

**PSEUDONORMALITY AND INFORMATIVE  
LAGRANGE MULTIPLIERS**

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## Optimality Conditions

- Let  $x^*$  be a local minimum of the problem:

$$\begin{array}{ll} \text{minimize} & f(x) \\ \text{subject to} & g_j(x) \leq 0, \quad j = 1, \dots, r. \end{array}$$

- **Karush-Kuhn-Tucker Opt Conds:** Under some conditions,  $\exists$  scalars  $\mu_j^* \geq 0$ , called **Lagrange multipliers**, such that

$$\nabla f(x^*) + \sum_{j=1}^r \mu_j^* \nabla g_j(x^*) = 0,$$

where  $\mu_j^* = 0$  for all  $j$  with  $g_j(x^*) < 0$ . (**Complementary slackness**)

- **Main Issue:** What is the structure of the constraint set that guarantees the existence of Lagrange multipliers?

## Constraint Qualifications

- It is well-known that there exist Lagrange multipliers when the tangent cone has the form

$$\{y \mid \nabla g_j(x^*)'y \leq 0, \forall j \text{ with } g_j(x^*) = 0\}$$

⇒ **Quasiregularity Condition** (Proof via Farkas' Lemma)

- Classical work focused on **constraint qualifications** that guarantee quasiregularity
  - Requires complicated proofs (based on implicit function theorem)
  - This approach fails when there is an additional set constraint.
- **Fritz John Optimality Conditions**: There exist  $\mu_0^* \geq 0$  and  $\mu_j^* \geq 0$  such that

$$\mu_0^* \nabla f(x^*) + \sum_{j=1}^r \mu_j^* \nabla g_j(x^*) = 0$$

where  $\mu_j^* = 0$  for all  $j$  with  $g_j(x^*) < 0$ .

- *Question now becomes*: When is  $\mu_0^* > 0$ ?

## Our Development of Lagrange Multiplier Theory

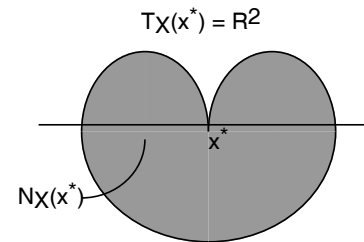
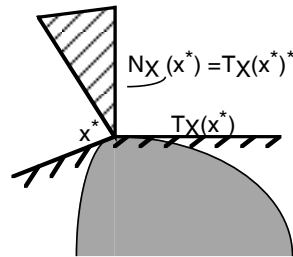
- Consider optimization problems of the form

$$\begin{array}{ll} \text{minimize} & f(x) \\ \text{subject to} & x \in X, \quad g_j(x) \leq 0, \quad j = 1, \dots, r. \end{array}$$

- Simple and powerful line of analysis
  - Based on an enhanced set of Fritz John conditions
  - Special Lagrange multipliers that carry significant sensitivity information
  - New conditions that extend and unify constraint qualifications
  - Connections to exact penalty functions
- In the first part of the talk, assume that  $f$  and the  $g_j$  are smooth functions, and  $X$  is a closed set.
- When  $X$  is not convex, need machinery from nonsmooth analysis.

## Conical Approximations of Constraint Sets

- **Polar cone** of a set  $T$  :  $T^* = \{y \mid y'x \leq 0, \forall x \in T\}$
- Two cones to go into the heart of issues about Lagrange multipliers
  - **Tangent cone**,  $T_X(x^*)$  : characterizes directions along which some feasible sequence converges to  $x^*$
  - **Normal cone**,  $N_X(x^*)$  : cone of limiting normal vectors  
[ $z \in N_X(x)$  if  $\exists$  sequences  $\{x_k\} \subset X$  and  $\{z_k\}$  such that  $x_k \rightarrow x$ ,  $z_k \rightarrow z$ , and  $z_k \in T_X(x_k)^*$ ]



- **Crucial property of constraint sets:** We say that  $X$  is **regular at  $x^*$**  when

$$T_X(x^*)^* = N_X(x^*)$$

## Definition of Lagrange Multipliers

Let  $x^*$  be a local minimum. Then  $\mu^* = (\mu_1^*, \dots, \mu_r^*)$  is a **Lagrange multiplier** if  $\mu_j^* \geq 0$  for all  $j$ ,  $\mu_j^* = 0$  for all  $j$  with  $g_j(x^*) < 0$ , and

- For  $X = \mathbb{R}^n$ ,

$$\nabla f(x^*) + \sum_{j=1}^r \mu_j^* \nabla g_j(x^*) = 0.$$

- For  $X$  any convex closed set,

$$\left( \nabla f(x^*) + \sum_{j=1}^r \mu_j^* \nabla g_j(x^*) \right)' (x - x^*) \geq 0, \quad \forall x \in X.$$

