

Matrix Algebra(1) Some Basic Results

$$(A+B)' = A' + B'$$

$$(AB)C = A(BC)$$

$$A(B+C) = AB+AC$$

$$(AB)' = B'A'$$

$$(A^{-1})' = (A')^{-1}$$

$$(AB)^{-1} = B^{-1}A^{-1} \quad \text{if } B^{-1} \text{ and } A^{-1} \text{ exist}$$

$$\text{tr}(cA) = c \text{tr}(A), c \in \mathbb{R}$$

$$\text{tr}(A+B) = \text{tr}(A) + \text{tr}(B) \quad \Rightarrow \text{trace is a linear operator}$$

$$\text{tr}(A') = \text{tr}(A)$$

$$\text{tr}(AB) = \text{tr}(BA)$$

$$\det(I) = 1.$$

$$\det(cA) = c^n \det(A) \quad \text{For } A \text{ } n \times n, c \in \mathbb{R}$$

$$\det(A') = \det(A)$$

$$\det(AB) = \det(A)\det(B)$$

$$\det(A^{-1}) = [\det(A)]^{-1}$$

A^{-1} exists $\Leftrightarrow \det(A) \neq 0$ in which case A is said to be nonsingular

$$\text{rank}(A) = \text{rank}(A') = \text{rank}(A'A) = \text{rank}(AA')$$

$$\text{rank}(AB) \leq \min \{ \text{rank}(A), \text{rank}(B) \}$$

$$\text{rank}(CAB) = \text{rank}(A) \quad \text{if } C, B \text{ are nonsingular}$$

$$A^{-1} \text{ exists } \Leftrightarrow \text{rank}(A) = n \text{ For } A \text{ } n \times n$$

where

• $\text{tr}(A) = \sum_{i=1}^n a_{ii}$ For A $n \times n$ trace of a (square) matrix

• $\det(A) = \begin{cases} a_{11}a_{22} - a_{12}a_{21} & A \text{ } 2 \times 2 \\ \sum_{j=1}^n a_{ij} (-1)^{i+j} \det(A_{ij}) & A \text{ } n \times n \end{cases}$ determinant of a square matrix

where i is any row of A and A_{ij} is the matrix obtained by deleting the i th row and j th column of A

(C1) Corollary: ... rank of any matrix is the number of nonzero eigenvalues in $A'A$ (since $\text{rank}(A) = \text{rank}(A'A)$).

(T2) Theorem The nonzero eigenvalues of AA' are the same as those of $A'A$.

Proof:

Let λ be a nonzero eigenvalue of AA' with corresponding eigenvector x . Then $AA'x = \lambda x$ and since $\lambda \neq 0$ and $x \neq 0$, we know that $A'x \neq 0$ also. Premultiply by A' to get $A'A A'x = \lambda A'x$ or $A'Ay = \lambda y$ where $y = A'x \neq 0$ is now an eigenvector of $A'A$ with nonzero eigenvalue λ . We can use the same proof to show that $A'Ay = \lambda y$, $\lambda \neq 0$, $y \neq 0$ implies that $Ay \neq 0$ and hence $AA'(Ay) = \lambda Ay$ or $AA'x = \lambda x$ for $x = Ay \neq 0$. Thus every nonzero eigenvalue of AA' is a nonzero eigenvalue of $A'A$ and vice versa. //

(T3) Theorem: The trace of a symmetric matrix equals the sum of its eigenvalues

proof: $\text{tr}(A) = \text{tr}(C \Delta C') = \text{tr}(C'C \Delta) = \text{tr}(\Delta) = \sum_{i=1}^n \lambda_i$

(T4) Theorem: The determinant of a symmetric matrix equals the product of its eigenvalues

$$\det(AB) = \det(A) \det(B)$$

proof: $\det(A) = \det(C \Delta C') = \det(C) \det(\Delta) \det(C') = \det(C') \det(C) \det(\Delta) = \det(C'C) \det(\Delta) = \det(I) \det(\Delta) = \det(\Delta) = \prod \lambda_i$

(T5) Theorem For any symmetric matrix A , the eigenvalues of A^2 are the square of the eigenvalues of A and the eigenvectors are the same

Proof: $A^2 = C \Delta \underbrace{C'C}_{I} \Delta C' = C \Delta^2 C'$ and $[\Delta^2]_{ii} = \lambda_i^2$

(C5) Corollary: $A^p = C \Delta^p C'$ $p = 0, 1, 2, \dots$

(T6) Theorem: For any nonsingular symmetric matrix A , the eigenvalues of A^{-1} are the reciprocals of the eigenvalues of A and the eigenvectors are the same

proof: $A^{-1} = (C \Delta C')^{-1} = \underbrace{C'C^{-1}}_{I} \Delta^{-1} C^{-1} = C \Delta^{-1} C'$ and $[\Delta^{-1}]_{ii} = 1/\lambda_i$

(C6) Corollary: $A^p = C \Lambda^p C'$ $p \in \mathbb{Z} = \{\text{integers}\}$ for A symmetric, nonsingular

For any symmetric matrix A with strictly positive eigenvalues we define $A^r = C \Lambda^r C'$ $\forall r \in \mathbb{R}$. If A has nonnegative eigenvalues then A^r is defined similarly but only for $r \in \mathbb{R}^+$.

