

MASSACHUSETTS INSTITUTE OF TECHNOLOGY
Department of Electrical Engineering and Computer Science

6.334 Power Electronics

Practice Exam A

Problem 1

Figure 1 shows the internal structure and dimensions of a power diode mounted in an axial lead package. The diode is cooled by conduction through its leads, which are soldered to terminals that are assumed to be at temperature T_A . Heat is generated at the junction of the diode, which is planar and centered between the two surfaces. The thermal resistivity of Silicon is $1.2\text{ }^\circ\text{C-cm/W}$, and the thermal resistivity of copper is $0.25\text{ }^\circ\text{C-cm/W}$.

- Draw the analog circuit model for the thermal system of Fig. 1
- If the maximum permissible junction temperature of the diode is T_J is $225\text{ }^\circ\text{C}$, determine the maximum permissible dissipation for $T_A = 75\text{ }^\circ\text{C}$.

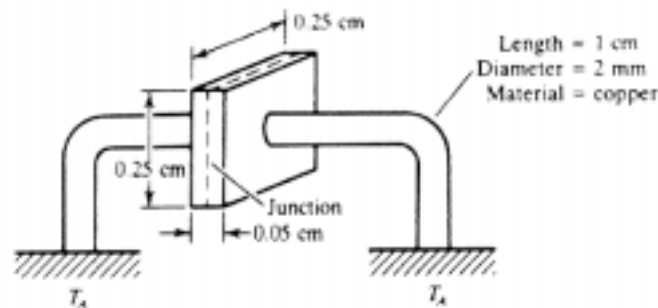


Figure 1

Problem 2

The switch S of the circuit of Fig. 2 is operated at a *constant* duty ratio D and a switching frequency f_s . At $t = 0$ the capacitor is charged to an initial voltage V_o and the inductor current is zero. Calculate and sketch the *local averages* of $i_L(t)$ and $v_C(t)$ for $t > 0$ under the assumption that $\omega f_s \gg (1-D)(LC)^{-1/2}$.

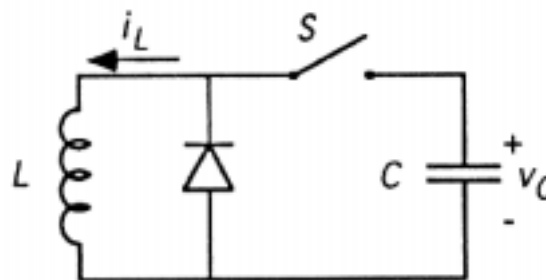


Figure 2

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Practice Exam B

Problem 1

The switch in the circuit of Fig. 1 is operated at a constant duty ratio D and a switching frequency f_s . At $t = 0$, the inductor is carrying a current I_0 and the capacitor is uncharged. The switching frequency is much higher than $(1-D)(LC)^{-0.5}$. Calculate and sketch $i_L(t)$ and $v_C(t)$ for $t > 0$.

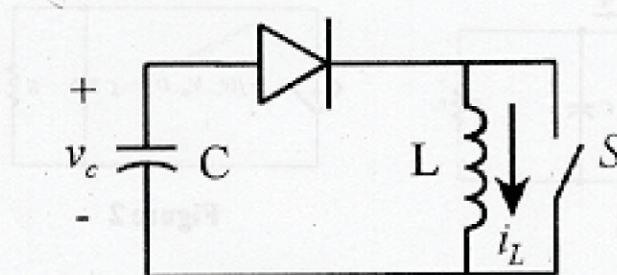


Figure 1

Problem 2

Derive an averaged model for the up/down converter of Fig. 2 under duty ratio control. You may derive such a model by either direct circuit averaging or by state space averaging. Is the model linear in terms of the control variable d ? Why or why not?

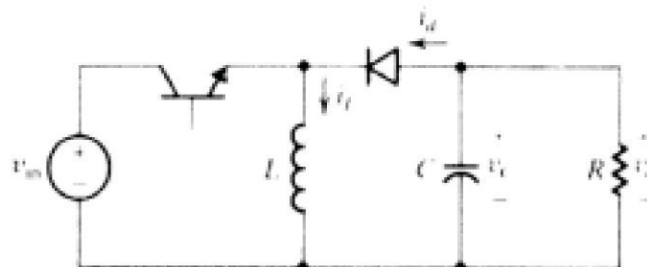


Figure 2

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Practice Exam C

Problem 1

Fig. 3 shows an input filter for a switching power converter. The current drawn by the converter is represented as i_x , and the voltage supplying the converter is v_Y . The converter switching frequency $1/T$ is 100 kHz. You may assume the filter components are ideal.

- a. Select component values L , C , and R for the filter such that
 - i. The maximum output impedance of the filter, Z_O , is 1Ω or less at all frequencies
 - ii. The filter achieves an attenuation of approximately 40 dB (a factor of 100) in current at the switching frequency. That is, $|i_Y / i_X| \approx 0.01$ at the switching frequency.
 - iii. The filter is well damped, such that it has less than 10 dB of peaking in $|i_Y / i_X|$ near the undamped natural frequency of the filter.
- b. Suppose that the load on the filter (slowly) adjusts the local average current $\langle i_X \rangle$ drawn based on the local average voltage $\langle v_X \rangle$ to maintain a constant average power draw P_O . Please find a (low-frequency) equivalent small-signal resistance r_E for this load for the operating point $P_O = 10 \text{ W}$ and $V_X = 100 \text{ V}$. Will this load greatly affect the filter damping?
- c. Please propose a simple filter modification (e.g., an addition of no more than one component) that would provide higher-order attenuation performance (and increased attenuation) at and above the switching frequency, without harming filter damping. Please specify values for any added or modified components.

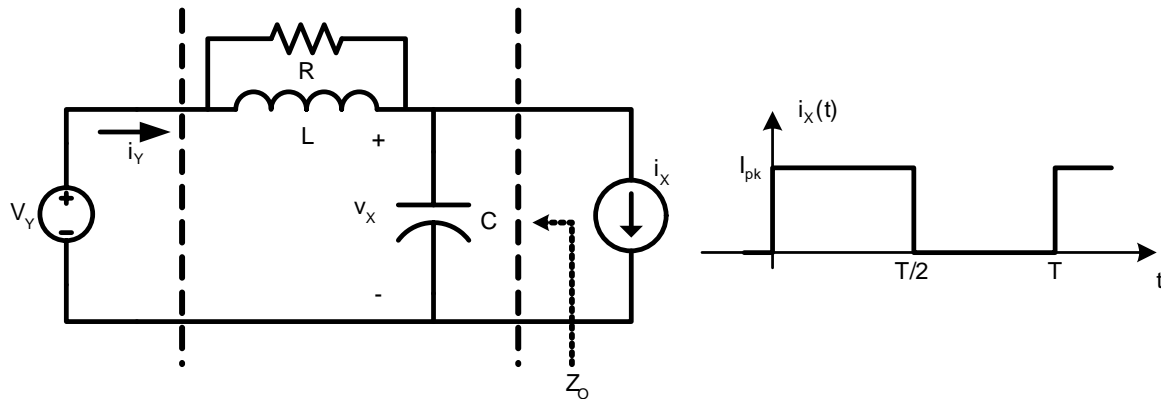


Figure 3

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Practice Exam D

Problem 1

Consider the buck/boost converter of Fig. 1 operating in the discontinuous conduction mode. (That is, operating such that the inductor current returns to zero before the end of each switching cycle.)

