

Steric effects in the dynamics of electrolytes at large applied voltages. I. Double-layer charging

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The classical Poisson-Boltzmann (PB) theory of electrolytes assumes a dilute solution of point charges with mean-field electrostatic forces. Even for very dilute solutions, however, it predicts absurdly large ion concentrations (exceeding close packing) for surface potentials of only a few tenths of a volt, which are often exceeded, e.g., in microfluidic pumps and electrochemical sensors. Since the 1950s, several modifications of the PB equation have been proposed to account for the finite size of ions in equilibrium, but in this two-part series, we consider steric effects on diffuse charge dynamics (in the absence of electro-osmotic flow). In this first part, we review the literature and analyze two simple models for the charging of a thin double layer, which must form a condensed layer of close-packed ions near the surface at high voltage. A surprising prediction is that the differential capacitance typically varies nonmonotonically with the applied voltage, and thus so does the response time of an electrolytic system. In PB theory, the differential capacitance blows up exponentially with voltage, but steric effects actually cause it to decrease while remaining positive above a threshold voltage where ions become crowded near the surface. Other nonlinear effects in PB theory are also strongly suppressed by steric effects: The net salt adsorption by the double layers in response to the applied voltage is greatly reduced, and so is the tangential “surface conduction” in the diffuse layer, to the point that it can often be neglected compared to bulk conduction (small Dukhin number).

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I. INTRODUCTION

In this two-part series, we develop a simple analytical theory for the dynamics of electrolytes, taking into account steric effects of finite ion size. Motivated by recent experiments in microfluidics, microbatteries, and electrochemical sensors, our motivation is to describe the response of an electrolyte to an applied voltage of several volts, which is large enough to cause crowding of ions near a surface, even if the bulk solution is very dilute and in the absence of surface reactions. The ions thus lose their classical Poisson-Boltzmann distribution, which has major implications for their dynamics.

As a guide to the reader, we summarize the main results. The present “Part I” begins in this section with a historical review of dilute solution theory, its limitations at large voltages, and attempts to account for steric hindrance, specific interactions, and many-body electrostatics. As a first approximation, we focus only on steric effects and analyze the dynamical response of a thin diffuse layer to a large applied voltage, using two simple continuum models (Sec. II). The key results, common to both steric models, are (i) the diffuse layer’s differential capacitance is bounded and decreases at large voltage (Sec. III), and (ii) it cannot easily engulf enough ions to perturb the bulk concentration or to conduct significant tangential currents (Sec. IV). These predictions are completely opposite to those of dilute solution theory (based on the Gouy-Chapman model of the diffuse layer). In the companion paper, “Part II” [1], we propose general, time-dependent equations with steric constraints and revisit the parallel-plate charging problem in more detail.

A. Dilute solution theory

For the past century, dilute solution theory has provided the standard model of electro-diffusion of ions [2–4] and electrokinetic phenomena [5,6]. The fundamental assumption is that the chemical potential of a pointlike ion i in a dilute solution has the simple form

$$\mu_i = kT \ln c_i + z_i e \psi, \quad (1)$$

where $z_i e$ is the charge, c_i the concentration, and ψ the electrostatic potential, determined in a mean-field approximation by Poisson’s equation,

$$-\nabla \cdot (\epsilon \nabla \psi) = \rho = \sum_i z_i e c_i, \quad (2)$$

typically with a constant permittivity ϵ . The form (1) is sometimes called the “ideal” component of the chemical potential [7], to which various “excess” components at finite concentration can be added (see below).

In many situations, it is assumed that the ions are in quasi-thermal equilibrium with a Boltzmann distribution,

$$c_i = c_i^0 e^{-z_i e \psi / kT} \quad (3)$$

with a reference concentration c_i^0 , in which case Eq. (2) reduces to the Poisson-Boltzmann equation (PB). For example, to analyze a thin double layer, it is natural to choose c_i^0 to be the concentration of species i in the nearby neutral bulk solution. In most situations, the PB equation is hard enough to solve that the Debye-Hückel linearization for small potentials, $|\psi| \ll \psi_T$, is required for analytical progress, where $\psi_T = kT / z_i e$ is the thermal voltage (≈ 25 mV for monovalent ions at room temperature).

The well-known exception, which admits a simple solution, is the case of a symmetric binary z_+z_- electrolyte in a one-dimensional (1D) geometry, where the PB equation in the form

$$\varepsilon \frac{\partial^2 \psi}{\partial x^2} = 2z_+ z_- e c_0 \sinh\left(\frac{z_+ e \psi}{kT}\right) \quad (4)$$

was solved analytically by Gouy [8] and Chapman [9] (GC) for a semi-infinite electrolyte of bulk concentration $c_0 = c_+^0 = c_-^0$ near a flat charged surface [2,3,5]. (It is less well-known that Gouy [8] also solved the case of an asymmetric $2z_+z_-$ electrolyte.) Although this solution may seem quite special, it describes the most common situation where diffuse charge is confined to a thin capacitorlike “double layer” near a solid surface. The width of the diffuse layer is the Debye [10] (or, more properly, Gouy [8]) screening length,

$$\lambda_D = \sqrt{\frac{\varepsilon kT}{2z_+^2 e^2 c_0}} \quad (5)$$

as can be seen by scaling Eq. (4) with $\tilde{x} = x/\lambda_D$ and $\tilde{\psi} = \psi/\psi_T$ to obtain the dimensionless form, $\tilde{\psi}'' = \sinh \tilde{\psi}$. The screening length ($\lambda_D \approx 1-100$ nm in aqueous electrolytes) is typically much smaller than any geometrical length, so bulk solution remains quasineutral with diffuse charge confined to thin, locally flat, quasiequilibrium double layers.

Due to its analytical simplicity and wide applicability, the Gouy-Chapman solution has become the standard model for highly charged double layers. It is the basis for the classical theory of tangential “surface conduction” through the diffuse layer [11–14], as well as the recently noted phenomenon of salt “adsorption” (or “uptake”) from the neutral bulk by the diffuse layer in response to a large applied voltage [15,16]. Such predictions of the GC model have major implications for electrokinetic phenomena of the first kind, such as electro-osmosis, electrophoresis, streaming potential, and diffusio-phoresis, at large surface potentials [5,6].

Dilute solution theory has also been used in nearly every model of diffuse charge during the passage of current. Near equilibrium, the flux density of ion i is proportional to the gradient of its chemical potential (1),

$$F_i = -b_i c_i \nabla \mu_i = -D_i \left(\nabla c_i + \frac{z_i e}{kT} c_i \nabla \psi \right), \quad (6)$$

where Einstein’s relation, $D_i = b_i/kT$, relates the ion’s mobility b_i to its diffusivity D_i . For a system in quasisteady state, $\nabla \cdot F_i = 0$, the nonzero current, $J = \sum_i z_i e F_i$, only slightly perturbs the Boltzmann distribution of the ions. As a result, the GC solution is also widely used to describe diffuse-layer effects on electrode reaction kinetics [3,17] (the Frumkin correction [18]), up to Nernst’s limiting current, where the bulk concentration of an electroactive species vanishes. At larger “superlimiting” currents, the PB equation loses validity, but dilute-solution theory is still used to describe diffuse charge, which loses its Boltzmann distribution [19] and extends into the bulk as “space charge” [20], while retaining an inner boundary layer at the screening length [21]. The dilute-solution space-charge model is the basis for theories of elec-

trokinetic phenomena of the second kind, such as superfast electrophoresis [22] and hydrodynamic instability at a limiting current [23].

Dilute solution theory has also been used to describe the dynamics of electrolytes, subject to time-dependent applied voltages. The classical description comes from the Poisson-Nernst-Planck equations (PNP), which consist of Eq. (2) and mass conservation laws for the ions,

$$\frac{\partial c_i}{\partial t} = -\nabla \cdot F_i = D_i \left[\nabla^2 c_i + \frac{z_i e}{kT} \nabla \cdot (c_i \nabla \psi) \right], \quad (7)$$

where $D_i = \text{constant}$ is normally assumed. Again, general solutions are only possible upon linearization, where the potential satisfies the Debye-Falkenhagen equation [10]. In the nonlinear regime, for thin double layers, the GC solution again holds since the diffuse-charge remains in quasiequilibrium, and the diffuse-layer acts like a voltage-dependent differential capacitance in series with a bulk resistor [24]. Such equivalent circuit models can be derived systematically from the PNP equations by asymptotic analysis, which also reveals corrections at large voltages, due to bulk diffusion in response to salt adsorption [15] and surface conduction [16] at large applied voltages. Such nonlinear diffuse-layer effects could be important in interpreting impedance spectra in electrochemical sensing [25,26], or in understanding high-rate thin-film rechargeable batteries [27–30].

Another current motivation to study nonlinear diffuse-charge dynamics comes from “induced-charge” electrokinetic phenomena [31]. The preceding models of double-layer relaxation have been used extensively in theories of ac pumping of liquids over electrode arrays [32–37], induced-charge electro-osmotic flows around metallic colloids [38,39] and microstructures [33,40,41], and dielectrophoresis [42–44] and induced-charge electrophoresis [31,44–46] of polarizable particles in electrolytes, although a nonlinear analysis based on the PNP equations has not yet been attempted for any of these situations. This may be a good thing, however, since we will show that dilute solution theory generally breaks down in the regime of experimental interest, where the applied voltage is much larger than the thermal voltage, $V > \psi_T$.

B. Validity of the nonlinear model for dilute solutions

Dilute solution theory provides a natural starting point to understand nonlinear effects in electrolytes, and the GC model is used in all of the examples above to model the diffuse layer at large applied potentials. In spite of its mathematical appeal, however, nonlinear dilute solution theory has limited applicability, due to the exponential sensitivity of the counterion concentration to voltage. For example, in the typical case of quasiequilibrium, the Boltzmann factor (3) brings nonlinearity to the PB equation (4) when $\psi > \psi_T$, but this dependence is so strong that the surface potential cannot get much larger without invalidating the assumption of a dilute solution.