Let A be an $n \times n$ matrix. Then A is idempotent if $A^2 = A$. Note that this implies that $A^p = A$ for any $p = 1, 2, \dots$

(T7) Theorem: The eigenvalues of any symmetric, idempotent matrix A are either 0 or 1.

proof:

Let λ be an eigenvalue of A with eigenvector x . Then by an earlier theorem λ^2 is an eigenvalue of A^2 , also having eigenvector x . Thus, we have $\lambda x = Ax = A^2 x = \lambda^2 x \Rightarrow \lambda = \lambda^2$ since $x \neq 0$
 $\Rightarrow \lambda \in \{0, 1\}$.

(T8) Theorem: The only full rank, symmetric, idempotent matrix is the identity matrix.

proof:

Let A be an $n \times n$ symmetric, idempotent matrix. Then $\text{rank}(A) = n \Leftrightarrow \det(A) \neq 0$. But from an earlier theorem $\det(A) = \prod_{i=1}^n \lambda_i \neq 0 \Leftrightarrow \lambda_i \neq 0 \Leftrightarrow \lambda_i = 1 \forall i \Leftrightarrow \Lambda = I$. Hence $\text{rank}(A) = n \Leftrightarrow A = C I C' = C C' = I$.

(C8) Corollary: All symmetric idempotent matrices except the identity matrix are singular

(T9) Theorem: The rank of a symmetric idempotent matrix equals its trace.
 $\text{rank } A = \text{tr } A$ A -sym, idempotent

proof:

$\text{tr}(A) = \sum_{i=1}^n \lambda_i = \# \text{ of nonzero eigenvalues of } A \text{ (since } \lambda_i \in \{0, 1\}) = \text{rank}(A)$

$\text{tr}(A) = \text{tr}(C \Lambda C')$

$\text{rank}(C \Lambda C') = \text{rank } \Lambda$

$$\Lambda = \begin{bmatrix} \lambda_1 & & 0 \\ & \ddots & \\ 0 & & 0 \end{bmatrix}$$

(T10) Cholesky Factorization. Any symmetric matrix A with positive eigenvalues can be written as the product of a lower triangular matrix L and its transpose (which is upper triangular) $L' = U'$:

$$A = LL' = LU = U'U \quad \Rightarrow \quad A^{-1} = (L')^{-1}L^{-1} = U^{-1}L^{-1} = U^{-1}(U')^{-1}$$

where L' is lower triangular and U' is upper triangular (check for 2×2 case).

(3) Quadratic Forms and Definite Matrices

A quadratic form in the $n \times n$ matrix A and $n \times 1$ vector x is the scalar $x'Ax$.

A is	<u>Negative Definite</u> (ND)	if	$x'Ax < 0$	$\forall x \neq 0$
"	<u>Negative Semi-Definite</u> (NSD)	"	≤ 0	"
"	<u>Positive Semi-Definite</u> (PSD)	"	≥ 0	"
"	<u>Positive Definite</u> (PD)	"	> 0	"

(T11) Theorem: Let A be a symmetric matrix. Then

- (1) A is PD (ND) $\Leftrightarrow \lambda_i > 0$ (< 0) \forall eigenvalues λ_i of A
 (2) A is PSD (NSD) $\Leftrightarrow \lambda_i \geq 0$ (≤ 0) \forall eigenvalues λ_i of A

Proof:

where $A = C\Lambda C'$

\Rightarrow

For each $i=1, \dots, n$ let $x^i = Ce^i$ where $e_i^i = 1$ and $e_j^i = 0$ $j \neq i$. Then $\forall i$, $x^{i'}Ax^i = e^{i'}C'CAC'e^i = e^{i'}\Lambda e^i = \lambda_i$ and so we have A PD (PSD, NSD, ND) $\Rightarrow 0 < (\leq, \geq, >) x^{i'}Ax^i = \lambda_i \forall i$.

\Leftarrow

Suppose that $\lambda_i > 0$ and $\lambda_j < 0$ \Rightarrow can be p.d. for some i, j and wlog assume $i=1, j=2$. Since C' is nonsingular we can find an $x \neq 0$ such that $C'x = (y_1, y_2, 0, \dots, 0)'$. For any choice of y_1 and y_2 such that $y \neq 0$ (Specifically, $x = Cy \neq 0$ since C nonsingular and $y \neq 0$), in which case $x'Ax = \lambda_1 y_1^2 + \lambda_2 y_2^2$, which can be made positive or negative by choosing (y_1, y_2) appropriately. Thus, if $\{\lambda\}$ violate any of the conditions of the theorem it is impossible for $x'Ax$ to be of one

sign $\forall x \neq 0$.

$\forall x \neq 0 \quad y = C'x \neq 0$

$x'Ax = x'CAC'x = y'\Lambda y = \sum \lambda_i y_i^2$

if $\lambda_i > 0 \Rightarrow x'Ax > 0$
 $\lambda_i \geq 0 \Rightarrow \geq 0$
 $\lambda_i < 0 \Rightarrow < 0$

Some More Results

- (T12) $\left\{ \begin{array}{l} A \text{ symmetric PD (PSD, NSD, ND)} \Rightarrow \det(A) > 0 \text{ (}\geq 0, \leq 0, < 0\text{)} \\ A \text{ symmetric PD (ND)} \Leftrightarrow A^{-1} \text{ symmetric PD (ND)} \quad (x^T = \frac{1}{x}) \\ \text{The Identity matrix is PD} \\ \text{Every symmetric, idempotent matrix is PSD} \end{array} \right.$

(T13) Theorem: IF A is $n \times k$ w/ $n > k$ and $\text{rank}(A) = k$ then $A'A$ is PD $k \times k$ and AA' is PSD $n \times n$.