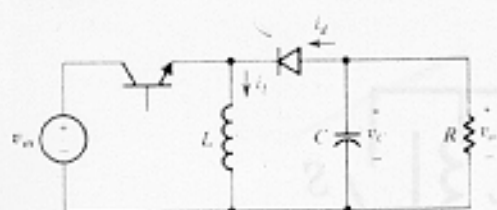


Figure 1

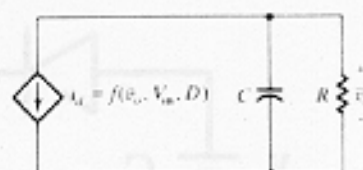
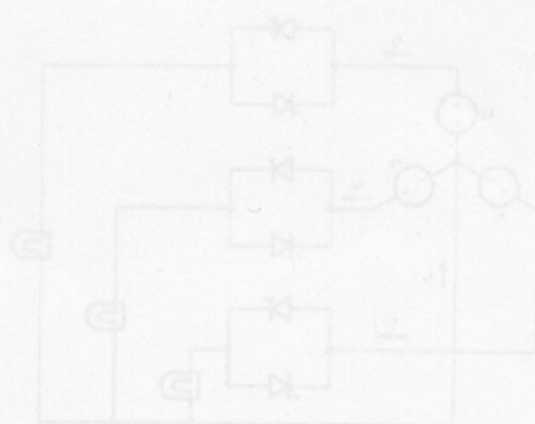


Figure 2

- Find an averaged model for the system of the form shown in Fig. 2 assuming that the inductor current and output voltage do not vary much over a switching cycle.
- Assume $R = 2$ Ohms, $C = 220$ uF, $L = 0.25$ mH, $V_{in} = 12$ V, $V_o = -9$ V. Find a linearized model for the system for perturbations in the duty ratio about this operating point, and identify the open loop pole location.

Problem 2

A double-insulated window is made of panes of glass 4 mm thick spaced 1 cm apart. Window glass has a thermal resistivity of 100 °C-cm/W, and still air has a thermal resistivity of 3050 °C-cm/W. If the interior of the building is at 25 °C, and the exterior is at 0 °C, what is the rate of heat loss by conduction through the window in kW/m²?



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Practice Exam E

Problem 1

The dc/dc converter of Figure 1 takes in an input voltage V_1 , and generates an output current I_2 . Derive an averaged model for this converter in continuous conduction under duty ratio control. You may derive such a model by either direct circuit averaging or by state space averaging, but you should express your results as a pair of state-space equations in terms of the local averages of state variables i_L and v_C .

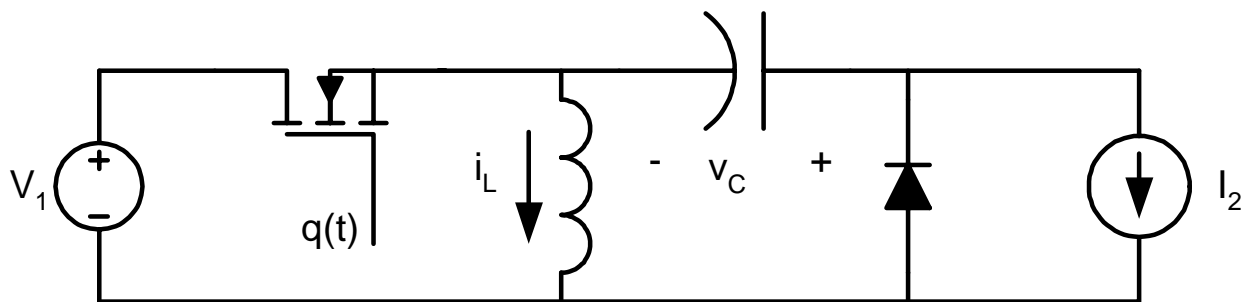


Figure 1

Problem 2

Figure 2 shows an RF power amplifier, an L-section matching network, and a resistive load.

- a. Derive an expression for the input impedance Z_{in} of the matching network and load in terms of L , C , R , and ω .
- b. Find the frequency ω for which the specified matching network components provide an impedance match between the RF amplifier and the load resistance R .
- c. Design a different L-section (2 component) matching network that will match the RF power amplifier to the load *at an operating frequency of 100 MHz*. Specify the component values to be used. (*Hint: use a "high-pass" L-section, rather than the "low-pass" L-section that is shown in Fig. 2.*)

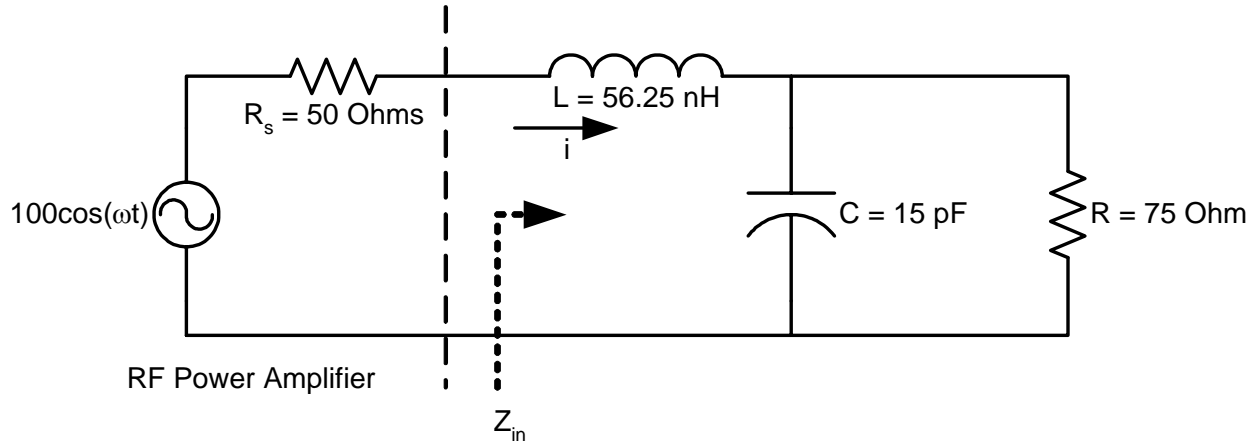


Figure 2

Problem 3

Figure 3 shows a semiconductor device mounted to a heatsink via an insulating pad. The Semiconductor device has a junction-to-case thermal resistance of $R_{\theta_{jc}} = 1.2^\circ\text{C/W}$, and the thermal insulating pad results in a case-to-sink thermal resistance of $R_{\theta_{cs}} = 0.8^\circ\text{C/W}$. The heat sink has a sink-to-ambient thermal resistance of $R_{\theta_{sa}} = 4^\circ\text{C/W}$, and a thermal capacitance $C_{\theta_s} = 70 \text{ J/}^\circ\text{C}$. The thermal capacitance of the device and thermal pad are negligible. The system operates at an ambient temperature $T_A = 100^\circ\text{C}$. We denote the semiconductor device dissipation in Watts as P_D , and the junction temperature of the device as T_j .

- Draw the thermal model for the system of Fig. 3.
- What is the largest average device dissipation P_D that is permissible if the junction temperature T_j of the device is to be kept below 175°C ?
- At startup (after being at zero dissipation for a long time), the device is subjected to a dissipation of 30 W for 0.1 s before dropping to a much lower steady-state level (below that of part B). Please calculate the peak device junction temperature reached during the startup transient for an ambient temperature $T_A = 100^\circ\text{C}$. (Note: An accuracy of 1°C is sufficient. You may make reasonable approximations as long as you justify them.)

