

# Lecture 8: Perfect Diamagnetism

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## Outline

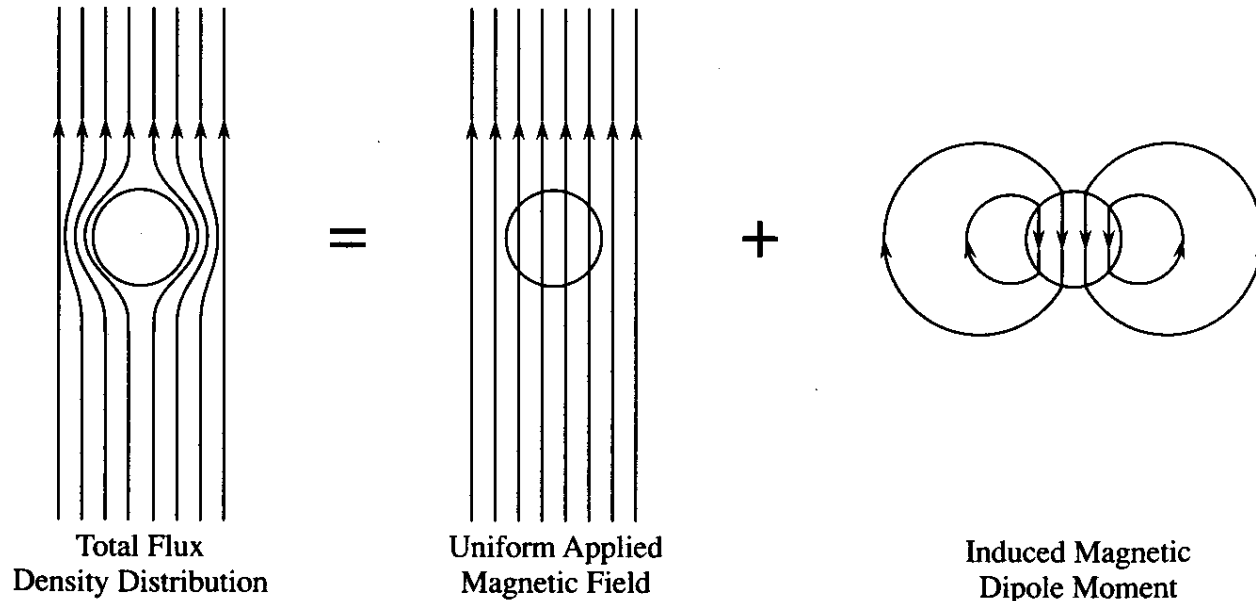
- 1. Description of a Perfect Diamagnet**
  - **Method I and Method II**
  - **Examples**
- 2. Energy and Coenergy in Methods I and II**
- 3. Levitating magnets and Maglev trains**

September 30, 2003



# Description of Perfect Diamagnetism

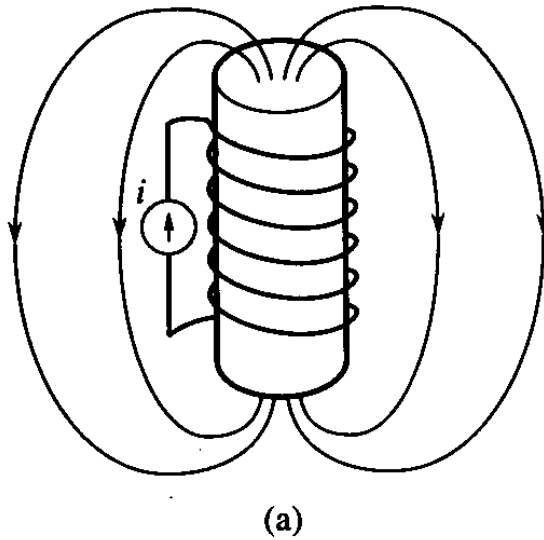
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Surface currents or internal induced magnetization?

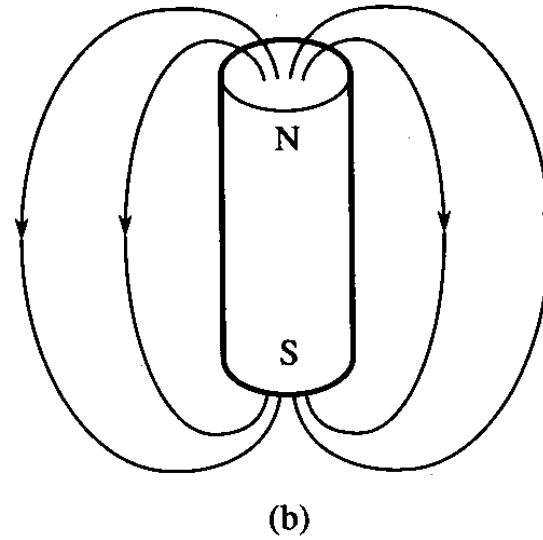
# Methods I and II

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$$\mathbf{B} = \mu_0 \mathbf{H}^I$$

