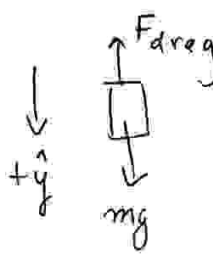


Practice Exam 3 Solutions

Problem 1:



$$\begin{array}{c} F_y = m a_y \\ \hline mg - F_{\text{drag}} = 0 \\ mg = F_{\text{drag}} \end{array}$$

$a_y = 0$ since $(v_y)_{\text{term}}$ is a constant!

a) $d = v_{\text{term}} t \Rightarrow t = \frac{d}{v_{\text{term}}} = \frac{1.6 \text{ km}}{5.0 \times 10^1 \text{ m/s}} = 32 \text{ s}$

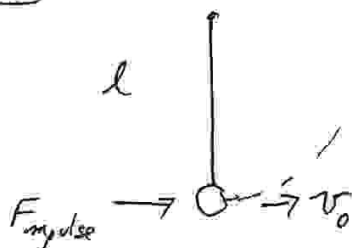
b) $W_{\text{grav}} = mgd = (8.0 \times 10^1 \text{ kg})(9.8 \frac{\text{m}}{\text{s}^2})(1.6 \times 10^3 \text{ m}) = 1.25 \times 10^6 \text{ J}$

c) $W_{\text{drag}} = -F_{\text{drag}} d = -mgd = -1.25 \times 10^6 \text{ J}$

d) $P_{\text{drag}} = \frac{W_{\text{drag}}}{t} = \frac{-mgd}{t} = \frac{-1.25 \times 10^6 \text{ J}}{3.2 \times 10^1 \text{ s}} = -3.92 \times 10^4 \text{ W}$

e) $E_{\text{drag}} = W_{\text{drag}} = -mgd = -3.92 \times 10^4 \text{ J}$. This energy shows up as heat; heating both the skydiver and the air.

Problem 3:



$+ \tan \leftarrow + \text{rad}$

$v_f \leftarrow$

(1) $T + mg = \frac{mv_f^2}{l}$

$F_{\text{rota}} = m a_{\text{radial}}$

a)

2

Med. Energy is conserved since T is always perpendicular to the displacement

$$\Delta K + \Delta P.E. = W_{n.c.}$$

$$\frac{1}{2} m(v_f^2 - v_o^2) + mg(2l) = 0$$

solving for $v_f^2 = v_o^2 - 2g(2l)$

$$v_f = \left((7.0 \text{ m/s})^2 - (2)(9.8 \frac{\text{m}}{\text{s}^2})(2)(.5 \text{ m}) \right)^{1/2} = 5.4 \frac{\text{m}}{\text{s}}$$

$$b) T = \frac{mv_f^2}{l} - mg = \frac{m(v_o^2 - 2g(2l))}{l} - mg$$

$$T = \frac{mv_o^2}{l} - 5mg = \frac{(.1 \text{ kg})(7.0 \frac{\text{m}}{\text{s}})^2}{(.5 \text{ m})} - (5)(.1 \text{ kg})(9.8 \frac{\text{m}}{\text{s}^2})$$

$$T = 4.9 \text{ N}$$

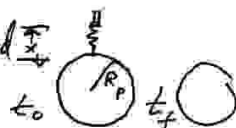
~~1~~ $\rightarrow \infty$

Problem 3:

the pen should have zero velocity at ∞

a)

compressed $\frac{1}{2}$



$$x_o \neq 0 \quad x_f = 0$$

$$v_o = 0 \quad v_f = 0$$

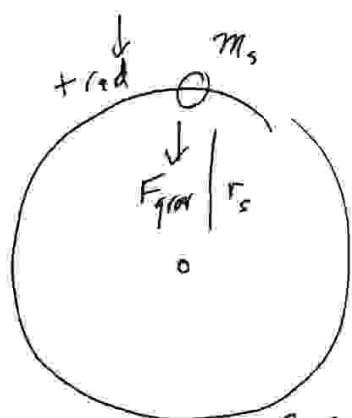
Energy is conserved

$$\Delta K + \Delta P.E. = W_{n.c.}$$

$$0 + \frac{1}{2} k(x_f^2 - x_o^2) - Gm_1 m_2 \left(\frac{1}{\infty} - \frac{1}{R_p} \right) = 0$$