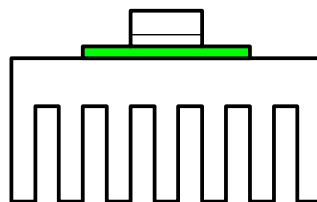
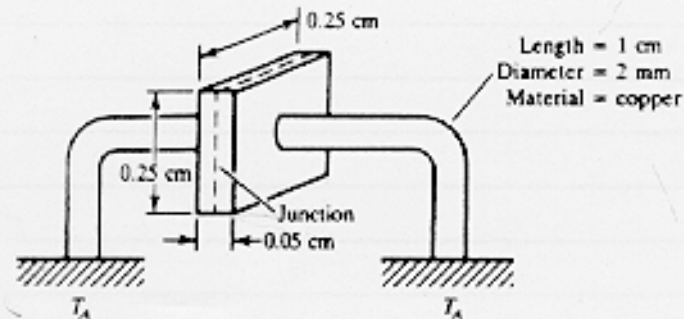


Figure 3

6.334 Practice Exam 2 - Solutions

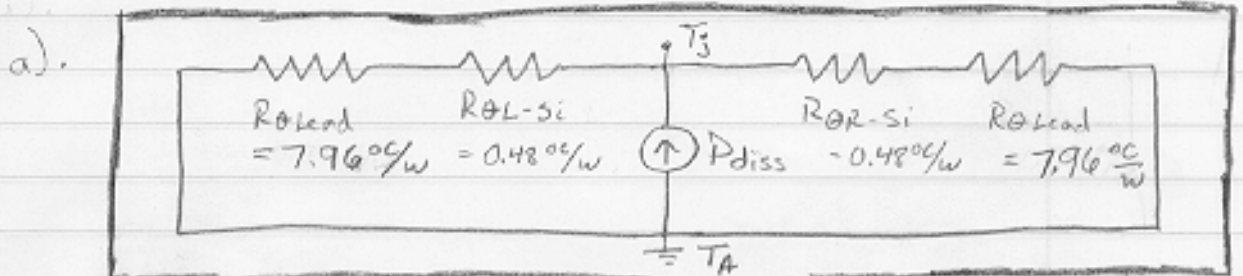
①

PA.1



$$\rho_{\text{Si}} = 1.2 \frac{\text{C-cm}}{\text{W}}$$

$$\rho_{\text{Cu}} = 0.25 \frac{\text{C-cm}}{\text{W}}$$



$$R = \frac{\rho l}{A} \Rightarrow R_{\text{L-Si}} = R_{\text{R-Si}} = \frac{(1.2)(0.025 \text{ cm})}{(\frac{0.25 \text{ cm}}{2})^2} = 0.48 \text{ } ^\circ\text{C/W}$$

$$R_{\text{Lead}} = \frac{(0.25)(1 \text{ cm})}{\pi (\frac{0.2 \text{ cm}}{2})^2} = 7.96 \text{ } ^\circ\text{C/W}$$

b). $T_{J \text{ max}} = 225 \text{ } ^\circ\text{C}$
 $T_A = 75 \text{ } ^\circ\text{C}$

KCL of analog circuit:

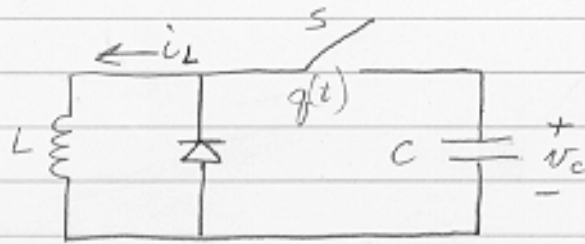
$$\frac{2(T_J - T_A)}{R_{\text{Lead}} + R_{\text{Si}}} = P_{\text{diss}}$$

$$\frac{2(225 - 75)}{7.96 \text{ } ^\circ\text{C/W} + 0.48 \text{ } ^\circ\text{C/W}} = P_{\text{diss}}$$

$$35.6 \text{ W} = P_{\text{diss}}$$

5

PA.2.



$v_C(\emptyset) = V_0$ constant duty ratio D
 $i_L(\emptyset) = \emptyset$ switching frequency f_s

Assume: $2\pi f_{sw} \gg D(LC)^{-1/2}$

Recall local average $\bar{x}(t) = \frac{1}{T} \int_{t-T}^t x(t) dt$

★ $v_L(t) = L \frac{di_L(t)}{dt} = q(t) v_C(t)$

$L \frac{d\bar{i}_L(t)}{dt} = \overline{q(t) v_C(t)} = D \bar{v}_C(t)$

★ $i_C(t) = q(t) (-i_L(t)) = C \frac{dv_C(t)}{dt}$

$-\overline{q(t) i_L(t)} = C \frac{d\bar{v}_C(t)}{dt} = -D \bar{i}_L(t)$

True as long as $v_C > 0$.

When $v_C \leq 0$, diode stays on regardless of the position of the switch.

$C \frac{d\bar{v}_C(t)}{dt} = \frac{LC}{D} \frac{d^2 \bar{i}_L(t)}{dt^2} = -D \bar{i}_L(t)$

$\frac{d^2 \bar{i}_L(t)}{dt^2} + \frac{D^2}{LC} \bar{i}_L(t) = 0$

$r^2 + \frac{D^2}{LC} = 0 \rightarrow r = \pm j \frac{D}{\sqrt{LC}}$

$\rightarrow \bar{i}_L(t) = K_1 \sin\left(\frac{D}{\sqrt{LC}} t\right) + K_2 \cos\left(\frac{D}{\sqrt{LC}} t\right)$

$\rightarrow \bar{v}_C(t) = \frac{L}{D} \frac{d\bar{i}_L(t)}{dt} = K_1 \sqrt{\frac{L}{C}} \cos\left(\frac{D}{\sqrt{LC}} t\right) - K_2 \sqrt{\frac{L}{C}} \sin\left(\frac{D}{\sqrt{LC}} t\right)$

(3)

(continued)

PA.2

$$\bar{i}_L(0) = 0 = k_1 \sin\left(\frac{D}{\sqrt{LC}}(0)\right) + k_2 \cos\left(\frac{D}{\sqrt{LC}}(0)\right) = k_2 = 0$$

$$\bar{v}_C(0) = V_0 = k_1 \sqrt{\frac{C}{L}} \cos\left(\frac{D}{\sqrt{LC}}(0)\right) \Rightarrow k_1 = V_0 \sqrt{\frac{L}{C}}$$

$$\Rightarrow \bar{i}_L(t) = V_0 \sqrt{\frac{C}{L}} \sin\left(\frac{D}{\sqrt{LC}} t\right)$$

while $\bar{v}_C(t) > 0$

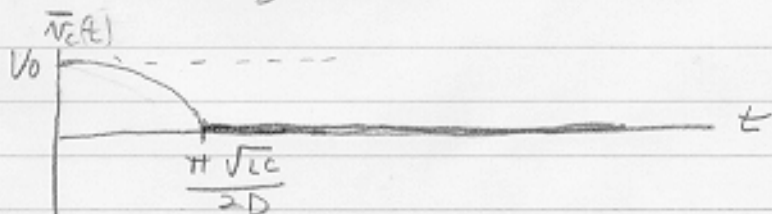
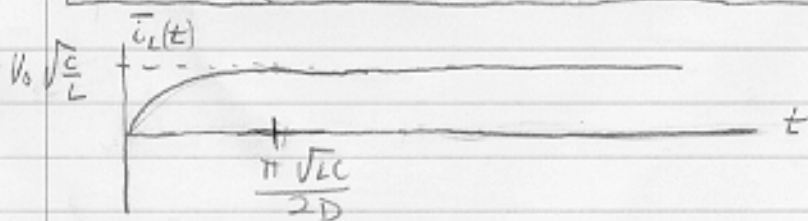
$$\Rightarrow \bar{v}_C(t) = V_0 \cos\left(\frac{D}{\sqrt{LC}} t\right)$$

$$\bar{v}_C(t) = 0 \text{ at } \frac{D}{\sqrt{LC}} t = \frac{\pi}{2} \Rightarrow t = \frac{\pi \sqrt{LC}}{2D}$$

At $t = \frac{\pi \sqrt{LC}}{2D}$, the diode clamps $D\bar{v}_C(t)$ to 0, meaning that $\bar{i}_L(t)$ remains at its peak value and $\bar{v}_C(t)$ remains at 0 forever.