To see this, note that there must be a maximum concentration, $c_{\max} = a^{-3}$, of counterions packed with typical spacing a near a highly charged surface. This effective ion size is

clearly no smaller than the ionic radius (typically $\approx 1 \text{ \AA}$), although it could be considerably larger (several nm), taking into account hydration effects and ion-ion correlations, especially in a large electric field. For the sake of argument, consider a very dilute bulk solution, $c_0=10^{-5} \text{ M}$, with $a=3 \text{ \AA}$ and $z=1$. The nonlinear regime begins at a diffuse-layer potential $\Psi_D \approx kT/ze=25 \text{ mV}$, but the steric limit is reached in dilute solution theory at $\Psi_c \approx 13kT/ze=330 \text{ mV}$, where

$$\Psi_c = -\frac{kT}{ze} \ln(a^3 c_0) = \frac{kT}{ze} \ln\left(\frac{c_{max}}{c_0}\right). \quad (8)$$

Since the solution ceases to be “dilute” well below the steric limit, there is only a narrow window of surface potentials ($\approx 25\text{--}200 \text{ mV}$), sometimes called “weakly nonlinear regime” [15], where nonlinearity arises and the fundamental assumption (1) remains valid.

Unfortunately, the most interesting predictions of the nonlinear PB theory tend to be in the “strongly nonlinear regime,” where the dilute approximation fails dramatically. For example, the Dukhin number, which controls the relative importance of tangential conductivity in a thin diffuse layer, σ_s , compared to bulk conductivity, σ , at a geometrical scale L , has the following form [11–13],

$$\text{Du} = \frac{\sigma_s}{\sigma L} = 4 \frac{\lambda_D}{L} \sinh^2\left(\frac{ze\Psi_D}{4kT}\right), \quad (9)$$

assuming the Gouy-Chapman model. This is also the dimensionless ratio, Γ_s/c_0L , of the excess surface concentration of ions, Γ_s , relative to the bulk concentration, so it also governs the (positive) adsorption of neutral salt from the bulk in response to an applied voltage [15,47]. The general derivation of Eq. (9) assumes a thin double layer [16], but in that case ($\lambda_D \ll L$) a large Dukhin number corresponds to situations where the steric constraint is significantly violated, $\Psi_D > \Psi_c$, rendering Eq. (9) inappropriate. Similar concerns apply to other nonlinear effects in Gouy-Chapman theory, such as the rapid increase of the differential capacitance (defined below) with surface potential,

$$C_D = \frac{\varepsilon}{\lambda_D} \cosh\left(\frac{ze\Psi_D}{2kT}\right), \quad (10)$$

which would have important implications for electrochemical relaxation around conductors [15,16,48] and for ac electro-osmosis [49,50].

C. Beyond the Poisson-Boltzmann picture

We are certainly not the first to recognize the limitations of dilute solution theory. Historically, concerns about the unbounded capacitance of a thin diffuse layer in the GC solution (10) first motivated Stern [51] to hypothesize that there must also be a compact layer of adsorbed ions on the surface, as originally envisioned by Helmholtz [52]. The Stern layer is where electrochemical reactions, such as ion dissociation (setting the equilibrium charge on a dielectric) and/or redox couples (setting the Faradaic current at an electrode), are believed to occur, within a molecular distance of the solid

surface [2,6]. The Stern layer capacitance (see below) helps to relieve the overcharging of the diffuse layer in Gouy-Chapman theory, but, due to steric constraints, it too cannot conceivably withstand a voltage much larger than Ψ_c . Instead, at larger voltages, the region of ion accumulation must inevitably extend away from the surface into the solution, where ions undergo hindered transport in a concentrated solution without having specific interactions with the solid.

The most basic aspect of a concentrated solution is the finite molecular length scale, a_0 . Over half a century ago, Wicke and Eigen [53–55] made perhaps the first attempts to extend dilute solution theory to account excluded volume effects in a simple statistical mechanical treatment. The theory was developed further in the past decade by Iglic and Kral-Iglic [56–59] and Borukhov, Andelman, and Orland [60–62]. These authors proposed free energy functionals, based on continuum (mean-field) approximations of the entropy of equal-sized ions and solvent molecules, which they minimized to derive modified Poisson-Boltzmann equations (MPB). The motivation for this work was mainly to address the effect of large ions, whose sizes may be comparable to the screening length, in an equilibrium diffuse layer with $\Psi_D \approx \psi_T$. Our main point here is that crowding effects can also be very important for small ions near a polarizable surface, when subjected to a “large” voltage exceeding the threshold Ψ_c . No matter how dilute is the bulk solution, a sufficiently large electric field can always draw enough ions to the surface to create a concentrated solution in the diffuse layer.

There have also been attempts to go beyond the mean-field approximation of steric effects, by treating specific (and in some cases also Coulombic) ion-ion and ion-wall interactions. Simple MPB equations have been proposed, which modify the charge density to account for the spatial correlation function between an ion in solution and a flat wall (via an effective external potential) based on molecular dynamics simulations [63–65], but such models are not easily extended to any other geometry, such as a rough wall [66]. Corrections of this type can also be obtained from a general probabilistic model of interacting ions, whose dynamics are given by nonlinearly coupled Langevin equations. Using this approach, Schuss, Nadler, and Eisenberg rigorously derived “conditional PNP” (and PB) equations where each ion concentration $c_i(\mathbf{r})$ in the mean-field Poisson’s equation (2) is replaced by the conditional probability density of finding an ion at a certain position, given the positions of the other ions [67–69], although a simple closure of the model requires further assumptions about statistical correlations.

There are a variety of general statistical mechanical approaches from liquid state theory [70], which have been applied to electrolytes, taking into account not only steric effects, but also many-body electrostatic correlations [71]. Since the 1970s, the modest, but challenging, goal has been to accurately predict the equilibrium distribution of ions in Monte Carlo simulations of the “primitive model” of charged hard spheres in a homogeneous dielectric continuum bounded by a hard, charged wall. Typically, the model is studied in the limit of “small” surface potentials ($\Psi_D \approx kT/e$) relevant for equilibrium surfaces. For example, a plethora of MPB equations (such as “MPB4,” “MPB5,” ...)

perturbing Gouy-Chapman theory have been derived by variations on the mean spherical approximation [72–78]. More complicated, but often more accurate, theories have also been derived using statistical density functional theory (DFT) [79–85]. By writing the ion flux as the gradient of an electrochemical potential obtained from the DFT free energy functional [7] (as we do in Part II [1], using the much simpler functional of Borukhov *et al.* [61]), it has been shown that the selectivity of ion channels can be understood to a large extent in terms of entropic effects of charged hard spheres [86].

In spite of many successes and the appealing first-principles nature of liquid-state theories, however, they are not ideally suited for our purpose here of capturing time-dependent, large-voltage effects in a simple model. Liquid-state theories are not analytically tractable and thus not easily coupled to macroscopic continuum models, although perhaps empirical fits could be developed for quantities of interest. For example, the DFT approach requires nontrivial numerical methods, just to evaluate the steady flux in a one-dimensional ion channel [7,86]. Another concern is that liquid-state theories have been designed and tested only for “small” voltages ($\Psi_D \approx kT/e$) at equilibrium surfaces, so it is not clear how well they would perform at large, time-dependent voltages, since there are no rigorous error bounds. For example, the double-layer differential capacitance in modified PB theories often increases with voltage [75], sometimes even faster than in PB theory [78], but we will argue below that it must decrease at large voltages, especially in concentrated solutions. In light of the scaling $e\Psi_D/kT$ from PB theory (3), a related problem is that, until recently [72,81], most theories have been unable to predict the decay of capacitance at low temperature in concentrated solutions. Although liquid-state theories for large voltages should certainly be developed, we will focus on much simpler mean-field, continuum descriptions of steric effects, in the hope of at least capturing some qualitative features of nonlinear dynamics analytically, across a large range of applied voltages.

Consistent with this approach, we will also work with the mean-field continuum description of electrostatic interactions (2), which neglects discrete many-body correlations. In passing, we point the reader to some of the extensive literature on corrections to PB electrostatics, e.g., reviewed by Attard [71]. The majority of work going beyond the mean-field approximation has focused on the simplest possible model of an equilibrium liquid of pointlike charges in a uniform dielectric medium. In the absence of specific interactions (such as steric repulsion), the fundamental length scale for ion-ion correlations is the Bjerrum length ($\approx 7 \text{ \AA}$ in water at room temperature),

$$l_B = \frac{e^2}{4\pi\epsilon kT}$$

at which the bare Coulomb energy balances the thermal energy. Interesting consequences of many-body electrostatics, not present in the mean-field PB description, include Oosawa-Manning condensation of counterions around

charged rods in polyelectrolytes [87–89], renormalized charge of colloidal spheres [90–92], enhanced counterion localization around discrete surface charges [93], negative capacitance of electric double layers due to “overcharging” with multivalent ions [94–97], and counterion-mediated attraction of like-charged objects [98–100]. The latter phenomenon is believed to be responsible for the condensation of DNA in multivalent electrolytes [101], as well as the adhesion of cement paste [98,102]. A key part of the physics is the attraction between an ion and its “correlation hole” resulting from a fluctuation, which has recently been incorporated into a modified PB equation for a flat wall [103]. In all of these problems, however, the equilibrium surface charge is typically small (up to a monolayer of ions); it would be interesting to study electrostatic correlations at a much more highly charged surface, such as an electrode applying a large voltage, $V \gg \psi_T$ (our focus here).