Proof:

$\text{rank}(A) = k \Rightarrow$ columns of A are linearly independent $\Rightarrow Ax \neq 0$ if $x \neq 0$ (Ax is a linear combination of the columns of A). Thus, we have $x'A'Ax = (Ax)'(Ax) > 0$ since $Ax \neq 0$. Also, we see that $y'A'A'y = (A'y)'(A'y) \geq 0$ since $\text{rank}(A') = \text{rank}(A) = k < n = \#$ of columns in A' implies that $Ay = 0$ for some $y \neq 0$.

(T14) Theorem: IF A is PD and B is nonsingular then $B'AB$ is PD

proof:

$x'B'ABx = (Bx)'A(Bx) > 0$ since $x \neq 0$ and B nonsingular $\Rightarrow Bx \neq 0$ and since A is PD.

We say that a square matrix A is bigger than another matrix B of the same dimension if $A - B$ is PSD. Notationally we write

$$A > (\geq) B \Leftrightarrow A - B \text{ is PD (PSD)} \Leftrightarrow x'Ax > (\geq) x'Bx \quad \forall x \neq 0.$$

(T15) Theorem: Let A and B be symmetric, PD matrices. Then $A - B$ is PD (PSD) $\Leftrightarrow B^{-1} - A^{-1}$ is PD (PSD) (Sorry, no proof)

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Appendix

(4) Kronecker Products: (will show up when we do panel data models)

$$\begin{array}{l}
 A: m \times n \\
 B: p \times q
 \end{array}
 \quad
 A \otimes B \equiv \begin{bmatrix} a_{11}B & \dots & a_{1n}B \\ \vdots & \dots & \vdots \\ a_{m1}B & \dots & a_{mn}B \end{bmatrix} : mp \times nq$$

So $m \times n \otimes p \times q = mp \times nq$. Some properties of Kronecker products are:

(116) $\left\{ \begin{array}{l} (A \otimes B)(C \otimes D) = (AC) \otimes (BD) \quad \text{assuming conformable dimensions} \\ (A \otimes B)^{-1} = A^{-1} \otimes B^{-1} \quad \text{for } A, B \text{ invertible} \\ (A \otimes B)' = A' \otimes B' \\ (A \otimes B) \text{ is symmetric when } A \text{ and } B \text{ are symmetric} \\ \det(A \otimes B) = [\det(A)]^m [\det(B)]^p \quad \text{for } A \text{ } m \times m \text{ and } B \text{ } p \times p \\ \text{tr}(A \otimes B) = \text{tr}(A)\text{tr}(B) \quad (\text{not true for "normal" product}) \end{array} \right.$

(5) Some Special Symmetric Idempotent Matrices

Let X be an $n \times k$ matrix with $n > k$ and $\text{rank}(X) = k$. Since the $k \times k$ matrix $X'X$ has $\text{rank}(X'X) = \text{rank}(X) = k$, we know that it is invertible. In fact we know from an earlier theorem that it is PD. We can therefore define the following matrices.

$$P \equiv X(X'X)^{-1}X' \quad \text{and} \quad Q \equiv I - X(X'X)^{-1}X' = I - P$$

Claim: P and Q are symmetric, idempotent and $PX = X$, $QX = 0$, $PQ = QP = 0$
 \Rightarrow psd

proof:

Symmetry of P is obvious

$$P^2 = X(X'X)^{-1}X'X(X'X)^{-1}X' = X(X'X)^{-1}X' = P$$

$$Q' = (I - P)' = I - P' = I - P = Q$$

$$Q^2 = (I - P)(I - P) = I - P - P + P^2 = I - P = Q$$

$$PX = X(X'X)^{-1}X'X = X$$

$$QX = (I - P)X = X - PX = X - X = 0$$

$$PQ = P(I - P) = P - P^2 = 0 = P - P^2 = (I - P)P = QP //$$

Now let y be an $n \times 1$ vector and observe that we can write

$$y = Py + (I - P)y = Py + Qy = \hat{y} + \hat{e} \quad \hat{y} = Py, \quad \hat{e} = Qy$$

How should we interpret \hat{y} and \hat{e} ? To help with this observe the following:

• $\hat{e}'x = (Qy)'x = y'Qx = 0 \Rightarrow \hat{e}$ is orthogonal to each column of X (since $\hat{e}'x = [\hat{e}'x_1 \quad \hat{e}'x_2 \quad \dots \quad \hat{e}'x_k]$ where x_j is the j th column of X) and so is contained in the subspace of \mathbb{R}^n which is orthogonal to the space spanned by the columns of X . This offers us the following interpretation of Q

Q projects $n \times 1$ vectors onto the subspace of \mathbb{R}^n which is orthogonal to the k -dimensional linear subspace spanned by the columns of X .

• $\hat{y} = Py = X(X'X)^{-1}X'y = Xb = x_1b_1 + \dots + x_kb_k$ where $b = (X'X)^{-1}X'y$ ($k \times 1$) and again x_j is the j th column of X . Thus, \hat{y} is just a linear combination of the columns of X and so is contained in the linear subspace of \mathbb{R}^n spanned by those columns. Hence

P projects $n \times 1$ vectors onto the k -dimensional linear subspace of \mathbb{R}^n spanned by the columns of X .

