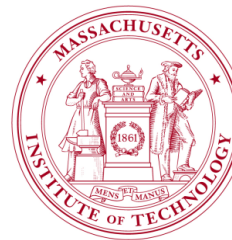


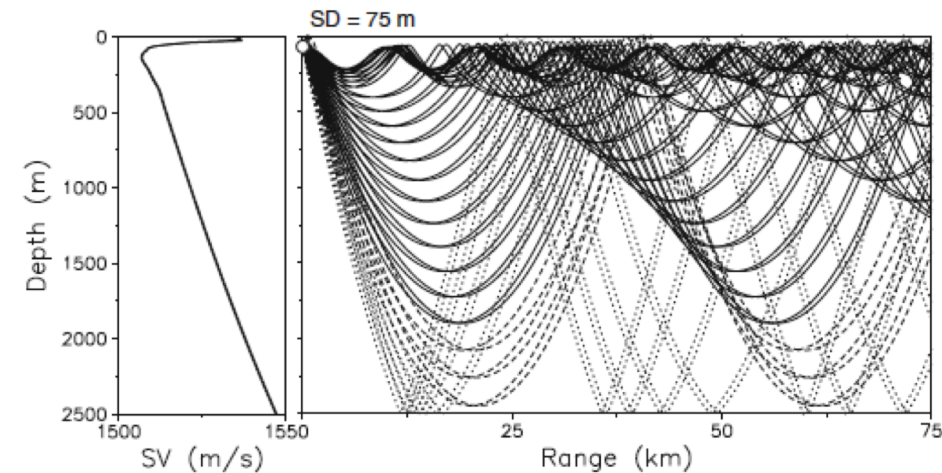
# The Level Set Method for Acoustic Propagation

Manmeet Bhabra



# Introduction

- Modeling of high frequency acoustic propagation is prevalent in numerous applications (ex: underwater ocean acoustics).
- Traditionally accomplished using a method known as ray tracing (a Lagrangian approach).
- In this work, we look to investigate an alternate Eulerian approach to tackle this problem through the Level Set Method.



# The Acoustic Wave Equation

- Define the following variables:

$$\rho_0 = \text{Equilibrium Density}$$

$$\rho = \text{Instantaneous Density}$$

$$\rho_a = \rho - \rho_0 = \text{Acoustic Density}$$

$$p_0 = \text{Equilibrium Pressure}$$

$$p = \text{Instantaneous Pressure}$$

$$p_a = p - p_0 = \text{Acoustic Pressure}$$

$$\mathbf{v} = \text{Particle Velocity}$$

- Now consider the propagation of acoustic waves:

## Continuity Equation

$$\frac{\partial \rho}{\partial t} + \nabla \cdot \rho \mathbf{v} = 0$$

$$\frac{\partial \rho_a}{\partial t} + \nabla \cdot \rho_0 \mathbf{v} = 0$$

## Euler's Equation

$$\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} = -\frac{1}{\rho} \nabla p$$

$$\frac{\partial \mathbf{v}}{\partial t} + \frac{1}{\rho_0} \nabla p_a = 0$$

## Equation of State

$$p = p_0 + \rho_a \left( \frac{\partial p}{\partial \rho} \right)_s + \frac{1}{2} \rho_a^2 \left( \frac{\partial^2 p}{\partial \rho^2} \right)_s + \dots$$

$$p_a = \rho_a \left( \frac{\partial p}{\partial \rho} \right)_s$$

**Assumption** : Acoustic Pressure and Density Small

$$\rho_a \nabla \cdot \left( \frac{1}{\rho_a} \nabla p_a \right) - \frac{1}{c^2} \frac{\partial^2 p_a}{\partial t^2} = 0$$

$$\nabla^2 p_a - \frac{1}{c^2} \frac{\partial^2 p_a}{\partial t^2} = 0$$

**Acoustic Wave Equation**

# The High Frequency Solution

- We consider now solving for the evolution of acoustic waves at high frequencies.

