1.2 First order ordinary differential equations

1.2.1 General solution

Equation (1.1.10) is a typical first order ordinary differential equation (ODE). The stationary points of a general such ODE of the form $\dot{x} = F(x)$ are obtained by as solutions to $F(x^*) = 0$. To plot the trajectory of motion, starting from $x(t = 0) = x_0$, we can use the following procedure²

$$\frac{dx}{dt} = F(x), \implies \frac{dx}{F(x)} = dt, \implies t = \int_{x_0}^{x(t)} \frac{dx'}{F(x')}.$$
 (1.2.3)

Assuming that we can evaluate the integral in the final expression, we still need to invert the result to obtain the explicit form of x(t).

Let us redrive the solution for the decaying linear spring in Eq. (1.1.11), with $F(x) = -\gamma x$, noting:

$$t = \int_{x_0}^{x(t)} \frac{dx'}{(-\gamma x')} = -\frac{1}{\gamma} \ln\left(\frac{x(t)}{x_0}\right), \quad \Longrightarrow \quad x(t) = x_0 e^{-\gamma t}, \tag{1.2.4}$$

as obtained in Eq. (1.1.15) by summing the Taylor series.

A slight variations is obtained by considering $F(x) = u - \gamma x$, starting from x = 0 and t = 0, in which case

$$t = \int_0^{x(t)} \frac{dx'}{(u - \gamma x')} = -\frac{1}{\gamma} \ln \left(\frac{u - \gamma x(t)}{u} \right), \quad \Longrightarrow \quad x(t) = \frac{u}{\gamma} \left(1 - e^{-\gamma t} \right). \tag{1.2.5}$$

Once again, the coordinate approaches its equilibrium point, $x^* = u/\gamma$ (solution of $F(x^*) = 0$ exponentially. Indeed this solution is identical to the previous one, obtained by a shifting the variable x by $x^* = x_0$.

$$x(t+dt) = x(t) + \frac{dx}{dt}dt + \text{terms of order } dt^2 \text{ and higher.}$$
 (1.2.1)

Thus to lowest order in dt as $dt \to 0$,

$$dx \equiv x(t+dt) - x(t) = dt \frac{dx}{dt} \implies dt = \frac{dx}{dx/dt}.$$
 (1.2.2)

²To justify the first step in Eq. (1.2.3), recall that from the Taylor series