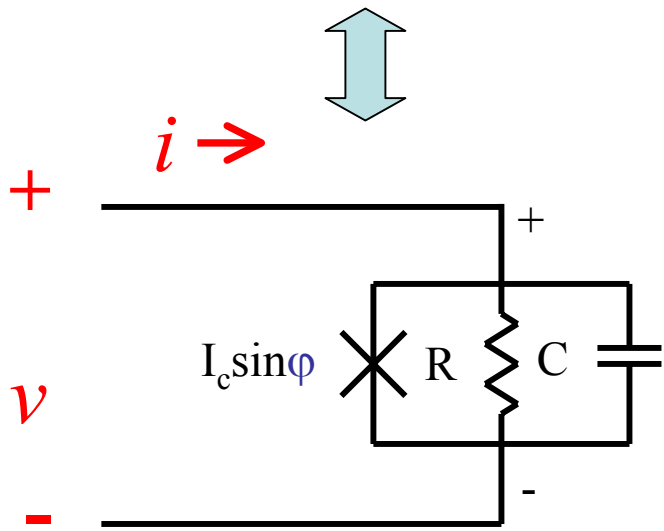
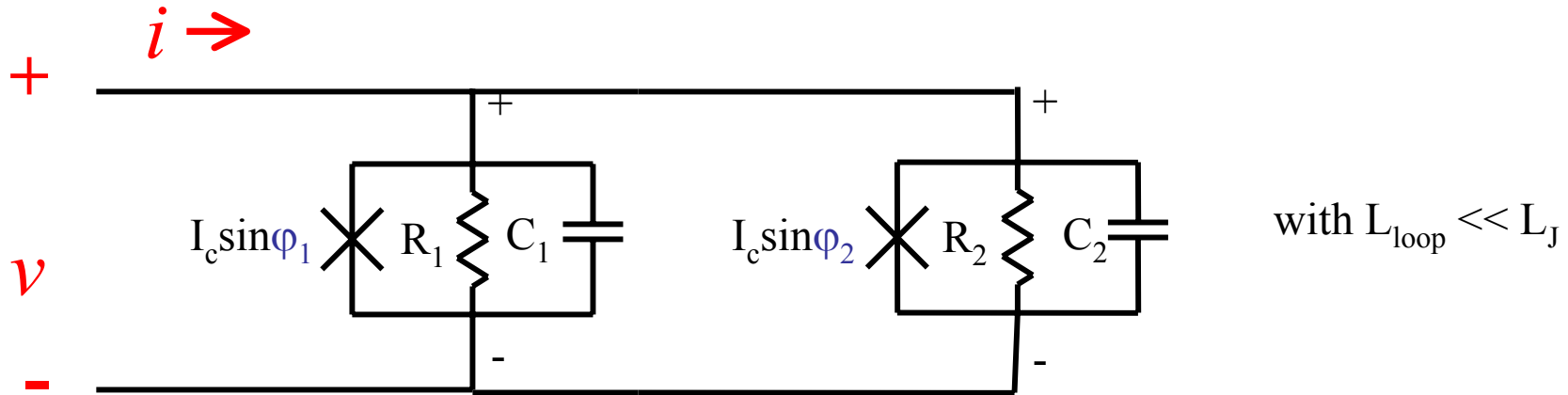
Assume again that $L_s > L_J = \Phi_0 / 2\pi I_c(\Phi_{\text{ext}})$, then to prevent thermal noise from effecting the SQUID's performance, one needs

Energy stored in the SQUID \gg Thermal Energy

$$\frac{1}{2} \frac{\Phi_0^2}{L} \gg \frac{1}{2} k_B T$$

Therefore, $L_s < 1$ nH at 4 K, and 0.1 nH at 100 K.