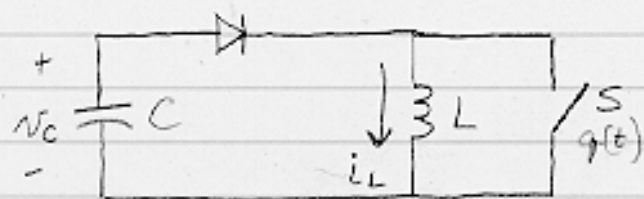
$$\bar{i}_L(t) = \begin{cases} V_0 \sqrt{\frac{C}{L}} \sin\left(\frac{D}{\sqrt{LC}} t\right) & \text{for } 0 \leq t \leq \frac{\pi \sqrt{LC}}{2D} \\ V_0 \sqrt{\frac{C}{L}} & \text{for } t > \frac{\pi \sqrt{LC}}{2D} \end{cases}$$

$$\bar{v}_C(t) = \begin{cases} V_0 \cos\left(\frac{D}{\sqrt{LC}} t\right) & \text{for } 0 \leq t \leq \frac{\pi \sqrt{LC}}{2D} \\ 0 & \text{for } t > \frac{\pi \sqrt{LC}}{2D} \end{cases}$$



6.334 Practice Exam 2 (parts C+D) - Solutions

PC.1



$i_L(\emptyset) = I_0$ constant duty ratio D
 $v_c(\emptyset) = \emptyset$ switching frequency f_s

Assume $2\pi f_{sw} \gg (1-D)(LC)^{-1/2}$

★ $v_L(t) = L \frac{di_L(t)}{dt} = v_c(t)(1-q(t))$

$L \frac{d\bar{i}_L(t)}{dt} = \overline{v_c(t)(1-q(t))} = D'\bar{v}_c(t)$

★ $i_c(t) = C \frac{dv_c(t)}{dt} = -i_L(t)(1-q(t))$

$C \frac{d\bar{v}_c(t)}{dt} = -\overline{i_L(t)(1-q(t))} = -D'\bar{i}_L(t)$

True as long as $i_L > \emptyset$.
If i_L tries to go in the opposite direction, it cannot flow through the diode.

$C \left(\frac{L}{D'} \frac{d^2 \bar{i}_L(t)}{dt^2} \right) = -D' \bar{i}_L(t)$

$\frac{d^2 \bar{i}_L(t)}{dt^2} + \frac{D'^2}{LC} \bar{i}_L(t) = \emptyset$

$r^2 + \frac{D'^2}{LC} = \emptyset \rightarrow r = \pm j \frac{D'}{\sqrt{LC}} = \pm j \frac{1-D}{\sqrt{LC}}$

$\rightarrow \bar{i}_L(t) = K_1 \sin\left(\frac{1-D}{\sqrt{LC}} t\right) + K_2 \cos\left(\frac{1-D}{\sqrt{LC}} t\right)$

$\rightarrow v_c(t) = \frac{L}{1-D} \frac{d\bar{i}_L(t)}{dt} = K_1 \sqrt{\frac{L}{C}} \cos\left(\frac{1-D}{\sqrt{LC}} t\right) - K_2 \sqrt{\frac{L}{C}} \sin\left(\frac{1-D}{\sqrt{LC}} t\right)$

(2)

(continued)

PC.1

$$\bar{i}_L(0) = I_0 = k_1 \sin\left(\frac{1-D}{\sqrt{LC}}(0)\right) + k_2 \cos\left(\frac{1-D}{\sqrt{LC}}(0)\right) \Rightarrow k_2 = I_0$$

$$\bar{v}_C(0) = 0 = k_1 \sqrt{\frac{L}{C}} \cos\left(\frac{1-D}{\sqrt{LC}}(0)\right) \Rightarrow k_1 = 0$$

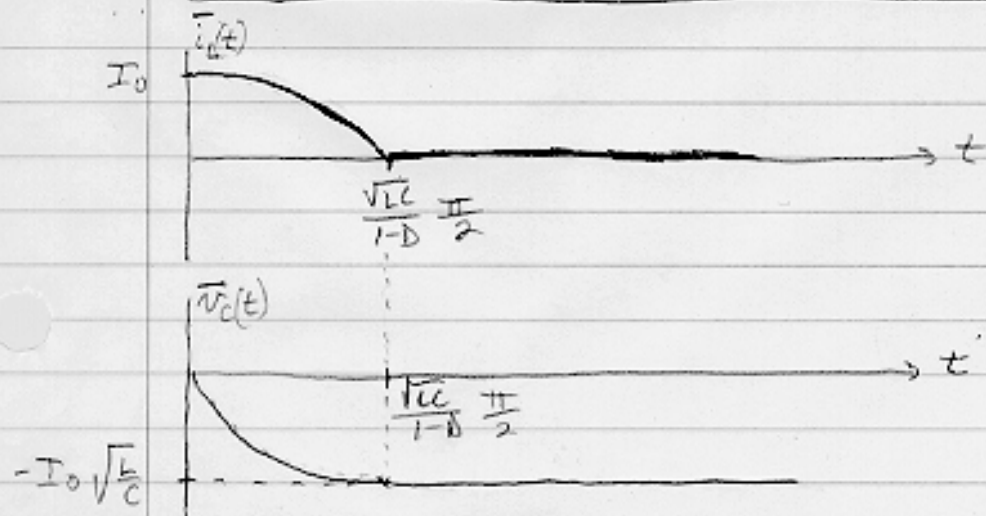
$$\Rightarrow \bar{i}_L(t) = I_0 \cos\left(\frac{1-D}{\sqrt{LC}} t\right)$$

$$\Rightarrow \bar{v}_C(t) = -I_0 \sqrt{\frac{L}{C}} \sin\left(\frac{1-D}{\sqrt{LC}} t\right)$$

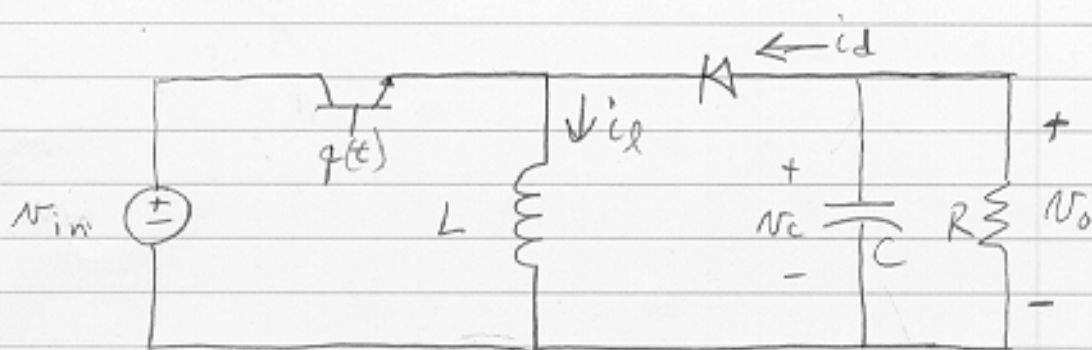
$\bar{i}_L(t) = 0$ at $t = \frac{\sqrt{LC}}{1-D} \frac{\pi}{2}$. At this time, current attempts to circulate the opposite way through the capacitor, which is impossible because of the diode. Thus, $i_L = 0$ for $t > \frac{\pi}{2} \frac{\sqrt{LC}}{1-D}$, and \bar{v}_C remains at its (negative) peak value.