- Assume a solution of the following form:

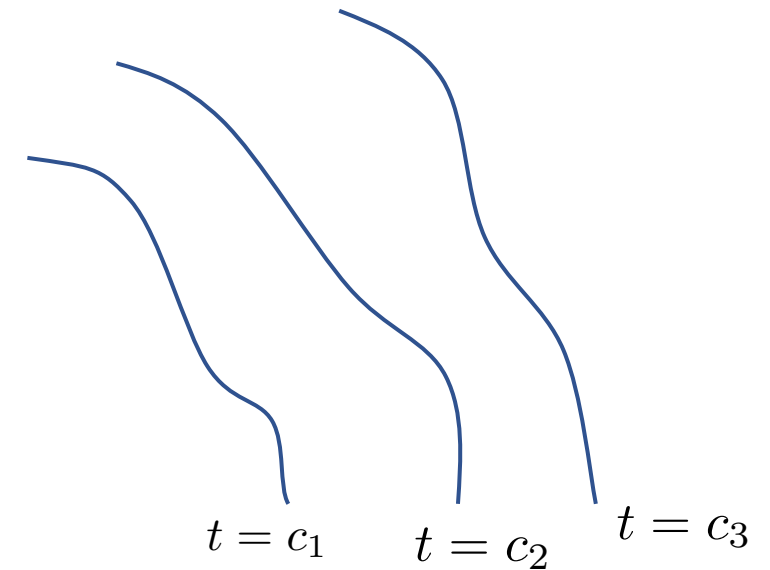
$$p(\mathbf{x}, t) = e^{i\omega S(\mathbf{x}, t)} \sum_{k=0}^{\infty} A_k(\mathbf{x}, t) (i\omega)^{-k}$$

- $S(\mathbf{x}, t)$  is the phase function. At any given point of time, the level surfaces of  $S(\mathbf{x}, t)$  correspond to points at which the phase is the same (surfaces of constant phase).
  - We refer to these surfaces of constant phase as the wavefront as well.

- Substitution into the wave equation, (and retaining the highest order terms in  $\omega$ ) we obtain:

$$S(\mathbf{x}, t) + c|\nabla S(\mathbf{x}, t)| = 0$$

- This has the form a Hamilton-Jacobi Equation.



**Hamilton-Jacobi Equation  
General Form**

$$\frac{\partial u(\mathbf{x}, t)}{\partial t} + H(\mathbf{x}, \nabla u) = 0$$

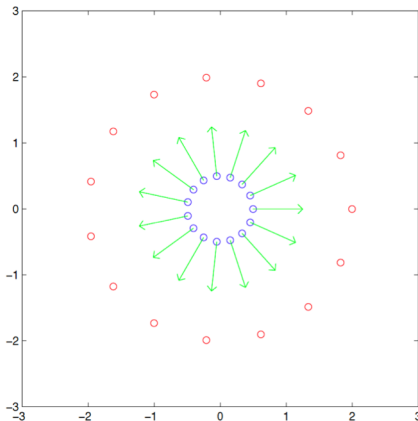
# Approaches to Evolve the Wavefront

## Lagrangian Approach

- Considers a discrete set of particles on the initial wavefront:
  - Trajectory of each point governed by characteristics of the Hamiltonian system:

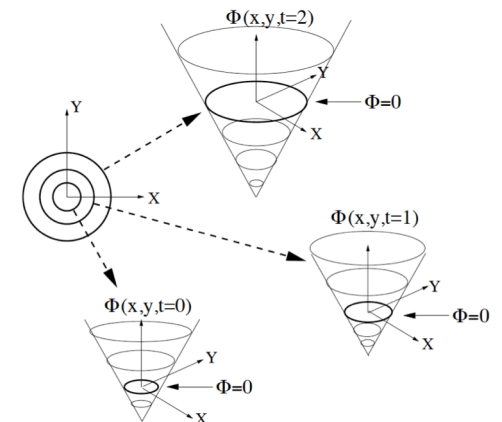
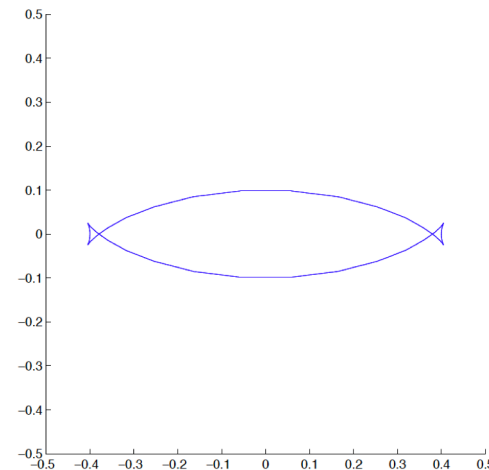
$$\frac{d\mathbf{x}}{dt} = c(\mathbf{x})^2 \mathbf{p}$$
$$\frac{d\mathbf{p}}{dt} = -\frac{1}{c(\mathbf{x})} \nabla_x c(\mathbf{x})$$

- **Difficulty:** Points originally close together may diverge at later times (poor wavefront resolution)



