

14.383

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REVIEW

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14-383: Revision for general

Outline

→ Note if $\text{Var}(Z) \rightarrow \infty$, then OLS (with endogenous vars in RHS) is consistent.

1. Identification: ~~the~~

- total $M(M-1)$ further restrictions after normalization

- Rank condition (for single equation), linear restriction

$$\text{Rank} [\bar{\Phi} A] = M$$

where $A = \begin{bmatrix} B \\ \Pi \end{bmatrix}$, $\bar{\Phi}$ = matrix of restrictions on 1st equation

$$\bar{\Phi} A_1 = \phi$$

$\bar{\Phi}$ includes the normalization restriction

- Order condition

$$\text{no. of restrictions } g \geq M$$

- Interpretation → there must be enough "instruments" from other eqns, and these restrictions must be, in a sense, independent of no other eqn.

should satisfy the same set of restrictions.

$$2. \text{ SF: } \underset{\Gamma M \times M}{Y} B + \underset{\Gamma X \times K}{Z} \Pi = \underset{\Gamma \times M}{U} \quad ; \quad y_t B + z_t \Pi = u_t$$

Assume: B is non singular

$$\text{rank}(Z) = k \text{ (full column rank)}$$

$$E(u_t' u_{t'}) = 0 \text{ for } t \neq t'$$

$$E \begin{pmatrix} u_t' \\ u_t \end{pmatrix} = \Sigma$$

$$\text{plus } \frac{1}{T} Z' U = \text{plus } \frac{1}{T} \sum_{t=1}^T \begin{pmatrix} z_t' \\ u_t \end{pmatrix} = 0$$

(Exogeneity of Z 's).

3. Predetermined variables:

$$y_i \text{ is predetermined in equation } j \text{ if} \\ \text{plim } \frac{1}{T} y_i' u_j = 0 \Leftrightarrow \text{plim } \frac{1}{T} v_i' u_j = 0$$

where v_i is the error term in the RF of equation i .

$$V = UB^{-1} \Rightarrow v_i = UB_i^{-1} \\ \Rightarrow \text{plim } \frac{1}{T} v_i' u_j = B_i^{-1'} \text{plim } \frac{1}{T} U' u_j = B_j^{-1'} \Sigma_j$$

\Rightarrow predeterminedness depends on the whole system; not just on eqns i and j .

4. Single equation IV:

we have k exclusion restrictions and q endogenous vars to instrument for. Choose a linear combination

$$W = \begin{matrix} \hat{Z} \hat{A} \\ T \times k & k \times q \end{matrix} \text{ of the possible instruments. } (rk(A)=q)$$

$$\hat{\delta}_{IV} = (W'X)^{-1} W'y_1 = (\hat{A}'Z'X)^{-1} \hat{A}'Z'y_1$$

Under just id, there is no choice to make $\rightarrow \hat{\delta}_{IV}$ is unique.

$$\begin{aligned} \text{plim } \hat{\delta}_{IV} &= \text{plim} (\hat{A}'Z'X)^{-1} \hat{A}'Z'X \delta + (\hat{A}'Z'X)^{-1} \hat{A}'Z'u \\ &= \delta + \text{plim} \left(\frac{\hat{A}'Z'X}{T} \right)^{-1} \text{plim } \hat{A}' \cdot \text{plim} \frac{Z'u}{T} \\ &= \delta \end{aligned}$$

$$\sqrt{T}(\hat{\delta}_{IV} - \delta) = \sqrt{T} \left(\frac{\hat{A}'Z'X}{T} \right)^{-1} \hat{A}' \cdot \frac{Z'u}{T}$$

$$\xrightarrow{d} N(0, V)$$

$$\text{where } V = (A'G)^{-1} A' Q A (G'A)^{-1}$$

$$A = \text{plim } \hat{A}, \quad G = \text{plim} \frac{Z'X}{T}, \quad Q = \text{plim} \frac{Z'u_1 u_1' Z}{T} \quad (2)$$

$$\hat{\delta}_{OIV} = \operatorname{argmin} (y - X\delta)' Z' Z (y - X\delta)$$

Optimal $J = \operatorname{Var}$

This is minimized iff $G\tilde{B} = QA$ for some \tilde{B} non-singular
 \Rightarrow min. asympt. var. is $(G'Q^{-1}G)^{-1}$

$$\text{or } A = Q^{-1}G\tilde{B} \rightarrow$$

Wlog. take $\tilde{B} = I$, so we need $A = Q^{-1}G$.