• $\hat{y}'\hat{e} = (Py)'Qy = y'PQy = 0 \Rightarrow \hat{y}$ and \hat{e} are orthogonal.

Thus, P and Q allow us to write y as the sum of two orthogonal components, \hat{y} and \hat{e} , the first contained in the linear subspace of \mathbb{R}^n spanned by the columns of X and the second contained in the subspace orthogonal to that. In essence what we have done is divide y into a component which can be represented as a linear function of the columns of X (\hat{y}) and a component which cannot (\hat{e}).

$$P_0 = \frac{1}{n} \mathbf{1}\mathbf{1}' = \frac{1}{n} \begin{bmatrix} 1 & & \\ & \ddots & \\ & & 1 \end{bmatrix}_{n \times n}$$

(E1) Ex:

Let \mathbf{c} be an $n \times 1$ vector of 1's and define $P_0 = \mathbf{c}(\mathbf{c}'\mathbf{c})^{-1}\mathbf{c}'$ $Q_0 = \mathbf{I} - P_0$

$$P_0 \mathbf{y} = \mathbf{c}(\mathbf{c}'\mathbf{c})^{-1}\mathbf{c}'\mathbf{y} = \mathbf{c}(\mathbf{1}'\mathbf{y}/n) = \bar{y}\mathbf{c}$$

$$Q_0 \mathbf{y} = \mathbf{y} - P_0 \mathbf{y} = \mathbf{y} - \bar{y}\mathbf{c} \leftarrow \mathbf{y} \text{ in deviation from means form}$$

Thus, the projection of \mathbf{y} onto the 1-dimensional space spanned by \mathbf{c} is its mean, \bar{y} , and the component orthogonal to that projection is the deviations from this mean, $\mathbf{y} - \bar{y}\mathbf{c}$. Further,

$$\mathbf{y}' Q_0 \mathbf{y} = \mathbf{y}' Q_0' Q_0 \mathbf{y} = (Q_0 \mathbf{y})'(Q_0 \mathbf{y}) = (\mathbf{y} - \bar{y}\mathbf{c})'(\mathbf{y} - \bar{y}\mathbf{c}) = \sum_{i=1}^n (y_i - \bar{y})^2$$

is the sum of squared deviations from the mean.

(6) Partitioned Matrices

$$A = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} \quad B = \begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} \quad \text{are partitioned matrices w/ partitions } A_{ij} \text{ } A_{ji}$$

Note: A_{ij} and B_{ij} are unrelated to the minors A_{ij} used in defining the determinant and inverse of a square matrix

$$A + B = \begin{bmatrix} A_{11} + B_{11} & A_{12} + B_{12} \\ A_{21} + B_{21} & A_{22} + B_{22} \end{bmatrix} \quad \text{for conformably partitioned } A, B$$

$$AB = \begin{bmatrix} A_{11}B_{11} + A_{12}B_{21} & A_{11}B_{12} + A_{12}B_{22} \\ A_{21}B_{11} + A_{22}B_{21} & A_{21}B_{12} + A_{22}B_{22} \end{bmatrix} \quad \text{for conformably partitioned } A, B$$

$$A' = \begin{bmatrix} A'_{11} & A'_{21} \\ A'_{12} & A'_{22} \end{bmatrix}$$

(E2) Ex:

Let X be an $n \times k$ matrix and let X'_i be the $1 \times k$ vector representing the i th row of X and X_i its $k \times 1$ transpose. Then,

$$X = \begin{bmatrix} X'_1 \\ \vdots \\ X'_n \end{bmatrix} \Rightarrow X'X = \begin{bmatrix} X'_1 \\ \vdots \\ X'_n \end{bmatrix}' \begin{bmatrix} X'_1 \\ \vdots \\ X'_n \end{bmatrix} = [X_1 \quad \dots \quad X_n] \begin{bmatrix} X'_1 \\ \vdots \\ X'_n \end{bmatrix} = \sum_{i=1}^n X_i X'_i$$

(E3) Ex:

Let X be $n \times k$ again but this time let X_1 be the $n \times k_1$ matrix

Containing the first k_1 columns of X and let X_2 be the $n \times k_2$ matrix containing the last k_2 columns of X where $k_1 < n$ and $k_1 + k_2 = n$. Then,

$$X = [X_1 \ X_2] \Rightarrow X'X = [X_1 \ X_2]' [X_1 \ X_2] = \begin{bmatrix} X_1' \\ X_2' \end{bmatrix} [X_1 \ X_2] = \begin{bmatrix} X_1'X_1 & X_1'X_2 \\ X_2'X_1 & X_2'X_2 \end{bmatrix}$$

(T17) Theorem: Let A be an invertible matrix partitioned into 4 submatrices w/ A_{ii} invertible $i=1, 2$. Then:

$$A^{-1} = \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix}^{-1} = \begin{bmatrix} F_1 & -F_1 A_{12} A_{22}^{-1} \\ -F_2 A_{21} A_{11}^{-1} & F_2 \end{bmatrix} = \begin{bmatrix} F_1 & -A_{11}^{-1} A_{12} F_2 \\ -A_{22}^{-1} A_{21} F_1 & F_2 \end{bmatrix}$$

where $F_1 = [A_{11} - A_{12} A_{22}^{-1} A_{21}]^{-1}$ and $F_2 = [A_{22} - A_{21} A_{11}^{-1} A_{12}]^{-1}$

Proof:

Let $B = A^{-1}$ be conformably partitioned. Then $BA = AB = I$ and we have

$$\begin{bmatrix} B_{11} & B_{12} \\ B_{21} & B_{22} \end{bmatrix} \begin{bmatrix} A_{11} & A_{12} \\ A_{21} & A_{22} \end{bmatrix} = \begin{bmatrix} I & 0 \\ 0 & I \end{bmatrix}$$

$$\begin{aligned} F_2 A_{22} A_{22}^{-1} &= A_{22}^{-1} A_{22} F_2 \\ A_{11} A_{22}^{-1} (A_{11} - A_{21} A_{22}^{-1} A_{12}) &= (A_{11} - A_{21} A_{22}^{-1} A_{12}) A_{22}^{-1} A_{22} \\ A_{12} - A_{21} A_{22}^{-1} A_{22} A_{12} &= \dots \quad (\text{use}) \end{aligned}$$

(1) $B_{11} A_{11} + B_{12} A_{21} = I$

(2) $B_{11} A_{12} + B_{12} A_{22} = 0 \Rightarrow B_{12} = -B_{11} A_{12} A_{22}^{-1}$

(3) $B_{21} A_{11} + B_{22} A_{21} = 0 \Rightarrow B_{21} = -B_{22} A_{21} A_{11}^{-1}$

(4) $B_{21} A_{12} + B_{22} A_{22} = I$

(1), (2) $\Rightarrow B_{11} A_{11} - B_{11} A_{12} A_{22}^{-1} A_{21} = I \Rightarrow B_{11} [A_{11} - A_{12} A_{22}^{-1} A_{21}] = I$

$$\begin{aligned} &\Rightarrow B_{11} = F_1 \equiv [A_{11} - A_{12} A_{22}^{-1} A_{21}]^{-1} \\ &\Rightarrow B_{12} = -F_1 A_{12} A_{22}^{-1} \end{aligned}$$

(3), (4) $\Rightarrow -B_{22} A_{21} A_{11}^{-1} A_{12} + B_{22} A_{22} = I \Rightarrow B_{22} [A_{22} - A_{21} A_{11}^{-1} A_{12}] = I$

$$\begin{aligned} &\Rightarrow B_{22} = F_2 \equiv [A_{22} - A_{21} A_{11}^{-1} A_{12}]^{-1} \\ &B_{21} = -F_2 A_{21} A_{11}^{-1} \end{aligned}$$

This gives the First Formula. The second is obtained by post multiplying by B using the same partition as above (this is conformable) and equality of the two matrices follows from the uniqueness of A^{-1} .

(E4) Ex: $X = [x_1 \ x_2]$

$$(X'X) = \begin{bmatrix} x_1'x_1 & x_1'x_2 \\ x_2'x_1 & x_2'x_2 \end{bmatrix} \text{ which implies that } \geq$$

$$F_1 = [x_1'x_1 - x_1'x_2(x_2'x_2)^{-1}x_2'x_1]^{-1} = [x_1'(I - x_2(x_2'x_2)^{-1}x_2')x_1]^{-1} = (x_1'Q_2x_1)^{-1}$$

$$F_2 = [x_2'x_2 - x_2'x_1(x_1'x_1)^{-1}x_1'x_2]^{-1} = [x_2'(I - x_1(x_1'x_1)^{-1}x_1')x_2]^{-1} = (x_2'Q_1x_2)^{-1}$$

$$(X'X)^{-1} = \begin{bmatrix} (x_1'Q_2x_1)^{-1} & -(x_1'Q_2x_1)^{-1}x_1'x_2(x_2'x_2)^{-1} \\ -(x_2'Q_1x_2)^{-1}x_2'x_1(x_1'x_1)^{-1} & (x_2'Q_1x_2)^{-1} \end{bmatrix} \quad \text{First Formula}$$

$$= \begin{bmatrix} (x_1'Q_2x_1)^{-1} & -(x_1'x_1)^{-1}x_1'x_2(x_2'Q_1x_2)^{-1} \\ -(x_2'x_2)^{-1}x_2'x_1(x_1'Q_2x_1)^{-1} & (x_2'Q_1x_2)^{-1} \end{bmatrix} \quad \text{Second Formula}$$

Now recall that the coefficient vector from our projection problem is $b = (X'X)^{-1}X'y$ or, using the First Formula (Note: this formula was derived by premultiplying $(X'X)$ by $(X'X)^{-1}$ and so will make terms simplify more easily when being substituted into a formula in which $(X'X)^{-1}$ premultiplies X' or $X'X$), we have:

$$\begin{bmatrix} b_1 \\ b_2 \end{bmatrix} = \begin{bmatrix} x_1'x_1 & x_1'x_2 \\ x_2'x_1 & x_2'x_2 \end{bmatrix}^{-1} \begin{bmatrix} x_1'y \\ x_2'y \end{bmatrix} = \begin{bmatrix} (x_1'Q_2x_1)^{-1} & -(x_1'Q_2x_1)^{-1}x_1'x_2(x_2'x_2)^{-1} \\ -(x_2'Q_1x_2)^{-1}x_2'x_1(x_1'x_1)^{-1} & (x_2'Q_1x_2)^{-1} \end{bmatrix} \begin{bmatrix} x_1'y \\ x_2'y \end{bmatrix}$$