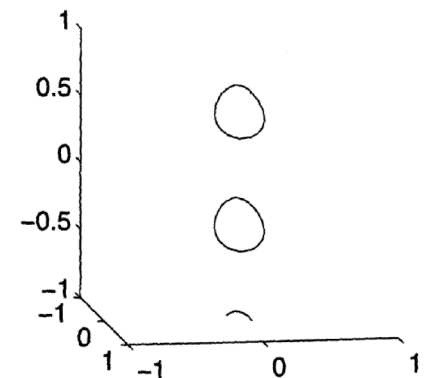
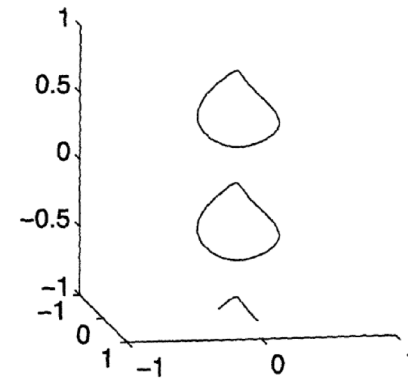
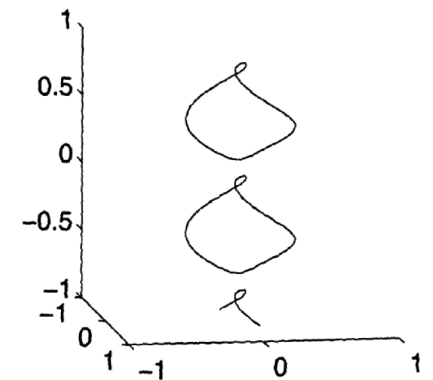
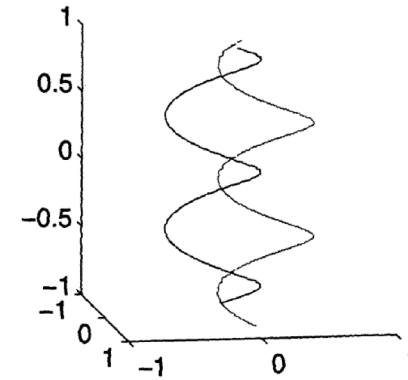
## Eulerian Approach

- Consider the front to be the level surface of an implicit function ( $\phi$ ) in a higher dimension:
  - Evolve the implicit function by solving a PDE governing the implicit functions evolution (the Hamilton-Jacobi equations).
- **Difficulty:** The Level Set method has issues when wavefronts become multivalued.



# Level Set Methods with Codimension-Two Objects

- Traditional Level Set Methods use codimension-one objects:
  - **Example:** If we are interested in solving for the evolution of an interface in  $\mathbb{R}^2$ , evolve the surface as the zero isocontour of an implicit function in  $\mathbb{R}^3$ .
- Codimension-two objects in Level Set Methods:
  - **Example:** Points in  $\mathbb{R}^2$ , Curves in  $\mathbb{R}^3$ .
  - Represent the object in the level set framework as the **intersection** of the isocontours of **two** functions  $\phi_1$  and  $\phi_2$ .
    - Evolve each level set function as in the standard approach.
    - Treatment may be needed to evolve the level sets while keeping them as orthogonal as possible.



# Level Set Formulation in a Reduced Phase Space

- We look to evolve the acoustic wavefront as a curve/strip in a higher dimensional reduced phase space with coordinates  $(x, y, \theta)$ .
  - $\theta$  gives the normal direction of a given point on the wavefront (measured from the  $+x$  axis).
  - The wavefront is then found by projecting this curve onto the  $(x, y)$  plane.
- The velocity field for the strip's propagation can be derived to be:

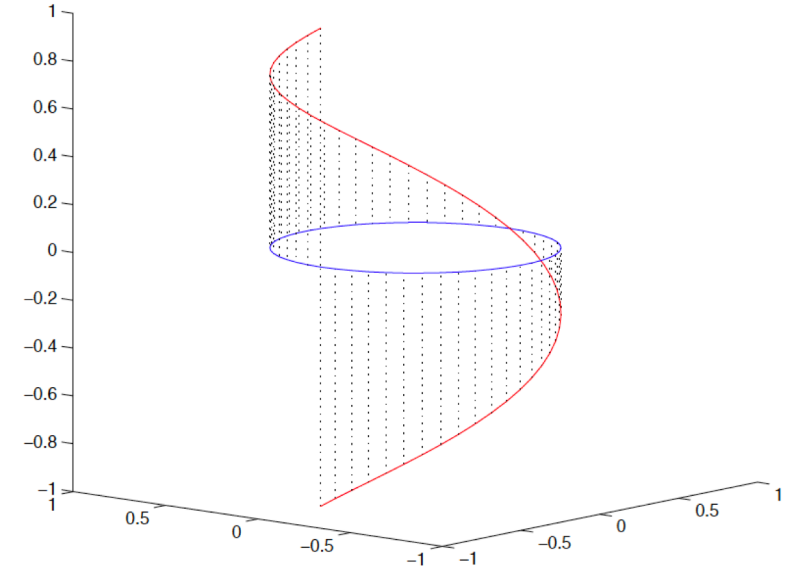
$$\mathbf{V}(\mathbf{x}, \theta) = \begin{bmatrix} c(\mathbf{x}) \cdot \cos(\theta) \\ c(\mathbf{x}) \cdot \sin(\theta) \\ \frac{\partial c(\mathbf{x})}{\partial x} \cdot \sin(\theta) - \frac{\partial c(\mathbf{x})}{\partial y} \cdot \cos(\theta) \end{bmatrix}$$

