## Special Relativity

For any pair of space-time events measured from two inertial reference frames S and S', where S' is moving relative to S with constant velocity v in the positive x direction:

$$\gamma \equiv \frac{1}{\sqrt{1 - \frac{v^2}{c^2}}}$$

$$\Delta x = \gamma(\Delta x' + v\Delta t')$$

$$\Delta y = \Delta y'$$

$$\Delta z = \Delta z'$$

$$\Delta t = \gamma(\Delta t' + \frac{v}{c^2}\Delta x')$$

$$\Delta x' = \gamma(\Delta x - v\Delta t)$$

$$\Delta y' = \Delta y$$

$$\Delta z' = \Delta z$$

$$\Delta t' = \gamma(\Delta t - \frac{v}{c^2}\Delta x)$$

If  $\Delta t'$  is the proper time between two events, then the time interval measured from another frame will be

$$\Delta t = \gamma \Delta t'$$

If  $\Delta x'$  is the proper length of an object, then the length measured from another frame will be

$$\Delta x = \frac{\Delta x'}{\gamma}$$

For a particle moving with velocity  $\vec{u}$  relative to S (and velocity  $\vec{u}'$  relative to S'),

$$u_{x} = \frac{u'_{x} + v}{1 + \frac{v}{c^{2}} u'_{x}}$$

$$u'_{x} = \frac{u_{x} - v}{1 - \frac{v}{c^{2}} u_{x}}$$

$$u'_{y} = \frac{u'_{y}}{\gamma (1 + \frac{v}{c^{2}} u'_{x})}$$

$$u'_{z} = \frac{u_{z}}{\gamma (1 + \frac{v}{c^{2}} u'_{x})}$$

$$u'_{z} = \frac{u_{z}}{\gamma (1 - \frac{v}{c^{2}} u_{x})}$$

### **Electrostatics**

$$\vec{F} = q\vec{E}$$
 (electric force on a particle with charge q)

The electric field at point P due to a small element of charge dq is

$$\mathrm{d}\vec{E} = \frac{1}{4\pi\epsilon_0} \frac{\mathrm{d}q}{r^2} \hat{r}$$

where  $\vec{r} (= r\hat{r})$  is the displacement vector that points from dq to P.

For any closed surface S,

$$\oint_{S} \vec{E} \cdot d\vec{A} = \frac{1}{\epsilon_0} Q_{\text{enclosed by S}}$$
 (Gauss's Law)

### **Known Electric Field Strengths**

$$E = \frac{Q}{4\pi\epsilon_0 r^2}$$
 (point charge  $Q$ )
$$E = \frac{\lambda}{2\pi\epsilon_0 r}$$
 (infinite line of uniform charge density  $\lambda$  C/m)
$$E = \frac{\sigma}{2\epsilon_0}$$
 (infinite sheet of uniform charge density  $\sigma$  C/m<sup>2</sup>)

### **Electric Potential**

$$U=qV$$
 (electrostatic potential energy of a particle with charge  $q$ ) 
$$V_b-V_a=-\int_{\vec{r}_a}^{\vec{r}_b} \vec{E}\cdot d\vec{l} \qquad \text{(finding electric potential from electric field)}$$
 
$$\vec{E}=-\vec{\nabla}V \qquad \qquad \text{(finding electric field from electric potential)}$$

The electrostatic potential at point P due to a small element of charge dq, relative to  $V(r = \infty) = 0$ , is

$$\mathrm{d}V = \frac{1}{4\pi\epsilon_0} \frac{\mathrm{d}q}{r}$$

where r is the distance from dq to P.