$$= \begin{bmatrix} (x_1'Q_2x_1)^{-1}x_1'y - (x_1'Q_2x_1)^{-1}x_1'x_2(x_2'x_2)^{-1}x_2'y \\ (x_2'Q_1x_2)^{-1}x_2'y - (x_2'Q_1x_2)^{-1}x_2'x_1(x_1'x_1)^{-1}x_1'y \end{bmatrix}$$

$$= \begin{bmatrix} (x_1'Q_2x_1)^{-1}x_1'[I - x_2(x_2'x_2)^{-1}x_2']y \\ (x_2'Q_1x_2)^{-1}x_2'[I - x_1(x_1'x_1)^{-1}x_1']y \end{bmatrix} = \begin{bmatrix} (x_1'Q_2x_1)^{-1}x_1'Q_2y \\ (x_2'Q_1x_2)^{-1}x_2'Q_1y \end{bmatrix}$$

$$= \begin{bmatrix} (x_1'Q_2'Q_2x_1)^{-1}x_1'Q_2'Q_2y \\ (x_2'Q_1'Q_1x_2)^{-1}x_2'Q_1'Q_1y \end{bmatrix} = \begin{bmatrix} [(Q_2x_1)'(Q_2x_1)]^{-1}(Q_2x_1)'(Q_2y) \\ [(Q_1x_2)'(Q_1x_2)]^{-1}(Q_1x_2)'(Q_1y) \end{bmatrix}$$

Recalling our interpretation of Q from before, we see that b_1 is the same coefficient vector as would be obtained by taking the residual vector from the projection of y on x_2 and projecting it onto the residual matrix from the projections of x_1 on x_2 . b_2 can be interpreted analogously.

(7) Matrix Calculus

Let $F: \mathbb{R}^m \times \mathbb{R}^n \rightarrow \mathbb{R}^p \times \mathbb{R}^q$ be a matrix-valued function. That is, given a real $m \times n$ matrix X , $F(X)$ is the $p \times q$ matrix:

$$F(X) = \begin{bmatrix} f_{11}(X) & \dots & f_{1q}(X) \\ \vdots & & \vdots \\ f_{p1}(X) & \dots & f_{pq}(X) \end{bmatrix} \quad \begin{matrix} X \\ (m \times n) \end{matrix}$$

(p x q)

where each $f_{ij}(X)$ is a scalar-valued function of the matrix X . Hence $f_{ij}: \mathbb{R}^m \times \mathbb{R}^n \rightarrow \mathbb{R} \quad \forall ij$. We define the derivative of $F()$ wrt X as follows:

$$\frac{\partial F(X)}{\partial X} = \begin{bmatrix} \frac{\partial F(X)}{\partial x_{11}} & \dots & \frac{\partial F(X)}{\partial x_{1n}} \\ \vdots & & \vdots \\ \frac{\partial F(X)}{\partial x_{m1}} & \dots & \frac{\partial F(X)}{\partial x_{mn}} \end{bmatrix} \quad \begin{matrix} \text{Note: Each partition of this} \\ \text{matrix is itself a } p \times q \\ \text{matrix (defined below)} \end{matrix}$$

(mp x ng)

where

$$\frac{\partial F(X)}{\partial x_{ij}} = \begin{bmatrix} \frac{\partial f_{11}(X)}{\partial x_{ij}} & \dots & \frac{\partial f_{1q}(X)}{\partial x_{ij}} \\ \vdots & & \vdots \\ \frac{\partial f_{p1}(X)}{\partial x_{ij}} & \dots & \frac{\partial f_{pq}(X)}{\partial x_{ij}} \end{bmatrix} \quad \begin{matrix} \forall i = 1, \dots, m \\ j = 1, \dots, n \end{matrix}$$

(p x q)

(ES) Ex: Matrix-Valued Function of a scalar
 $m = n = 1 \Rightarrow X = x \in \mathbb{R}$

$$\frac{\partial F(x)}{\partial x} = \begin{bmatrix} \frac{\partial f_{11}(x)}{\partial x} & \dots & \frac{\partial f_{1q}(x)}{\partial x} \\ \vdots & & \vdots \\ \frac{\partial f_{p1}(x)}{\partial x} & \dots & \frac{\partial f_{pq}(x)}{\partial x} \end{bmatrix}$$

For example if $F(x) = xI$, then $\partial F/\partial x = I$ (replace $F(x)$ w/ $V(E)$ and x w/ σ^2 and we just took the derivative of the variance-covariance matrix of a random vector E wrt its common variance term σ^2).

(E6) Ex: Scalar-valued function of a matrix:

$$p = q = 1 \Rightarrow F(x) = f(x) \in \mathbb{R}$$

$$\frac{\partial F(x)}{\partial x} = \begin{bmatrix} \frac{\partial f(x)}{\partial x_{11}} & \dots & \frac{\partial f(x)}{\partial x_{1n}} \\ \vdots & & \vdots \\ \frac{\partial f(x)}{\partial x_{m1}} & \dots & \frac{\partial f(x)}{\partial x_{mn}} \end{bmatrix} \quad (m \times n)$$

(E7) Ex: Scalar-valued function of a scalar

$$m = n = 1 \Rightarrow x = x \in \mathbb{R}$$

$$p = q = 1 \Rightarrow F(x) = f(x) \in \mathbb{R}$$

$$\frac{\partial F(x)}{\partial x} = \frac{\partial f(x)}{\partial x} = f'(x) \leftarrow \text{standard derivative from univariate calculus.}$$