Equivalent Tunable Junction



$$I_c = 2I_{c1} \cos\left(\frac{\pi\Phi_{\text{ext}}}{\Phi_0}\right)$$

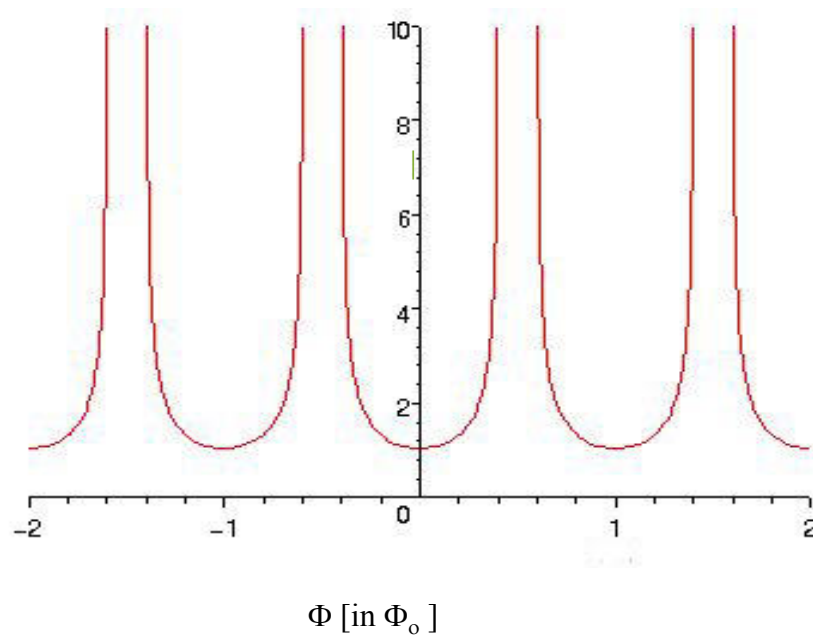
$$\frac{1}{R} = \frac{1}{R_1} + \frac{1}{R_2} \quad C = C_1 + C_2$$

$$\beta_c = \frac{\tau_{RC}}{\tau_J} = \frac{R^2 C}{L_J} = \frac{2\pi I_c R^2 C}{\Phi_0}$$

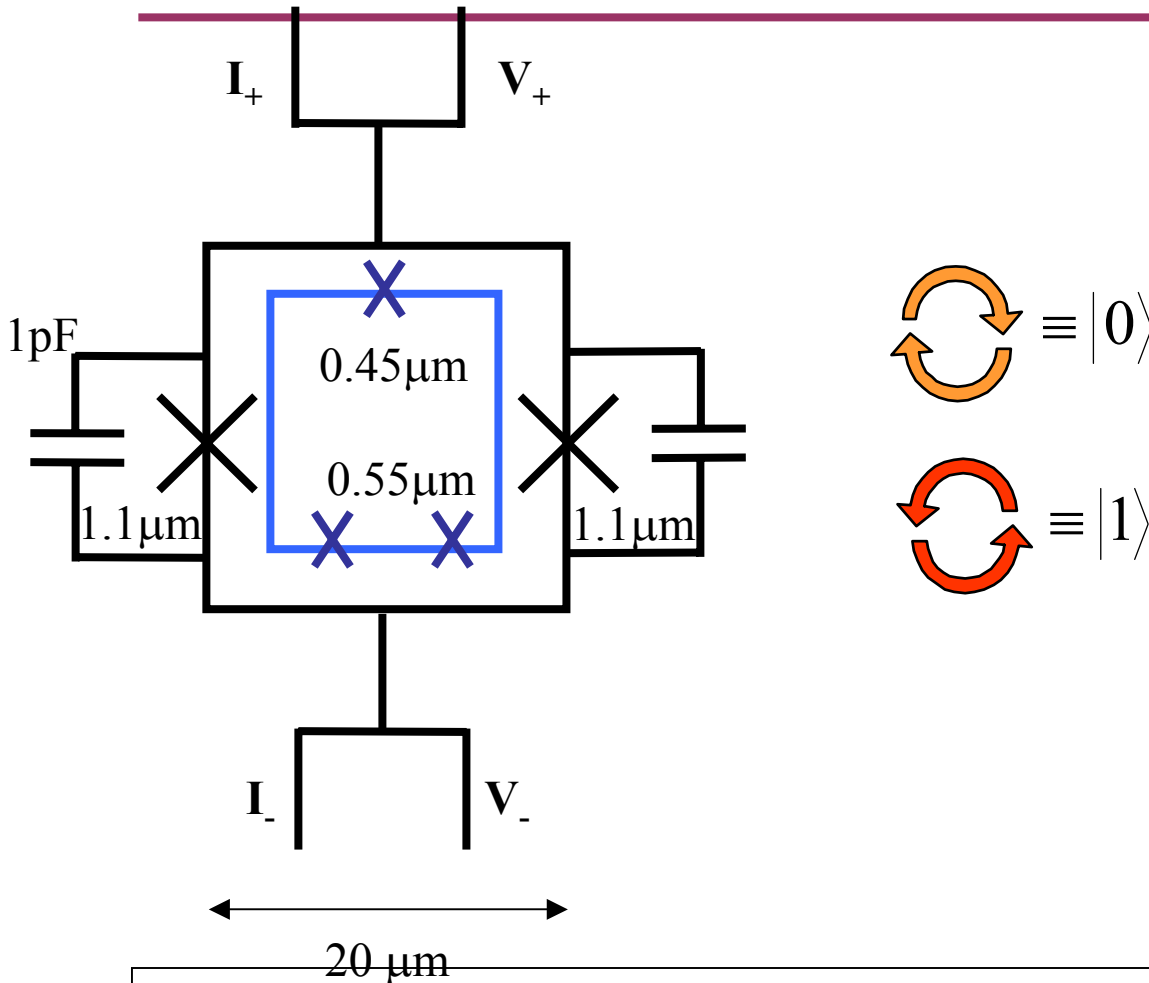


Tunable Inductance along $V=0$ branch

$$L_J \approx \frac{\Phi_o}{2\pi I_C \sqrt{1 - (I_o/I_C)^2}}$$
$$L\left[\frac{\Phi_o}{2\pi I_C}\right]$$