Method I

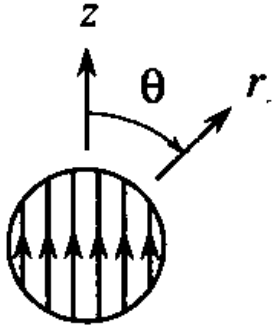


$$\mathbf{B} = \mu_0 (\mathbf{H}^{II} + \mathbf{M})$$

Method II

***B field is the same in both methods.***

# Example: Magnetized Sphere



$$\mathbf{M} = M_0 \mathbf{i}_z = M_0 (\cos \theta \mathbf{i}_r - \sin \theta \mathbf{i}_\theta) \quad \text{for } r \leq R.$$

**M Lines**

$$\begin{array}{l} \nabla \times \mathbf{H} = \mathbf{J} = 0 \\ \nabla \cdot \mathbf{B} = 0 \\ \mathbf{B} = \mu_0 (\mathbf{H} + \mathbf{M}) \end{array} \left. \vphantom{\begin{array}{l} \nabla \times \mathbf{H} = \mathbf{J} = 0 \\ \nabla \cdot \mathbf{B} = 0 \\ \mathbf{B} = \mu_0 (\mathbf{H} + \mathbf{M}) \end{array}} \right\} \begin{array}{l} \longrightarrow \mathbf{H} = -\nabla \psi \\ \longrightarrow \nabla^2 \psi = \nabla \cdot \mathbf{M} \end{array}$$

For this example:  $\nabla^2 \psi = 0$  Laplace's equation



# Boundary Conditions

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Inside the sphere:

$$\psi(r \leq R) = C_1 r \cos \theta \quad \longrightarrow \quad \mathbf{H}(r \leq R) = -C_1 (\cos \theta \mathbf{i}_r - \sin \theta \mathbf{i}_\theta)$$

Outside the sphere:

$$\psi(r \geq R) = C_2 \frac{\cos \theta}{r^2} \quad \longrightarrow \quad \mathbf{H}(r \geq R) = \frac{C_2}{r^3} (2 \cos \theta \mathbf{i}_r + \sin \theta \mathbf{i}_\theta)$$

Boundary Conditions:

$$\mathbf{n} \times (\mathbf{H}_2 - \mathbf{H}_1) = \mathbf{K} \quad \longrightarrow \quad C_1 R^3 = C_2$$

$$\mathbf{n} \cdot (\mathbf{B}_2 - \mathbf{B}_1) = 0 \quad \longrightarrow \quad \mathbf{i}_r \cdot (\mathbf{H}|_{r=R^+} - \mathbf{H}|_{r=R^-}) = \mathbf{i}_r \cdot \mathbf{M}|_{r=R^-}$$

$$\text{Therefore, } \mathbf{M} = M_o (\cos \theta \mathbf{i}_r - \sin \theta \mathbf{i}_\theta) \quad \longrightarrow \quad C_1 = \frac{M_o}{3}$$

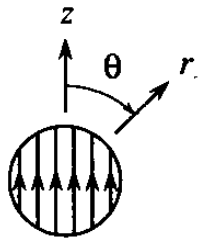


# Magnetized Sphere

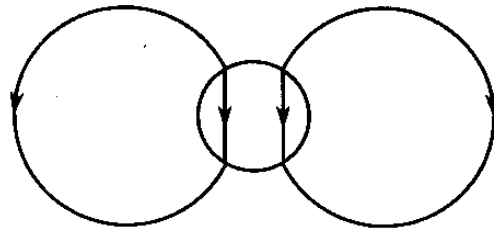
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$$\mathbf{H}(r \leq R) = -\frac{M_o}{3} \mathbf{i}_z = -\frac{M_o}{3} (\cos \theta \mathbf{i}_r - \sin \theta \mathbf{i}_\theta)$$

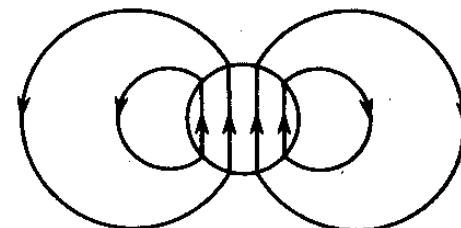
$$\mathbf{H}(r \geq R) = \frac{M_o}{3} \left(\frac{R}{r}\right)^3 (2 \cos \theta \mathbf{i}_r + \sin \theta \mathbf{i}_\theta)$$