Quick Update

$$X: m \times n$$

$$F(x): p \times q$$

$$x_{ij}: 1 \times 1 \quad i=1, \dots, m, \quad j=1, \dots, n$$

$$f_{rel}(x): 1 \times 1 \quad k=1, \dots, p \quad l=1, \dots, q$$

$$\frac{\partial F(x)}{\partial x}: mp \times nq$$

$$\frac{\partial F(x)}{\partial x_{ij}}: p \times q$$

$$\frac{\partial f_{rel}(x)}{\partial x_{ij}}: 1 \times 1$$

(T18) Claim: $\left(\frac{\partial F(x)}{\partial x}\right)' = \frac{\partial F(x)'}{\partial x'}$

Proof:

$$\left(\frac{\partial F(x)}{\partial x_{ij}}\right)' = \begin{bmatrix} \frac{\partial f_{11}(x)}{\partial x_{ij}} & \dots & \frac{\partial f_{1g}(x)}{\partial x_{ij}} \\ \vdots & & \vdots \\ \frac{\partial f_{p1}(x)}{\partial x_{ij}} & \dots & \frac{\partial f_{pg}(x)}{\partial x_{ij}} \end{bmatrix}' = \begin{bmatrix} \frac{\partial f_{11}(x)}{\partial x_{ij}} & \dots & \frac{\partial f_{p1}(x)}{\partial x_{ij}} \\ \vdots & & \vdots \\ \frac{\partial f_{1g}(x)}{\partial x_{ij}} & \dots & \frac{\partial f_{pg}(x)}{\partial x_{ij}} \end{bmatrix} = \frac{\partial F(x)'}{\partial x_{ij}}$$

where $F(x)'$ is the $g \times p$ transpose of $F(x)$. Thus, we have

$$\begin{aligned} \left(\frac{\partial F(x)}{\partial x}\right)' &= \begin{bmatrix} \frac{\partial F(x)}{\partial x_{11}} & \dots & \frac{\partial F(x)}{\partial x_{1n}} \\ \vdots & & \vdots \\ \frac{\partial F(x)}{\partial x_{m1}} & \dots & \frac{\partial F(x)}{\partial x_{mn}} \end{bmatrix}' = \begin{bmatrix} \left(\frac{\partial F(x)}{\partial x_{11}}\right)' & \dots & \left(\frac{\partial F(x)}{\partial x_{1n}}\right)' \\ \vdots & & \vdots \\ \left(\frac{\partial F(x)}{\partial x_{m1}}\right)' & \dots & \left(\frac{\partial F(x)}{\partial x_{mn}}\right)' \end{bmatrix} \quad \text{using the formula for the transpose of a partitioned matrix.} \\ &= \begin{bmatrix} \frac{\partial F(x)'}{\partial x_{11}} & \dots & \frac{\partial F(x)'}{\partial x_{1n}} \\ \vdots & & \vdots \\ \frac{\partial F(x)'}{\partial x_{m1}} & \dots & \frac{\partial F(x)'}{\partial x_{mn}} \end{bmatrix} = \frac{\partial F(x)'}{\partial x'} \quad // \end{aligned}$$

(T19) Theorem: Given $x: n \times 1$, $b: n \times 1$, $B: m \times n$, $A: n \times n$. we have

(1) $\frac{\partial b'x}{\partial x} = b \Rightarrow \frac{\partial b'x}{\partial x'} = b'$ $\frac{\partial (x'b)}{\partial x} = b$ v/b = (x'b) / (x' b)

(2) $\frac{\partial Bx}{\partial x} = B \Rightarrow \frac{\partial (Bx)'}{\partial x} = B'$ $\frac{\partial x'B}{\partial x} = B$ v/b = (x'b) / (x' b)

(3) $\frac{\partial x'Ax}{\partial x} = (A+A')x$ $\Rightarrow \frac{\partial x'Ax}{\partial x'} = x'(A+A')$

$2A \leftarrow$ if A is symmetric $\rightarrow 2A$

Note: (3) holds replacing A w/ A' and vice versa in $x'Ax$, $x'A'x$

$$\left(\frac{\partial (x'Ax)}{\partial x}\right)' = \left(\frac{\partial \sum_{i,j} x_i A_{ij} x_j}{\partial x_i}\right)' = \left(\sum_{i,j} A_{ij} x_j + \sum_{i,j} A_{ji} x_i\right)' = Ax + A'x$$

$x \ (n \times 1)$

! (4) $\frac{\partial x'Ax}{\partial A} = xx'$

$\left(\sum_{k=1}^n x_k A_{kj} x_k \right) \Rightarrow x \cdot x_j$
 $= \begin{pmatrix} x_1 x_1 & x_1 x_2 & \dots & x_1 x_n \\ x_2 x_1 & x_2 x_2 & \dots & x_2 x_n \\ \vdots & \vdots & \ddots & \vdots \\ x_n x_1 & x_n x_2 & \dots & x_n x_n \end{pmatrix} = xx' = \begin{pmatrix} x_1 & x_1 & \dots & x_1 \\ x_2 & x_2 & \dots & x_2 \\ \vdots & \vdots & \ddots & \vdots \\ x_n & x_n & \dots & x_n \end{pmatrix} = xx'$

(5) $\frac{\partial \det(A)}{\partial A} = \det(A) A^{-1}$

$\det A = \sum_j a_{ij} (-1)^{i+j} \det(A_{ij})$ разрежающее по строке
то $i=0$
опорке
 $\frac{\partial \det A}{\partial a_{ik}} = (-1)^{i+k} \det(A_{ik}) \Rightarrow \frac{(-1)^{i+k} \det(A_{ik})}{\det A} = (A^{-1})_{ki}$