- For  $X$  any closed set,

$$\left( \nabla f(x^*) + \sum_{j=1}^r \mu_j^* \nabla g_j(x^*) \right)' y \geq 0, \quad \forall y \in T_X(x^*).$$

## Enhanced Fritz John Optimality Conditions

**Proposition:** Let  $x^*$  be a local minimum. Then there exist multipliers  $\mu_0^*, \mu_j^*$  s.t.

1.  $-\left(\mu_0^* \nabla f(x^*) + \sum_{j=1}^r \mu_j^* \nabla g_j(x^*)\right) \in N_X(x^*)$ .
2.  $\mu_j^* \geq 0$  for all  $j$ , and  $\mu_0^*, \dots, \mu_j^*$  are not all equal to 0.
3. If the set  $J = \{j \neq 0 \mid \mu_j^* > 0\}$  is nonempty, arbitrarily close to  $x^*$ ,  $\exists$  some  $x \in X$  s.t.:

$$f(x) < f(x^*), \quad g_j(x) > 0, \quad \forall j \in J,$$

while violation of constraints with 0 multipliers is arbitrarily small.

- Proof using a quadratic penalty function approach.
- We call condition (3) the **complementary violation (CV)** condition  
 $\Rightarrow$  Stronger than complementary slackness condition:

$$g_j(x^*) = 0, \quad \forall j \in J.$$

## New Condition - Pseudonormality

A feasible vector  $x^*$  is **pseudonormal** if there are no scalars  $\mu_1, \dots, \mu_r$ , and no sequence  $\{x^k\} \subset X$  such that

1.  $-\left(\sum_{j=1}^r \mu_j \nabla g_j(x^*)\right) \in N_X(x^*)$ .
2.  $\mu_j \geq 0$ , for all  $j$ , and  $\mu_j = 0$  for all  $j$  with  $g_j(x^*) < 0$ .
3.  $\{x^k\}$  converges to  $x^*$  and

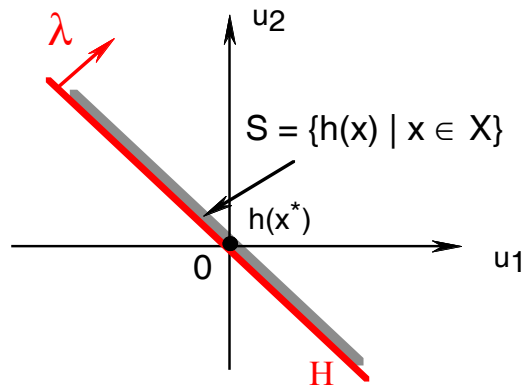
$$\sum_{j=1}^r \mu_j g_j(x^k) > 0, \quad \forall k.$$

- If  $x^*$  is a pseudonormal local minimum and  $X$  is regular at  $x^*$ , then there exist Lagrange multipliers (of special type).
- Classical CQs for  $X = \mathfrak{R}^n$  (such as linear indep. of const. gradients, Slater cond.) can easily be shown to imply pseudonormality.
- Yields new CQs for  $X \neq \mathfrak{R}^n$  (extended Mangasarian-Fromovitz cond., conds for problems with linear equality constraints).



## Insight into Pseudonormality

- Consider the problem: minimize  $f(x)$   
subject to  $h_i(x) = 0, i = 1, \dots, m$ .
- $x^*$  is **pseudonormal** if there are no scalars  $\lambda_1, \dots, \lambda_m$  and no sequence  $\{x_k\}$  such that
  1.  $\sum_{i=1}^m \lambda_i \nabla h_i(x^*) = 0$ .
  2.  $x_k \rightarrow x^*$  and  $\sum_{i=1}^m \lambda_i h_i(x_k) > 0$ .
- Linear independence of  $\nabla h_i(x^*) \Rightarrow$  pseudonormality.
- $h_i$ 's affine  $\Rightarrow$  pseudonormality.



## Informative Lagrange Multipliers

- We say that a Lagrange multiplier  $\mu^*$  is **informative** if, in addition to Lagrangian stationarity condition, it satisfies the CV condition, i.e.,  $\exists$  some  $x \in X$  s.t.:

$$f(x) < f(x^*), \quad g_j(x) > 0, \quad \forall j \text{ with } \mu_j^* > 0,$$

$$g_j(x) = o\left(\min_{j \in J} g_j(x)\right), \quad \forall j \text{ with } \mu_j^* = 0.$$

- Provide significant amount of sensitivity interpretation by indicating which constraints to violate to effect a cost reduction.
- **Proposition:** Assume that  $T_X(x^*)$  is convex. If the set of Lagrange multipliers is nonempty, then the Lagrange multiplier with minimum norm is an informative Lagrange multiplier.