**M Lines**



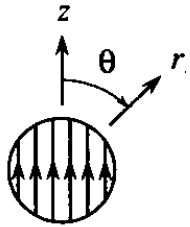
**H Lines**



**B Lines**

# Magnetized Sphere in field

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$$\mathbf{H}_{\text{app}} = H_o \mathbf{i}_z$$

$$\mathbf{H}(r \leq R) = \left( H_o - \frac{M_o}{3} \right) \mathbf{i}_z$$

$$\begin{aligned} \mathbf{H}(r \geq R) = & \left( H_o + \frac{2}{3} M_o \left( \frac{R}{r} \right)^3 \right) \cos \theta \mathbf{i}_r \\ & - \left( H_o - \frac{1}{3} M_o \left( \frac{R}{r} \right)^3 \right) \sin \theta \mathbf{i}_\theta \end{aligned}$$

For this to describe a superconductor (bulk limit), then  $\mathbf{B}=0$  inside.

$$\text{Therefore, } 0 = \mathbf{M} + \mathbf{H}(r \leq R) = M_o \mathbf{i}_z + \left( H_o - \frac{M_o}{3} \right) \mathbf{i}_z$$

$$\text{So that } M = -\frac{3}{2} H_o$$



# Comparison of Methods

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Method I

$$\mathbf{B}^I = \mu_o \mathbf{H}^I$$

Method II

$$\mathbf{B} = \mu_o (\mathbf{H}^{II} + \mathbf{M})$$

Inside a bulk superconducting sphere:

$$\mathbf{B}^I = 0$$

$$\mathbf{H}^I = 0$$

$$\mathbf{K}^I = -\text{Re} \left\{ \frac{3}{2} \hat{H}_o \sin \theta \right\} \mathbf{i}_\phi$$

$$\mathbf{B}^{II} = 0$$

$$\mathbf{H}^{II} = \frac{3}{2} H_o \mathbf{i}_z$$

$$\mathbf{M} = -\frac{3}{2} H_o \mathbf{i}_z$$

$$\mathbf{K}^{II} = 0$$

**B** field is the same, but not **H**.





# Methods I and II: Summary

## Maxwell's Equations

Method I

$$\nabla \times \mathbf{H}^I = \mathbf{J}^I$$

$$\mathbf{B} = \mu_0 \mathbf{H}^I$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}^I$$

$$\mathbf{J}^I = \underbrace{(\mathbf{J}_{s,\text{app}} + \mathbf{J}_{s,\text{ind}})}_{\mathbf{J}_s^I} + \mathbf{J}_n$$

$$\nabla \cdot \mathbf{B} = 0$$

Method II

$$\nabla \times \mathbf{H}^{II} = \mathbf{J}^{II}$$

$$\mathbf{B} = \mu_0 (\mathbf{H}^{II} + \mathbf{M})$$

$$\nabla \times \mathbf{B} = \mu_0 \mathbf{J}^{II} + \underbrace{\mu_0 \nabla \times \mathbf{M}}_{\mathbf{J}_{s,\text{ind}}}$$

$$\mathbf{J}^{II} = \mathbf{J}_{s,\text{app}} + \mathbf{J}_n$$

## London Equations

$$\mathbf{E} = \frac{\partial}{\partial t} (\wedge \mathbf{J}_s^I)$$

$$\nabla \times (\wedge \mathbf{J}_s^I) = -\mathbf{B}$$

$$\mathbf{E} = \frac{\partial}{\partial t} (\wedge \mathbf{J}_s^{II}) + \frac{\partial}{\partial t} (\wedge (\nabla \times \mathbf{M}))$$

$$\nabla \times (\wedge \mathbf{J}_s^{II}) + \nabla \times (\wedge (\nabla \times \mathbf{M})) = -\mathbf{B}$$



# Why Method II

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Question:

The constitutive relations and London's Equations have gotten much more difficult. So why do Method II?

Answer:

The Energy and Thermodynamics are easier, especially when there is no applied current.

So we will find the energy stored in both methods.

Poynting's theorem is a result of Maxwell's equation, so both methods give

$$-\oint_{\Sigma} (\mathbf{E} \times \mathbf{H}) \cdot d\mathbf{s} = \int_V \left( \mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t} + \mathbf{H} \cdot \frac{\partial \mathbf{B}}{\partial t} + \mathbf{E} \cdot \mathbf{J} \right) dv$$



# Method I: The Energy

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Combining the constitutive relations with Poynting's theorem,

$$-\oint_{\Sigma} (\mathbf{E} \times \mathbf{H}^I) \cdot d\mathbf{s} = \int_V \left( \mathbf{E} \cdot \frac{\partial \mathbf{D}}{\partial t} + \mathbf{H}^I \cdot \frac{\partial \mathbf{B}}{\partial t} + \mathbf{J}_S^I \cdot \frac{\partial}{\partial t} (\wedge \mathbf{J}_S^I) \right) dv + \int_V \mathbf{E} \cdot \mathbf{J}_n dv$$