Finally, we mention solvent effects, which are much less studied, and surely also very important at large voltages. Electrochemists widely believe that water dipoles in the Stern layer are so highly aligned by large electric fields that the effective permittivity drops by an order of magnitude (e.g., from $80\epsilon_0$ to $5\epsilon_0$) [104]. At large applied voltages, where typical fields are of order V/nm, it is reasonable to expect that the reduced permittivity would extend into the diffuse layer. This could have a major effect on ion-ion correlations, since the Bjerrum length $l_B \propto \epsilon^{-1}$ could get as large as 10 nm. The dipolar nature of water molecules has also been incorporated into some DFT theories to replace the continuous dielectric medium in the primitive model [82–85]. Other aspects of water structure, such as hydrogen bonded networks, could also be altered by large electric fields and large ion concentrations. Such effects are taken into account in molecular dynamics simulations with empirical potentials (at low voltage) [63–66], but it could be crucial to perform *ab initio* quantum-mechanical simulations to validate and guide theories of highly charged double layers.

D. Scope of the present work

In spite of the considerable literature on MPB descriptions of electrolytes in *equilibrium* or in *steady state* conduction, we are not aware of any attempt to go beyond dilute solution theory (PNP equations) in analyzing the *dynamics* of electrolytes in response to time-dependent perturbations, such as ac voltages. Accordingly, here we develop only some very simple models with the goal of identifying generic new features of diffuse-charge dynamics in a concentrated solution. As such, it is preferable to start with equations that capture the essential physics, while remaining analytically tractable, at least in some representative cases. For this reason, we focus on mean-field theories of steric effects and specifically build on the MPB equation of Iglic and Kralj-Iglic [58,59] and Borukhov *et al.* [60–62], which can be integrated analytically in a few simple geometries. Such models also make reasonable predictions across the entire range of voltages.

The contribution is broken into two parts. Here, in Part I, we consider the canonical problem of charging a thin double layer, viewed as an effective circuit element [15]. We begin

in Sec. II by describing two simple models for steric effects in a quasiequilibrium diffuse layer: (i) A “composite layer” model, consisting of a dilute PB outer region and, at high voltage, an inner “condensed layer” of ions packed at the steric limit, and (ii) the MPB model which describes the same transition in a continuous fashion. In Sec. III, we then analyze the diffuse-layer capacitance and its role in equivalent circuit approximations. In Sec. IV, we calculate steric effects on salt adsorption and tangential surface conduction by the diffuse layer and discuss how these high-voltage effects affect and modify the applicability of circuit models. In Sec. V, we also briefly discuss the effects of a compact dielectric layer (which could model a Stern layer of adsorbed ions, or, more accurately, a thin film coating the solid), before concluding in Sec. VI.

In Part II [1], we consider explicitly time-dependent problems with a general formalism, not only applicable to thin double layers. We start with the free energy functional of Borukhov *et al.* and derive modified Poisson-Nernst-Planck (MPNP) equations, based on a simple generalization of chemical potential (1) for concentrated solutions. As an illustration, we then repeat the nonlinear asymptotic analysis of Ref. [15] for the response of a blocking electrochemical cell (no reactions at the electrodes) to a suddenly applied voltage, to expose some general consequences of steric effects at large voltage. We also clarify the range of validity of the thin-double-layer circuit approximations derived here in Part I.

II. TWO MODELS OF STERIC EFFECTS IN A THIN DIFFUSE LAYER

We focus on the response of a thin diffuse layer to an applied voltage, where it suffices to consider only quasiequilibrium properties [15], as we justify carefully in Part II [1]. Following Gouy and Chapman, we consider the case of a symmetric $z:z$ electrolyte here, although our reasoning is readily extendible to the general case. We also assume that the permittivity ϵ is constant in space, which is certainly not correct when dense layers of ions form close to the surface. However, this can be taken into account in a following step and does not change the qualitative picture emerging from the following analysis. We will return to this point below in Sec. V.

There are at least three important lengths in our models. The first is the Debye length λ_D given by Eq. (5), which sets the width of the diffuse layer at low voltage and low bulk concentration, c_0 . The second is the mean spacing of ions in the bulk electrolyte, $l_0 = (2c_0)^{-1/3}$, and the third is the mean spacing of ions (essentially of the same sign) at the maximum concentration, $a = c_{max}^{-1/3}$. A fourth scale L would characterize the geometry, as in Part II [1], but here we consider the regime of thin double layers, where $\lambda_D \ll L$. A fifth scale would be the Bjerrum length l_b , which we neglect by making the usual mean-field approximation.

From the first three lengths, there are two dimensionless groups. The first is a/λ_D , which we assume to be small for simple electrolytes in somewhat dilute solutions, so that steric effects are important only very close to the surface, at

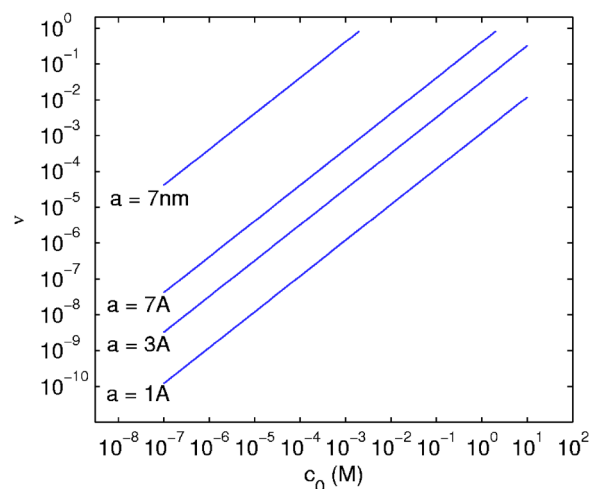


FIG. 1. (Color online) The dependence of the dimensionless parameter ν as a function of the bulk concentration c_0 and effective ion size a .

the inner portion of the diffuse layer (and even then, only at large voltages). The second dimensionless group can be written as the mean volume fraction of ions in the bulk,

$$\nu = 2a^3 c_0 = (a/l_0)^3, \quad (11)$$

a natural measure of nondiluteness, which controls the importance of steric effects, along with the dimensionless voltage, $ze\Psi_D/kT$. In the figures below, we display results for $\nu = 0.00005, 0.005$, and 0.5 to span the range from dilute to highly concentrated solutions.

We stress that the phenomenological parameter a is not necessarily the diameter of an ion, $a_0 \approx 1 \text{ \AA}$. We prefer to think of it as a cutoff for the unphysical divergences of PB theory, which we know must exist, and our goal is to understand its consequences. This cutoff length could include at least a solvation shell, e.g., $a \approx 3 \text{ \AA}$, but ion-ion correlations could effectively increase it further, since the Bjerrum length is at least 7 \AA . As noted above, taking into account the decrease of permittivity (by as much as a factor of 10) or other solvent effects at large fields could make l_b , and thus perhaps also a , as large as 10 nm. As a guide to using our results, we refer to Fig. 1 for the value of the dimensionless parameter ν for different values of a and c_0 .

A. A composite diffuse-layer model

In this model, we assume that the concentration fields are governed by Boltzmann distributions

$$c_{\pm} = c_0 e^{\mp ze\psi/kT} \quad (12)$$

wherever they are meaningful, that is, whenever these concentrations are weaker than a physical limit $1/a^3$, which is set by the ion size. For both ion species, if the formula (12) yields a quantity bigger than $1/a^3$, we set the concentration field of the counterion to be $1/a^3$, and assume that the coions are excluded from the corresponding condensed layer. The basic physics is shown in Fig. 2.

For most geometries, such as rough surface, this model is ill-posed and would require additional constraints to deter-

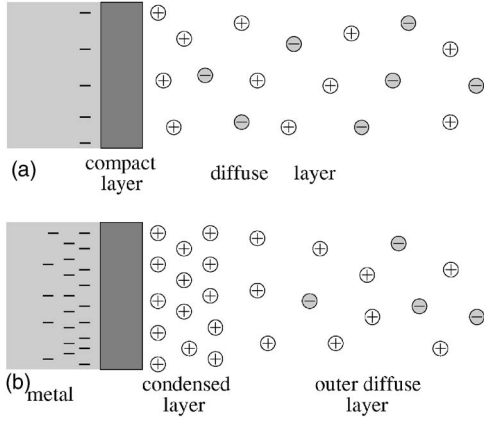


FIG. 2. (a) Most prior work in electrokinetics has dealt with surfaces of preexisting equilibrium charge at the scale of one electron per surface atom or less. This charge can be screened by roughly a monolayer of ions (partly in the diffuse layer) which corresponds to a “small” double layer voltage, of order $\psi_T = kT/ze$. (b) In contrast, nonlinear electrokinetics deals with polarizable (mainly metal) surfaces, where much higher surface charge densities can be produced by an applied voltage or electric field nearby, and thus the double layer can “overcharge” to the point where dilute-solution theory no longer applies. The existence of a minimum ion spacing implies the formation of a condensed layer of counterions near the surface.

mine the location of the sharp free boundary separating the “dilute” Boltzmann region and the “condensed” region at the maximum density. For a flat, semi-infinite diffuse layer with a given total charge q_D or total voltage Ψ_D , however, the transition occurs at a single well-defined position, $x=l_c$, away from the solid surface (at $x=0$). In that case, we separate the diffuse layer into two parts if the potential is strong enough

$$\begin{aligned} c_{\pm} &= c_0 e^{\mp ze\psi/kT} & \text{if } a^3 c_{\pm} < 1, & \quad x > l_c, \\ c_{\pm} &= a^{-3}, c_{\mp} = 0 & \text{if } a^3 c_0 e^{\mp ze\psi/kT} \geq 1, & \quad 0 < x < l_c. \end{aligned} \quad (13)$$

Note that in this simplistic dichotomy the concentration field for coions is slightly discontinuous at the critical potential mentioned earlier,

$$\Psi_c = \frac{kT}{ze} \ln \frac{2}{\nu}, \quad (14)$$

where again $\nu = 2a^3 c_0$ is volume fraction occupied by (all) ions at zero potential in the bulk. Although very simple, this model already captures steric effects at large voltages to a great extent.