If we have conditional homoscedasticity, then

$$Q = \sigma^2 \operatorname{plim} \frac{Z'Z}{T}$$

$\Rightarrow \hat{A} = \left(\frac{Z'Z}{T}\right)^{-1} \frac{Z'X}{T} = (Z'Z)^{-1} Z'X$ would give us
 the optimal IV estimator.

This is nothing but 2SLS!

Generally we have $\hat{Q} = \frac{1}{T} \sum_{t=1}^T \hat{u}_t^2 z_t' z_t$

$$\Rightarrow \hat{\delta}_{OIV} = (X'Z \hat{Q}^{-1} Z'X)^{-1} X'Z \hat{Q}^{-1} Z'y_1$$

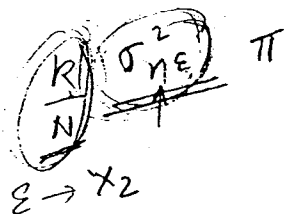
Note that this \hat{Q} is just White's estimator for the variance matrix. If we suspect autocorrelation as well, we could use the Newey-West estimator of the variance matrix. A consistent estimate of \hat{u}_{it} 's can be obtained from 2SLS (~~\Rightarrow this optimal IV is exactly the same as the 3SLS discussed later~~ NO!).

5. Overid tests : to check orthogonality of instruments
 ie. H_0 : $\operatorname{plim} \frac{Z'u_1}{T} = 0$ vs H_1 : $\operatorname{plim} \frac{Z'u_1}{T} \neq 0$.

Under just id $Z'u_1 \equiv 0$, so no test is possible.

Alternatively, there is only a unique IV estimate, so no comparison is possible.

USS IV



$$\begin{aligned} y_2 &= X_2\beta + \varepsilon \\ X &= Z\Pi + \eta \end{aligned}$$

$$\begin{aligned} \hat{X}_2 &= Z\Pi \\ \hat{\Pi} &\rightarrow \eta_1 \end{aligned}$$

Overid test statistic is $\hat{u}_1' Z \hat{V}^{-1} Z' \hat{u}_1 \xrightarrow{d} \chi^2_{k-q}$

where $\hat{V} = \hat{\sigma}^2 Z'Z$ in the homoscedastic case

where $\hat{u}_1 = y_1 - X_1 \hat{\delta}_{OIV}$

In the homoscedastic case, $\hat{V} = \hat{\sigma}^2 (Z'Z)$

\Rightarrow test statistic is $\frac{\hat{u}_1' P_Z \hat{u}_1}{\hat{\sigma}^2}$

where $\hat{\sigma}^2 = \frac{\hat{u}_1' \hat{u}_1}{T}$

This test can reject if (i) instruments are correlated with errors (ii) included exogenous vars are correlated with errors.

6. Hausman specification test: This again checks both the exogeneity of included exogenous vars + validity of instruments. Under (= specification). Under correct specification, $\text{plim } \hat{\delta}_{2SLS} = \text{plim } \hat{\delta}_{OIV} = \delta$. and $\hat{\delta}_{OIV}$ is efficient. Under wrong specification, both $\hat{\delta}_{2SLS}$ and $\hat{\delta}_{OIV}$ are inconsistent and have different limits \Rightarrow

$$h = T(\hat{\delta}_{2SLS} - \hat{\delta}_{OIV})' \left[\hat{V}(\hat{\delta}_{2SLS}) - \hat{V}(\hat{\delta}_{OIV}) \right] \times (\hat{\delta}_{2SLS} - \hat{\delta}_{OIV})$$

$$\xrightarrow{d} \chi^2_{(\dim(\delta))}$$

where $\sqrt{T}(\hat{\delta}_i - \delta) \rightarrow N(0, V_i)$

Ques: What if we indeed have homoscedasticity?

