

**Space Propulsion Field Exam: Space Propulsion/Plasma Physics**  
**REQUIRED BY ALL STUDENTS**

From the outside, an Ion Engine and a Hall thruster are very similar devices: in both of them a Noble Gas is partially ionized, the ions are made to fall through a potential difference, and the electrons are captured by an anode and joined to the ions to form a plasma beam. The overall performance of the two is also similar, although not identical.

You are asked to comment on a few of the differences. Specifically,

- 1) For a given thrust and specific impulse, an ion engine is physically larger than a Hall thruster. Explain why.
- 2) Both devices use magnetic fields, even though they both are electrostatic ion accelerators. Explain the role of the magnetic field in each of them, and how this guides the layout of these  $\vec{B}$  fields.
- 3) One advantage of ion engines over Hall thrusters is a better collimated beam (smaller plume divergence). Explain why this is so and what could be done to reduce the beam divergence in a Hall thruster to something approaching ion engine levels.
- 4) The efficiency has been historically higher for ion engines than for Hall thrusters (at a fixed specific impulse). Comment on possible reasons and remedies (in the Hall thruster case).

### Space Propulsion Field Exam: Astrodynamics elective

A satellite is initially in an elliptic Geosynchronous Transfer Orbit about Earth, and it is desired to use a low-thrust engine to raise continuously its energy to escape conditions, without rotating its orbit's line of apses or its plane. The thrusting acceleration  $f = F/m$  ( $F = \text{thrust}$ ,  $m = \text{mass}$ ) can be modulated as a function of the true anomaly  $\theta$ , and the thrust vector  $\vec{F}$  is to be aligned with the velocity vector  $\vec{v}$ .

Formulate a set of first-order time differential equations for  $\theta$ ,  $a$  (the instantaneous semi-major axis) and  $e$  (the instantaneous eccentricity). These equations should be numerically (or perhaps analytically) solvable once  $f(\theta)$  is specified. What should be the end condition indicating when escape is reached?

Hint: What is the rate of change of orbital energy?