Let us compute the thickness l_c of the corresponding layer of “condensed” counterions. We consider an electrode to which a strong negative potential Ψ_D is applied to the diffuse layer with respect to the bulk, such that $|\Psi_D| = -\Psi_D > \Psi_c$ which leads to a condensed layer of positive ions in its vicinity.

Poisson’s equation for the thin diffuse layer reads

$$\varepsilon \frac{d^2 \psi}{dx^2} = -\rho,$$

$$\psi(x=0) = \Psi_D, \quad \frac{d\psi}{dx}(x=0) = \frac{q_{cl}}{\varepsilon}, \quad (15)$$

since (for now) the permittivity ε is assumed constant. Within the condensed layer, we have $\rho = zec_+ = ze/a^3$, so by integrating, we obtain

$$\frac{d\psi}{dx} = -\frac{ze}{\varepsilon a^3} x + \frac{q_{cl}}{\varepsilon}, \quad \psi = -\frac{1}{2} \frac{ze}{\varepsilon a^3} x^2 + \frac{q_{cl}}{\varepsilon} x + \Psi_D, \quad (16)$$

where $-q_{cl}$ is the surface charge density on the electrode, so that q_{cl} is the total charge per unit area in the diffuse layer.

Within the outer diffuse layer, the standard PB equation holds,

$$\varepsilon \frac{d^2 \psi}{dx^2} = 2zec_0 \sinh\left(\frac{ze\psi}{kT}\right),$$

$$\psi(x \rightarrow \infty) = 0, \quad \frac{d\psi}{dx}(x \rightarrow \infty) = 0, \quad (17)$$

which gives

$$\frac{d\psi}{dx} = -2 \sqrt{\frac{2kTc_0}{\varepsilon}} \sinh\left(\frac{ze\psi}{2kT}\right). \quad (18)$$

At the interface between the condensed layer and the diffuse layer, we require the continuity of the electric field,

$$q_{cl} = 2zec_0 \lambda_D \left(\sqrt{\frac{2}{\nu}} - \sqrt{\frac{\nu}{2}} \right) + \frac{ze}{a^3} l_c, \quad (19)$$

and of the electrostatic potential, so that

$$-\Psi_c = -\frac{kT}{ze} \ln(2/\nu) = -|\Psi_D| - \frac{1}{2} \frac{ze}{\varepsilon a^3} l_c^2 + \frac{q_{cl}}{\varepsilon} l_c. \quad (20)$$

Combining these equations and solving for l_c yields

$$l_c = \lambda_D \sqrt{2\nu} \left\{ -1 + \frac{\nu}{2} + \sqrt{\left(1 - \frac{\nu}{2}\right)^2 + \left[\frac{ze|\Psi_D|}{kT} - \ln(2/\nu) \right]} \right\}, \quad (21)$$

which is plotted in Fig. 3 for several values of ν . Generally, the condensed layer forms when the diffuse layer voltage Ψ_D becomes only a few times the thermal voltage kT/ze , and then it grows sublinearly, proportionally to the square root of the potential drop as anticipated from Poisson’s equation with a constant charge density.

From this equation and Eq. (19), we finally obtain the charge/potential relation for the composite diffuse layer:

$$q_{cl} = 2zec_0 \lambda_D \sqrt{\frac{2}{\nu}} \sqrt{\left(1 - \frac{\nu}{2}\right)^2 + \left[\frac{ze|\Psi_D|}{kT} - \ln(2/\nu) \right]}, \quad (22)$$

which holds for $|\Psi_D| > \Psi_c$, as assumed here. For weaker potentials, there is no condensed layer and the standard PB model holds:

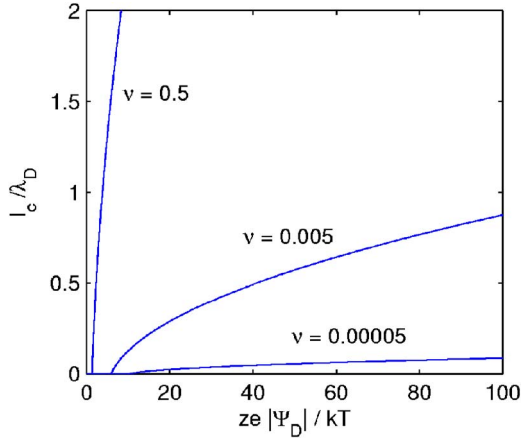


FIG. 3. (Color online) The thickness of the condensed layer thickness l_c as a function of the total voltage drop Ψ_D across the diffuse and the condensed layers.

$$q_{pb} = -4ze c_0 \lambda_D \sinh\left(\frac{ze\Psi_D}{2kT}\right). \quad (23)$$

We note that, when compared to the PB charge density q_{pb} , the composite-layer charge density q_{cl} is significantly reduced by the steric effects at higher Ψ_D . In particular, it increases only sublinearly, as opposed to exponentially in the PB model.

B. The modified PB model

The second model we consider is the classical mean-field description of steric effects in equilibrium mentioned in the Introduction. For a symmetric $z:z$ electrolyte, the free energy is assumed to take the form

$$\begin{aligned} F &= U - TS, \\ U &= \int d\mathbf{r} \left(-\frac{\epsilon}{2} |\nabla\psi|^2 + zec_+\psi - zec_-\psi \right) \\ -TS &= \frac{kT}{a^3} \int d\mathbf{r} \{ c_+ a^3 \ln(c_+ a^3) + c_- a^3 \ln(c_- a^3) \\ &\quad + (1 - c_+ a^3 - c_- a^3) \ln(1 - c_+ a^3 - c_- a^3) \}. \quad (24) \end{aligned}$$

This formula can be derived either by a lattice-gas formalism [62], or by a continuum approach along with the assumption that the total number of ions, counterions, and solvent molecules is constant in (infinitely small) volume elements of the same size [59]. In either case, the microscopic details of the solvent and the ions are ignored, and the electrostatic potential and charge density are assumed to be meaningful smooth functions of space, and the correlation effects are not considered. We refer the reader to the literature [53–62] for more details on the derivation and statistical mechanical assumptions of the free energy (24).

The concentrations in the diffuse layer as a function of the electrostatic potential with respect to the bulk ψ are given by the modified Boltzmann distribution

$$c_{\pm} = \frac{c_0 e^{\mp ze\psi/kT}}{1 + 2\nu \sinh^2\left(\frac{ze\psi}{2kT}\right)}, \quad (25)$$

where the packing parameter $\nu = 2a^3 c_0$ is again the bulk ion density scaled to its maximum value and a is the effective size of the ions and the solvent molecules. Note that the concentration of each ion saturates and cannot exceed the steric limit. The distributions (25) can be derived by minimizing the free energy (24).

In a mean-field approximation with these ion concentrations, the potential satisfies the modified Poisson-Boltzmann (MPB) equation,

$$\begin{aligned} \nabla^2 \psi &= \frac{zec_0}{\epsilon} \frac{2 \sinh\left(\frac{ze\psi}{kT}\right)}{1 + 2\nu \sinh^2\left(\frac{ze\psi}{2kT}\right)}, \\ \psi(x=0) &= \Psi_D, \quad \psi(x \rightarrow \infty) = 0, \quad \frac{d\psi}{dx}(x \rightarrow \infty) = 0. \quad (26) \end{aligned}$$

Unlike the composite layer model, the MPB model can be applied to any geometry (just like the PB model). In the case of a flat diffuse layer, it gives a similar description, except that steric effects enter smoothly with increasing voltage, and there is no sharply defined condensed layer.

As for the first model, we can integrate the MPB equation across a thin double layer to obtain the normal electric field at the inner part of the diffuse layer,

$$\frac{d\psi}{dx} = -\text{sgn}(\psi) \frac{2zec_0 \lambda_D}{\epsilon} \sqrt{\frac{2}{\nu} \ln \left[1 + 2\nu \sinh^2\left(\frac{ze\psi}{2kT}\right) \right]}. \quad (27)$$

Integrating Eq. (15) using Eq. (27), we obtain for this model the relation between the charge per unit area in the diffuse layer q_{mpb} and the potential drop across it, Ψ_D :

$$q_{mpb} = -\text{sgn}(\Psi_D) 2zec_0 \lambda_D \sqrt{\frac{2}{\nu} \ln \left[1 + 2\nu \sinh^2\left(\frac{ze\Psi_D}{2kT}\right) \right]}. \quad (28)$$

This formula is illustrated in Fig. 4, and compared to the analogous formula for the composite diffuse-layer model (22). Although the MPB concentrations (13) have been analyzed carefully by previous authors [56–62], it seems the charge-voltage relation (28) has been overlooked, or at least is not stated explicitly in these papers. (Similarly, Chapman was the first to explicitly write down the formula (23) for the total charge [9], even though Gouy had thoroughly analyzed the concentration and potential profiles in the ‘‘Gouy-Chapman model’’ a few years earlier [8].)

We note in passing that the asymptotic behavior at large voltages is similar for the two models presented and corresponds to a layer of essentially constant charge density, which results using Poisson’s equation in a total charge proportional to the square root of the potential drop.

