

MASSACHUSETTS INSTITUTE OF TECHNOLOGY

Department of Economics

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Solving Moral Hazard Models

1. Benchmark: effort is observable and contract can depend on it: $\tilde{s}(x, e)$

- IC drops out.
 - Simply pay $\tilde{s}(x, e) = 0$ unless correct effort is chosen (depends on reservation utility)
- First Best \longrightarrow still use a sharing rule, $\tilde{s}(x, e) = s(x)$ if $e = e^*$
 - gains from trade in risk-sharing (unless same utility functions)
- Program

$$\max_{e, s(\cdot)} \int v(x - s(x)) f(x | e) dx$$

$$\text{s.t.} \quad \int u(s(x)) f(x | e) dx - c(e) \geq \underline{u} \quad (\text{IR})$$

1. • – λ multiplier on (IR)
- – Can drop IC due to observability, don't pay them unless see the effort specified

- To Solve: Take a 2 step approach
 - notice IR must bind (or can lower $u(s(x))$ by a constant, Principal better off
 - maximize the objective pointwise
 - * if x is discrete, clearly this approach is right
 - * optimal control: same thing works if you choose a function
- FOC: differentiate w.r.t. $s(x)$

$$-v'(x - s(x)) f(x | e) + \lambda u'(s(x)) f(x | e) = 0$$

$$\lambda = \frac{v'(x - s(x))}{u'(s(x))}, \quad \forall x$$

- Ratio of marginal utilities is constant (characteristic of optimal risk-sharing)
- Observe:
 - if $f(x | e)$ is degenerate $e \longrightarrow x_e$
(no uncertainty, no risk)
 - if $v(w) = w$ (risk neutral principal)
 - * agent bears no risk
 - * risk-neutral agent bears all the uncertainty (insurance contract)

$$\underbrace{\lambda}_{\text{optimal risk-sharing constant}} = \frac{1}{u'(s(x))} \implies u'(s(x)) = \text{constant}$$

$$\implies s(x) = \text{constant}$$

Question: If principal is risk-neutral, how do we find the effort?

Answer: IR

$$u(w(e)) - c(e) = \underline{u}, \quad (\text{will bind})$$

$$w(e) = u^{-1}[\underline{u} + c(e)]$$

- Principal (think of u^{-1} as converting monetary units to utils of principal)

$$\begin{aligned} & \max_e \underbrace{\int x f(x(e)) dx}_{\text{benefits}} - \underbrace{u^{-1}[\underline{u} + c(e)]}_{\text{cost} \longrightarrow \text{deterministic}} \\ &= E[x | e] - u^{-1}[\underline{u} + c(e)] \end{aligned}$$

- equalize marginal benefit (MB) of effort with monetary cost of effort
- To see this, take FOC \longrightarrow differentiate \longrightarrow get marginals \longrightarrow no distortion

2. Unobservable Effort

- No Risk Aversion (either principal or agent) \longrightarrow no need for insurance

Proposition 1 *First Best can be attained. Principal “sell the firm” to Agent.*

$$s(x) = x - \alpha, \quad \alpha = \text{price of firm} \\ (\text{Agent is the residual claimant})$$

$$\text{IR: } \int x f(x | e) dx - c(e) - \alpha \geq \underline{u}$$

IC:

$$\begin{aligned} e^* &= \arg \max_e \int x f(x | e) dx - c(e) - \alpha \\ &= \arg \max_e E[x | e] - c(e) \quad (\text{First Best incentives}) \\ &= \int v(x - s(x)) f(x | e) dx + \int u(s(x)) f(x | e) dx - c(e) \\ &\quad (\text{choice of effort that maximizes joint surplus}) \end{aligned}$$

$\longrightarrow e^*$ is FB

set α so that IR binds (e.g. taxi pays dispatcher for the day and keeps the rest):

$$\alpha = E[x | e^{FB}] - c(e^{FB}) - \underline{u}$$

- Risk-Averse Agent, Principal Risk-Neutral (two effort model)

$$\begin{aligned} e_L, e_H \quad c(e) &= c_H, c_L, \quad (c_H > c_L) \\ F(x | e) &= \begin{cases} F_H(x) \\ F_L(x) \end{cases} \end{aligned}$$

Remark 2 Assume $F_H(x) \underset{FOSD}{\geq} F_L(x)$

$\implies F_H \leq F_L, \quad \forall x \Leftrightarrow \int g(x) dF_H(x) \geq \int g(x) dF_L(x), \quad \forall g$
non-decreasing

(check true for all step functions)

$E(g) = 1 - F \implies$ increase mass to the right

- Question: How is the e_L implemented?

Answer: Optimal Risk Sharing

- s_L is constant since $e_L > e_H \implies IC$ satisfied
- make IR bind with fixed wage (constant wage)

- Question: How is the e_H implemented?