Three-Junction Loop Measurements



Three-junction Loop
 Jct. Size $\sim 0.45\mu\text{m}, 0.55\mu\text{m}$
 Loop size $\sim 16 \times 16\mu\text{m}^2$
 $L_{3\text{-junction}} \sim 30\text{pH}$
 $I_c \sim 1 \text{ \& } 2\mu\text{A}$
 $E_J/E_c \sim 350 \text{ \& } 550$

DC SQUID
 Shunt capacitors $\sim 1\text{pF}$
 Jct. Size $\sim 1.1\mu\text{m}$
 Loop size $\sim 20 \times 20\mu\text{m}^2$
 $L_{\text{SQUID}} \sim 50\text{pH}$
 $I_c \sim 10 \text{ \& } 20\mu\text{A}$
 $M \sim 35\text{pH}$
 $J_c \sim 350 \text{ \& } 730\text{A/cm}^2$

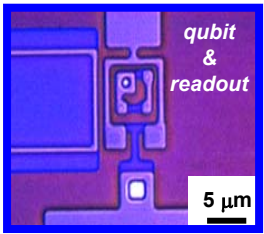
- Measure switching current of DC SQUID
- Vary external flux, temperature and SQUID ramp rate



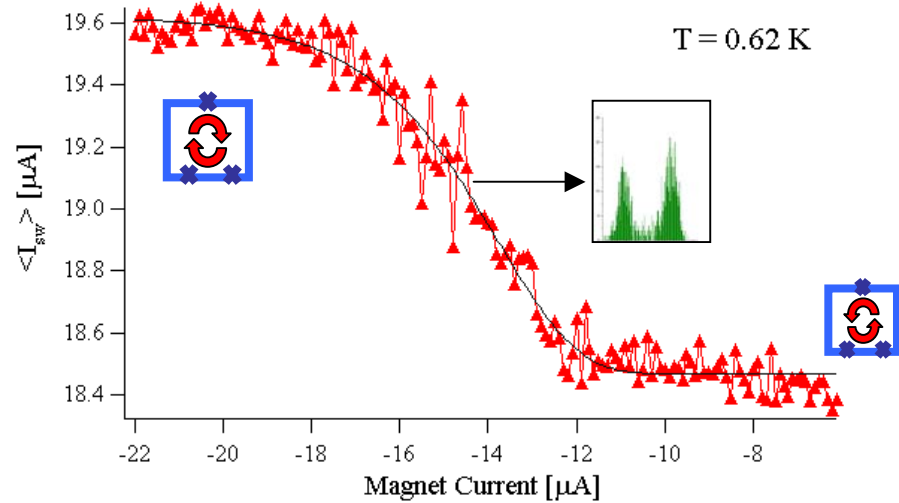
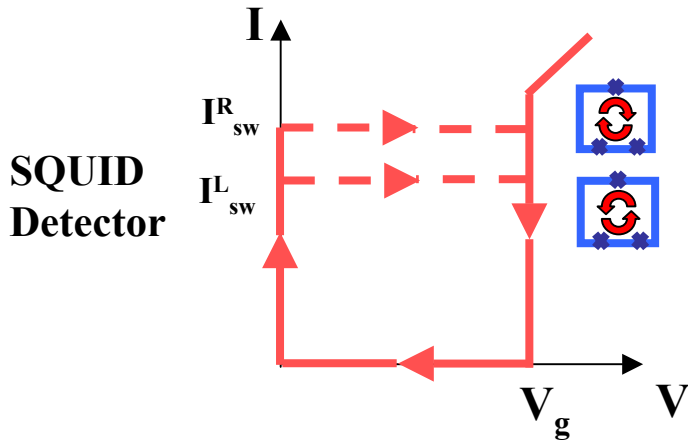
Thermal Activation of Nb Persistent Current Qubit



5/6/03



SFQ on-chip oscillator and qubit



	J_c	E_J	E_J/E_c	Jct. width	α	Q
Device A:	365 A/cm ²	2400 μ eV	380	0.563 μ m	0.613	1.0x10 ⁶
Device B:	730 A/cm ²	4000 μ eV	560	0.529 μ m	0.589	1.2x10 ⁶

Highest Q of any submicron Nb junction



Coupling between qubits

Equivalent, tunable 3rd junction