$$-\frac{1}{2} k x_o^2 + \frac{Gm_1 m_2}{R_p} = 0 \Rightarrow x_o^2 = \frac{2Gm_1 m_2}{R_p k}$$

$$x_o = \left(\frac{(2)(6.67 \times 10^{-11} \frac{\text{N} \cdot \text{m}^2}{\text{kg}^2})(.01 \text{ kg})(2.6 \times 10^{15} \text{ kg})}{(5.0 \times 10^3 \text{ m})(400 \text{ N/m})} \right)^{1/2} = .042 \text{ m} = 4.2 \text{ cm}$$



$$\frac{F_{\text{rad}}}{\frac{G m_s m_p}{r_s^2}} = \frac{m_s g_{\text{rad}}}{m_s r_s \left(\frac{2\pi}{T} \right)^2}$$

solve for

$$r_s^3 = \frac{G m_p T^2}{4\pi^2}$$

$$r_s = \left(\frac{(6.67 \times 10^{-11} \frac{\text{N} \cdot \text{m}^2}{\text{kg}^2}) (2.6 \times 10^{15} \text{ kg}) ((2)(3.6 \times 10^3 \text{ sec}))^2}{4\pi^2} \right)^{1/3}$$

$$r_s = 6.1 \times 10^3 \text{ m}$$

$$v_s = \frac{2\pi r_s}{T} = \frac{(2\pi)(6.1 \times 10^3 \text{ m})}{(7.2 \times 10^3 \text{ sec})} = 5.3 \text{ m/s}$$

d) At the radius r_s , the conservation of mechanical energy can be used to calculate the velocity of the pen



$$\begin{aligned} t_0, \quad v_0 &= 0 \\ x_0 &= 4.2 \text{ cm} \\ &\text{from part c)} \\ r_0 &= R_p \end{aligned}$$



$$\begin{aligned} t', \quad v' &\neq 0 \\ x_f &= 0 \\ r' &= r_s \\ &\text{from part c)} \end{aligned}$$

$$\frac{\Delta K + \Delta P.E.}{\frac{1}{2} m_2 v'^2 - \frac{1}{2} k x_0^2 - G m_1 m_2 \left(\frac{1}{r_s} - \frac{1}{R_p} \right)} = \frac{W_{nc}}{0} \quad (1)$$

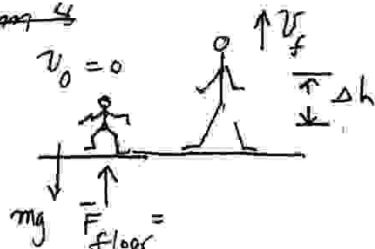
recall from part a) that $\frac{1}{2} k x_0^2 = \frac{G m_1 m_2}{R_p}$

So eq (1) becomes $\frac{1}{2} m_2 v'^2 - \frac{G m_1 m_2}{r_s} = 0$

$$v' = \left(\frac{2 G m_1}{r_s} \right)^{1/2} = \left(\frac{(2)(6.67 \times 10^{-11} \frac{\text{N} \cdot \text{m}^2}{\text{kg}^2}) (2.6 \times 10^{15} \text{ kg})}{6.1 \times 10^3 \text{ m}} \right)^{1/2}$$

$$v' = 7.54 \text{ m/s}$$

Problem 4



solve for v_f :

$$\Delta K + \Delta P.E. = W_{nc}$$

$$\frac{1}{2} m v_f^2 + m g (\Delta h) = \bar{F}_{floor} \Delta h$$

$$\bar{F}_{floor} = 3 m g$$

$$v_f = \left(\frac{2(\bar{F}_{floor} - m g) \Delta h}{m} \right)^{1/2} = \left(\frac{(2)(2 m g) \Delta h}{m} \right)^{1/2}$$