Would $\hat{\delta}_{OIV}$ & $\hat{\delta}_{2SLS}$ have different plims

under H_0 then? If not, then how to do this test?

Then $\text{plim}(\hat{\beta}_{GLS} - \hat{\beta}_{FGLS}) = 0$ and they have the same asymptotic distribution. One way to make $\hat{\beta}_{FGLS}$ is to do OLS equation-by-equation, get the residuals and form $\hat{\Sigma}$ and then make $\hat{\beta}_{FGLS}$. If we iterate this procedure, then this converges to the MLE ($\hat{\beta}_{GLS}$) under normality.

Drawback: If even one equation is misspecified, then all ^{the} estimates become inconsistent! Also this is good only when all the RHS vars are exogenous & for RF. ~~We can make~~

Interesting property (for RF): If $X_j = X \forall j$, then

$$\hat{\beta}_{GLS} \equiv \hat{\beta}_{OLS}$$

How? $\bar{X} = I_M \otimes X$

$$\hat{\beta}_{GLS} = [(I \otimes X') (\Sigma \otimes I)^{-1} (I \otimes X)]^{-1} (I \otimes X') (\Sigma \otimes I)^{-1} \bar{y}$$

$$= (\Sigma^{-1} \otimes X' X)^{-1} (\Sigma^{-1} \otimes X') \bar{y}$$

$$= (\Sigma \otimes (X' X)^{-1})^{-1} (\Sigma^{-1} \otimes X') \bar{y}_1$$

$$= [I \otimes (X' X)^{-1} X'] \bar{y} = \hat{\beta}_{OLS}$$

So, for RF estimates, doing OLS ^{eqn-by-eqn} is efficient even in the presence of Σ non-diagonal.

We can make a Hausman test to check for exogeneity/misspecification $H_0: \text{plim} \frac{1}{T} X_j' E_k = 0 \forall j, k$

$\hat{\beta}_{GLS}$ and $\hat{\beta}_{OLS}$ are both consistent under H_0 & $\hat{\beta}_{GLS}$ is efficient; under H_1 , $\hat{\beta}_{GLS}$ is inconsistent, $\hat{\beta}_{OLS}$ is consistent. (6)

So we get the system IV as follows:

Stage 1 & 2: Do 2SLS equation-by-equation.

Find residuals \hat{u}_j . Compute $\hat{\Sigma}_{jk} = \frac{\hat{u}_j' \hat{u}_k}{T}$

Stage 3: Compute $\bar{W} = (I \otimes Z) \hat{A} = (\hat{\Sigma}^{-1} \otimes P_Z) \bar{X}$

$$\hat{\delta}_{3SLS} = \left[\bar{X}' (\hat{\Sigma}^{-1} \otimes P_Z) \bar{X} \right]^{-1} \bar{X}' (\hat{\Sigma}^{-1} \otimes P_Z) \bar{y}$$

Note: $\hat{\delta}_{3SLS} = \left[\hat{X}' (\hat{\Sigma}^{-1} \otimes I) \hat{X} \right]^{-1} \hat{X}' (\hat{\Sigma}^{-1} \otimes I) \bar{y}$
 where $\hat{X} = P_Z \bar{X}$

$\Rightarrow \hat{\delta}_{3SLS}$ is the SUR estimate of the model
 $y_j = \hat{X}_j \delta_j + v_j$ using $\hat{\Sigma}$ as the estimated variance matrix

9. Since $\hat{\delta}_{3SLS}$ is optimal System IV, it is in general better than doing 2SLS equation-by-equation. However, if all the equations are just id, then 3SLS \equiv 2SLS (same feature as OIV \equiv 2SLS). Similarly, if a subset of equations is exactly identified, then 3SLS on the remaining equations gives the same estimates as 2SLS. Intuition: 3SLS uses info from other equations to fine-tune our instruments (here single-equation OIV = 2SLS), but if a set of eqns. is just id, there is no information "left over" to exploit.