! (6) $\frac{\partial \ln \det(A)}{\partial A} = A^{-1}$

$= \frac{1}{\det A} \frac{\partial \det A}{\partial A} = A^{-1}$

Proof:

(1) $b'x = \sum_{i=1}^n b_i x_i \Rightarrow \frac{\partial b'x}{\partial x_j} = \frac{\partial \sum_{i=1}^n b_i x_i}{\partial x_j} = b_j \quad j=1, \dots, n$

$\Rightarrow \frac{\partial b'x}{\partial x} = \begin{bmatrix} \frac{\partial b'x}{\partial x_1} \\ \vdots \\ \frac{\partial b'x}{\partial x_n} \end{bmatrix} = \begin{bmatrix} b_1 \\ \vdots \\ b_n \end{bmatrix} = b \Rightarrow \frac{\partial b'x}{\partial x'} = \left(\frac{\partial b'x}{\partial x} \right)' = b'$
 Since $(b'x)' = x'b = b'x$

(2) Notice that, using our results from partitioned matrices, we can write Bx as:

$Bx = [B_1 \dots B_n] \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} = \sum_{i=1}^n B_i x_i \Rightarrow \frac{\partial Bx}{\partial x_j} = \frac{\partial \sum_{i=1}^n B_i x_i}{\partial x_j} = B_j \quad j=1, \dots, n$

where B_i is the i th column of B . Thus, we have

$\frac{\partial Bx}{\partial x'} = \left[\frac{\partial Bx}{\partial x_1} \dots \frac{\partial Bx}{\partial x_n} \right] = [B_1 \dots B_n] = B \Rightarrow \frac{\partial (Bx)'}{\partial x} = \left(\frac{\partial Bx}{\partial x'} \right)' = B'$

(3) $x'Ax = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j = \sum_{i=1}^n a_{ii} x_i^2 + \sum_{i=1}^n \sum_{j \neq i} a_{ij} x_i x_j$

$\frac{\partial x'Ax}{\partial x_k} = 2a_{kk} x_k + \sum_{j \neq k} a_{kj} x_j + \sum_{i \neq k} a_{ik} x_i$
 $= \sum_{j=1}^n a_{kj} x_j + \sum_{i=1}^n a_{ik} x_i$

$$= \sum_{j=1}^n [A]_{kj} x_j + \sum_{i=1}^n [A']_{ki} x_i = (Ax)_k + (A'x)_k$$

where $[A]_{kj} = a_{kj}$ is the element from the k th row and j th column of A while $[A']_{ki} = a_{ik}$ is the element from the k th row and i th column of A' , and where $(Ax)_k$ and $(A'x)_k$ are the k th elements from the $n \times 1$ vectors Ax and $A'x$. Thus, we have

$$\frac{\partial x'Ax}{\partial x} = \begin{bmatrix} \frac{\partial x'Ax}{\partial x_1} \\ \vdots \\ \frac{\partial x'Ax}{\partial x_n} \end{bmatrix} = \begin{bmatrix} (Ax)_1 + (A'x)_1 \\ \vdots \\ (Ax)_n + (A'x)_n \end{bmatrix} = \begin{bmatrix} (Ax)_1 \\ \vdots \\ (Ax)_n \end{bmatrix} + \begin{bmatrix} (A'x)_1 \\ \vdots \\ (A'x)_n \end{bmatrix} = \underbrace{(Ax)}_{Ax} + \underbrace{(A'x)}_{A'x} = (A+A')x$$

$$\Rightarrow \frac{\partial x'A'x}{\partial x'} = \left(\frac{\partial x'Ax}{\partial x} \right)' = x'(A+A')$$

Also, $\frac{\partial x'A'x}{\partial x} = (A+A')x$ and $\frac{\partial x'Ax}{\partial x'} = x'(A+A')$

$$(4) \quad x'Ax = \sum_{i=1}^n \sum_{j=1}^n a_{ij} x_i x_j \Rightarrow \frac{\partial x'Ax}{\partial a_{ij}} = x_i x_j \quad \forall i, j = 1, \dots, n$$

$$\Rightarrow \frac{\partial x'Ax}{\partial A} = \begin{bmatrix} \frac{\partial x'Ax}{\partial a_{11}} & \dots & \frac{\partial x'Ax}{\partial a_{1n}} \\ \vdots & & \vdots \\ \frac{\partial x'Ax}{\partial a_{n1}} & \dots & \frac{\partial x'Ax}{\partial a_{nn}} \end{bmatrix} = \begin{bmatrix} x_1 x_1 & \dots & x_1 x_n \\ \vdots & & \vdots \\ x_n x_1 & \dots & x_n x_n \end{bmatrix} = \begin{bmatrix} x_1 \\ \vdots \\ x_n \end{bmatrix} \underbrace{[x_1 \dots x_n]}_{x'}$$

(5) Recall from the beginning of this handout (many pages ago) that

$$\det(A) = \sum_{j=1}^n a_{ij} (-1)^{i+j} \det(A_{ij}) \Rightarrow \frac{\partial \det(A)}{\partial a_{ij}} = (-1)^{i+j} \det(A_{ij}),$$

↑
For any $i = 1, \dots, n$

where A_{ij} is the $(n-1) \times (n-1)$ matrix formed by deleting the i th row and j th column from A . Recall also that