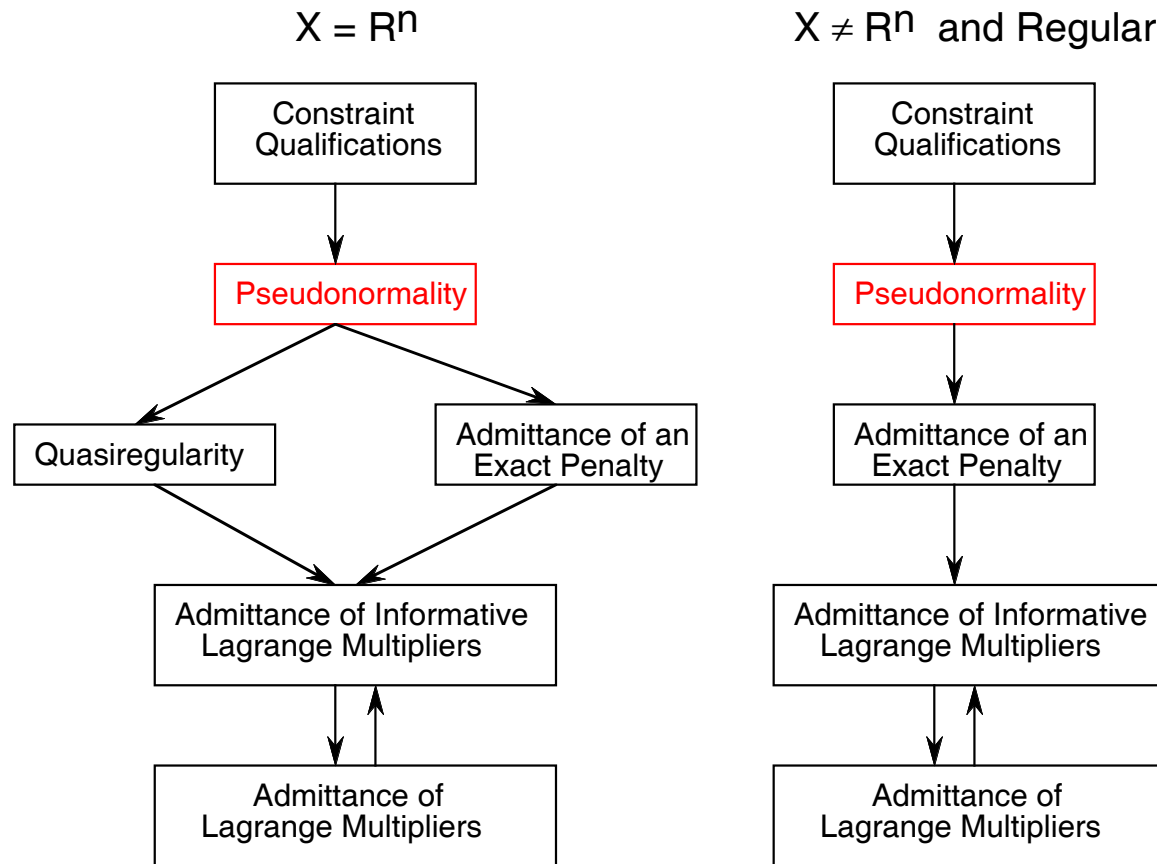
## Exact Penalty Functions

- Consider the penalized problem for some finite value of  $c$

$$\begin{array}{ll} \text{minimize} & F_c(x) = f(x) + c \sum_{j=1}^r \max\{0, g_j(x)\} \\ \text{subject to} & x \in X. \end{array}$$

- There exists an exact penalty at  $x^*$ , if for every smooth  $f$  for which  $x^*$  is a strict local minimum of original problem, there is a  $c > 0$ , such that  $x^*$  is also a local minimum of  $F_c$  over  $X$ .
- **Proposition:** If  $x^*$  is pseudonormal, then there exists an exact penalty at  $x^*$ .
- Proves in a unified way the existence of an exact penalty for a much larger variety of constraint qualifications.

## Unifying Role of Pseudonormality



- Pseudonormality also provides unification in the case when  $X$  is not regular.

## Multipliers and Convex Programming

Consider the problem

$$\begin{array}{ll} \text{minimize} & f(x) \\ \text{subject to} & x \in X, \quad g_j(x) \leq 0, \quad j = 1, \dots, r, \end{array}$$

where  $X$  is a convex set, and  $f$  and  $g_j$  are convex over  $X$ . Assume that optimal value of this problem  $f^*$  is finite.

