Electrostatics

$$\vec{F} = q\vec{E}$$
 (electric force on a particle with charge q)

The electric field at point P due to a small element of charge $\mathrm{d} q$ is

$$\mathrm{d}\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{\mathrm{d}q}{r^2} \hat{r}$$

where $\vec{r} (= r\hat{r})$ is the displacement vector that points from dq to P. For any closed surface S,

$$\oint_{S} \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} Q_{\text{enclosed by S}}$$
(Gauss's Law)

Known Electric Field Strengths

$$E = \frac{Q}{4\pi\epsilon_0 r^2}$$
(point charge Q)

$$E = \frac{\lambda}{2\pi\epsilon_0 r}$$
(infinite line of uniform charge density λ C/m)

$$E = \frac{\sigma}{2\epsilon_0}$$
(infinite sheet of uniform charge density σ C/m²)

Electric Potential

$$U = qV$$
$$V_b - V_a = -\int_{\vec{r}_a}^{\vec{r}_b} \vec{E} \cdot d\vec{l}$$
$$\vec{E} = -\vec{\nabla}V$$

(electrostatic potential energy of a particle with charge q) (finding electric potential from electric field) (finding electric field from electric potential)

The electrostatic potential at point P due to a small element of charge dq, relative to $V(r = \infty) = 0$, is

$$\mathrm{d}V = \frac{1}{4\pi\epsilon_0} \frac{\mathrm{d}q}{r}$$

where r is the distance from dq to P.

Capacitance

Q = CV (definition of capacitance) $C = \epsilon_0 \frac{A}{d}$ (for a vacuum- or air-filled parallel-plate capacitor with area A and separation d) $U = \frac{1}{2}CV^2$ (energy stored in a capacitor)

Electric Field Energy

Electric fields store energy with a density (J/m^3) of

 $u = \frac{1}{2}\epsilon_0 E^2$

Dielectrics

$$E = \frac{E_0}{K}$$
 (electric field inside a dielectric material placed in an external field E_0)

$$C = \epsilon \frac{A}{d} = K \epsilon_0 \frac{A}{d}$$
 (for a parallel-plate capacitor filled with a dielectric material)

Current

$$I = \frac{\mathrm{d}q}{\mathrm{d}t} = \int \vec{J} \cdot \mathrm{d}\vec{A} \qquad (\text{definition of current and current density})$$

For any closed surface S,

 $I_{\text{leaving S}} = \oint_{S} \vec{J} \cdot d\vec{A} = -\frac{d}{dt} Q_{\text{enclosed by S}}$ (continuity equation)

In a non-ideal conductor with conductivity σ (resistivity $\rho = \frac{1}{\sigma}$),

$$\vec{J} = \sigma \vec{E} = \frac{1}{\rho} \vec{E}$$

Resistance

V = IR	(definition of resistance)
$R = \rho \frac{l}{A}$	(for a wire with length l and cross-sectional area A)

Magnetostatics

 $\vec{F} = q\vec{v} \times \vec{B}$ (magnetic force on a particle with charge q and velocity \vec{v}) $d\vec{F} = Id\vec{l} \times \vec{B}$ (magnetic force on a small segment $d\vec{l}$ of wire carrying a current I)

The magnetic field at point P due to a small segment of wire $d\vec{l}$ carrying a current I is

$$\mathrm{d}\vec{B} = \frac{\mu_0}{4\pi} \frac{I \mathrm{d}\vec{l} \times \hat{r}}{r^2}$$

where $\vec{r} (= r\hat{r})$ is the displacement vector that points from $d\vec{l}$ to P.

For any closed loop C,

$$\oint_{C} \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed by C}}$$
(Ampere's Law)

Known Magnetic Field Strengths

$$B = \frac{\mu_0 I}{2\pi r}$$
 (infinite straight wire carrying current I)

$$B = \mu_0 n I$$
 (inside a long tightly-wrapped solenoid with *n* turns per unit length)

Induction

$$\mathcal{E} = \oint \vec{E} \cdot d\vec{l} = \frac{-d\Phi_B}{dt}$$
(Faraday's Law)