- The strip is represented as the intersection of two level set functions whose evolution is governed by:

$$\begin{aligned} \frac{\partial \phi_1}{\partial t} + \mathbf{V}(x, y, \theta) \cdot \nabla \phi_1 &= 0 \\ \frac{\partial \phi_2}{\partial t} + \mathbf{V}(x, y, \theta) \cdot \nabla \phi_2 &= 0 \end{aligned} \quad \longleftarrow \quad \begin{cases} \phi_1 = \phi_1(x, y, \theta, t) \\ \phi_2 = \phi_2(x, y, \theta, t) \end{cases}$$

- The wavefront (surfaces of constant phase) is given as:

$$W(x, y, t) = \{(x, y) \mid \phi_1(x, y, \theta, t) = \phi_2(x, y, \theta, t) = 0\}$$



# Implementation

$$\frac{\partial \phi_1}{\partial t} + \mathbf{V}(x, y, \theta) \cdot \nabla \phi_1 = 0$$
$$\frac{\partial \phi_2}{\partial t} + \mathbf{V}(x, y, \theta) \cdot \nabla \phi_2 = 0$$

Discretize explicitly in time. In this work, have used TVD Runge-Kutta Schemes.



Discretize in space using upwinding for all spatial derivatives.

- **Boundary Conditions:**

- Absorbing BCs implemented by imposing a zero-Neumann condition on the boundary.
- Reflecting BCs implemented by imposing a Dirichlet BC given by:

$$\phi_1(x, y, \theta_{refl}, t) = \phi_1(x, y, \theta_{inc}, t)$$

$$\phi_2(x, y, \theta_{refl}, t) = \phi_2(x, y, \theta_{inc}, t)$$

$$\theta_{refl} = 2\theta_B - \theta_{inc} - \pi$$



# Case 1: Constant Wave Speed (Open Domain)

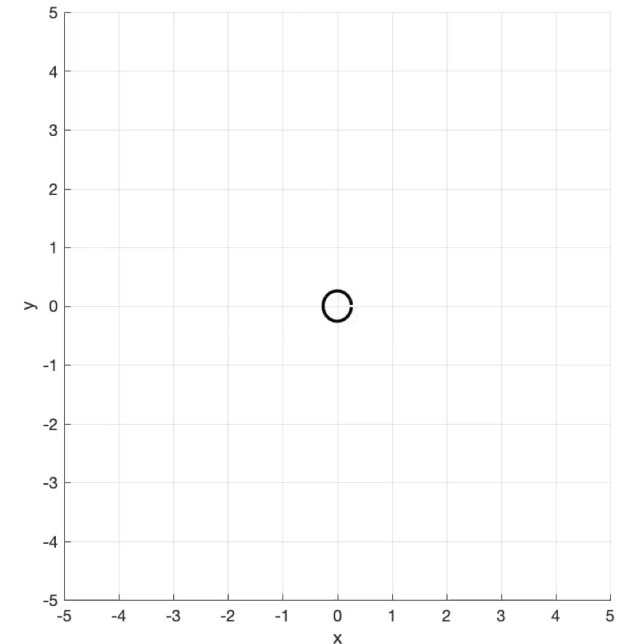
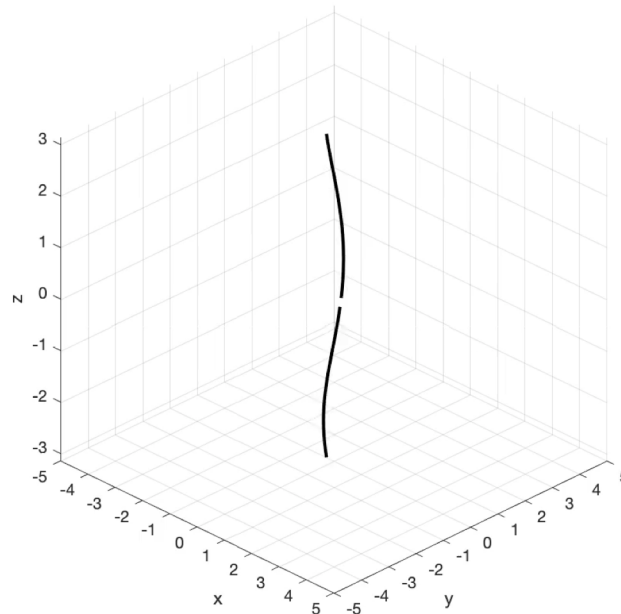
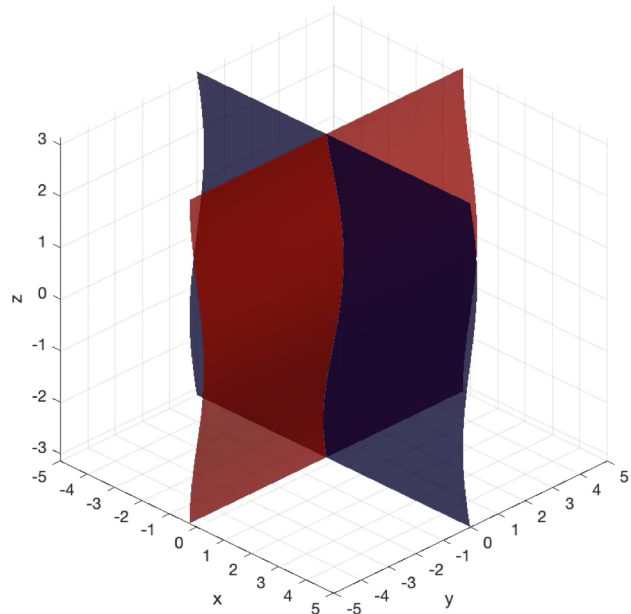
**Wave Speed:** Constant value of 1