$$\bar{i}_L(t) = \begin{cases} I_0 \cos\left(\frac{1-D}{\sqrt{LC}} t\right) & \text{for } 0 \leq t \leq \frac{\sqrt{LC}}{1-D} \frac{\pi}{2} \\ 0 & \text{for } t > \frac{\sqrt{LC}}{1-D} \frac{\pi}{2} \end{cases}$$

$$\bar{v}_C(t) = \begin{cases} -I_0 \sqrt{\frac{L}{C}} \sin\left(\frac{1-D}{\sqrt{LC}} t\right) & \text{for } 0 \leq t \leq \frac{\sqrt{LC}}{1-D} \frac{\pi}{2} \\ -I_0 \sqrt{\frac{L}{C}} & \text{for } t > \frac{\sqrt{LC}}{1-D} \frac{\pi}{2} \end{cases}$$



PB.2.



$$\star \frac{di_L}{dt} = \frac{v_{in}}{L} q(t) + \frac{v_o}{L} (1-q(t))$$

$$\star \frac{dv_C}{dt} = -\frac{v_o}{RC} - \frac{i_C}{C} (1-q(t))$$

$$\star \frac{d\bar{i}_L}{dt} = \frac{\bar{v}_{in}}{L} \bar{q}(t) + \frac{\bar{v}_o}{L} (1-\bar{q}(t))$$

$$(1) \quad \boxed{\frac{d\bar{i}_L}{dt} = \frac{\bar{v}_{in}}{L} d(t) + \frac{\bar{v}_o}{L} d'(t)}, \quad \text{where } \bar{q}(t) = d(t)$$

$$\star \frac{d\bar{v}_C}{dt} = -\frac{\bar{v}_o}{RC} - \frac{\bar{i}_C}{C} (1-\bar{q}(t))$$

$$(2) \quad \boxed{\frac{d\bar{v}_C}{dt} = -\frac{\bar{v}_o}{RC} - \frac{\bar{i}_C}{C} d'(t)}$$

Consider equation (1):

$$(d(t) + d'(t)) \frac{d\bar{i}_L}{dt} = \frac{\bar{v}_{in}}{L} d(t) + \frac{\bar{v}_o}{L} d'(t)$$

$$\left(\frac{d\bar{i}_L}{dt} - \frac{\bar{v}_{in}}{L} \right) d(t) = \left(\frac{\bar{v}_o}{L} - \frac{d\bar{i}_L}{dt} \right) d'(t)$$

⑦

PB.2

(continued)

$$\left(\frac{N_2}{L} \bar{i}_L - \frac{d\bar{i}_L}{dt} \right) = \frac{d(t)}{d'(t)} \left(\frac{d\bar{i}_L}{dt} - \frac{N_1}{L} \bar{i}_L \right)$$

Looks like a transformer with turns ratio

$$\frac{N_2}{N_1} = \frac{d(t)}{d'(t)} \quad \checkmark$$

Consider equation (2): By average model, we need average circuit to the left of the capacitor to provide current $-\bar{i}_L d'(t)$ to the capacitor.

If we model switch and diode together as a transformer with $N_2 = d(t)$ and $N_1 = d'(t)$, then the current through the secondary winding will be:

$$\begin{aligned} \frac{I_2}{I_1} &= \frac{N_1}{N_2} \Rightarrow I_2 = \frac{N_1}{N_2} I_1 \\ &= \frac{d'(t)}{d(t)} I_1 = -\bar{i}_L d'(t) \end{aligned}$$

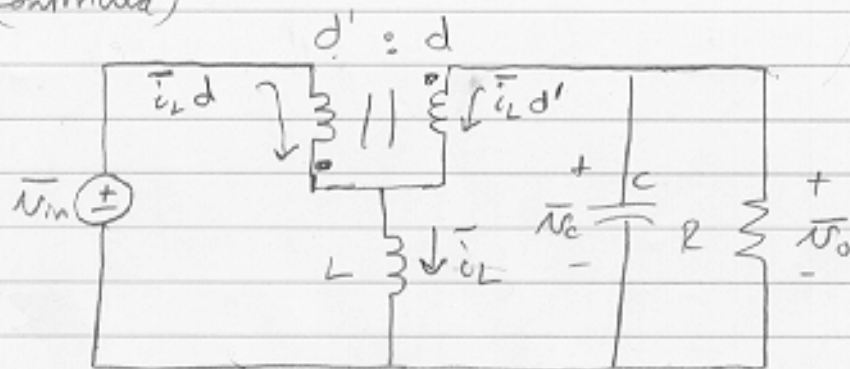
$$\text{So, } I_1 = -d(t) \bar{i}_L$$

$$\text{and } I_2 - I_1 = -\bar{i}_L d'(t) - d(t) \bar{i}_L = -\bar{i}_L \quad \checkmark$$

Thus, all of the above is consistent with an average model containing a transformer with $N_1 = d'(t)$, $N_2 = d(t)$, and whose connection between the primary and secondary sides connects to L.

PB. 2

(continued)



This model is nonlinear in terms of the control variable d , because the control d (or $d' = 1 - d$) is multiplied by the state variables \bar{i}_L and \bar{v}_o ($= \bar{v}_c$) in the two average-model state equations.

Practice Exam C.

Problem 1

a) Select L, C, R such:

$$+ |Z_o|_{\max} = 1 \Omega \quad + \left| \frac{i_y}{i_x} \right|_{\omega = \omega_0} = 0.01 \quad + \left| \frac{i_y}{i_x} \right|_{\max} = 100$$

The impedance Z_o is: $Z_o(\omega) = R // \omega L // \omega C$

$|Z_o|(\omega)$ will be maximum at resonance $\omega_0 = \frac{1}{\sqrt{LC}}$

and will be equal to $|Z_o|_{\max} = R$

Hence we want $R \leq 1 \Omega$

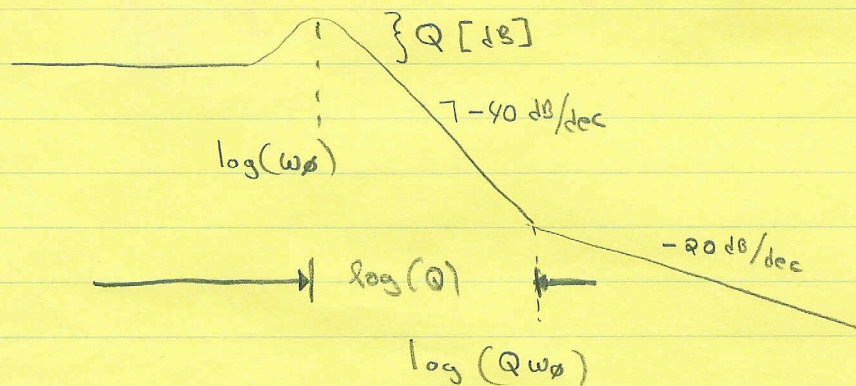
Now let's take a look at $\left| \frac{i_y}{i_x} \right|(\omega)$:

$$\frac{i_y}{i_x} = \frac{1}{sC} = \frac{1}{\frac{1}{sL} + \frac{sL}{1+s\frac{L}{R}} + \frac{s^2 LC}{1+s\frac{L}{R}}} = \frac{1}{1 + \frac{s^2 LC}{1+s\frac{L}{R}}} = \frac{1 + s\frac{L}{R}}{1 + \frac{sL}{R} + s^2 LC}$$

$$\frac{i_y}{i_x}(s) = \frac{1 + s\frac{L}{R}}{1 + \frac{s}{Q\omega_0} + \frac{s^2}{\omega_0^2}} = \frac{1 + \frac{s}{Q\omega_0}}{1 + \frac{s}{Q\omega_0} + \frac{s^2}{\omega_0^2}}$$

$$\text{where } \omega_0 = \frac{1}{\sqrt{LC}} \quad Q = R\sqrt{\frac{C}{L}}$$

The Bode Plot of $\left| \frac{iy}{ix} \right|$ is :



