

# Communications and Networks: Data Networks Option

## Probability: Sum of Independent Gaussian Variables

Let  $Z = X + Y$  where  $X$  and  $Y$  are two independent Gaussian r.v.'s with means  $\mu_X$  and  $\mu_Y$ , and variances  $\sigma_X^2$  and  $\sigma_Y^2$ , respectively, i.e.,  $X \sim \mathcal{N}(\mu_X, \sigma_X^2)$  and  $Y \sim \mathcal{N}(\mu_Y, \sigma_Y^2)$ .

1. Determine the distribution of  $Z$ .
2. Determine the mean  $\mu_Z$  and the variance  $\sigma_Z^2$  of  $Z$ .

If you want to use characteristic functions, then the characteristic function of a Gaussian r.v.  $\theta$  with mean  $\mu_\theta$  and variance  $\sigma_\theta^2$  is  $\phi_\theta(w) = \mathbb{E}\{e^{jw\theta}\} = \exp(+jw\mu_\theta - \frac{1}{2}w^2\sigma_\theta^2)$ .

## Data Networks Option

Consider a simple communication system with two links. Packets arrive for transmission through link  $i$  according to an arrival process  $\{A_i(t)\}$ ,  $i = 1, 2$ . The arrival processes are assumed IID over time slots, mutually independent, with arrival rates  $\mathbb{E}[A_i(0)] = \lambda_i$ , and finite second moments. Packets are buffered in dedicated queues until they are transmitted; let  $Q_i(t)$  be the number of packets that await to be transmitted through link  $i$ , at time slot  $t$ . At each time slot a scheduler takes one of the following four actions: (i) serves only the queue of link 1 at rate 3 packets per slot (schedule  $\pi_1$ ); (ii) serves only the queue of link 2 at rate 3 packets per slot (schedule  $\pi_2$ ); (iii) serves both queues at rate 2 packets per slot each (schedule  $\pi_3$ ); (iv) does not serve any queue (schedule  $\pi_4$ ). Thus, the service rate vector  $R(t) = (R_1(t), R_2(t))$  belongs to the set  $\mathcal{R} = \{(3, 0), (0, 3), (2, 2), (0, 0)\}$ , at each time slot.

(a) Derive the stability region of the system, i.e., the necessary conditions that the arrival rates have to satisfy for the system to be stable;

(b) Write the difference equations that govern the evolution of the system, and provide an upper bound on the drift of the Lyapunov function  $L(t) = \sum_{i=1,2} Q_i^2(t)$  under these dynamics. The drift of  $L(\cdot)$  is defined as  $\Delta(t) = \mathbb{E}[L(t+1) - L(t) \mid Q(t)]$ ;

(c) Propose a scheduling policy that stabilizes the system whenever the arrival rates are in the interior of the stability region.