- A vector  $\mu^*$  is said to be a **geometric multiplier** if  $\mu^* \geq 0$  and

$$f^* = \inf_{x \in X} \left\{ f(x) + \mu^{*\prime} g(x) \right\}.$$

- Fritz John type optimality conditions can be derived using convex set support/separation arguments.
  - These do not include conditions analogous to CV condition.

## Enhanced Fritz John Conditions

**Proposition:** Assume that  $X$  is closed and convex, and the  $f$  and the  $g_j$  are convex and lower semicontinuous over  $X$ . Then there exist multipliers  $\mu_0^*$ ,  $\mu_j^*$  s.t.

1.  $\mu_0^* f^* = \inf_{x \in X} \left\{ \mu_0^* f(x) + \sum_j \mu_j^* g_j(x) \right\}$ .
2.  $\mu_j^* \geq 0$  for all  $j$ , and  $\mu_0^*, \dots, \mu_j^*$  are not all equal to 0.
3. If  $J = \{j \neq 0 \mid \mu_j^* > 0\}$  is nonempty,  $\exists$  some sequence  $\{x^k\} \subset X$  s.t.:

$$\lim_{k \rightarrow \infty} f(x^k) = f^*, \quad \limsup_{k \rightarrow \infty} g_j(x^k) \leq 0$$

and for all  $k$

$$g_j(x) > 0, \quad \forall j \in J, \quad g_j(x) = o(\min_{j \in J} g_j(x)), \quad \forall j \notin J.$$

- Proof via saddle point theory and compactification arguments.

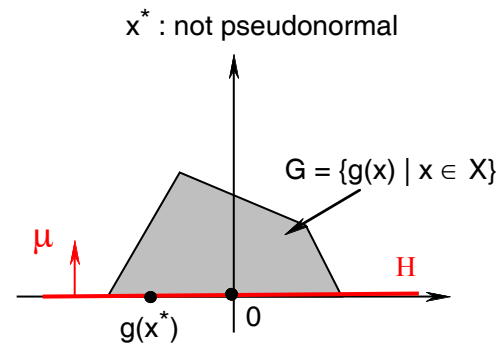
## Pseudonormality of Constraint Set

Consider the convex program under the closedness assumptions of the preceding proposition. The constraint set is **pseudonormal** if there are no nonnegative scalars  $\mu_1, \dots, \mu_r$ , and no sequence  $\{x^k\} \subset X$  such that

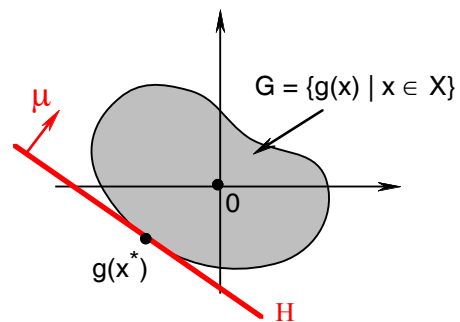
1.  $0 = \inf_{x \in X} \mu' g(x)$ .
  2.  $\limsup_{k \rightarrow \infty} g(x^k) \leq 0$  and  $\mu' g(x^k) > 0$  for all  $k$ .
- If the problem has a convex lower semicontinuous cost function and a pseudonormal constraint set, then **there exist geometric multipliers (of special type)**.

## Geometric Interpretation of Pseudonormality

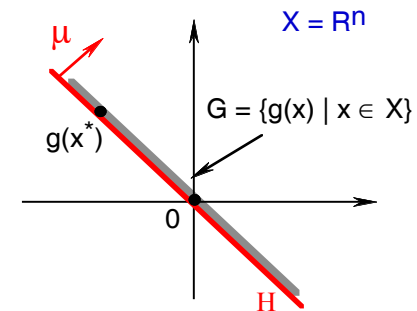
- Consider the set  $G = \{g(x) \mid x \in X\}$  and hyperplanes that support this set at  $g(x^*)$ .



$x^*$  : pseudonormal, Slater Condition



$x^*$  : pseudonormal, Linear Constraints





## Summary

- A new approach to Lagrange multiplier theory based on an enhanced set of Fritz John conditions.
- Motivates the notion of “**constraint pseudonormality**” as the linchpin of a theory of constraint qualifications and the connection with exact penalty functions.
- Existence of informative Lagrange multipliers.
- Extension of pseudonormality to convex programming and geometric multipliers.
- Existence of informative geometric multipliers.