Hence to achieve a maximum of 10 dB peaking near ω_0 I need

$$Q = R \sqrt{\frac{C}{L}} < 3.1622 \text{ [10 dB]}$$

The attenuation at $\omega = Q\omega_0$ is

$$\left| \frac{iy}{ix} \right| \approx -40 \log(Q) \quad \text{for } Q = 3.1622$$

$$\left| \frac{iy}{ix} \right| = -20 \text{ dB}$$

Hence to achieve -40 dB attenuation at $\omega = \omega_s$ I need

$$Q\omega_0 = 0.1 \omega_s = R/L$$

$$\omega_0 = \frac{0.1 (2\pi \cdot 100k)}{3.1622} = 19.869 \times 10^3 \text{ rad/s} = \frac{1}{\sqrt{LC}}$$

with $R = 1 \Omega$

$$L = \frac{1}{0.1 (2\pi \times 100k)} = 15.9155 \mu\text{H}$$

$$\omega_0^2 = \frac{1}{LC} = \left(\frac{0.1 \omega_s}{Q} \right)^2$$

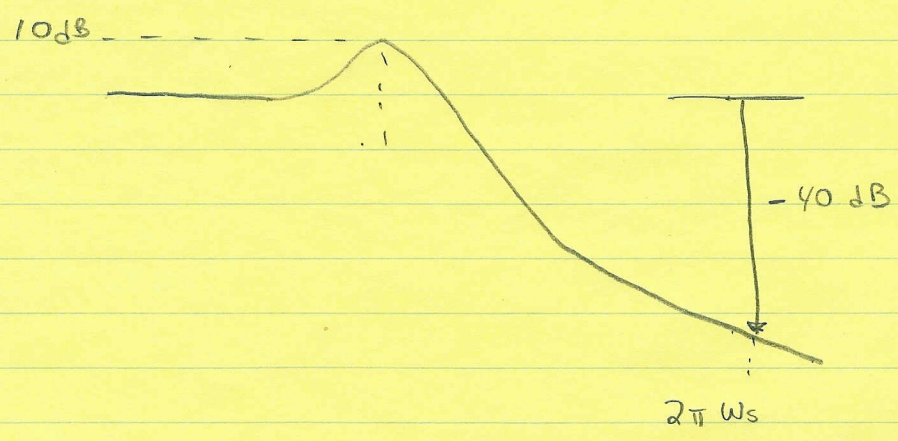
hence $C = \frac{1}{L \left[\frac{0.1 \omega_s}{Q} \right]^2} = \frac{1}{15.9155 \mu \left[\frac{0.1 \times 2 \times \pi \times 100k}{3.1622} \right]^2}$

$$C = 159.1549 \mu F$$

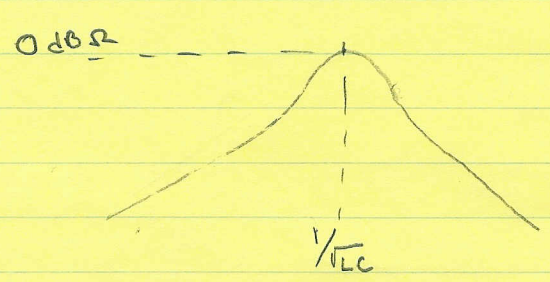
The component values for the filter are:

$$R = 1 \Omega \quad L = 15.9155 \mu H \quad C = 159.1549 \mu F$$

$\left| \frac{V_o}{V_i} \right|$



$|Z_p|$



$$b) \quad i = \frac{P_0}{v} \quad R_{eq} = \left(\frac{di}{dv} \right)_{v_x}^{-1} = - \frac{P_0}{v_x^2} \Big|_{v_x} = \left(- \frac{P_0}{v_x^2} \right)^{-1}$$

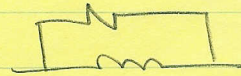
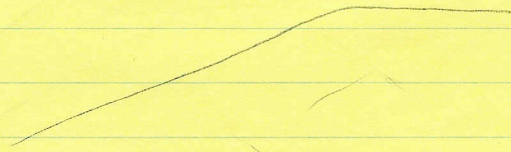
$$R_{eq} = \left(\frac{-10}{(100)^2} \right)^{-1} = - \frac{(100)^2}{10} = -1k \Omega$$

$|R_{eq}| \gg |Z_{filt}|_{max}$ hence it won't affect the filter damping

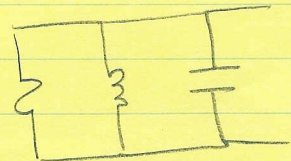
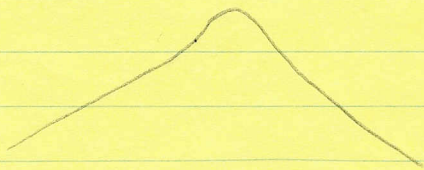
$$c) \quad \frac{i_y}{i_x} = \frac{Z_c}{Z_c + Z_{RLL}} \cdot \frac{Z_{RLL}}{Z_{RL}} = \frac{Z_c \parallel Z_{RLL}}{Z_{RL}}$$

$Z_{RLL} \approx$

R/L

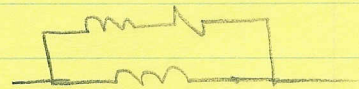
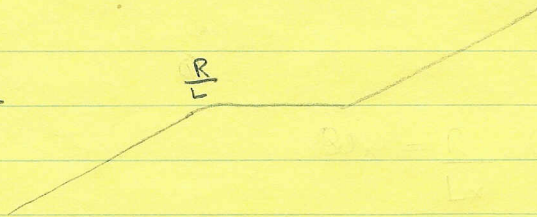


$Z_c \parallel Z_{RLL}$



Desired Z_{RLL}

R/L



$$L_x < L_2$$

(5)