Power  $dW/dt$  in the E&M field

The energy stored in the electromagnetic field is

$$dW = \int_V \left( \mathbf{E} \cdot d\mathbf{D} + \mathbf{H}^I \cdot d\mathbf{B} + \mathbf{J}_S^I \cdot d(\wedge \mathbf{J}_S^I) \right) dv$$

So that the energy  $W$  is a function of  $\mathbf{D}$ ,  $\mathbf{B}$ , and  $\wedge \mathbf{J}_S^I = \mathbf{v}_s \cdot$ .  
However, one rarely has control over these variables, but rather over their conjugates  $\mathbf{E}$ ,  $\mathbf{H}^I$ , and  $\mathbf{J}_S^I$ .



# Method I: The Coenergy

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The coenergy is a function of  $\mathbf{E}$ ,  $\mathbf{H}^I$ , and  $\mathbf{J}_S^I$  is defined by

$$W + \tilde{W} = \int_V \left( \mathbf{E} \cdot \mathbf{D} + \mathbf{H}^I \cdot \mathbf{B} + \mathbf{J}_S^I \cdot (\wedge \mathbf{J}_S^I) \right) dv$$

and with

$$dW = \int_V \left( \mathbf{E} \cdot d\mathbf{D} + \mathbf{H}^I \cdot d\mathbf{B} + \mathbf{J}_S^I \cdot d(\wedge \mathbf{J}_S^I) \right) dv$$

gives

$$\leftarrow \text{EQS} \rightarrow \quad \longleftarrow \text{MQS} \longrightarrow$$

$$d\tilde{W} = \int_V \left( \mathbf{D} \cdot d\mathbf{E} + \mathbf{B} \cdot d\mathbf{H}^I + \wedge \mathbf{J}_S^I \cdot d\mathbf{J}_S^I \right) dv$$

(The coenergy is the Free Energy at zero temperature.)

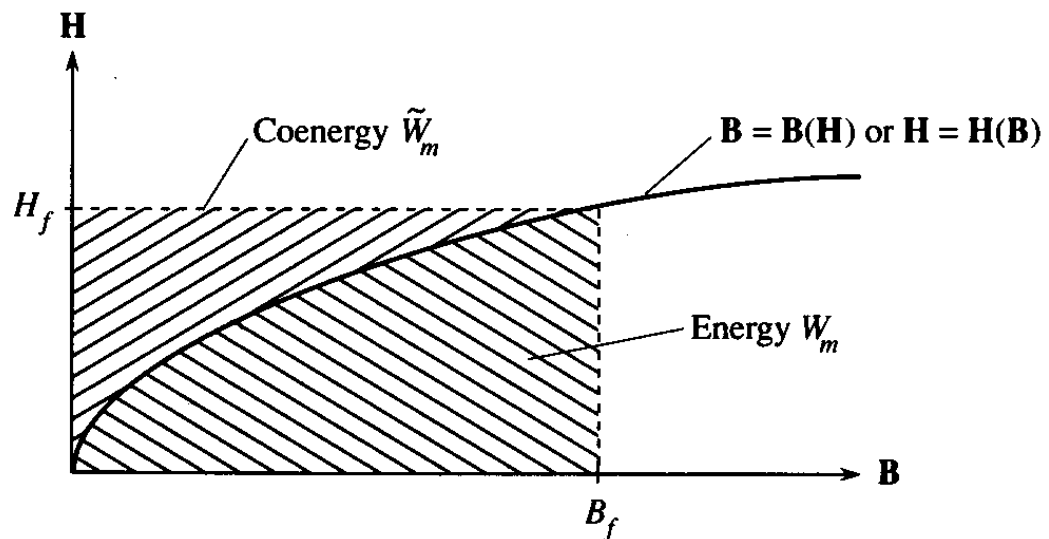


# Interpretation of the Coenergy

Consider the case where there are only magnetic fields:

$$\tilde{W} = \int_{\mathbf{H}^I} d\tilde{W} = \int_V \mathbf{B} \cdot d\mathbf{H}^I dv \quad W = \int_{\mathbf{B}} dW = \int_{\mathbf{B}} \int_V \mathbf{H}^I \cdot d\mathbf{B} dv$$

$$W_m + \tilde{W}_m = H_f B_f$$



The energy and coenergy contain the same information.