Answer:

- sharing has to reward high output more

$$\max_{s(-)} \int (x - s(x)) f_H(x) \text{ such that}$$

$$IC : \int u(s(x)) f_H(x) - e_H \geq \int u(s(x)) f_L(x) dx - e_L, \quad \mu$$

$$IR : \int u(s(x)) f_H(x) dx - e_H \geq u, \quad \lambda$$

- use pointwise optimization

$$\max_{s(x)} -s(x) f_H(x) + \mu [u(s(x)) [f_H(x) - f_L(x)]] + \lambda u(s(x))$$

$$\text{differentiate} : -f_H(x) + \mu u'(s(x)) (f_H(x) - f_L(x)) + \lambda u'(s(x)) f_H$$

$$\text{re-arrange} : \frac{1}{u'(s_H(x))} = \lambda + \mu \left[1 - \frac{f_L}{f_H} \right]$$

- IR binds: if did not bind, sharing rule would not satisfy IC.

$$u(s(x)) - u(\hat{s}(x)) = \Delta \text{ doesn't depend on } x, \quad \lambda > 0$$

- Question: Could we have $\mu = 0$?
Answer: full insurance, $MU = \text{constant}$
 - Contradiction - full insurance can't be incentive compatible (IC violated), $\lambda > 0$
- Interpretations
 - deviating from first best
 - * not full insurance which we know is first best
 - * μ : extent to which IC matters (distorts our choice)
 - Question: Given x we observe, how likely is it that they chose high effort?
Answer: $\frac{f_H(x)}{f_L(x)}$ (likelihood ratio)
 - * $\frac{f_H(x)}{f_L(x)} = 1 \longrightarrow$ don't want to reward or punish
 - * low more likely than high \longrightarrow punish
 - * high more likely than low \longrightarrow reward
- Optimal Sharing Rule varies only with $\frac{f_H(x)}{f_L(x)}$

$$\text{find } s^*(x) = \frac{1}{u'(s^*(x))} = \lambda$$

$$s_H(x) > s^*(x) \text{ iff } \frac{f_H(x)}{f_L(x)} > 1$$

$$s_H(x) < s^*(x) \text{ iff } \frac{f_H(x)}{f_L(x)} < 1$$

- Interpretation: rewarded for evidence of good behavior, punished for bad
 $s_H(x)$ strictly increasing in $\frac{f_H(x)}{f_L(x)}$

Remark 3 *This is not a statistical inference problem. In eqbm, you know what agent did (implement e_H). You behave as if inference problem. Provide incentives to get the other guy to truthfully reveal effort.*

- Question: $s_H(x)$ monotone in x ?

Answer: only true if $\frac{f_H(x)}{f_L(x)}$ is monotone

– e.g.: suppose $x = e + \theta$, θ has two humps

$s_H(x)$ monotone iff $\frac{f_H(x)}{f_L(x)} \uparrow$ (monotone) in x (MLRP)

- MLRP \longrightarrow local. Can condition on two points.

$MLRP \implies FOSD$, but $FOSD \not\Rightarrow MLRP$

- PROOF: log supermodularity

$$f(x, e) : \frac{\partial^2}{\partial x \partial e} f(x, e) \geq 0 \Leftrightarrow \text{supermodularity}$$

$$\frac{\partial^2}{\partial x \partial e} \ln f(x, e) \geq 0 \Leftrightarrow \text{log supermodularity}$$

- increasing differences: $f(x, e)$ supermodular $\Leftrightarrow f(x, e_H) - f(x, e_L) \uparrow x \forall e_H > e_L$
- increasing ratios: $f(x, e)$ log supermodular $\Leftrightarrow \frac{f(x, e_H)}{f(x, e_L)} \uparrow x \forall e_H > e_L$

Theorem 4 $f(x, e)$ log sprm $\rightarrow \int_a^b f(x, e) dx$ log sprm in (a, b, e)
use for uncertainty, risk aversion, elasticity

- f MLRP $\Leftrightarrow f$ log sprm

$$\implies \int_{-\infty}^x f(x, e) dx \text{ is log sprm} \implies \frac{F(x, e_H)}{F(x, e_L)} \uparrow x \forall e_H > e_L \text{ (by def'n)}$$

$$\text{but } \lim_{x \rightarrow \infty} \frac{F(x, e_H)}{F(x, e_L)} = 1 \text{ (by def'n CDF)}$$

$$\implies F(x, e_H) \leq F(x, e_L)$$

- x can be interpreted generally if Principal is risk neutral

$$\int (\pi - s(x)) f_H\left(\frac{\pi}{x}\right) dx$$

x is just a signal

e.g.: x = exam score, π = how good a researcher you will be

- Add'l information - multiple signal

$$x = (x_1, x_2), \quad \frac{1}{u'(s_H(x_1, x_2))} = \lambda + \mu \left[1 - \frac{f_L(x_1, x_2)}{f_H(x_1, x_2)} \right]$$

s depends on x_i iff $\frac{f_H}{f_L}(x_1, \dots, x_n)$ depends on x_i

- if π is a sufficient statistic for (x_1, \dots, x_n) then WLOG $s(\pi)$

$$\frac{f_H(x_1, \dots, x_n, \pi)}{f(x_1, \dots, x_n, \pi)} = \frac{f_H(\pi)}{f_L(\pi)}$$

- Random Schemes are not optimal