

High-Precision Thermodynamic and Critical Properties from Tensor Renormalization-Group Flows

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The recently developed tensor renormalization-group (TRG) method provides a highly precise technique for deriving thermodynamic and critical properties of lattice Hamiltonians. The TRG is a local coarse-graining transformation, with the elements of the tensor at each lattice site playing the part of the interactions that undergo the renormalization-group flows. These tensor flows are directly related to the phase diagram structure of the infinite system, with each phase flowing to a distinct surface of fixed points. Fixed-point analysis and summation along the flows give the critical exponents, as well as thermodynamic functions along the entire temperature range. Thus, for the ferromagnetic triangular lattice Ising model, the free energy is calculated to better than 10^{-5} along the entire temperature range. Unlike previous position-space renormalization-group methods, the truncation (of the tensor index range D) in this general method converges under straightforward and systematic improvements. Our best results are easily obtained with $D = 24$, corresponding to 4624-dimensional renormalization-group flows.

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I. INTRODUCTION

The tensor renormalization-group (TRG) method, recently introduced by Levin and Nave [1] is versatile, accurate, and conceptually interesting. The versatility of TRG comes from being a genuinely local renormalization-group transformation, that is a mapping between local Hamiltonians on the original and coarse-grained lattices, expressed in terms of tensors at sites of each lattice. Thus, although TRG has been demonstrated by obtaining very accurate phase transition temperatures and magnetization curves for frustrated and unfrustrated classical Ising models on the triangular lattice, we believe that it can be extended to yield the critical properties and entire thermodynamics of complicated multi-critical systems, including quenched random systems, by renormalization-group flow analysis.

In the present work, we show that the renormalization-group flows of the tensor elements can be analyzed in the same manner as the flows of Hamiltonian interaction parameters, which was not done in the previous work. Each thermodynamic phase region corresponds to a basin of attraction in the space of tensor elements, and critical temperatures and exponents (not obtained before) are deduced from characteristics of the boundaries between the different basins. Practically, this means that the phase diagram, thermodynamic, and critical properties of the infinite system can be derived directly from the flows. Moreover, the flows themselves have an interesting and unconventional nature, since a phase region does not flow to single isolated sink, but rather to a continuous surface of fixed points. Using the ferromagnetic triangular lattice Ising model as an example, we show that the accuracy of the calculated free energy, critical temperature, and thermal critical exponent can be easily and systematically improved on by increasing

D , the cutoff on the index range of the tensors. In this ability to converge toward exact values with larger cutoffs, TRG is more general and dependable than position-space renormalization-group techniques [2, 3, 4] whose successes have been based on system-specific heuristics [5, 6, 7]. The TRG approach combines the straightforward interpretative framework of traditional renormalization group—analysis of flows in a parameter space—with the accuracy of techniques depending on finite-size scaling of large systems.

II. TENSOR RENORMALIZATION-GROUP TRANSFORMATION

The TRG method [1] can be applied to any classical lattice Hamiltonian satisfying the following conditions: (1) it can be expressed in terms of degrees of freedom on the bonds of the lattice; (2) the Boltzmann weight of a configuration can be written as the product of individual Boltzmann weights for each lattice site, that only depend on the bond variables adjoining the site. This is a broad category including many common statistical physics systems like the Ising and Potts models, both of which can be mapped onto this form through duality transformations, as well as all vertex models. For such Hamiltonians, the partition function can be written as a *tensor network* [8, 9]: We start with a lattice of N sites where each site has coordination number q and each bond is in one of d possible states. The Boltzmann weight of an individual site depends on the configuration of the q bonds meeting at the site and can be written as a tensor $T_{i_1 i_2 \dots i_q}$, where each index i_α runs from 1 to d . For configurations of bond variables that are not allowed, the corresponding element of T is zero. The tensor is real-valued and cyclically symmetric. The transformation described below works