# Method II

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$$dW = \int_V \left( \mathbf{E} \cdot d\mathbf{D} + \mathbf{H}^{\text{II}} \cdot d\mathbf{B} + \mathbf{J}_S^{\text{II}} \cdot d(\wedge \mathbf{J}_S^{\text{II}} + \wedge \nabla \times \mathbf{M}) \right) dv$$

$$d\widetilde{W} = \int_V \left( \mathbf{D} \cdot d\mathbf{E} + \mathbf{B} \cdot d\mathbf{H}^{\text{II}} + (\wedge \mathbf{J}_S^{\text{II}} + \wedge \nabla \times \mathbf{M}) \cdot d\mathbf{J}_S^{\text{II}} \right) dv$$

In the important case when of the MQS limit and  $\mathbf{J}_S^{\text{II}} = \mathbf{J}_{S,\text{app}} = 0$

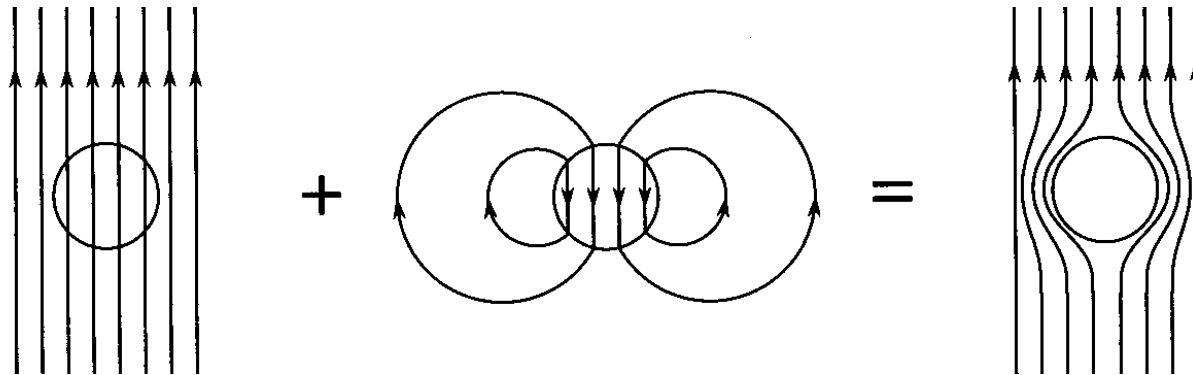
$$dW|_{\mathbf{J}_{S,\text{app}}=0} = \int_V \left( \mathbf{H}^{\text{II}} \cdot d\mathbf{B} \right) dv$$

$$d\widetilde{W}|_{\mathbf{J}_{S,\text{app}}=0} = \int_V \left( \mathbf{B} \cdot d\mathbf{H}^{\text{II}} \right) dv$$

Note that these two relations apply also in free space.



# Example: Energy of a Superconducting Sphere



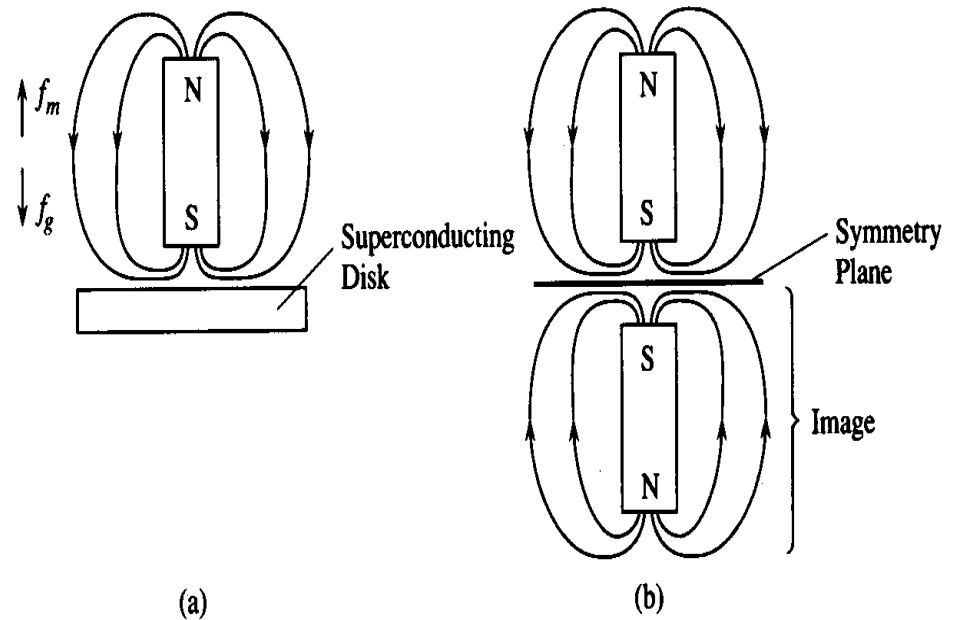
$$\mathbf{B}(r \leq R) = 0 \quad \mathbf{H}^{II}(r < R) = \frac{3}{2} H_0 \mathbf{i}_z$$