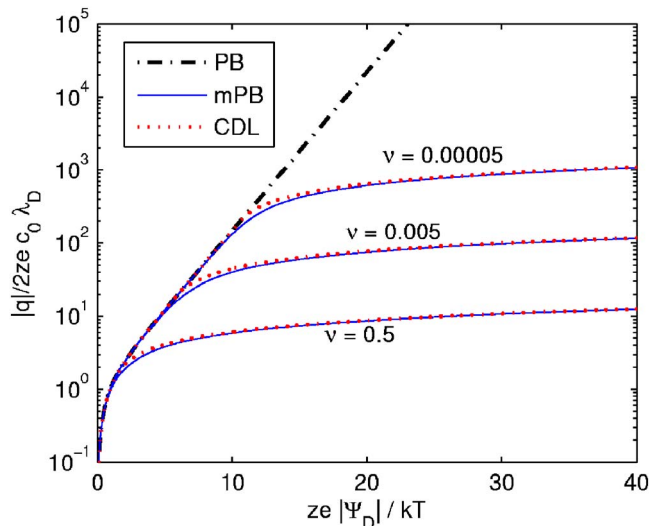


FIG. 4. (Color online) The diffuse layer charge given by PB, MPB, and CDL models as a function of the across potential drop.

III. EQUIVALENT CIRCUIT ELEMENTS

A. A word on circuit models

As widely recognized in electrochemistry [25,26,105], it is often appropriate to describe the effect of the double layers on the dynamic properties of a system through effective resistances and capacitances. The underlying assumption is that the equilibration time of the double layer is fast compared to the dynamics of the global “circuit” considered, essentially because it is so thin that transport processes within the double layer are rapid. A mathematical justification, starting from the simple PNP equations, can be given in terms of an asymptotic analysis of the thin double layer limit [15].

Therefore we anticipate that for the many situations where the double layer is thin compared to the system size, the dynamics can be understood to a significant extent using the *equilibrium characteristics* of the double layer. These then provide appropriate boundary conditions for the dynamic transport processes in the bulk.

In particular, the analysis presented in Ref. [15] shows that the capacitance, or more precisely the differential capacitance “ C ,” of the double layer is a central quantity allowing the modeling of the system in terms of an “RC” circuit. The second quantity of relevance, as it characterizes the entrance into the strongly nonlinear regime, is the neutral salt uptake by the double layer which can result in an appreciable depletion of the bulk, leading to modifications of its conductivity (affecting the resistance “ R ” in the circuit) and thus of the dynamics. This paper and a subsequent one [16] also pointed out (in the context of dilute solution theory) that the tangential conduction through the diffuse layer is intimately tied to neutral salt adsorption, and indeed is governed by the same dimensionless “Dukhin number.”

Therefore we will proceed to compute all of these dynamical quantities for a thin quasi-equilibrium double layer, focusing on the general consequences of steric effects, which are common to the two models. After that, we will return to

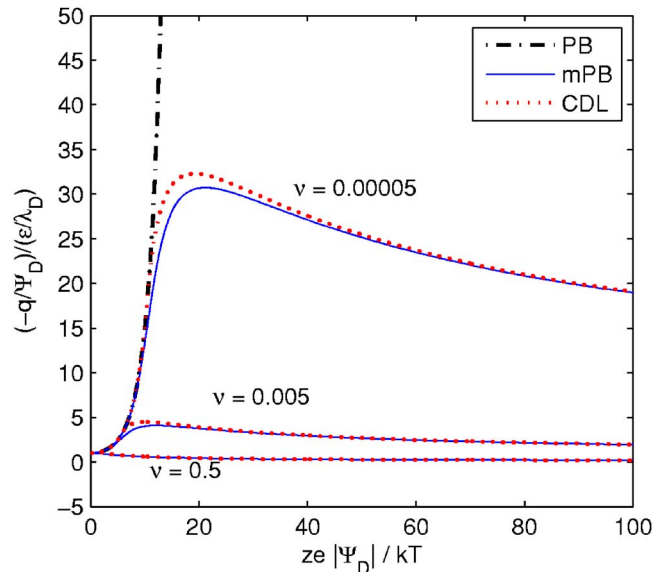


FIG. 5. (Color online) The total capacitance $-q(\Psi_D)/\Psi_D$ of the diffuse layer as a function of Ψ_D .

the question of surface capacitance and consider the effect of a thin dielectric layer (such as an oxide coating on a metal electrode, or perhaps a frozen Stern layer of adsorbed ions) on the overall dynamical response of the double layer.

B. Total and differential capacitances

The total capacitance of the diffuse layer can be obtained directly from the previous equations relating q (the charge per unit area in the diffuse layer) to Ψ_D (the voltage drop across the double layer), as simply $-q(\Psi_D)/\Psi_D$. We have already computed these quantities above, and they are compared to the PB result ($\nu=0$) in Fig. 5. It is immediately obvious that the capacitance is greatly reduced at high voltage, compared to the predictions of dilute solution theory. The effect is so dramatic that the capacitance in both models reaches a maximum not much larger than the zero-voltage value, and even *decreases* for all values of voltage at sufficiently high concentration—the opposite trend from PB theory.

As noted above, the differential capacitance, defined for the diffuse layer as

$$C_D(\Psi_D) = -\frac{dq}{d\Psi_D} \quad (29)$$

is the relevant quantity for the dynamical response to an applied voltage. Throughout this paper, to be clear, we will use the notation C only for the differential capacitance. In the PB model ($\nu=0$), the differential capacitance from Eq. (23) has already been noted above:

$$C_D^\nu = \frac{\varepsilon}{\lambda_D} \cosh\left(\frac{ze\Psi_D}{2kT}\right). \quad (30)$$

For the composite diffuse layer (CDL) model introduced above, Eq. (19) yields

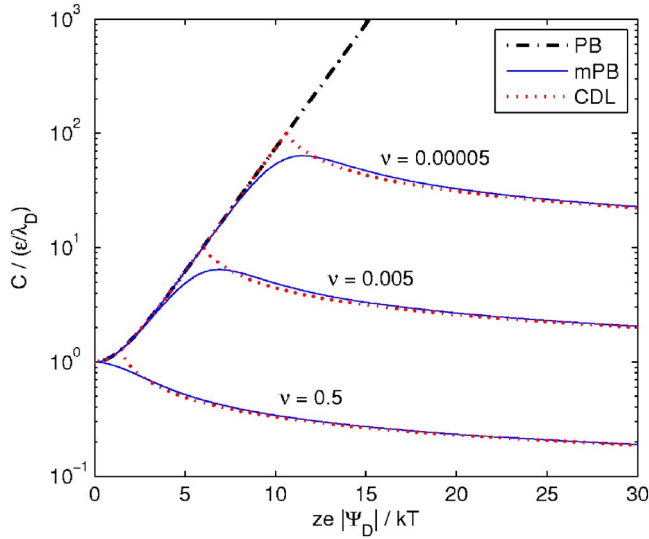


FIG. 6. (Color online) The diffuse layer differential capacitance as a function of the potential drop across itself.

$$C_D^\nu = \frac{\varepsilon}{\lambda_D} \frac{1}{\sqrt{2\nu} \sqrt{\left(1 - \frac{\nu}{2}\right)^2 + \left[\frac{ze|\Psi_D|}{kT} - \ln(2/\nu)\right]}} \quad (31)$$

when $\Psi_D > \Psi_c$. Otherwise, the PB formula Eq. (30) still holds. For the MPB diffuse layer model, using Eq. (28), we find

$$C_D^\nu = \frac{\varepsilon}{\lambda_D} \frac{\left| \sinh\left(\frac{ze\Psi_D}{kT}\right) \right|}{\left[1 + 2\nu \sinh^2\left(\frac{ze\Psi_D}{2kT}\right) \right] \sqrt{\frac{2}{\nu} \ln\left[1 + 2\nu \sinh^2\left(\frac{ze\Psi_D}{2kT}\right) \right]}}. \quad (32)$$

The different models are compared in Figs. 6 and 7.

The qualitative trends in C are again similar in both models of steric effects and dramatically different from PB theory. For both models, the differential capacitance increases at very low potentials (comparable to the thermal voltage, kT/ze) as it does in the PB model because steric effects are still negligible. These enter the picture at larger potentials and limit the storing capacity of the layer, with a differential capacitance that actually decreases to zero at large potentials. As a consequence both models predict a nonmonotonic differential capacitance, and show a maximum at intermediate values.

Of course, there are some clear differences in the detailed predictions of the two models, shown in Figs. 6 and 7. Although the limiting behaviors at large and small voltage are similar, the transition is unphysically sudden in the CDL model, compared to the more reasonable, smooth transition in the MPB model. This is especially true at low concentrations, where the sudden, delayed appearance of steric effects in the CDL model gives rise to a sharp cusp in the differential capacitance versus voltage. At high concentrations,

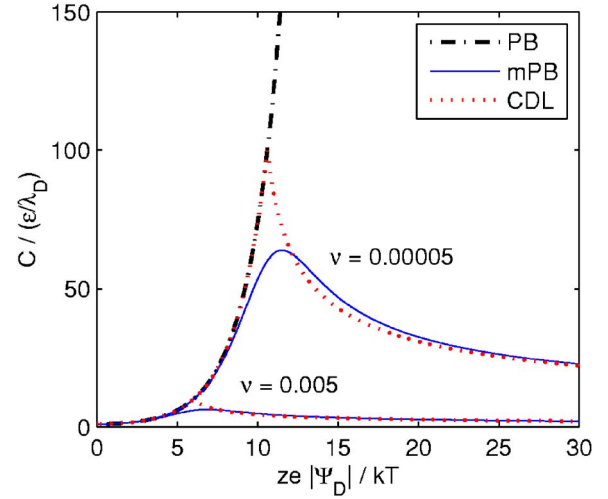


FIG. 7. (Color online) Same as Fig. 6, except with a linear scale on the y -axis. The case $\nu=0.5$ is not shown.

where the “low voltage” regime of dilute solution theory effectively vanishes, the CDL model also fails to predict the immediate onset of steric effects, even at small voltages, which causes a monotonic decrease in differential capacitance—the opposite trend of the PB model. Nevertheless, the CDL model manages to approximate the trends of the MPB model well, with an appealingly simple physical picture.