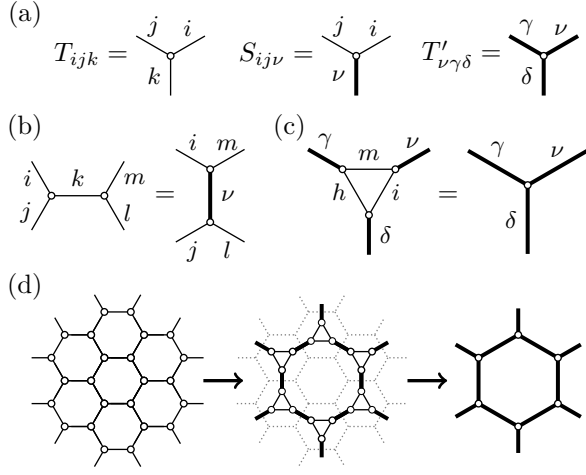


FIG. 1: (a) Graphical representation of the tensors. (b) Rewiring. (c) Decimation. (d) Renormalization group transformation applied to the entire hexagonal lattice, with the first arrow showing the rewiring step, and the second arrow showing the decimation.

also for the more general case of complex-valued, cyclically symmetric tensors, onto which our original tensor network system is mapped after a single renormalization step. The partition function is a product over the N site tensors, with each index contracted between two different tensors (since each bond is shared between two sites),

$$Z = \sum_{i_1, \dots, i_M=1}^d T_{i_1 i_2 \dots i_q} T_{i_1 i_r \dots i_s} T_{i_2 i_t \dots i_u} \dots \quad (1)$$

The position-space renormalization-group transformation of this system allows us to express the partition function equivalently as a tensor network over a coarse-grained lattice with $N' = N/b^2$ vertices, in two spatial dimensions, with a length rescaling factor $b > 1$. It is accomplished in two steps, which we call rewiring and decimation. For simplicity, we shall focus in this work on applying the transformation to the hexagonal lattice, though this two-step procedure can easily be adapted to a variety of two-dimensional lattices, including the square [1] and Kagome lattices.

Rewiring: Graphically, let us represent the tensor T_{ijk} at each point of the hexagonal lattice as a three-legged vertex as shown on the left of Fig. 1(a), and a contraction of an index between two tensors as a connection between two vertex legs. We use the convention that the order of indices in the tensor matches the counterclockwise ordering of the labels on the vertex legs. The rewiring step for a pair of neighboring tensors consists of reconnecting the bonds in the manner of Fig. 1(b), rewriting them as a contraction of two new tensors S ,

$$\sum_{k=1}^d T_{ijk} T_{klm} = \sum_{\nu=1}^{d^2} S_{mi\nu} S_{j\nu l}. \quad (2)$$

The first two indices in the tensor $S_{mi\nu}$ run up to d , but the third index ν runs up to d^2 . We shall distinguish these types of indices by a Greek letter label, and graphically depict them as thick legs [Fig. 1(a) center]. To see that such a rewiring is possible, let us introduce composite indices $\alpha \equiv (m, i)$ and $\beta \equiv (j, l)$, and write the tensor contraction on the left-hand side of Eq. (2) as a $d^2 \times d^2$ matrix $M_{\alpha\beta} \equiv \sum_k T_{ijk} T_{klm}$. Then Eq. (2) becomes

$$M_{\alpha\beta} = \sum_{\nu} S_{\alpha\nu} S_{\beta\nu}, \quad (3)$$

or $M = SS^T$. We can find S using the fact that $M = M^T$, as can be checked using the cyclical symmetry of the T tensors. Any symmetric matrix M admits a variant of singular value decomposition known as Takagi factorization [10]: $M = U\Sigma U^T$, where U is a $d^2 \times d^2$ unitary square matrix and Σ is a $d^2 \times d^2$ diagonal matrix containing the singular values of M . If $\Sigma_{\nu\nu}$ is the ν th singular value (assumed ordered from largest to smallest with increasing ν), then the elements of S are given by $S_{\alpha\nu} = \sqrt{\Sigma_{\nu\nu}} U_{\alpha\nu}$. The resulting decomposition $M = SS^T$ is not unique, because we can replace S by SO , where O is a complex orthogonal matrix ($OO^T = I$). However, we shall always use the S given directly by the Takagi factorization, so if the ν th singular value $\Sigma_{\nu\nu}$ is nondegenerate, the ν th column of S is uniquely determined up to a factor of ± 1 . The rewiring procedure described above is applied globally to the entire hexagonal lattice as shown by the first arrow in Fig. 1(d), grouping the T tensors into pairs, and replacing each pair by S tensors.