$$\mathbf{H}(r \geq R) = \text{Re} \left\{ \hat{H}_0 \left( 1 - \left( \frac{R}{r} \right)^3 \right) \cos \theta \right\} \mathbf{i}_r - \text{Re} \left\{ \hat{H}_0 \left( 1 + \frac{1}{2} \left( \frac{R}{r} \right)^3 \right) \sin \theta \right\} \mathbf{i}_\theta$$

$$W_{inside} = \int_B \int_V (\mathbf{H}^{II} \cdot d\mathbf{B}) dv = 0$$

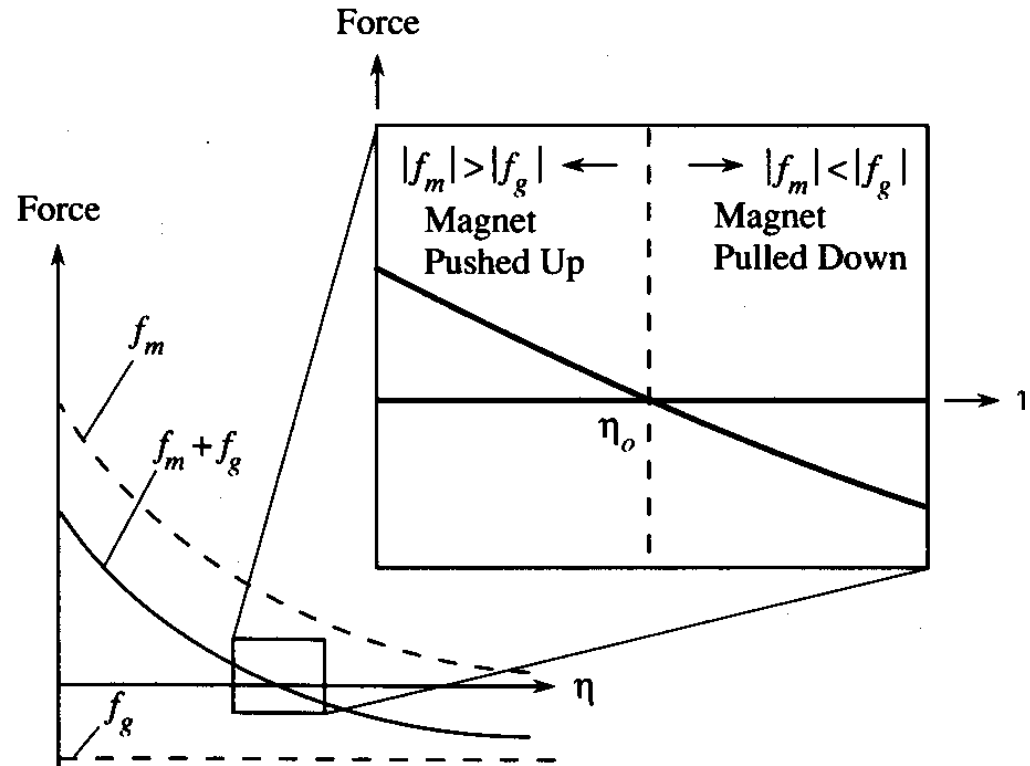
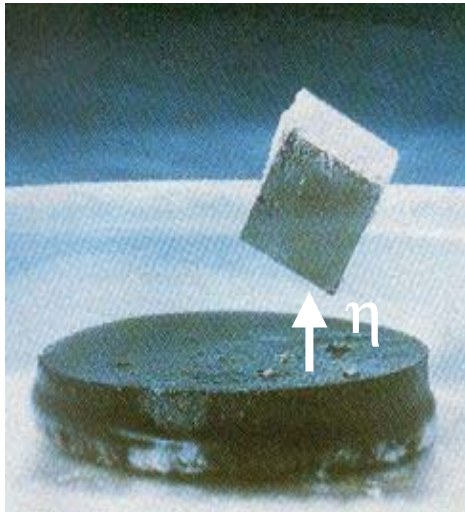
$$W_{outside} = \int_B \int_V (\mathbf{H}^{II} \cdot d\mathbf{B}) dv = \int_V \frac{1}{\mu_0} \mathbf{B}^2 dv \neq 0$$

