

MODEL REDUCTION Group MEETING 3/30/09

ASSUME: LINEAR SYSTEMS

ERROR ESTIMATION:

input/parameter: $u \in \mathcal{U}$

state: $x \in X$ $x_m \in X_m$

outputs: $y = \underline{y}$ $y_m \in \underline{Y}$

full-order model: $\mathcal{F}: \mathcal{U} \rightarrow X \rightarrow \underline{Y}$

reduced-order model: $\mathcal{R}: \mathcal{U} \rightarrow X_m \rightarrow \underline{Y}$

let $r \in \mathcal{R}$ s.t. $r: \mathcal{U} \rightarrow X_m \rightarrow \underline{Y} \ni y_r$

and $f \in \mathcal{F}$ s.t. $f: \mathcal{U} \rightarrow X \rightarrow \underline{Y} \ni y$

define absolute error:

$$e(r) = \max_{\substack{u \in \mathcal{U}_T \\ \mathcal{U}_T}} \left\{ \| y(u) - y_r(u) \|_y^2 \right\} du$$

where \mathcal{U}_T is a test set s.t. $\mathcal{U}_T \subset \mathcal{U}$.

Also of interest may be relative error.

let \tilde{m} be fixed positive integer.

define $e^*(r) = e(r^*)$ and $r^* = \underset{\substack{r \in \mathcal{R}, \\ m=\tilde{m}}}{\arg \min} e(r)$

then,

$$e_{\text{rel}}(r) = \frac{e(r)}{e^*(r)}$$