Decimation: The second step in the renormalization procedure consists of tracing over the degrees of freedom in the triangular clusters that are formed after the rewiring. As illustrated in Fig. 1(c), each such cluster can be replaced by a single renormalized tensor T' ,

$$\sum_{m,i,h=1}^d S_{hm\gamma} S_{mi\nu} S_{ih\delta} = T'_{\gamma\delta\nu}. \quad (4)$$

Introducing the notation $S^{(\gamma)}$ for the $d \times d$ matrix with elements $S_{hm\gamma}$ at fixed γ , then the above equation has the form

$$\text{Tr}[S^{(\gamma)} S^{(\nu)} S^{(\delta)}] = T'_{\gamma\delta\nu}. \quad (5)$$

It is clear from Eq. (5) that the renormalized tensor will be cyclically symmetric. Since the S tensor is constructed from the unitary matrix U , the elements of T' will in general be complex. The second arrow of Fig. 1(d) shows the decimation applied to every triangular cluster, and the result is a hexagonal lattice of T' tensors with the lattice spacing larger by a factor of $b = \sqrt{3}$ compared to the original hexagonal lattice.

The renormalization-group transformation described so far is an exact mapping of one tensor network onto another, preserving the partition function Z . However, the

renormalized tensors have a more complicated structure than the original ones, since the indices of $T'_{\gamma\delta\nu}$ run up to d^2 . If this procedure is repeated, the index range grows exponentially with iteration number, making numerical implementation impractical. This is analogous to the difficulty encountered when applying naive position-space renormalization to Hamiltonians on lattices, where the number of couplings in the Hamiltonian grows with each iteration. Some kind of approximate truncation is required to keep the complexity of the renormalized model bounded. In our case this truncation can be done in a straightforward and systematic fashion by setting an upper bound D for the index range. Rather than use the full $d^2 \times d^2$ matrix $S_{\alpha\nu}$ to calculate T' , we use only the first \bar{d} columns, where $\bar{d} \equiv \min(d^2, D)$. Using this truncated $d^2 \times \bar{d}$ matrix, which we call \bar{S} , means that the rewiring step is implemented only approximately, $M \approx \bar{S}\bar{S}^T$. However, this is the best approximation possible, since the first \bar{d} columns of S correspond to the \bar{d} largest singular values of M . The decimation step of Eq. (4) is still carried out exactly, but with S replaced by \bar{S} . The resulting tensor $T'_{\gamma\delta\nu}$ has indices that run up to \bar{d} .

III. RENORMALIZATION-GROUP FLOWS AND THERMODYNAMIC BEHAVIOR OF THE TRIANGULAR LATTICE ISING MODEL

In order to illustrate the nature of the renormalization-group flows resulting from the transformation outlined above and the methods by which thermodynamic information can be extracted from them, we turn now to a specific example: the triangular lattice ferromagnetic Ising model. This model is mapped onto a tensor network through a duality transformation, giving an equivalent partition function in terms of bond variables on a hexagonal lattice.[1] Each bond in this dual lattice has two states, $\sigma_1 = 1$ or $\sigma_2 = -1$, corresponding to a bond between parallel or antiparallel Ising spins. These states respectively contribute energies $-J < 0$ and J to the total Hamiltonian \mathcal{H} . The tensor for each lattice site has the form

$$T_{ijk} = e^{\frac{\beta J}{2}(\sigma_i + \sigma_j + \sigma_k)} \frac{1}{2}(\sigma_i \sigma_j \sigma_k + 1), \quad (6)$$

where $\beta = 1/k_B T$, and the factor multiplying the exponential is a projection operator that is equal to 1 for allowed configurations of the bonds and 0 otherwise. For simplicity we set $J/k_B = 1$, effectively measuring temperatures in units of J/k_B . If the triangular lattice has N sites, the dual hexagonal lattice has $2N$ sites, and the partition function is a contraction of the $2N$ site tensors.