# Magnetic Levitation

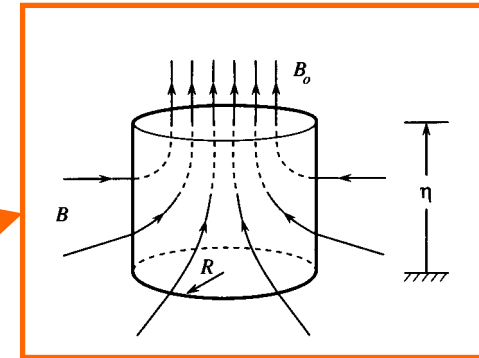
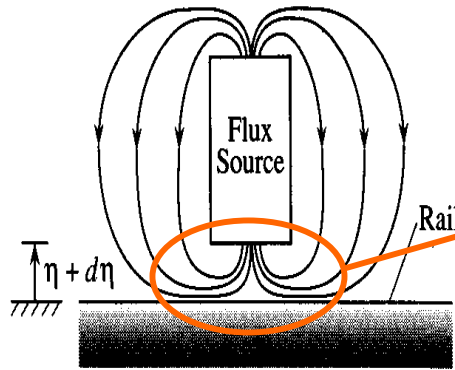
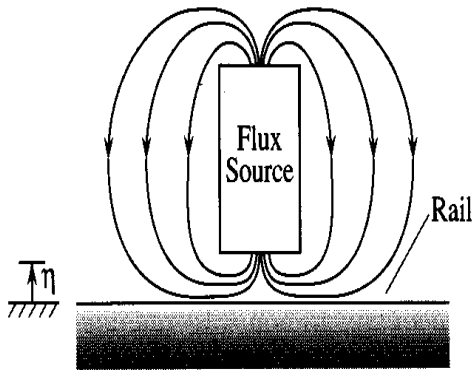




# Magnetic vs. Gravitational Forces



# Magnetic Levitation Equilibrium Point



Force mainly due to bending of flux lines here.

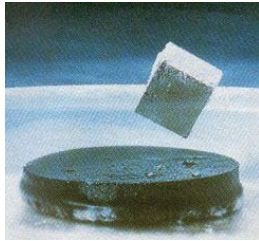
$$\Phi = \pi R^2 B_0 = 2\pi R\eta B$$

$$W_m = \int_V \frac{1}{\mu_0} B^2 dv \approx \frac{\pi R^2 \eta}{\mu_0} B^2 = \frac{\Phi^2}{8\pi\mu_0\eta}$$

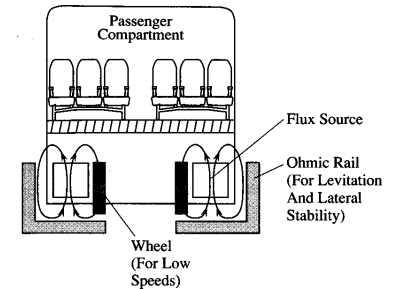
$$f_m = -\frac{\partial}{\partial \eta} W_m(\Phi, \eta) \approx \frac{\Phi^2}{8\pi\mu_0\eta^2} \quad \text{Force is upwards}$$

Equilibrium point  $f_m(\eta_0) = mg \rightarrow \eta_0 = \sqrt{\frac{\Phi^2}{8\pi\mu_0 mg}}$