Implication: 3SLS is a purely system method; it is no good for estimating a single eqn. if other eqns. are specified only in reduced form. (F)

10. Maximum Likelihood Estimation : FIML.

$$Y_t B + Z_t \Gamma = u_t.$$

Assume $u_t' \sim N(0, \Sigma)$. Then log-likelihood for B , and Σ^{-1} in terms of \underline{Y} can be written as

$$\begin{aligned} \mathcal{L}(B, \Gamma, \Sigma^{-1}) = & \text{const.} + T \underbrace{\log |\det B|}_{\text{Jacobian term}} + \frac{T}{2} \log |\det (\Sigma^{-1})| \\ & - \frac{1}{2} \text{tr} (\Sigma^{-1} U' U) \\ & \quad \downarrow \\ & \quad YB + Z\Gamma \end{aligned}$$

FOC wrt unknown (unrestricted) elements are:

$$\frac{\partial \mathcal{L}}{\partial B^u} = [TB^{-1'} - Y'U \Sigma^{-1}]^u = 0 \quad (1)$$

$$\frac{\partial \mathcal{L}}{\partial \Gamma^u} = [-Z'U \Sigma^{-1}]^u = 0 \quad (2)$$

$$\frac{\partial \mathcal{L}}{\partial \Sigma^{-1u}} = \left[\frac{T}{2} \Sigma - \frac{1}{2} U'U \right]^u = 0 \quad (3)$$

Usually Σ is unrestricted $\Rightarrow^{(3)} \hat{\Sigma}_{MLE} = \frac{U'U}{T}$. — (*)

$$\text{FOC for } B_{jk}^u : \Pi_{(j)}' (Z'U) \Sigma_{(k)}^{-1} = 0$$

$$\text{FOC for } \Gamma_{jk}^u : Z_{(j)}' U \Sigma_{(k)}^{-1} = 0 \Leftrightarrow S_j' (Z'U) \Sigma_{(k)}^{-1} = 0$$

where S_j is the selection matrix which picks out the j th column

$$\Rightarrow D_k' Z'U \Sigma_{(k)}^{-1} = 0 \quad \text{for the } k\text{th equation}$$

$$\text{where } D_k = [\Pi_k \ S_k]$$

This means that 3SLS is asymptotically efficient under normality. Ques: Should we ever do FIML?

Note: Since FIML is an IV estimator, it is always consistent under correct specification.

12. LIML: MLE for single equation.

Do FIML on $y_1 = \gamma_1 \beta_1 + z_1 \gamma_1 + u_1$

$y_2 = z_2 \pi_1 + v_1 \rightarrow$ if for all other endogenous vars.

FOC leads to $\boxed{D_1' Z' U = 0}$

\Rightarrow LIML is also an IV estimator.

Since the remaining eqns are exactly identified,

$$\hat{\delta}_{1,2SLS} \equiv \hat{\delta}_{1,3SLS} \stackrel{\text{asympt}}{=} \hat{\delta}_{1,FIML} \stackrel{\text{dfn}}{=} \hat{\delta}_{1,LIML}$$

\Rightarrow LIML is asymptotically equivalent to 2SLS.

But note that $\hat{\pi}_{1,LIML} \neq (Z'Z)^{-1} Z'y_1$ because 1st eqn is overid.

Let $\tilde{X} = X - u \cdot \frac{X'u}{u'u}$. Then LIML FOC is $\tilde{X}' P_Z (y - X\hat{\delta}) = 0$. FOC for 2SLS is $X' P_Z (y - X\hat{\delta}) = 0$. Since LIML has taken out some part of X correlated with u 's, it has smaller bias. Tradeoff is only the computational diff.

13. System overid test

$$LR: 2 [\log L(\hat{\Pi}^U, \hat{\Sigma}^U) - \log L(\hat{\Pi}^R, \hat{\Sigma}^R)] \xrightarrow{d} \chi^2_{\text{degree of over}}$$

$\hat{\Pi}^U, \hat{\Sigma}^U =$ normal reduced form estimates

$$\hat{\Pi}^R = -\hat{\Gamma}_{FIML} \hat{\beta}_{FIML}^{-1}; \hat{\Sigma}^R = \hat{\beta}_{FIML}^{-1} \hat{\Sigma}_{FIML} \hat{\beta}_{FIML}^{-1}$$