Iterating the renormalization-group transformation, we consider renormalization-group flows in the space of tensor element amplitudes $|T_{\alpha\beta\gamma}|$. For a cyclically symmetric tensor T_{ijk} with index range d , the maximum number of distinct elements is $d(2 + d^2)/3$. After the first few iterations, the index range of the renormalized

tensors reaches the cutoff D and remains there, so that the flows in the subsequent steps are in a space with dimension $D(2 + D^2)/3$. In this work we look at cutoffs in the range $D = 4$ to 24 , so the most complex flow space that we investigate is 4624-dimensional. A large number of the $D(2 + D^2)/3$ tensor elements are zero, corresponding to disallowed bond configurations, typically making up between 50-55% of the total in the later steps. The locations of the zero elements usually stay the same for a few steps at a time, but can shift abruptly during the flow. To minimize roundoff errors which can affect the results at later iterations, the singular value decomposition and matrix manipulations involved in TRG are all implemented at quadruple precision, using a customized version of the LAPACK library [11].

Due to the contraction during the decimation step, the tensor elements tend to increase in magnitude rapidly with each iteration, which can lead to numerical problems. These are avoided similarly to the procedure used in global strong-coupling flows in position-space renormalization-group theory. The physics described by the tensor network is unaffected by an overall constant multiplying each element in the tensor. Thus at each step we factor out the absolute value of a nonzero element, for example $T = |T_{111}|\tilde{T}$, yielding a reduced tensor \tilde{T} . The T_{111} element is a convenient choice, since it remains nonzero throughout the renormalization-group flow. The renormalization-group transformation is then applied to the reduced tensor \tilde{T} , giving a renormalized tensor T' . Let us denote T as $T^{(0)}$ and T' as $T^{(1)}$. The factorization and renormalization-group transformation are iterated, so at the n th step we have a tensor $T^{(n)} = |T_{111}^{(n)}|\tilde{T}^{(n)}$. As we shall see below, with this added factorization step the elements of $T^{(n)}$ tend to finite limiting values as $n \rightarrow \infty$.

Additionally, keeping track of the factors $|T_{111}^{(n)}|$ during the flow, as in standard position-space renormalization-group theory, allows us to easily determine the free energy of the system in the thermodynamic limit.[12] Defining $G^{(n)} \equiv \ln |T_{111}^{(n)}|$, the partition function is a contraction of $2N$ tensors $T^{(0)}$, which we write schematically as $Z = (T^{(0)})^{2N} = e^{2NG^{(0)}}(\tilde{T}^{(0)})^{2N}$. After a single renormalization-group step, this becomes $Z = e^{2NG^{(0)}}(T^{(1)})^{2N/3} = e^{2N(G^{(0)} + G^{(1)}/3)}(\tilde{T}^{(1)})^{2N/3}$. Thus after n steps we find

$$Z = e^{2N \sum_{i=0}^n 3^{-i} G^{(i)}} \left(\tilde{T}^{(n)} \right)^{2N/3^n}. \quad (7)$$

The free energy per original site $\beta f = -N^{-1} \ln Z$ is then

$$\beta f = -2 \sum_{i=0}^n 3^{-i} G^{(i)} - \frac{1}{N} \ln \left(\tilde{T}^{(n)} \right)^{2N/3^n}. \quad (8)$$

As $n \rightarrow \infty$ the elements of $\tilde{T}^{(n)}$ go to finite fixed values, and thus for large N the second term on the right in Eq. (8) becomes negligible. So the final result for the free energy is $\beta f = -2 \sum_{i=0}^{\infty} 3^{-i} G^{(i)}$. In practice the transformation is iterated for n steps until the value