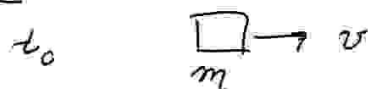
$$v_f = (2)(g \Delta h)^{1/2} = (2)\left(\frac{9.8 m}{s^2}\right)(0.2 m)^{1/2} = 2.8 \frac{m}{s}$$

Problem 5 a) $\Delta Q = m C_w \Delta T$

$$= (25 kg) \left(\frac{4190 J}{kg \cdot K} \right) (28 K) = 2.9 \times 10^4 J$$

$$b) P_{ave} = \frac{\Delta Q}{\Delta t} = \frac{2.9 \times 10^4 J}{60 s} = 4.9 \times 10^2 W$$

Problem 6:



$\rightarrow + \hat{i}$



momentum is conserved because there are no external forces. energy is not conserved due to the explosion.

$$\Delta p_x = 0$$

$$m_2 v_2 - m_1 v_1 = m v = 0$$

$$v_2 = \frac{m v + m_1 v_1}{m_2} = \frac{(2.0 kg) \left(\frac{2.0 m}{s} \right) + (0.5 kg) \left(\frac{1.0 m}{s} \right)}{(1.5 kg)}$$

$$= 6 m/s$$

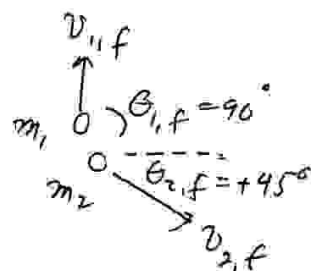
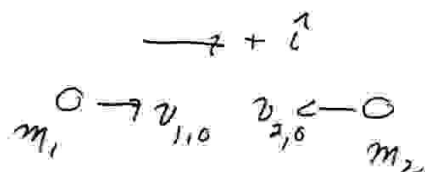
$$\Delta K_f = W_{n.c}$$

$$\frac{1}{2} m_2 v_2^2 + \frac{1}{2} m_1 v_1^2 - \frac{1}{2} m v^2 = W_{n.c.}$$

$$\left(\frac{1}{2}\right)(1.5 \text{ kg})\left(6 \frac{\text{m}}{\text{s}}\right)^2 + \left(\frac{1}{2}\right)(.5 \text{ kg})\left(10 \frac{\text{m}}{\text{s}}\right)^2 - \frac{1}{2}(2.0 \text{ kg})\left(2.0 \frac{\text{m}}{\text{s}}\right)^2 = 48 \text{ J}$$

is the increase in kinetic energy due to the explosion.

Problem 7:



$$\Delta P_x = 0 \Rightarrow P_{x,0} = P_{x,f}$$

$$m_1 v_{1,0} - m_2 v_{2,0} = m_2 v_{2,f} \cos \theta_{2,f} \quad (1)$$

$$\Delta P_y = 0 \Rightarrow P_{y,0} = P_{y,f}$$

$$0 = m_1 v_{1,f} - m_2 v_{2,f} \sin \theta_{2,f} \quad (2)$$

$$\Delta K = 0 \Rightarrow K_0 = K_f$$

$$\frac{1}{2} m_1 v_{1,0}^2 + \frac{1}{2} m_2 v_{2,0}^2 = \frac{1}{2} m_1 v_{1,f}^2 + \frac{1}{2} m_2 v_{2,f}^2 \quad (3)$$

Additionally - we are told that $v_{1,f} = \frac{v_{1,0}}{2}$

eq (2) can be rewritten using this fact as

$$m_2 v_{2,f} \sin \theta_{2,f} = \frac{m_1 v_{1,0}}{2}$$

eq (1) $m_2 v_{2,f} \cos \theta_{2,f} = m_1 v_{1,0} - m_2 v_{2,0}$

So dividing these equations yields

$$\tan \theta_{2,f} = \frac{m_1 v_{1,0} / 2}{m_1 v_{1,0} - m_2 v_{2,0}}$$

since $\tan \theta_{2,f} = \tan 45^\circ = 1$ we have b

$$1 = \frac{m_1 v_{1,0} / 2}{m_1 v_{1,0} - m_2 v_{2,0}} \quad \text{or} \quad m_1 v_{1,0} - m_2 v_{2,0} = \frac{1}{2} m_1 v_{1,0}$$

which we can solve for $v_{2,0}$

$$v_{2,0} = \frac{1}{2} \frac{m_1}{m_2} v_{1,0}$$

eq (2) can also be solved for $v_{2,f}$

$$v_{2,f} = \frac{m_1}{m_2} \frac{v_{1,0}}{2 \sin \theta_{2,f}} = \frac{m_1}{m_2} \frac{v_{1,0}}{2 \frac{\sqrt{2}}{2}} = \frac{m_1}{m_2} \frac{v_{1,0}}{\sqrt{2}}$$