In summary, three basic features show up in both models, which we take as an indication that they qualitatively hold irrespective of the specific approximations embedded in each model: (i) the differential capacitance $C_D(\Psi_D)$ is weaker at moderate and high potentials than if steric effects are neglected (as in the PB scheme); (ii) at moderate concentrations, the differential capacitance varies nonmonotonously with a peak at intermediate voltages and a slow decrease towards zero at higher voltages, (iii) at the steric limit ($\nu = 1$), the differential capacitance is a strictly decreasing function of voltage (in the MPB model). These effects are all explained by the strong tendency of ions to form a condensed inner layer at high voltage and/or high concentration, when steric effects are taken into account. This greatly reduces the differential (and total) capacitance compared to classical PB theory, which neglects the finite size of ions and thus predicts an absurd exponential pileup of ions extremely close to the surface (less than one molecular radius) in the nonlinear regime.

We expect these qualitative predictions to be quite robust, even in more sophisticated statistical mechanical theories. For example, many-body electrostatic correlations also tend to reduce the differential capacitance compared to PB theory. For multivalent counterions, this effect can be so strong as to give the double layer a negative capacitance, which corresponds to overscreening of the surface charge [94–97]. While such behavior arises in some systems at large voltages, the capacitance in our models remains strictly positive, since we adopt the classical mean-field approximation embodied by Poisson’s equation.

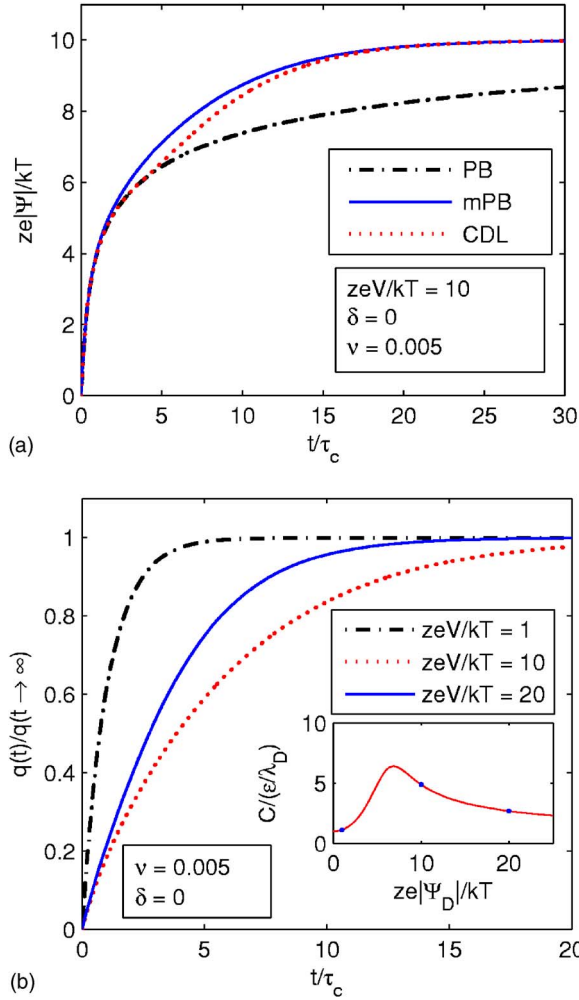


FIG. 8. (Color online) Diffuse-layer relaxation in response to a sudden voltage step across a blocking cell of width $2L$ and constant resistance R . Time is scaled with the charging time $\tau_c = \lambda_D L / D = RC(\Psi_D=0)$ ($\delta=0$). (a) Relaxation of the diffuse-layer voltage Ψ_D in the PB, MPB, and CDL models for the same applied voltage, $V=10kT/ze$. (b) Relaxation of the total diffuse-layer charge for different voltages, $zeV/kT=1, 10, 20$, in the MPB model with $\nu=0.005$, showing varying response times due to the nonmonotonic voltage dependence of the differential capacitance (inset).

C. Diffuse-layer charging dynamics

These revelations have important consequences for our understanding of double-layer charging in many situations. In the simplest picture of an equivalent RC circuit, with R the resistance of the bulk, these statements relate to the response time of the system to a step or an ac applied voltage. The typical response time for a driving of amplitude V is $\tau_c(V) = RC_D(V)$, so the classical picture from PB theory (30) has been that nonlinearity greatly slows down the charging dynamics [15,16,24,41,48,50]. Although this may occur in a dilute solution for a relatively small range of voltages (typically only several times the thermal voltage), steric effects in a concentrated solution bound the relaxation time at a value much less than expected from the PB model, in both the CDL and MPB models. This is clear in Fig. 8, where we

solve the RC circuit dynamics

$$C_D(\Psi_D) \frac{d\Psi_D}{dt} = \frac{V - \Psi_D}{R} \quad (33)$$

for the three models numerically, to obtain the diffuse-layer voltage $\Psi_D(t)$ in response to a suddenly applied voltage V across the layer in series with a bulk resistance R . In addition, importantly, the response time of an electrolytic cell is found to decrease with the amplitude of the applied voltage above the threshold for strong steric effects, $V > \Psi_c$. As shown in Fig. 8(b), the relaxation is faster for $V=20kT/ze$ than for $10kT/ze$, since $\Psi_c = 8.3kT/ze$ for $\nu=0.005$.

IV. BEYOND CIRCUIT MODELS

A. Diffuse layer salt adsorption

As recently pointed out in Ref. [15], circuit models can break down at large voltages if a large number of ions (mostly counterions) are engulfed by the diffuse layers with a resulting depletion of ions in the bulk. The total salt concentration in the diffuse layer (counterions plus coions) increases with voltage, regardless of the sign of the charge. Therefore a diffusion layer forms and relaxes into the neutral bulk whenever a voltage is applied across a double layer at a blocking surface (although reactions and/or rejection of adsorbed ions from the Stern layer could lead to negative adsorption or salt expulsion in other situations [47]). In the absence of salt injection by the surface, the *positive* adsorption of neutral salt by the diffuse layer is present in the PB description, where the counterion concentrations increase exponentially with voltage [15]. It is still present but obviously weaker in models accounting for steric effects, which severely limit the capacity of the diffuse layer to store additional ions at high voltage. We now quantify this statement using the two simple models introduced above.

Following notations introduced in Ref. [15], we define the excess neutral salt in the double layer as

$$w = w^\nu = \int_{\text{surface}}^{\text{bulk}} (c_+ + c_- - 2c_0) dx.$$

For the PB model one finds [15]

$$w^{\nu=0} = 8c_0\lambda_D \sinh^2\left(\frac{ze\Psi_D}{4kT}\right). \quad (34)$$

For the CDL model, the same equation holds for $\Psi_D < \Psi_c$, while above this value $\Psi_D > \Psi_c$ we obtain

$$w^\nu = \left(\frac{2}{\nu} - 2\right)c_0l_c + 2c_0\lambda_D \left(\sqrt{\frac{2}{\nu}} + \sqrt{\frac{\nu}{2}} - 2\right) \quad (35)$$

with $l_c(\Psi_D)$ to be extracted from Eq. (21). For the MPB model

$$w^\nu = \int_0^{ze\Psi_D/kT} \frac{(\cosh u - 1)}{1 + 2\nu \sinh^2 u} \frac{2c_0\lambda_D(1 - \nu)du}{\sqrt{\frac{2}{\nu}} \ln(1 + 2\nu \sinh^2 u)}, \quad (36)$$

which we can compute numerically.

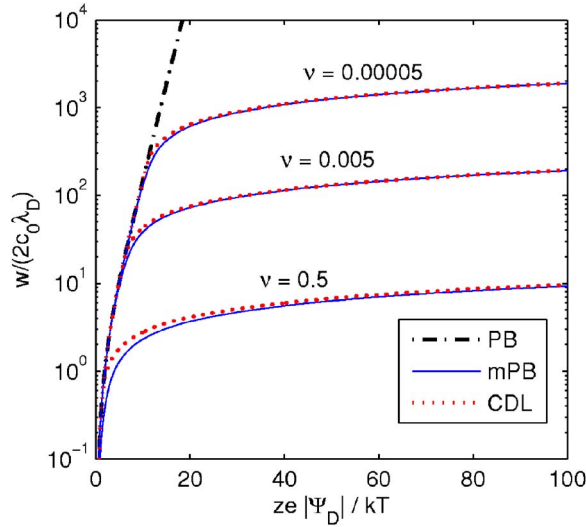


FIG. 9. (Color online) The diffuse layer neutral salt uptake w as a function of the potential difference Ψ_D .

Unlike the PB formula (34), which predicts exponentially diverging salt uptake for increasing Ψ_D , the steric modified formulas (35) and (36) predict sublinear (square-root-like) dependence on Ψ_D , at large voltages, as can be seen by inspection of Eqs. (34)–(36) or from the plots in Fig. 9. This can be understood qualitatively as a consequence of the roughly square-root voltage dependence of the condensed layer width (due to its constant charge density), since most of the adsorbed ions are condensed counterions at large voltages. [See Fig. 3 and Eq. (21) for the CDL model.] Another way to see it in both models is that the total salt adsorption is asymptotic to the total charge, $w \sim q/ze$, which is true for any nonlinear double layer model (PB, MPB, CDL,...) since the coion density goes to zero across most of the diffuse layer at large voltages. As explained in Ref. [15], in response to an applied voltage the neutral bulk electrolyte becomes depleted, as the electric field draws counterions into the diffuse layer and conducts coions away through the bulk, resulting in a slowly expanding diffusion layer, reducing the bulk concentration accordingly.