**Spatial Discretization:**  $N_x = N_y = N_z = 40$

**Temporal Discretization:**  $t \in [0.0, 6.0]$ ,  $\Delta t = 1 * 10^{-2}$

**Time Stepping Scheme:** Forward Euler

**Spatial Derivatives Scheme:** First Order Upwind Approximation



# Case 2: Variable Wave Speed (Open Domain)

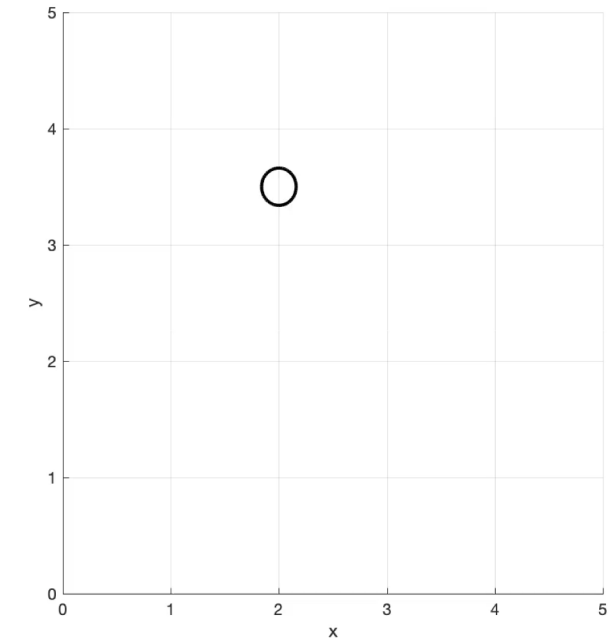
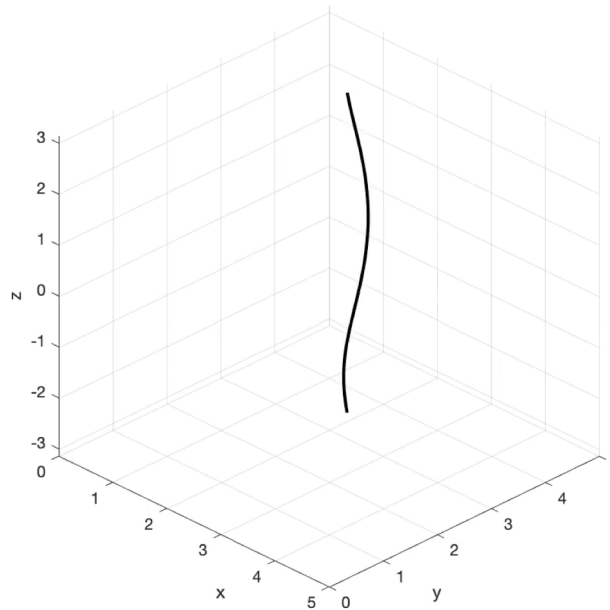
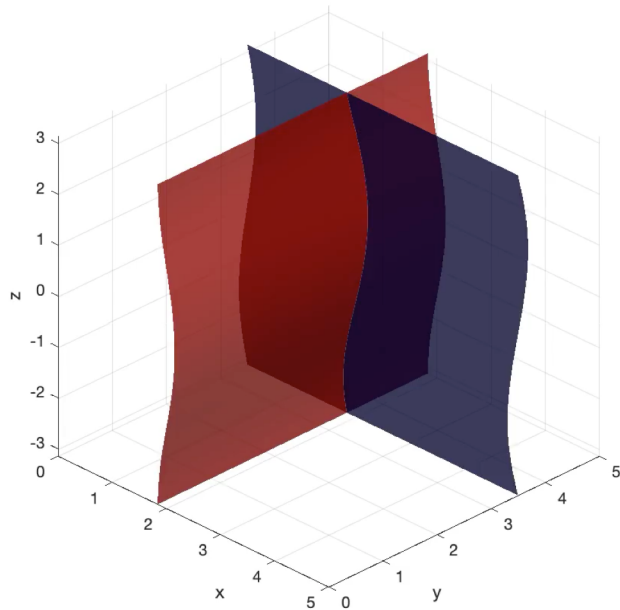
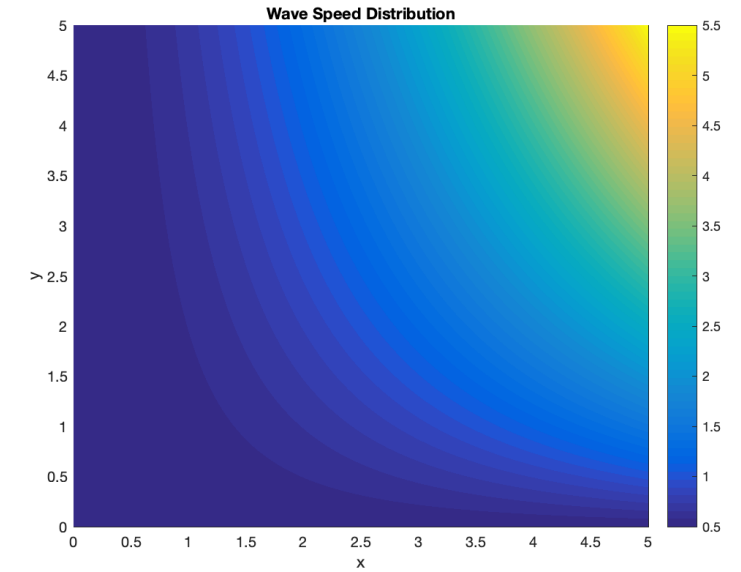
**Wave Speed:** Variable Distribution

