## 6.946 Assignment 10

## Dennis V. Perepelitsa

29 November 2006 Gerald Jay Sussman, Jack Wisdom

### Exercise 5.1: Rotations

We have  $q = F(t, q') = Rq'$  relating the two sets of coordinates. The canonical phase-space transformation is

$$
(t, q, p) = C(t, q', p') = (t, F(t, q'), p'(\partial_1 F(t, q'))^{-1})
$$

$$
= (t, Rq', p'(\partial_1 (Rq)))^{-1}) = (t, Rq', p'R^{-1})
$$

We can be sure that  $R^{-1}$  exists and is well-defined, since the inverse of a rotation is simply rotation along the same axis but in the opposite direction. The tranformation equations for the rectangular components of the momenta are  $p = p'R^{-1}$ , as above. The transformation equations for the rectangular components of the velocities are  $v = Dq = D(Rq') = R(Dq') = Rv'$  since R is time-independent.

Thus, unsurprisingly,  $pv = (p'R^{-1})(Rv') = p'v'$ , as shown in (5.10).

### Exercise 5.4: Polar-canonical transformations

We first define this transformation:

```
(define ((p-c-transform alpha beta) H-state)
  (let ((t (time H-state))
        (theta (coordinate H-state))
        (I (momentum H-state)))
    (let ((x (* beta (expt I alpha) (sin theta)))
          (p (* beta (expt I alpha) (cos theta))))
      (up t x p))))
```
Since the transformation is time-independent, we can run the time-independent test on it.

```
(show-expression
 ((time-independent-canonical?
    (p-c-transform 'alpha 'beta)) (up 't 'theta 'I)))
```

$$
\begin{pmatrix}\n0 \\
-\alpha\beta^2 \cdot x1116 \cdot I^{(-1)+\alpha}I^{\alpha} + x1116 \\
\alpha\beta^2 \cdot x1115 \cdot I^{(-1)+\alpha}I^{\alpha} - x1115\n\end{pmatrix}
$$

The x1116 and x1115 symbols represent small, unrelated real numbers, which can be factored out. For the expression above to be a vector of zeros as desired, we require

$$
\alpha\beta^2 I^{2\alpha-1}=1
$$

When  $\alpha = \frac{1}{2}$ , the I term is constant, and we are left with  $\frac{1}{2}\beta^2 = 1$ . The solution, for arbitrary *I*, is  $\alpha = \frac{1}{2}, \ \beta = \pm \sqrt{2}.$ 

For  $\alpha \neq \frac{1}{2}$ , the only solution is when I is a constant which can be expressed in terms of  $\alpha$  and  $\beta$ :

$$
I^{2\alpha - 1} = \frac{1}{\alpha \beta^2} \Rightarrow I = \left(\frac{1}{\alpha \beta^2}\right)^{1 - 2\alpha}
$$

But in general, only  $x = \pm \sqrt{2I} \sin \theta$  and  $p = \pm \sqrt{2I} \cos \theta$  are the transformations of this form that are canonical.

# Exercise 5.5: Standard map

Since the transformation that is the standard map has no explicit time-dependence, we can test that it is a canonical transformation with the implemented time-independent-canonical? procedure.

```
(define ((standard-transform K) H-state)
 (let ((t (time H-state))
        (theta (coordinate H-state))
        (I (momentum H-state)))
    (let ((thetaprime (+ theta I (* K (sin theta))))
          (Iprime ( + I (* K (sin theta))))(up t thetaprime Iprime))))
(print-expression
```

```
((time-independent-canonical?
    (standard-transform 'K)) (up 't 'theta 'I)))
(up 0 0 0)
```
So the transformation is canonical.

## Exercise 5.14: Rotating coordinates in extended phase space

An appropriate extended phase space type-2 generating function  $F_2^e$  $P_2^e(\tau; r, \theta, t; p'_r, p'_\theta, p'_t)$  can be constructed using (5.213). This has the same relations between coordinates and momenta as the normal phase space generating function of type-2, but with an extra  $t$  term in the coordinates and  $p_t$  in the momenta. Namely, let

$$
F_2^e(\tau; r, \theta, t; p'_r, p'_\theta, p'_t) = tp'_t + F_2(t; r, \theta; p'_r, p'_\theta) = tp'_t + rp'_r + (\theta - t\Omega)p'_\theta
$$

The original momenta and the transformed coordinates are

$$
\begin{bmatrix}\np_r \\
p_\theta \\
p_t\n\end{bmatrix} = \partial_1 F_2^e(\tau; r, \theta, t; p'_r, p'_\theta, p'_t)
$$
\n
$$
\begin{bmatrix}\nr' \\
\theta' \\
t'\n\end{bmatrix} = \partial_2 F_2^e(\tau; r, \theta, t; p'_r, p'_\theta, p'_t)
$$

Now that  $t$  is a coordinate, the momentum conjugate of the time transforms, compensating for the change in the identity of  $\theta'$ :

$$
\theta' = (\partial_2 F_2^e)^2 = \theta
$$
  

$$
p_t = (\partial_1 F_2^e)_2 = p'_t - \Omega p'_\theta
$$

The latter equation also defines the difference in the Hamiltonians

$$
H'(t;r',\theta';p'_r,p'_\theta)=H(t;r,\theta;p_r,p_\theta)-(\Omega p'_\theta)
$$

Which is the same as (5.234).

### Exercise 5.19: Standard-map generating function

We attempt to find an  $F_1$  type generating function for the standard map. Such a function must satisfy

$$
I = \partial_1 F_1(t, \theta, \theta'), \quad I' = -\partial_2 F_1(t, \theta, \theta')
$$

Thus, we want to express I and I' in terms of  $\theta$  and  $\theta'$  alone. The definition of the standard map is

$$
I' = (I + K \sin \theta) \mod 2\pi
$$

$$
\theta' = (\theta + I') \mod 2\pi
$$

It immediately follows from the second equality that  $I' = \theta' - \theta$ . We have

$$
\partial_2 F_2(t, \theta, \theta') = -I'
$$

$$
\frac{d}{d\theta'} F_2 = \theta - \theta'
$$

$$
F_2 = \theta \theta' - \frac{1}{2} [\theta']^2 + \phi_2(t, \theta)
$$

Where  $\phi_2(t, \theta)$  is constant with respect to  $\theta'$ . Similarly,  $I = I' - K \sin \theta = \theta' - \theta - K \sin \theta$ .

$$
\partial_1 F_2(t, \theta, \theta') = I
$$

$$
\frac{d}{d\theta} F_2 = \theta' - \theta - K \sin \theta
$$

$$
F_2 = \theta \theta' - \frac{1}{2} \theta^2 + K \cos \theta + \phi_1(t, \theta')
$$

Again,  $\phi_1(t, \theta')$  is constant in  $\theta$ . Let  $\phi_2 = -\frac{1}{2}$  $\frac{1}{2}\theta^2 - K \cos \theta$  and  $\phi_1 = -\frac{1}{2}$  $\frac{1}{2}$  [ $\theta$ ']<sup>2</sup>. Our generating function is therefore

$$
F_2(t, \theta, \theta') = \theta \theta' - \frac{1}{2} \left( \theta^2 + \left[ \theta' \right]^2 \right) - K \cos \theta
$$