### Capacitance

$$Q = CV \qquad \qquad \text{(definition of capacitance)}$$
 
$$C = \epsilon_0 \frac{A}{d} \qquad \qquad \text{(for a vacuum- or air-filled parallel-plate capacitor with area $A$ and separation $d$)}$$
 
$$U = \frac{1}{2}CV^2 \qquad \qquad \text{(energy stored in a capacitor)}$$

## **Electric Field Energy**

Electric fields store energy with a density  $(J/m^3)$  of

$$u = \frac{1}{2}\epsilon_0 E^2$$

### **Dielectrics**

$$E = \frac{E_0}{K}$$
 (electric field inside a dielectric material placed in an external field  $E_0$ )
$$C = \epsilon \frac{A}{d} = K \epsilon_0 \frac{A}{d}$$
 (for a parallel-plate capacitor filled with a dielectric material)

## Current

$$I = \frac{\mathrm{d}q}{\mathrm{d}t} = \int \vec{J} \cdot \mathrm{d}\vec{A}$$
 (definition of current and current density)

For any closed surface S,

$$I_{\text{leaving S}} = \oint_{S} \vec{J} \cdot d\vec{A} = -\frac{d}{dt} Q_{\text{enclosed by S}}$$
 (continuity equation)

In a non-ideal conductor with conductivity  $\sigma$  (resistivity  $\rho = \frac{1}{\sigma}$ ),

$$\vec{J} = \sigma \vec{E} = \frac{1}{\rho} \vec{E}$$

### Resistance

$$V=IR \label{eq:localization}$$
 (definition of resistance) 
$$R=\rho\frac{l}{A} \label{eq:localization}$$
 (for a wire with length  $l$  and cross-sectional area  $A$ )

## Magnetostatics

$$\vec{F} = q\vec{v} \times \vec{B}$$
 (magnetic force on a particle with charge  $q$  and velocity  $\vec{v}$ )  $d\vec{F} = Id\vec{l} \times \vec{B}$  (magnetic force on a small segment  $d\vec{l}$  of wire carrying a current  $I$ )

The magnetic field at point P due to a small segment of wire  $d\vec{l}$  carrying a current I is

$$\mathrm{d}\vec{B} = \frac{\mu_0}{4\pi} \frac{I \mathrm{d}\vec{l} \times \hat{r}}{r^2}$$

where  $\vec{r}$  (=  $r\hat{r}$ ) is the displacement vector that points from  $d\vec{l}$  to P.

For any closed loop C,

$$\oint_{\mathbf{C}} \vec{B} \cdot d\vec{l} = \mu_0 I_{\text{enclosed by C}}$$
 (Ampere's Law)

## **Known Magnetic Field Strengths**

$$B = \frac{\mu_0 I}{2\pi r}$$
 (infinite straight wire carrying current I)  
 $B = \mu_0 n I$  (inside a long tightly-wrapped solenoid with  $n$  turns per unit length)

## Induction

$$\mathcal{E} = \oint \vec{E} \cdot d\vec{l} = \frac{-d\Phi_B}{dt}$$
 (Faraday's Law)

### **Mutual Inductance**

$$M = \frac{\Phi_{B \text{ thru 2 due 1}}}{I_1} = \frac{\Phi_{B \text{ thru 1 due 2}}}{I_2}$$

$$\mathcal{E}_1 = -M \frac{\mathrm{d}I_2}{\mathrm{d}t}$$

$$\mathcal{E}_2 = -M \frac{\mathrm{d}I_1}{\mathrm{d}t}$$

## **Self Inductance**

$$L = \frac{\Phi_B}{I}$$

$$\mathcal{E} = -L \frac{\mathrm{d}I}{\mathrm{d}t}$$

$$U = \frac{1}{2}LI^2$$

(energy stored in an inductor)

### Magnetic Field Energy

Magnetic fields store energy with a density  $(J/m^3)$  of

$$u = \frac{1}{2} \frac{B^2}{\mu_0}$$

### Circuit Elements

Type	Relationship	Series Combination	Parallel Combination
Resistor Capacitor Inductor	$V = IR$ $I = C \frac{dV}{dt}$ $V = L \frac{dI}{dt}$	$R_{ m eq} = R_1 + R_2$ $rac{1}{C_{ m eq}} = rac{1}{C_1} + rac{1}{C_2}$ $L_{ m eq} = L_1 + L_2$	$egin{aligned} rac{1}{R_{ ext{eq}}} &= rac{1}{R_1} + rac{1}{R_2} \ C_{ ext{eq}} &= C_1 + C_2 \ rac{1}{L_{ ext{eq}}} &= rac{1}{L_1} + rac{1}{L_2} \end{aligned}$