**Spatial Discretization:**  $N_x = N_y = N_z = 50$

**Temporal Discretization:**  $t \in [0.0, 3.2]$ ,  $\Delta t = 1 * 10^{-2}$

**Time Stepping Scheme:** Second order TVD RK

**Spatial Derivatives Scheme:** Second Order Upwind Approximation



# Case 3: Constant Wave Speed (Reflecting Boundary)

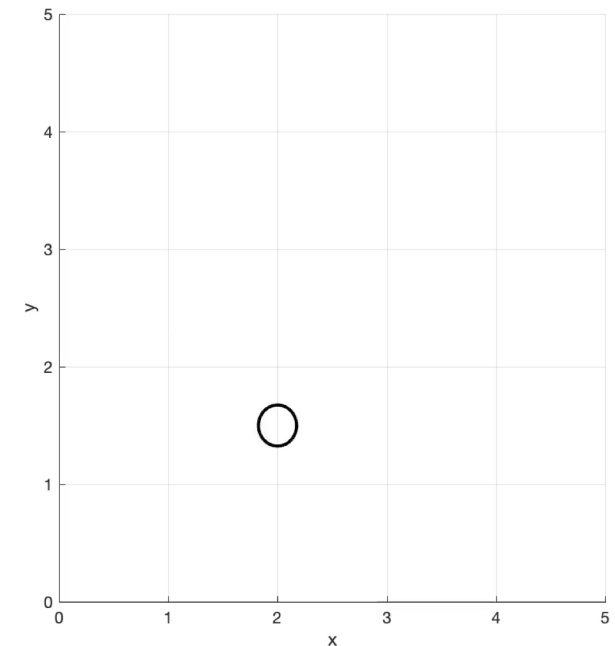
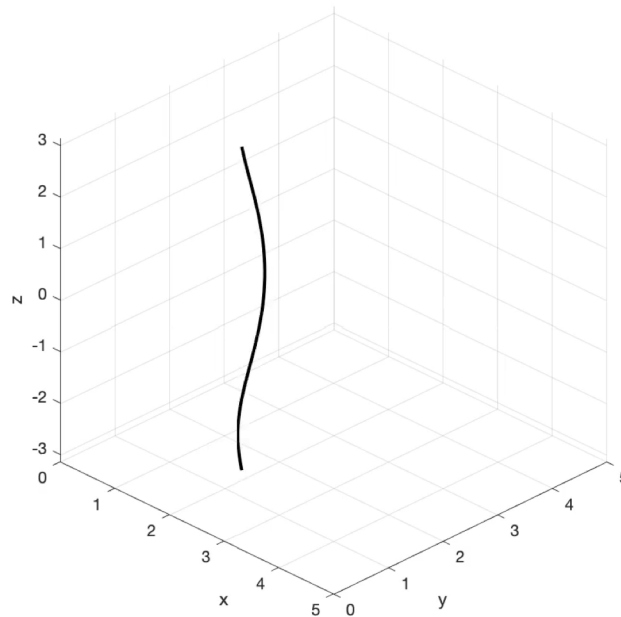
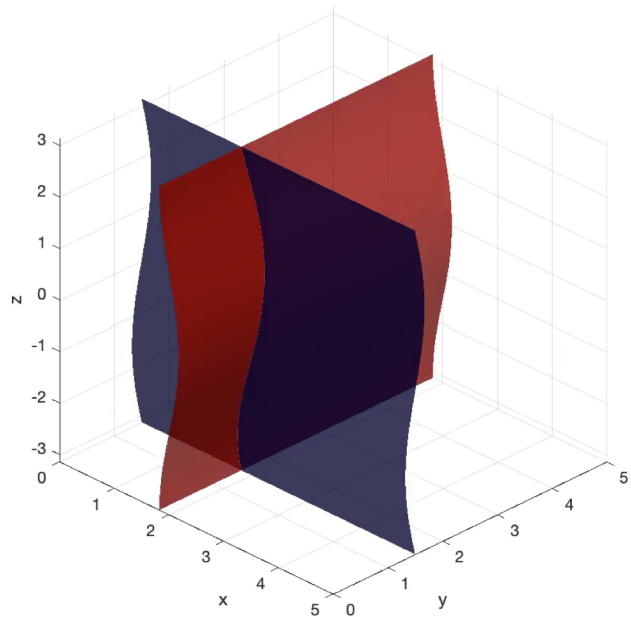
**Wave Speed:** Constant value of 2.5