The main feature, again common to both models, is that the salt uptake at large voltage is greatly reduced in comparison to the exponential growth predicted by the PB picture. This is important for the dynamics as this quantity sets the limit of applicability of the widely used RC circuit model [15]. This equivalent circuit approximation should thus hold up to much larger values of potential when steric effects are included.

B. Breakdown of circuit models

With analytical expressions for total salt adsorption by the diffuse layer, we can estimate the upper limits on the applied voltage where the circuit approximation breaks down in the various models. For an electrolyte cell of thickness $2L$, the salt uptake by the diffuse layer corresponds to a removal of $2w$ charge carriers (ions) per unit surface, from a bulk that contained $2c_0L$ such carriers initially. As long as the ratio of

these two quantities $w/(c_0L)$ is small, the total resistance of the RC circuit is roughly unaffected by the salt adsorption. So, an estimate for the limit is [15]

$$\alpha_s = \frac{w}{c_0L} \ll 1, \quad (37)$$

which translates an upper bound on the applied voltage, $|V| < V_{threshold}$ for the RC description to remain valid (in the thin double layer limit $\lambda_D/L \ll 1$). For the PB model, the upper bound

$$V_{threshold} \approx \frac{2k_B T}{ze} \ln\left(\frac{L}{4\lambda_D}\right) \quad (\text{dilute})$$

is not much larger than the thermal voltage, due to the weak logarithmic dependence on L/λ_D .

For the models accounting for steric effects, however, the upper bound is greatly increased in concentrated solutions,

$$V_{threshold} \approx \frac{k_B T}{ze} \left(\frac{L}{\lambda_D}\right)^2 a^3 c_0 \quad (\text{nondilute}).$$

This shows that the widely used circuit approximation for a thin double layer $\lambda_D \ll L$ does not break down until enormous voltages, $V \propto (L/\lambda_D)^2$, in a concentrated solution. In a very dilute solution, where $\nu = 2a^3 c_0 \ll 1$, the circuit approximation may break down at moderate voltages, but only in a microsystem, where the double layers are not so thin. For example, even in an (aqueous) electrolyte with $\lambda_D = 10$ nm, $c_0 = 10^{-3}$ M, $a = 5$ Å and in a microdevice with $L = 100$ μm features, the threshold voltage (with steric effects) is roughly 0.2 V.

This estimate, however, neglects the possibility of a transient breakdown of the RC circuit approximation, prior to diffusive relaxation across the entire cell. In the case of response to a suddenly applied dc voltage, the salt adsorption by each diffuse layer occurs over a time scale, $\tau_c = \lambda_D L/D$, during which diffusion spreads the nearby region of depleted neutral bulk solution over a distance $\sqrt{D\tau_c} = \sqrt{\lambda_D L}$. Therefore the requirement that the local bulk conductivity does not change significantly during charging dynamics yields the refined estimate [15]

$$\alpha_d = \frac{w}{c_0 \sqrt{\lambda_D L}} \ll 1,$$

which replaces L/λ_D by $\sqrt{L/\lambda}$ in the estimates above. This sets a lower bound for the limiting voltage for the validity of circuit models.

In the case of ac forcing at frequency ω , the bound $\alpha_d \ll 1$ is appropriate for low frequencies, $2\pi\omega\tau_c \ll 1$, but circuit models remain valid up to higher voltages at higher frequencies. At moderate frequencies, $2\pi\omega\tau_c > 1$, the double layer does not have enough time for complete charging, and the Warburg-like diffusion layer due to salt adsorption (which oscillates at twice the frequency) only propagates to a distance, $\sqrt{D/4\pi\omega}$. Therefore we may crudely estimate $(w/c_0)\sqrt{4\pi\omega/D} \ll 1$ to avoid significant changes in bulk conductivity in the diffusion layer. (A more careful estimate would take into account that only partial charging and salt

adsorption occur with increasing frequency.) At higher frequencies, $\omega\lambda_D^2/D \approx 1$, the diffuse layer does not have enough time to equilibrate, and little charging occurs.

These arguments can be made more precise using matched asymptotic expansions to describe the thin double layer limit, starting from an explicitly time-dependent model. For the case of one-dimensional response to a suddenly applied voltage, this was done in Ref. [15] starting from the Poisson-Nernst-Planck equations of (time-dependent) dilute solution theory. In Part II [1], we will derive modified PNP equations for dynamics with steric effects and repeat the same kind of asymptotic analysis to reach a similar conclusion as our simple arguments here: Steric effects greatly extend the range of applicability of RC circuit models, compared to what would be expected on the basis of dilute solution theory.

C. Diffuse-layer surface conduction

Another feature not present in circuit models is the possibility of current passed along the surface through the diffuse layer, demonstrated by Bikerman [11] and considered extensively in theories of electrokinetics by Dukhin and collaborators [14]. As first shown in Ref. [15] and elaborated in Ref. [16] in the setting of dilute solution theory, the relative strengths of tangential “surface fluxes” through the diffuse layer, compared to bulk fluxes, are controlled by the same dimensionless groups that govern ion adsorption (discussed above). This is actually quite a general result, as we now briefly explain. We will thus conclude that steric effects also greatly reduce the importance of surface conduction in the diffuse layer compared to the classical predictions of dilute solution theory.

Assuming small local perturbations from thermal equilibrium, the flux density (number/area.time) of ionic species i is given by

$$F_i = -b_i c_i \nabla \mu_i \quad (38)$$

where the chemical potential μ_i generally has a different form than Eq. (1) in a concentrated solution (e.g., see Part II [1]). Consider a thin diffuse layer near a charged surface, where the ion concentration c_i departs from its nearby neutral bulk value c_i^b . Due to fast relaxation at the small scale of the screening length, the diffuse-layer concentration remains in quasi-equilibrium at nearly constant chemical potential in the normal direction, $\mu_i \sim \mu_i^b$, in the thin double layer limit $\lambda_D/L \rightarrow 0$. There can, however, be small tangential gradients, $\nabla_{\parallel} \mu_i^b \neq 0$ at the macroscopic length scale leading to an excess diffuse-layer “surface” flux density (number/length.time).

Thin double layers can suck in significant amounts of excess ions, which is characterized by the excess surface concentration

$$\Gamma_i = \int_{\text{surface}}^{\text{bulk}} (c_i - c_i^b) dx \quad (39)$$

fed by the excess flux defined by

$$F_i^s = \int_{\text{surface}}^{\text{bulk}} (F_i - F_i^b) dx = \int_{\text{surface}}^{\text{bulk}} (-b_i c_i \nabla_{\parallel} \mu_i + b_i c_i^b \nabla_{\parallel} \mu_i^b) dx,$$

where $F_i^b = -b_i c_i \nabla \mu_i^b$ is the adjacent bulk value of the flux. In the thin double layer limit $\lambda_D/L \rightarrow 0$, we have $\nabla \mu_i \sim \nabla \mu_i^b$ and therefore

$$F_i^s \sim -\nabla_{\parallel} \mu_i^b \int_{\text{surface}}^{\text{bulk}} b_i (c_i - c_i^b) dx. \quad (40)$$

For a constant mobility b_i , this takes the same form as the bulk flux density (38),

$$F_i^s = -b_i \Gamma_i \nabla_{\parallel} \mu_i^b, \quad (41)$$

where the bulk concentration (number/volume) has been replaced by the diffuse-layer surface concentration (number/area) given by Eq. (39). In a concentrated solution, we generally expect that the mobility b_i might decrease in the diffuse layer, due to steric effects and large normal electric fields, so this formula may overestimate the surface flux density.

Following Bikerman [11,12,16], we may estimate the relative importance of surface to bulk flux densities at a length scale L by the dimensionless group

$$\frac{F_i^s}{F_i^b L} = \frac{\Gamma_i}{c_i^b L}, \quad (42)$$

which we see also measures the relative importance of “surface adsorption” of ion i in the diffuse layer relative to the bulk concentration. For a highly charged diffuse layer $|\Psi_D| \gg \Psi_c$, the ions are mostly of one type (counterions), so $\Gamma_i \sim q \sim w$. The surface current is also carried mostly by those ions, $J^s \sim ze F_i^s$, while the bulk current is carried by both ions, $J^b \approx 2(ze) F_i^b$ (neglecting diffusion compared to electromigration). Therefore we see that the “Dukhin number” comparing surface conduction at a highly charged diffuse layer to bulk conduction at nearly uniform concentration,

$$\text{Du} = \frac{J^s}{J^b L} \sim \frac{w}{2c_0 L} = \frac{\alpha_s}{2} \quad (43)$$

is roughly half of the dimensionless group α_s governing salt adsorption by the diffuse layer.

We have seen that steric effects greatly reduce w compared to the predictions of dilute solution theory, so that $\alpha_s = O(\lambda_D/L)$ remains small up to rather high voltages. Since the calculation above overestimates the importance of surface conduction, it is clear that steric effects also greatly reduce the Dukhin number compared to the predictions of dilute solution theory. We conclude that surface conduction in a thin diffuse layer does not become important until voltages large enough to violate the equivalent circuit approximation are applied across it. Compact layer surface conduction may still be important in some cases, but it too is limited by the same steric effects.

V. COMPACT LAYER EFFECTS

We now check the robustness of these conclusions to the additional presence of an insulating surface layer between the metal electrode and the electrolyte where the EDL models are applied. We suppose that this layer is not involved in the dynamics so that its properties do not change, and assume for the sake of simplicity that these properties are linear so that it can be described as a fixed surface capacitance C_s .