# Levitating magnets and trains



$$f_m \approx \frac{\Phi^2}{8\pi\mu_0\eta^2}$$



$B = 1$  Tesla

Area =  $0.5 \text{ cm}^2$

$\eta_0 = 1 \text{ cm}$

Force = 1 Newton

Enough to lift magnet,  
but not a train

$B = 2$  Tesla

Area =  $100 \text{ cm}^2$

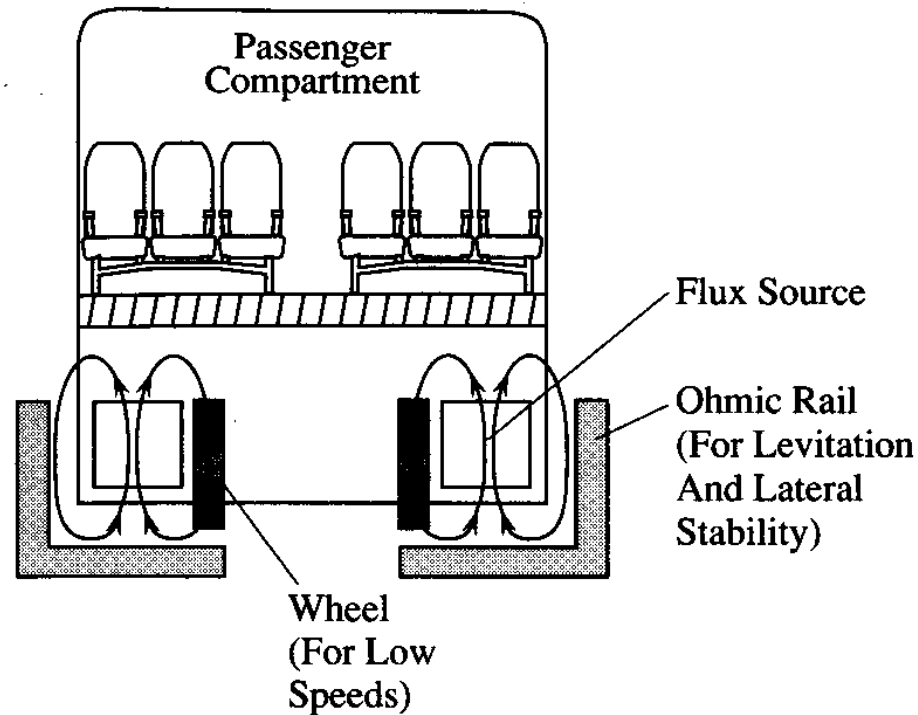
$\eta_0 = 10 \text{ cm}$

Force = 1,200 Newtons

Enough to lift a train

# Maglev Train

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Magnets on the train are superconducting magnets;  
the rails are ohmic!

# Principle of Maglev

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The train travels at a velocity  $U$ , and the moving flux lines and the rails “see” a moving magnetic field at a frequency of  $\omega \sim U/R$ .

If this frequency is much larger than the inverse of the magnetic diffusion time,

$$\tau_m = \mu\sigma_o R d$$

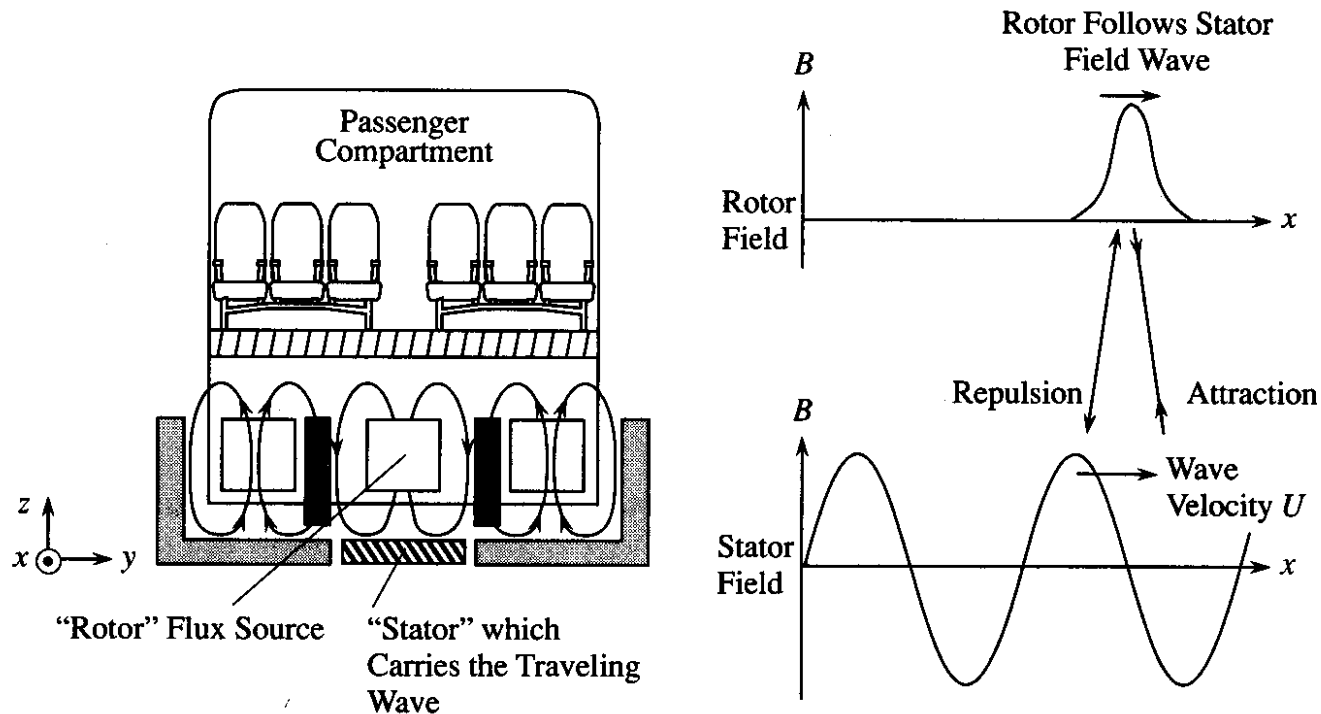
then the flux lines are “repelled” from the ohmic rails.

$$\omega\tau_m \gg 1 \qquad U \gg \frac{1}{\mu\sigma_o d}$$

From the previous numbers,  $U > 40$  km/hr for levitation.



# Real trains have wheels and high-voltage rails



Synchronous motor action down the rails provides thrust to accelerate train to the needed velocity to levitate, and provides a source of energy to further accelerate the train and to overcome the losses due to drag from the wind.

# Our Approach to Superconductivity