### **Electric Power**

$$P=VI$$
 (power consumed by any electrical device) 
$$P=I^2R$$
 (power dissipated as heat in a resistor) 
$$U=\frac{1}{2}CV^2$$
 (energy stored in a capacitor) 
$$U=\frac{1}{2}LI^2$$
 (energy stored in an inductor)

# Maxwell's Equations

## **Integral Form**

$$\oint \vec{E} \cdot d\vec{A} = \frac{Q}{\epsilon_0} \qquad \qquad \oint \vec{E} \cdot d\vec{l} = \frac{-d\Phi_B}{dt}$$

$$\oint \vec{B} \cdot d\vec{A} = 0 \qquad \qquad \oint \vec{B} \cdot d\vec{l} = \mu_0 I + \mu_0 \epsilon_0 \frac{d\Phi_E}{dt}$$
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### Differential Form

$$\vec{\nabla} \cdot \vec{E} = \frac{\rho}{\epsilon_0} \qquad \qquad \vec{\nabla} \times \vec{E} = \frac{-\partial \vec{B}}{\partial t}$$

$$\vec{\nabla} \cdot \vec{B} = 0 \qquad \qquad \vec{\nabla} \times \vec{B} = \mu_0 \vec{J} + \mu_0 \epsilon_0 \frac{\partial \vec{E}}{\partial t}$$

## **Electromagnetic Waves**

$$f(x,t) = f(x-vt,0) = g(x-vt) \qquad \text{(general form of a wave moving in the } + x \text{ direction)}$$

$$\frac{\partial^2 f}{\partial x^2} = \frac{1}{v^2} \frac{\partial^2 f}{\partial t^2} \qquad \text{(1-D wave equation to which } f(x,t) \text{ is a solution)}$$

$$f(x,t) = F_0 \sin(kx - \omega t) = F_0 \sin k(x-vt) \qquad \text{(a sinusoidal wave moving in the } + x \text{ direction)}$$

$$v = \frac{\omega}{k} \qquad \text{(speed of propagation)}$$

$$\lambda = \frac{2\pi}{k} \qquad \text{(wavelength)}$$

$$T = \frac{2\pi}{\omega} \qquad \text{(period)}$$

$$\lambda f = v \qquad \text{(relation between speed, wavelength, and frequency)}$$

$$c = \frac{1}{\sqrt{\mu_0 \epsilon_0}} = 3 \times 10^8 \text{ m/s} \qquad \text{(speed of EM waves in a vacuum)}$$

$$B = \frac{E}{c} \qquad \text{(relation between magnitudes of E and B in an EM plane wave)}$$

## Energy in EM Waves

The power density (energy transported per unit time per unit area) of an EM wave is given by

$$\vec{S} = \frac{1}{\mu_0} \vec{E} \times \vec{B}$$
 (Poynting vector)

Intensity is the time-averaged power density

$$S_{\text{avg}} = \frac{E_0 B_0}{2\mu_0}$$
 (intensity of an EM plane wave)

## Math Corner

### Solutions to Common Differential Equations

### **Decaying Exponential**

The differential equation

$$\tau \frac{\mathrm{d}f(t)}{\mathrm{d}t} + f(t) = F_0$$

has solutions of the form

$$f(t) = F_0 + Ae^{-t/\tau}$$

where:

 $\tau$  is called the time constant

A is an arbitrary constant that depends on the initial conditions

### Simple Harmonic Oscillator

The differential equation

$$\frac{\mathrm{d}^2 f(t)}{\mathrm{d}t^2} + \omega_0^2 f(t) = 0$$

has solutions of the form

$$f(t) = A\cos(\omega_0 t + \phi)$$

where:

 $\omega_0$  is called the angular frequency

A and  $\phi$  are arbitrary constants that depend on the initial conditions

### Damped Harmonic Oscillator

The differential equation

$$\frac{\mathrm{d}^2 f(t)}{\mathrm{d}t^2} + \gamma \frac{\mathrm{d}f(t)}{\mathrm{d}t} + \omega_0^2 f(t) = 0$$

with  $\gamma^2 < 4\omega_0^2$ , has solutions of the form

$$f(t) = Ae^{-\frac{\gamma}{2}t}\cos(\omega_1 t + \phi)$$

where:

 $\omega_1 = \sqrt{\omega_0^2 - \frac{\gamma^2}{4}}$  is the angular frequency A and  $\phi$  are arbitrary constants that depend on the initial conditions

#### Vector Calculus

$$\vec{\nabla} = \hat{\imath} \frac{\partial}{\partial x} + \hat{\jmath} \frac{\partial}{\partial y} + \hat{k} \frac{\partial}{\partial z}$$
 (the "del" operator) 
$$\vec{\nabla} f = \hat{\imath} \frac{\partial f}{\partial x} + \hat{\jmath} \frac{\partial f}{\partial y} + \hat{k} \frac{\partial f}{\partial z}$$
 (gradient) 
$$\vec{\nabla} \cdot \vec{F} = \frac{\partial}{\partial x} F_x + \frac{\partial}{\partial y} F_y + \frac{\partial}{\partial z} F_z$$
 (divergence) 
$$\vec{\nabla} \times \vec{F} = \begin{vmatrix} \hat{\imath} & \hat{\jmath} & \hat{k} \\ \frac{\partial}{\partial x} & \frac{\partial}{\partial y} & \frac{\partial}{\partial z} \\ F_x & F_y & F_z \end{vmatrix} = \hat{\imath} \left( \frac{\partial}{\partial y} F_z - \frac{\partial}{\partial z} F_y \right) - \hat{\jmath} \left( \frac{\partial}{\partial x} F_z - \frac{\partial}{\partial z} F_x \right) + \hat{k} \left( \frac{\partial}{\partial x} F_y - \frac{\partial}{\partial y} F_x \right)$$
 (curl) 
$$\oint_{S} \vec{F} \cdot d\vec{A} = \int_{\substack{\text{volume} \\ \text{bounded} \\ \text{by } S}} (\vec{\nabla} \cdot \vec{F}) dV$$
 (Divergence Theorem) 
$$\oint_{C} \vec{F} \cdot d\vec{l} = \int_{\substack{\text{orden} \\ \text{by } C}} (\vec{\nabla} \times \vec{F}) \cdot d\vec{A}$$
 (Curl Theorem)

### Vector Multiplication

$$\vec{A} \cdot \vec{B} = |\vec{A}| |\vec{B}| \cos \theta_{A,B} = AB_{\parallel \text{ to A}} = A_{\parallel \text{ to B}}B$$
$$|\vec{A} \times \vec{B}| = |\vec{A}| |\vec{B}| \sin \theta_{A,B} = AB_{\perp \text{ to A}} = A_{\perp \text{ to B}}B$$
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## Geometry

A sphere of radius R has volume  $\frac{4}{3}\pi R^3$  and surface area  $4\pi R^2$ .

A cylinder of radius R and height h has volume  $\pi R^2 h$  and surface area  $2\pi R h + 2\pi R^2$  (the first term is the area around the side, the second term is the area of the top and bottom).

### Trigonometry

$$\sin^2 \theta + \cos^2 \theta = 1$$

$$\sin^2 \theta = \frac{1}{2} - \frac{1}{2} \cos(2\theta)$$

$$\sin 45^\circ = \cos 45^\circ = \frac{1}{\sqrt{2}}$$

$$\sin(\theta + \phi) = \sin \theta \cos \phi + \cos \theta \sin \phi$$

$$\cos^2 \theta = \frac{1}{2} + \frac{1}{2} \cos(2\theta)$$

$$\sin 30^\circ = \cos 60^\circ = \frac{1}{2}$$

$$\cos(\theta + \phi) = \cos \theta \cos \phi - \sin \theta \sin \phi$$

$$\sin(2\theta) = 2 \sin \theta \cos \theta$$

$$\sin 60^\circ = \cos 30^\circ = \frac{\sqrt{3}}{2}$$

## Quadratic Formula

If 
$$ax^2 + bx + c = 0$$
 then  $x = \frac{-b \pm \sqrt{b^2 - 4ac}}{2a}$ .