**Spatial Discretization:**  $N_x = N_y = N_z = 50$

**Temporal Discretization:**  $t \in [0.0, 5.2]$ ,  $\Delta t = 1 * 10^{-2}$

**Time Stepping Scheme:** Third order TVD RK

**Spatial Derivatives Scheme:** Fifth Order Upwind Approximation  
(using WENO scheme)



# Case 4: Variable Wave Speed (Reflecting Boundary)

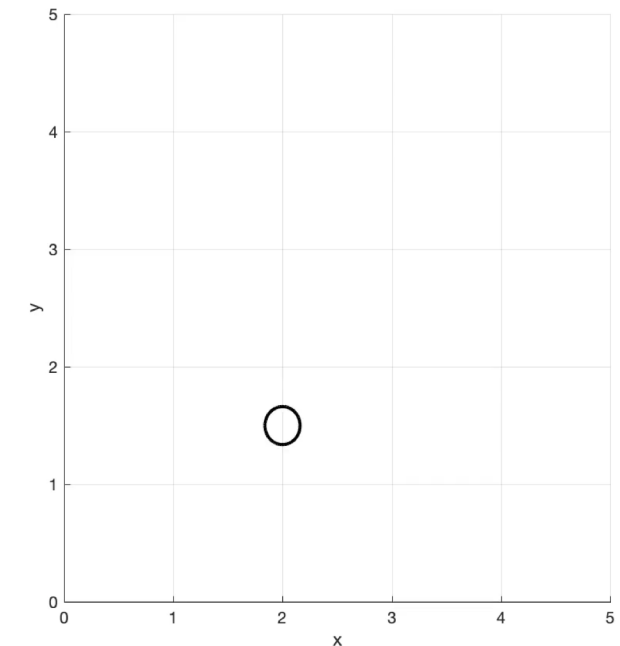
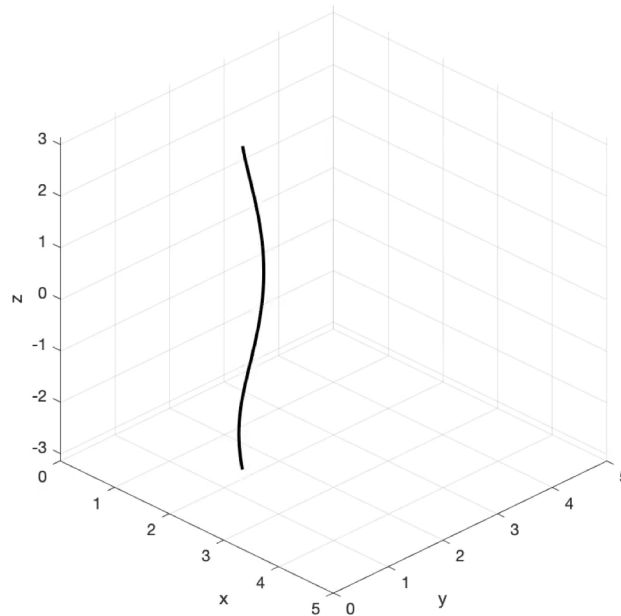
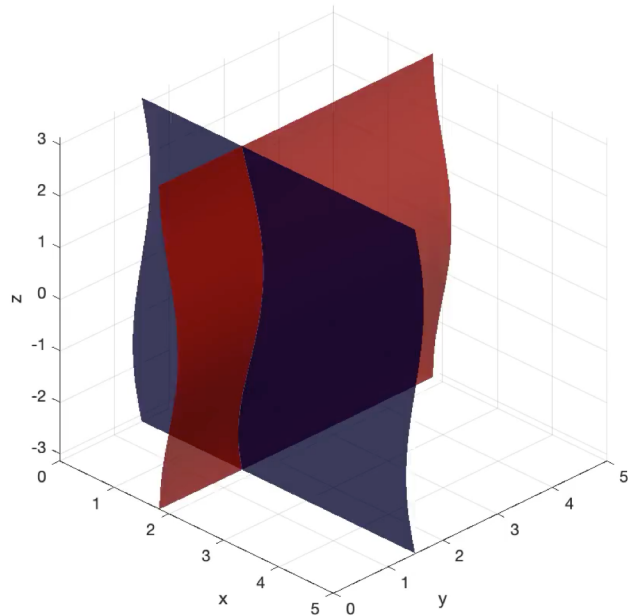
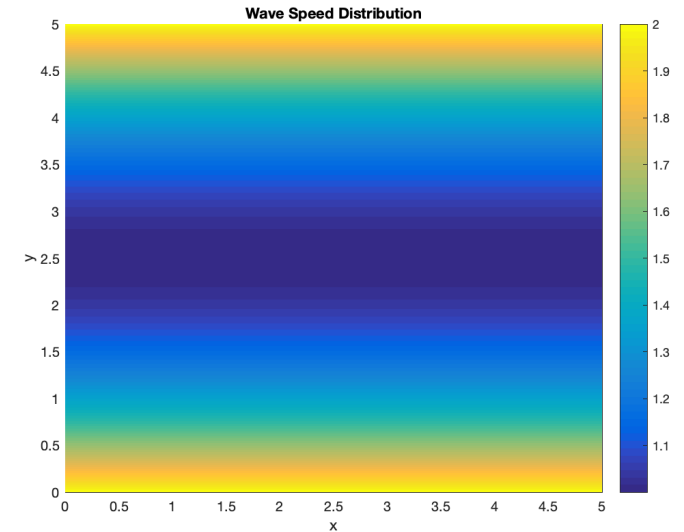
**Wave Speed:** Variable Distribution

**Spatial Discretization:**  $N_x = N_y = N_z = 50$

**Temporal Discretization:**  $t \in [0.0, 5.2]$ ,  $\Delta t = 1 * 10^{-2}$

**Time Stepping Scheme:** Third order TVD RK

**Spatial Derivatives Scheme:** Fifth Order Upwind Approximation  
(using WENO scheme)



# Conclusion

- Level set methods provide an effective approach to propagate wavefronts in an Eulerian framework relative to standard ray tracing methods.
- However, increased computational costs occurred as we are solving in a higher dimensional reduced phase space.
  - For 2D propagation, need to evolve level set implicit functions in  $\mathbb{R}^3$
  - For 3D propagation, need to evolve level set implicit functions in  $\mathbb{R}^5$
- Future Work:
  - Improve computational cost by incorporating the narrow band level set method.
  - Investigate the incorporation of schemes to compute the amplitude.

Thank You!