PD.1

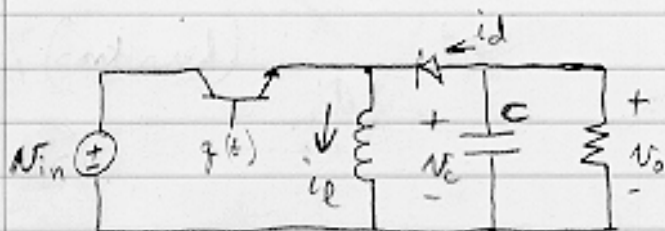


Fig 1

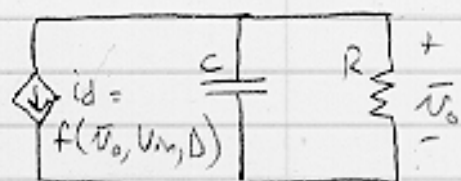
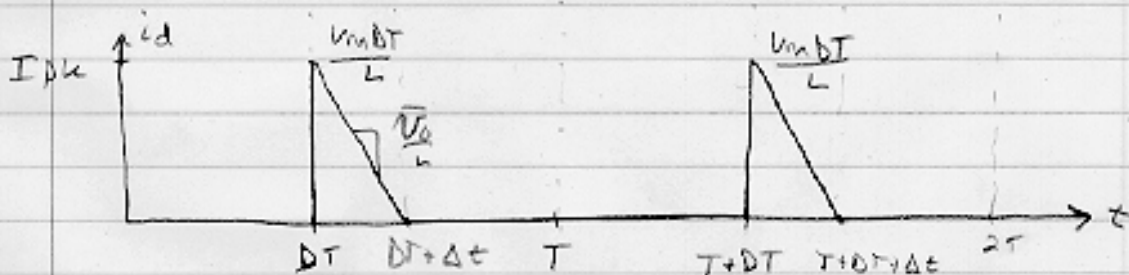
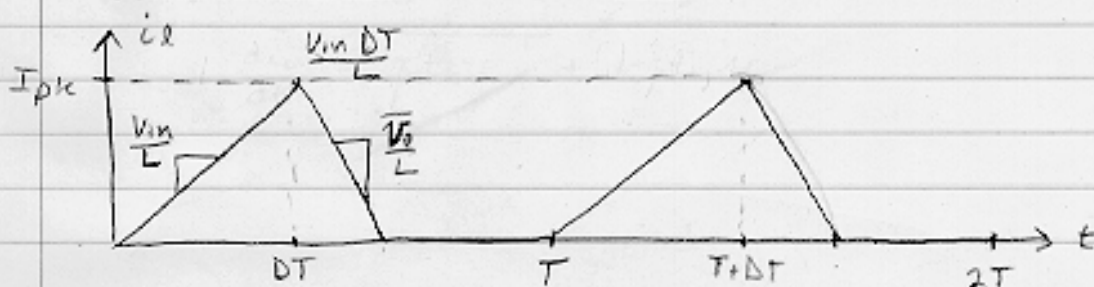


Fig 2

Discontinuous ConductionAssume constant $v_m = V_{in}$ 

$$\frac{\bar{V}_o}{L} \Delta t = \frac{V_m DT}{L} \Rightarrow \Delta t = -\frac{V_{in}}{\bar{V}_o} DT \quad (\text{since } \bar{V}_o \text{ is negative})$$

a) Find $\bar{i}_d = f(\bar{V}_o, V_{in}, D)$ geometrically

$$\bar{i}_d = \frac{1}{T} (\text{Area of triangle}) = \frac{1}{T} \left(\frac{1}{2} \right) (\text{base}) (\text{height})$$

$$= \frac{1}{2T} \left(-\frac{V_{in}}{\bar{V}_o} DT \right) \left(\frac{V_m DT}{L} \right) = \frac{-(D \cdot V_{in})^2 T}{2 \bar{V}_o L} = \bar{i}_d = f(\bar{V}_o, V_{in}, D)$$

The average model is in Figure 2.

b). $R = 2 \Omega$, $C = 220 \mu F$, $L = 0.25 \text{ mH}$, $V_{in} = 12 \text{ V}$, $V_o = -9 \text{ V}$ linearize $i_d = I_d + \tilde{i}_d$

$$V_o = V_o + \tilde{V}_o \rightarrow \tilde{V}_o = V_o - V_o$$

$$d = D + \tilde{d} \rightarrow \tilde{d} = d - D$$

(6)

(continued)

P.D.1

$$\text{Operating Point: } I_d = f(V_o, V_{in}, \Delta) = \frac{-(DV_{in})^2 T}{2V_o L}$$

First order Taylor expansion

$$i_d = I_d + \tilde{i}_d = f(V_o, V_{in}, \Delta) + \left. \frac{df}{d\Delta} \right|_{V_o, V_{in}, \Delta} \tilde{\Delta} + \left. \frac{df}{dV_o} \right|_{V_o, V_{in}, \Delta} (v_o - V_o)$$

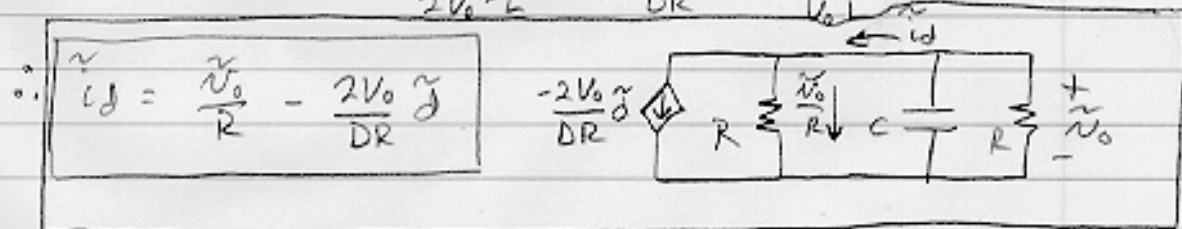
$$f_d + \tilde{i}_d = I_d - \frac{DV_{in}^2 T \gamma}{V_o L} + \frac{(DV_{in})^2 T}{2V_o^2 L} \tilde{v}_o$$

$$\tilde{i}_d = \frac{(DV_{in})^2 T}{2V_o^2 L} \tilde{v}_o - \frac{DV_{in}^2 T \gamma}{V_o L}$$

At operating point, capacitor is an open circuit.

$$\therefore I_d = \frac{-V_o}{R} = \frac{-(DV_{in})^2 T}{2V_o L} \Rightarrow R = \frac{2V_o^2 L}{(DV_{in})^2 T}$$

$$\frac{1}{R} = \frac{(DV_{in})^2 T}{2V_o^2 L} \Rightarrow \frac{2V_o}{DR} = \frac{DV_{in}^2 T}{V_o L}$$



$$\tilde{v}_o = \frac{-2V_o}{DR} \tilde{\Delta} (Z(s))$$

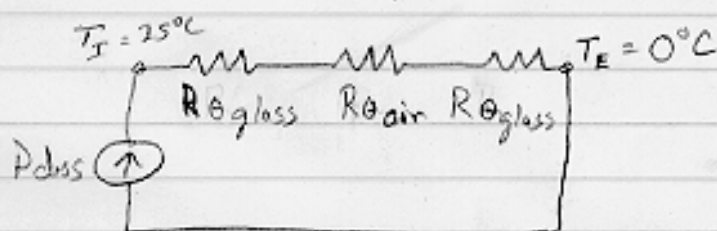
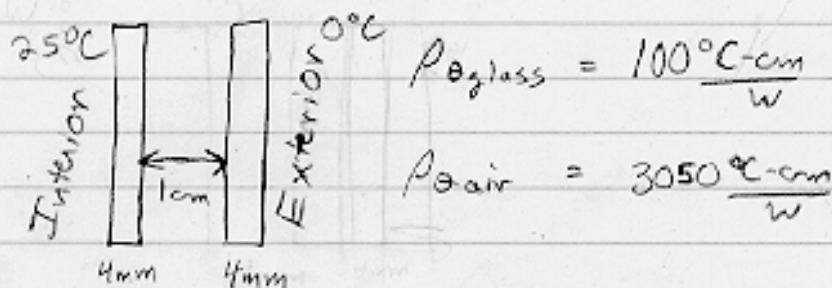
$$Z(s) = \frac{R}{\frac{1}{s}R + \frac{1}{sC}} = \frac{R}{sRC + 2}$$

$$\frac{\tilde{v}_o}{\tilde{\Delta}} = \frac{-2V_o}{DR} \frac{R}{sRC + 2} = \frac{-2V_o}{sRC + 2} = \frac{\tilde{v}_o}{\tilde{\Delta}}$$

Open loop pole is at $s = \frac{-2}{RC} = -4545.45$
Left-hand plane, so open-loop stable.

