

More on Cyclotron Fields

Equation 1.128 in B&B, and hence Eq. 1.129, is not as general as it could be. Arbitrary electric fields can be considered.

First, some notational things. I'd like to use t' as a dummy integration variable. This is a situation where the circumstances will be needed to recognize that t' is a dummy variable, not a derivative. Also, I'd like to allow for the possibility that the electric field has both an x - and a y -component, $\vec{E} = E_x \hat{x} + E_y \hat{y}$, and then let $\vec{\epsilon} \equiv \frac{q}{m} \vec{E}$. Recall that ω_c , the cyclotron frequency, is $\frac{qB_0}{m}$. The equations of motion are then

$$\dot{v}_x = \epsilon_x + \omega_c v_y, \quad \dot{v}_y = \epsilon_y - \omega_c v_x.$$

Denote the initial values of the velocity components (which we won't really need, but let's be complete) as $v_x(0) = v_{x0}$, $v_y(0) = v_{y0}$.

Now, similar to what was done in the text, by differentiating the first equation and substituting into the second we get a single equation, second order, for v_x ;

$$\ddot{v}_x + \omega_c^2 v_x = \dot{\epsilon}_x + \omega_c \epsilon_y.$$

The solution, which may be found any number of ways (see any differential equations text, or ask), is

$$\begin{aligned} v_x &= \frac{1}{\omega_c} \int_0^t \sin(\omega_c t - \omega_c t') \dot{\epsilon}_x(t') dt' \\ &\quad + \int_0^t \sin(\omega_c t - \omega_c t') \epsilon_y(t') dt' \\ &\quad + v_{x0} \cos \omega_c t + \left(\frac{\epsilon_{x0}}{\omega_c} + v_{y0} \right) \sin \omega_c t. \end{aligned}$$

Note that in the last term, $\dot{v}_x(0) = a_{x0} = \epsilon_x(0) + \omega_c v_{y0}$.

The first term may be integrated by parts;

$$\begin{aligned} &\frac{1}{\omega_c} \int_0^t \sin(\omega_c t - \omega_c t') \dot{\epsilon}_x(t') dt' \\ &= \frac{1}{\omega_c} \sin(\omega_c t - \omega_c t') \epsilon_x(t') \Big|_0^t + \int_0^t \cos(\omega_c t - \omega_c t') \epsilon_y(t') dt \\ &= -\frac{1}{\omega_c} (\sin \omega_c t) \epsilon_x(0) + \int_0^t \cos(\omega_c t - \omega_c t') \epsilon_y(t') dt, \end{aligned}$$

so that the result is

$$v_x = \int_0^t [\cos(\omega_c t - \omega_c t') \epsilon_x(t') + \sin(\omega_c t - \omega_c t') \epsilon_y(t')] dt' + v_{x0} \cos \omega_c t + v_{y0} \sin \omega_c t.$$

A similar result holds for v_y .

The above may be summarized very cleanly by use of matrix calculus. Sparing the details (although you are encouraged to check),

$$\vec{v} = \int_0^t M(\omega_c t - \omega_c t') \vec{e}(t') dt' + M(\omega_c t) \vec{v}_0,$$

where M is a matrix,

$$M(\theta) = \begin{bmatrix} \cos \theta & \sin \theta \\ -\sin \theta & \cos \theta \end{bmatrix}.$$

The matrix $M(\theta)$ has many amazing properties. It can be shown that

$$M(\theta) = \exp(R\theta), \quad \text{where } R = \begin{bmatrix} 0 & 1 \\ -1 & 0 \end{bmatrix},$$

and the exponentiation of a matrix is done *via* a series expansion. To be amazed, note that the eigenvalues of M and R are $\pm i$, $M(0) = I$, the identity matrix, $M(\pi/2) = R$, $\frac{dM}{d\theta} = RM$, and $M(\alpha)M(\beta) = M(\alpha + \beta)$. M rotates a vector by the angle θ , and R is known as the generator of rotations in the plane.