Mutual Inductance

$$M = \frac{\Phi_B \text{ thru } 2 \text{ due } 1}{I_1} = \frac{\Phi_B \text{ thru } 1 \text{ due } 2}{I_2}$$
$$\mathcal{E}_1 = -M \frac{\mathrm{d}I_2}{\mathrm{d}t}$$
$$\mathcal{E}_2 = -M \frac{\mathrm{d}I_1}{\mathrm{d}t}$$

Self Inductance

$$L = \frac{\Phi_B}{I}$$
$$\mathcal{E} = -L\frac{\mathrm{d}I}{\mathrm{d}t}$$
$$U = \frac{1}{2}LI^2$$

(energy stored in an inductor)

Magnetic Field Energy

Magnetic fields store energy with a density (J/m^3) of

$$u = \frac{1}{2} \frac{B^2}{\mu_0}$$

Circuit Elements

Type	Relationship	Series Combination	Parallel Combination
Resistor Capacitor Inductor	$V = IR$ $I = C\frac{\mathrm{d}V}{\mathrm{d}t}$ $V = L\frac{\mathrm{d}I}{\mathrm{d}t}$	$R_{eq} = R_1 + R_2$ $\frac{1}{C_{eq}} = \frac{1}{C_1} + \frac{1}{C_2}$ $L_{eq} = L_1 + L_2$	$\frac{\frac{1}{R_{eq}} = \frac{1}{R_1} + \frac{1}{R_2}}{C_{eq} = C_1 + C_2}$ $\frac{1}{L_{eq}} = \frac{1}{L_1} + \frac{1}{L_2}$

Electric Power

$$P = VI$$
$$P = I^{2}R$$
$$U = \frac{1}{2}CV^{2}$$
$$U = \frac{1}{2}LI^{2}$$

(power consumed by any electrical device)

(power dissipated as heat in a resistor)

(energy stored in a capacitor)

(energy stored in an inductor)

Maxwell's Equations

Integral Form

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q}{\epsilon_0} \qquad \qquad \oint \vec{E} \cdot d\vec{l} = \frac{-d\Phi_B}{dt}$$

$$\oint \vec{B} \cdot d\vec{A} = 0 \qquad \qquad \oint \vec{B} \cdot d\vec{l} = \mu_0 I + \mu_0 \epsilon_0 \frac{d\Phi_B}{dt}$$

Differential Form

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \qquad \qquad \vec{\nabla} \times \vec{E} = \frac{-\partial \vec{B}}{\partial t}$$
$$\vec{\nabla} \cdot \vec{B} = 0 \qquad \qquad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

Electromagnetic Waves

$$f(x,t) = f(x - vt, 0) = g(x - vt)$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2}$$

$$f(x,t) = F_0 \sin(kx - \omega t) = F_0 \sin k(x - vt)$$

$$v = \frac{\omega}{k}$$

$$\lambda = \frac{2\pi}{k}$$

$$T = \frac{2\pi}{\omega}$$

$$\lambda f = v$$

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = 3 \times 10^8 \text{ m/s}$$

$$B = \frac{E}{c}$$
(relation)

(1-D wave equation to which f(x,t) is a solution) (a sinusoidal wave moving in the +x direction) (speed of propagation) (wavelength) (period) (relation between speed, wavelength, and frequency)

(general form of a wave moving in the +x direction)

1, 0, 1, ,

(speed of EM waves in a vacuum)

(relation between magnitudes of E and B in an EM plane wave)

Energy in EM Waves

The power density (energy transported per unit time per unit area) of an EM wave is given by

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$$
 (Poynting vector)
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Intensity is the time-averaged power density

$$S_{\rm avg} = \frac{E_0 B_0}{2\mu_0}$$

Math Corner

Solutions to Common Differential Equations

Decaying Exponential

The differential equation

$\tau \frac{\mathrm{d}f(t)}{\mathrm{d}t} + f(t) = F_0$

has solutions of the form

$$f(t) = F_0 + Ae^{-t/\tau}$$

where:

 τ is called the time constant

 ${\cal A}$ is an arbitrary constant that depends on the initial conditions

Simple Harmonic Oscillator

The differential equation

$$\frac{\mathrm{d}^2 f(t)}{\mathrm{d}t^2} + \omega_0^2 f(t) = 0$$

has solutions of the form

 $f(t) = A\cos(\omega_0 t + \phi)$

where:

 ω_0 is called the angular frequency

A and ϕ are arbitrary constants that depend on the initial conditions

Damped Harmonic Oscillator

The differential equation

$$\frac{\mathrm{d}^2 f(t)}{\mathrm{d}t^2} + \gamma \frac{\mathrm{d}f(t)}{\mathrm{d}t} + \omega_0^2 f(t) = 0$$

with $\gamma^2 < 4\omega_0^2$, has solutions of the form

$$f(t) = Ae^{-\frac{\gamma}{2}t}\cos(\omega_1 t + \phi)$$

where:

 $\omega_1 = \sqrt{\omega_0^2 - \frac{\gamma^2}{4}}$ is the angular frequency A and ϕ are arbitrary constants that depend on the initial conditions Vector Calculus

$$\begin{split} \vec{\nabla} &= \hat{\imath} \frac{\partial}{\partial x} + \hat{\jmath} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} & \text{(the "del" operator)} \\ \vec{\nabla} f &= \hat{\imath} \frac{\partial}{\partial x} + \hat{\jmath} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z} & \text{(gradient)} \\ \vec{\nabla} \cdot \vec{F} &= \frac{\partial}{\partial x} F_x + \frac{\partial}{\partial y} F_y + \frac{\partial}{\partial z} F_z & \text{(divergence)} \\ \vec{\nabla} \times \vec{F} &= \left| \begin{array}{c} \hat{\imath} & \hat{\jmath} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{array} \right| = \hat{\imath} \left(\frac{\partial}{\partial y} F_z - \frac{\partial}{\partial z} F_y \right) - \hat{\jmath} \left(\frac{\partial}{\partial x} F_z - \frac{\partial}{\partial z} F_x \right) + \hat{k} \left(\frac{\partial}{\partial x} F_y - \frac{\partial}{\partial y} F_x \right) & \text{(curl)} \\ \oint_{S} \vec{F} \cdot d\vec{A} &= \int_{\substack{\text{volume} \\ \text{by } S}} (\vec{\nabla} \cdot \vec{F}) \, dV & \text{(Divergence Theorem)} \\ \oint_{C} \vec{F} \cdot d\vec{l} &= \int_{\substack{\text{area} \\ \text{bounded} \\ \text{by } C}} (\vec{\nabla} \times \vec{F}) \cdot d\vec{A} & \text{(Curl Theorem)} \end{split}$$

Vector Multiplication

$$\vec{A} \cdot \vec{B} = \left| \vec{A} \right| \left| \vec{B} \right| \cos \theta_{A,B} = AB_{\parallel \text{ to } A} = A_{\parallel \text{ to } B}B$$
$$\left| \vec{A} \times \vec{B} \right| = \left| \vec{A} \right| \left| \vec{B} \right| \sin \theta_{A,B} = AB_{\perp \text{ to } A} = A_{\perp \text{ to } B}B$$

Geometry

A sphere of radius R has volume $\frac{4}{3}\pi R^3$ and surface area $4\pi R^2$.

A cylinder of radius R and height h has volume $\pi R^2 h$ and surface area $2\pi Rh + 2\pi R^2$ (the first term is the area around the side, the second term is the area of the top and bottom).

Trigonometry

$$\sin^2 \theta + \cos^2 \theta = 1 \qquad \qquad \sin^2 \theta = \frac{1}{2} - \frac{1}{2}\cos(2\theta) \qquad \qquad \sin 45^\circ = \cos 45^\circ = \frac{1}{\sqrt{2}}$$
$$\sin(\theta + \phi) = \sin \theta \cos \phi + \cos \theta \sin \phi \qquad \qquad \cos^2 \theta = \frac{1}{2} + \frac{1}{2}\cos(2\theta) \qquad \qquad \sin 30^\circ = \cos 60^\circ = \frac{1}{2}$$
$$\cos(\theta + \phi) = \cos \theta \cos \phi - \sin \theta \sin \phi \qquad \qquad \sin(2\theta) = 2\sin \theta \cos \theta \qquad \qquad \sin 60^\circ = \cos 30^\circ = \frac{\sqrt{3}}{2}$$

Quadratic Formula

If
$$ax^2 + bx + c = 0$$
 then $x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$.