(7)

P D.2



$$R_{\text{glass}} = \frac{\rho_{\text{glass}} l}{A} = \frac{(100 \frac{^{\circ}\text{C}\cdot\text{cm}}{\text{w}})(0.4 \text{ cm})}{A \text{ cm}^2} = \frac{40^{\circ}\text{C}/\text{w}}{A}$$

$$R_{\text{air}} = \frac{\rho_{\text{air}} l}{A} = \frac{(3050 \frac{^{\circ}\text{C}\cdot\text{cm}}{\text{w}})(1 \text{ cm})}{A \text{ cm}^2} = \frac{3050^{\circ}\text{C}/\text{w}}{A}$$

$$T_I - T_E = P_{\text{diss}} (2R_{\text{glass}} + R_{\text{air}})$$

$$25^{\circ}\text{C} = P_{\text{diss}} \left(\frac{80^{\circ}\text{C}/\text{w}}{A} + \frac{3050^{\circ}\text{C}/\text{w}}{A} \right)$$

$$25^{\circ}\text{C} = P_{\text{diss}} \left(\frac{3130^{\circ}\text{C}/\text{w}}{A} \right)$$

$$P_{\text{diss}} = 0.00799 A \text{ (w)} \quad A \text{ is in cm}^2$$

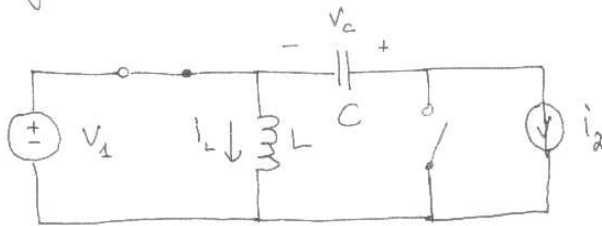
$$= 0.00000799 A \text{ (kw)}$$

$$\frac{P_{\text{diss}}}{\text{cm}^2} = 0.00000799 \frac{\text{kw}}{\text{cm}^2} \cdot \frac{(100 \text{ cm})^2}{\text{m}^2} = \boxed{0.0799 \frac{\text{kw}}{\text{m}^2}}$$

Problem 1:

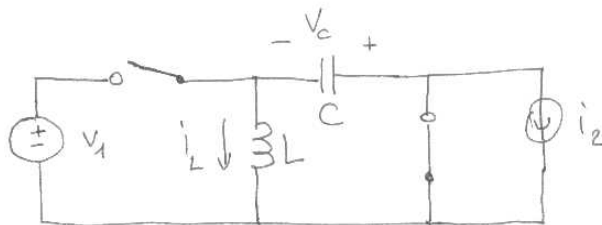
Using method of assumed states:

$q(t) = 1$



$$\begin{cases} L \frac{di_L}{dt} = V_1 \\ C \frac{dV_c}{dt} = -i_2 \end{cases}$$

$q(t) = 0$



$$\begin{cases} L \frac{di_L}{dt} = -V_c \\ C \frac{dV_c}{dt} = i_L \end{cases}$$

Averaging:

$$\begin{cases} L \frac{d\bar{i}_L}{dt} = d\bar{V}_1 - (1-d)\bar{V}_c \\ C \frac{d\bar{V}_c}{dt} = -d\bar{i}_L + (1-d)\bar{i}_L \end{cases} \quad \text{where } d = \overline{q(t)}$$

Problem 2

(a) $\boxed{Z_{in} = sL + \left(\frac{1}{sC} + R \right)}$

$= R \frac{s^2LC + \frac{L}{R}s + 1}{sRC + 1}$

$= \boxed{R \frac{(1-LC\omega^2) + j\omega \frac{L}{R}}{1 + j\omega RC}}$

(b) Separating the real and imaginary part of Z_{in} :

- 2 -

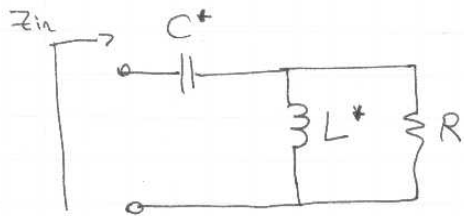
$$Z_{in} = R \frac{(1 - LC\omega^2) + j\omega \frac{L}{R}}{1 + j\omega RC} \cdot \frac{1 - j\omega RC}{1 - j\omega RC}$$
$$= \frac{R}{1 + \omega^2 R^2 C^2} + j \frac{\omega [R^2 C + R^2 C^2 L \omega^2 + L]}{1 + \omega^2 R^2 C^2}$$

Trusting the correct design of the matching network:

$$\frac{R}{1 + \omega_0^2 R^2 C^2} = R_s$$

$$\Rightarrow \boxed{\omega_0 = \frac{1}{RC} \cdot \sqrt{\frac{R}{R_s} - 1}} = \boxed{2 \cdot \pi \cdot 100 \cdot 10^3 \text{ rad/sec}}$$

(c) We will design a L-section network of the form:



The values of C^* , L^* can be easily obtained from the low-pass design by choosing these values:

$$\begin{cases} \frac{1}{sC^*} = -sL \\ sL^* = -\frac{1}{sC} \end{cases} \Rightarrow \begin{cases} C^* = \frac{1}{\omega^2 L} \\ L^* = \frac{1}{\omega^2 C} \end{cases}$$

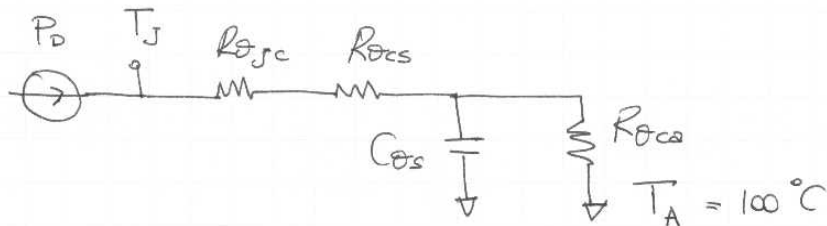
Problem

-3-

$$\therefore \begin{cases} C^* = 45.0 \text{ pF} \\ L^* = 169 \text{ nH} \end{cases}$$

Problem 3

(a)

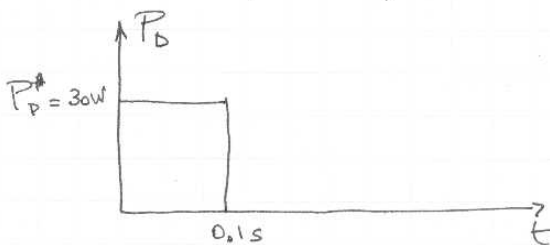


(b)

$$T_{J, \max} = 175 \text{ } ^\circ\text{C}$$

$$P_{D, \max} = \frac{T_{J, \max} - T_A}{R_{\theta_{JC}} + R_{\theta_{CS}} + R_{\theta_{CA}}} = 12.5 \text{ W}$$

(c) At startup we can assume $T_J = 0$ as well as T_s (sink temperature).



The amount of energy dissipated in this pulse is:

$$E_D = 3 \text{ J}$$

Therefore: T_s must always remain below $\frac{E_D^*}{C_{\theta S}} = 43 \text{ m}^\circ\text{C}$

Approximating: $T_J \approx P_D^* \cdot (R_{\theta JC} + R_{\theta CS}) + \frac{E_D^*}{\cos} + T_A$ -4-

$$\approx P_D^* (R_{\theta JC} + R_{\theta CS}) + T_A$$

$$= 160^\circ\text{C}$$