So eq (3), can be rewritten as

$$\frac{1}{2} m_1 v_{1,0}^2 + \frac{1}{2} m_2 \left(\frac{1}{2} \frac{m_1}{m_2} v_{1,0} \right)^2 = \frac{1}{2} m_1 \left(\frac{v_{1,0}}{2} \right)^2 + \frac{1}{2} m_2 \left(\frac{m_1}{m_2} \frac{v_{1,0}}{\sqrt{2}} \right)^2$$

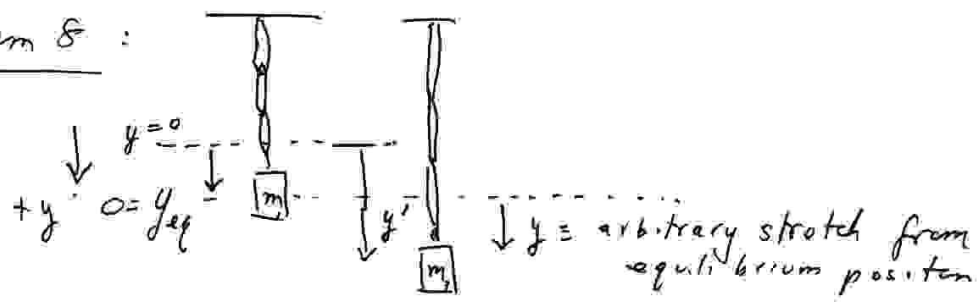
or

$$\frac{1}{2} m_1 v_{1,0}^2 + \frac{1}{2} m_2 \frac{1}{4} \frac{m_1^2}{m_2^2} v_{1,0}^2 = \frac{1}{2} m_1 \frac{v_{1,0}^2}{4} + \frac{1}{2} m_2 \frac{m_1^2}{m_2^2} \frac{v_{1,0}^2}{2}$$

$$\frac{3}{4} m_1 v_{1,0}^2 = \frac{1}{4} \frac{m_1^2}{m_2} v_{1,0}^2$$

$$\Rightarrow \boxed{3 = \frac{m_1}{m_2}}$$

Problem 8 :



The equilibrium position is already a slightly stretched position since at equilibrium

Free-body

F_y	mg
$mg - ky_{eq}$	$= 0$

$\Rightarrow y_{eq} = \frac{mg}{k}$

Then when the system is stretched an additional distance y_0 at $t=0$

F_y	mg
$mg - k(y + y_{eq})$	$= m \frac{d^2 y}{dt^2}$

$$\underbrace{mg - ky_{eq}}_0 - ky = m \frac{d^2 y}{dt^2}$$

$$m \frac{d^2 y}{dt^2} + ky = 0$$

here y is an arbitrary stretch from eq. pos we get
simple harmonic motion about y_{eq} position

$$y = A \cos \sqrt{\frac{k}{m}} t + B \sin \sqrt{\frac{k}{m}} t$$

$A = y_0, B = \frac{v_0}{\sqrt{k/m}} = 0$ released from rest

$$v = \frac{dy}{dt} = -\sqrt{\frac{k}{m}} A \sin \sqrt{\frac{k}{m}} t + \sqrt{\frac{k}{m}} B \cos \sqrt{\frac{k}{m}} t$$