Such models have been used in many circumstances, sometimes to describe the Stern layer corresponding to condensed ions. Our approach here is different in the sense that a layer of condensed ions would be involved in the charging/discharging process. What we have in mind is closer to a thin film, e.g., of oxide on the metal, of thickness h_s , and dielectric constant ε_s so that $C_s = \varepsilon_s/h_s$. This form has been proposed to model coating layers on electrodes in the context of ac electrokinetics [32].

The overall differential capacitance of the interface is now

$$\frac{1}{C} = \frac{1}{C_D} + \frac{1}{C_s}$$

with $C_s = -dq/d\Psi_s$, where q is the total charge per area in the double layer, and Ψ_s is the voltage drop across the aforementioned compact layer. The total voltage drop across the interface is $\Psi = \Psi_s + \Psi_D$, and $-q/\Psi$ is the total capacitance of the interface.

A useful dimensionless parameter to quantify the effect of this surface layer is the ratio of linearized diffuse layer capacitance to the Stern layer capacitance

$$\delta = \frac{(\varepsilon/\lambda_D)}{C_s},$$

which has been employed recently in general studies of diffuse-charge dynamics [15,106], as well as in theoretical models [31,32,35,36,41,50] and in the fitting of experimental data [40,107] for induced-charge (ac or dc) electrokinetics. No surface layer corresponds to $\delta=0$. In the above mentioned picture of the layer of oxide, $\delta = (\varepsilon/\varepsilon_s)(h_s/\lambda_D)$ so that even very thin oxide layers can yield not too small values of δ if $\varepsilon/\varepsilon_s$ is large.

Let us now compare the differential capacitance C (with surface layer) to the bare double layer differential capacitance previously plotted in Fig. 7, for the PB equation and the two models with steric effects. The corresponding plots are provided in Fig. 10 for $\delta=0.25$.

Many qualitative points are obvious. First, the PB differential capacitance does not blow up exponentially anymore, as the surface layer takes over when the double layer voltage gets large, so that C converges to the finite value C_s within the PB model. Most of the potential drop is then across the surface layer. Second, the two main consequences of steric effects pointed out above remain valid: C is weaker when steric effects are taken into account, and $C(\Psi)$ is nonmonotonous with a maximum at intermediate values and a further decrease to zero.

When the parameter δ is zero or small (i.e., the Stern layer capacitance is large), a closely packed “diffuse” layer has to

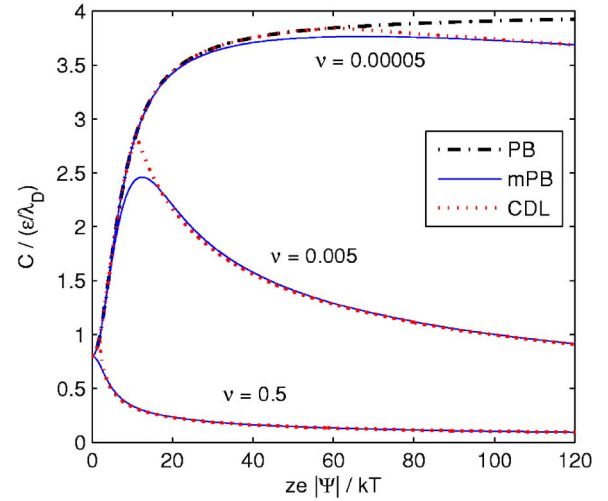


FIG. 10. (Color online) The total double layer differential capacitance in presence of a Stern layer with $\delta=0.25$ versus the total potential drop across the double layer.

form in response to a high potential drop. This is the case when the steric effects become important and the PB theory fails. However, for the higher values of δ , most of the potential drop is realized over the Stern layer, and the ions in the diffuse layer are not as densely packed. Thus the system stays below the steric limit, and the PB theory agrees with the MPB theory, as demonstrated by the total capacitance plots of Fig. 11. Similar comments can be made on Fig. 10, which shows that for $\delta=0.25$, steric effects may or may not be important depending on the value of the dimensionless parameter $\nu=2a^3c_0$. For the distribution of the voltage drop over the Stern layer and the diffuse layers, see Fig. 12.

This analysis, although correct, is somewhat misleading, however, since the assumption of a constant compact-layer capacitance may not always be reasonable. In many situations of interest, where several volts ($\approx 100kT/e$) are applied across the double layer, it is unlikely that the compact layer could withstand a significant fraction of the total voltage.

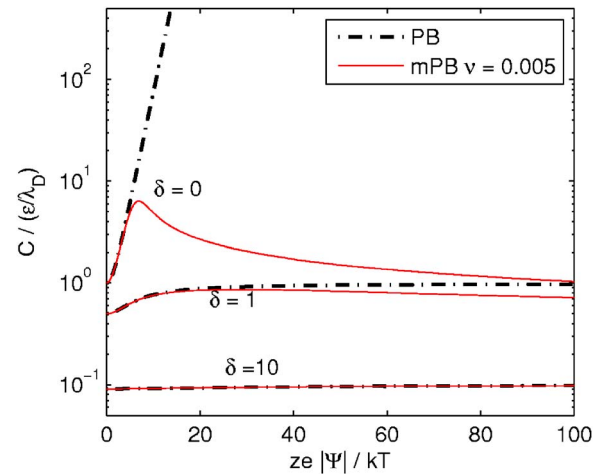


FIG. 11. (Color online) The differential capacitance C of the double layer as a function of potential difference Ψ for various values of Stern layer capacitance values.

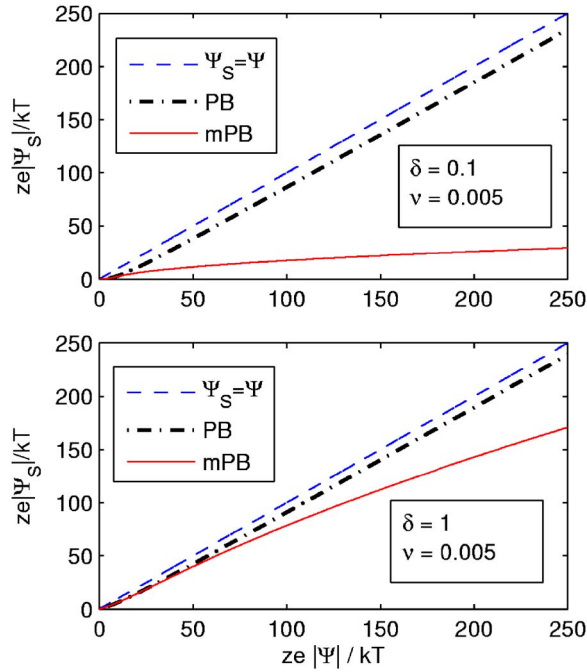


FIG. 12. (Color online) The Stern layer voltage drop as a function of the total double layer voltage difference. For reference, the line $\Psi_S = \Psi$ is also drawn. In the PB theory, almost all of the voltage drop is realized over the Stern layer when the voltage drop is on the order of a few voltages.

Note that dielectric breakdown in water can occur in average fields as low as $20 \text{ MV/m} = 0.02 \text{ V/nm}$ in experiments applying submicrosecond voltage pulses (well below the charging time of the double layers) [108]. The critical field may be higher in the Stern layer, where water is confined by ions at the outer Helmholtz plane [104], but it seems implausible for an atomic layer to sustain several volts without somehow “short circuiting” via electron cascades, electrolysis, Faradaic reactions, etc. In some cases, the compact layer models a dielectric thin film, which may be considerably thicker. Again, however, most coating materials, such as Teflon or various metal oxides, undergo dielectric breakdown in fields of order 10 MV/m , so a dielectric coating cannot easily withstand several volts unless it is at least 10 nm wide.

In general, we see that the capacitance of the compact layer must effectively decrease at large voltages, which corresponds to the limit $\delta \rightarrow 0$. As a result, a significant fraction of a large voltage must be sustained by the diffuse layer, making steric effects important in many situations of interest. Regardless of the accuracy of our simple models, therefore, we believe that the predicted qualitative effects of ion crowding are likely to have broad relevance for experimental systems applying large voltages.

VI. CONCLUSION

We have used two simple models for the double layer to account for crowding effects which necessarily take place at intermediate and large applied voltages. These models are both based on modifications of the Poisson Boltzmann description of dilute solutions. This strategy has led us to identify important operational consequences of these crowding effects of the thin double layers, namely a largely reduced double layer capacitance and a decreased ion uptake from the bulk.

We have provided in these sections explicit formulas for the total and differential capacitance and for the salt uptake of interfaces *at equilibrium*, as a function of the potential drop across the interface. More precisely we have recalled the PB results (no steric effects $\nu=0$), and given results for the two simple models with steric effects ($\nu \neq 0$), considering for all cases the possibility of a finite insulating layer on the electrode ($\delta \neq 0$).

The two models lead to remarkably similar results suggesting that these semi-quantitatively hold beyond the specifics of these models. Both showed marked differences with the PB approach: the differential capacitance and salt uptake are much weaker, and the former varies nonmonotonously with the applied potential.

These observations for the *equilibrium* properties have led us to make predictions for the *dynamics* of electrolyte cells of size quite larger than the Debye length: (i) an effective equivalent RC circuit description holds for a wider range of potentials than expected on the simple basis of the PB equation, (ii) the response time is much smaller than expected from PB at large voltages, and (iii) this time decreases at large voltages after an initial increase for lower values.

The dramatic effect of steric constraints in this problem also shows that other predictions of nonlinear PB theory, such as the change of scaling from V^2 to $|V| \log |V|$ for ac electro-osmosis [50], are limited in applicability and should be revisited with models taking crowding effects into account. More generally, this work suggests that, beyond the present problem of ionic transport in electrolytic systems, the description of electrokinetic effects at large applied voltages should be revisited to correct shortcomings of dilute-solution theory.

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