period $T = \frac{2\pi}{\sqrt{k/m}} \Rightarrow T = 2\pi \sqrt{\frac{m}{k}}$

we can find the velocity using

$$y = y_0 \cos \sqrt{\frac{k}{m_1}} t,$$

$$v_y = -\sqrt{\frac{k}{m_1}} y_0 \sin \sqrt{\frac{k}{m_1}} t$$

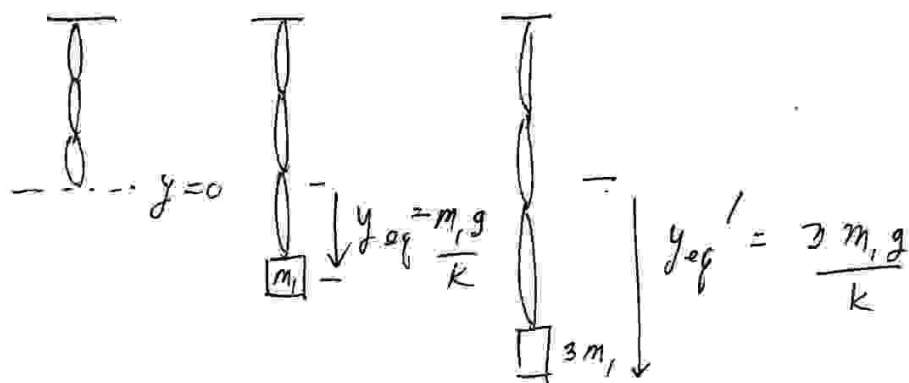
noting that when $\sqrt{\frac{k}{m_1}} t = \pi/2$, $\cos(\sqrt{\frac{k}{m_1}} t) = 0$
so $y = 0$, mass is back at eq. pos.

Also, $\sin\left(\frac{\pi}{2}\right) = 1$ so

$$v_y = -\sqrt{\frac{k}{m_1}} y_0 \quad \text{at eq. pos. } t_{eq} = \frac{\pi}{2} \sqrt{\frac{m_1}{k}}$$

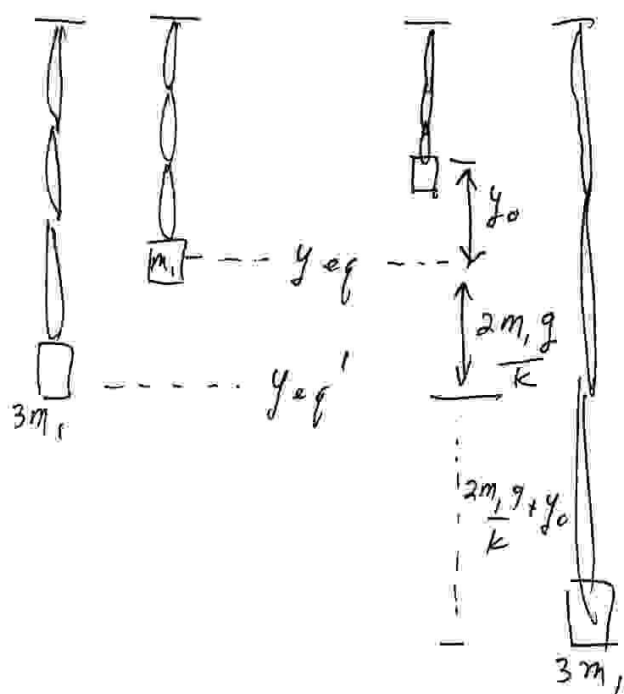
c) since a new mass $m_2 = 2m_1$
 $m_{total} = 3m_1$ and $T = 2\pi \sqrt{\frac{3m_1}{k}}$

d) since the collision occurred when
the mass was completely compressed,
the velocity was zero, hence for
the collision $\Delta K = 0$, no energy
was lost. Therefore, the new system
of mass $3m_1$ will satisfy
a new equilibrium condition
 $3m_1 g = k y_{eq'} \Rightarrow y_{eq'} = 3m_1 g / k$
and the oscillations are about this position.



So the new equilibrium position is lowered by $\frac{2m_1 g}{k}$

When the rubber bands were fully compressed by y_0 , the collision occurred. The



So with respect to the new equilibrium position the stretch is

$$y_0 + \frac{2m_1 g}{k}$$

Hence when the system is fully stretched, the mass $3m_1$ is at a position

$$y_0 + \frac{4m_1 g}{k}$$

from the original equilibrium position