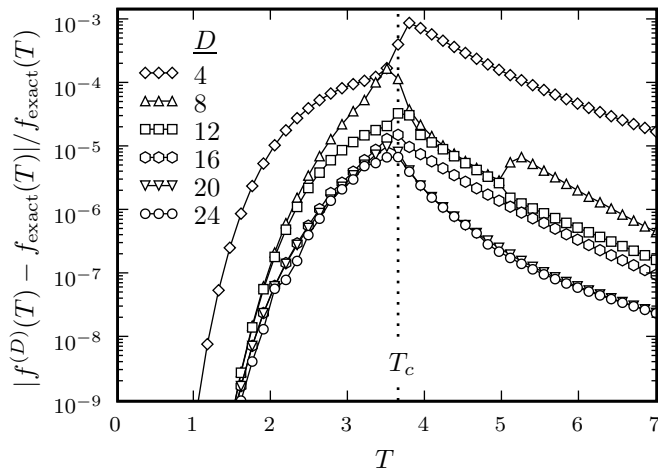


FIG. 2: The relative error of $f^{(D)}(T)$, the free energy per site of the triangular lattice Ising model calculated using TRG at various cutoffs $D = 4$ to 24 , compared to the exact free energy $f_{\text{exact}}(T)$, as a function of temperature T . The dotted line shows the exact critical temperature $T_c = 4/\ln 3$.

of $G^{(n)}$ has converged to the limit $G^{(\infty)}$ within the desired numerical precision. Then $\beta f \approx -2 \sum_{i=0}^{n-1} 3^{-i} G^{(i)} - 2G^{(n)} \sum_{i=n}^{\infty} 3^{-i} = -2 \sum_{i=0}^{n-1} 3^{-i} G^{(i)} - 3^{1-n} G^{(n)}$.

Even for small cutoffs D , the results of this free energy calculation can be remarkably accurate, as seen in Fig. 2, which shows the relative error of $f^{(D)}(T)$, the free energy per site using cutoff D , compared to the exact value $f_{\text{exact}}(T)$. The latter is calculated by numerical evaluation of the integral solution in Ref. [13]. Already at $D = 4$ the TRG free energy is within 0.09% of the exact value at all temperatures, and is considerably more accurate than this away from the critical region near $T_c = 4/\ln 3$. As noted in Ref. [1], the TRG method is expected to behave worst at criticality, and this is indeed what we see for all D , with the relative error curves peaked near T_c . Yet even here there is significant improvement as we go to larger cutoffs. At $D = 24$, the largest cutoff examined, the maximum error is 0.0007%. Overall, going from $D = 4$ to $D = 24$ we get an improvement between two and three orders of magnitude in the precision of the free energy result.

Further thermodynamic information can be gleaned by looking in detail at the behavior of the renormalization-group flows. The elements $|T_{ijk}^{(n)}|$ go to finite fixed values $|T_{ijk}^*|$ as $n \rightarrow \infty$, but unlike typical position-space renormalization-group transformations, there are no unique fixed points which act as a basins of attraction for the low- and high-temperature phases. Instead, at each different temperature T the system flows to a different fixed point $|T_{ijk}^*(T)|$. However there is a way to distinguish the low- and high-temperature phases, since each flows to a different continuous surface of fixed points in the space of tensor elements. There is a boundary temperature $T_c^{(D)}$, depending on the cutoff D , such that for $T > T_c^{(D)}$ the flows tend to one fixed surface, while for

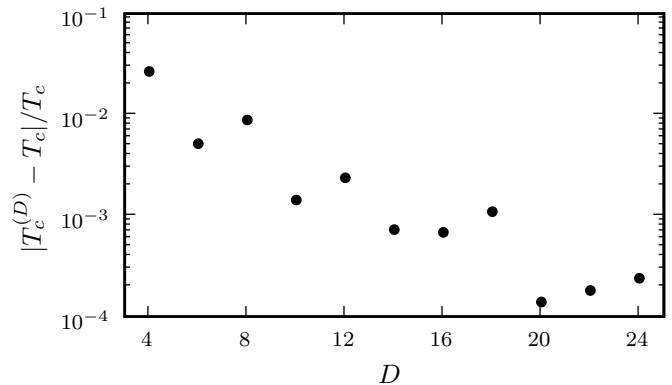


FIG. 3: The relative error of the critical temperature $T_c^{(D)}$ for the triangular lattice Ising model calculated from TRG flows at various cutoffs $D = 4$ to 24 , compared to the exact $T_c = 4/\ln 3$.

$T < T_c^{(D)}$ they tend to the other. As D becomes larger, $T_c^{(D)}$ gives a rapidly converging estimate of the exact critical temperature $T_c = 4/\ln 3$. Fig. 3 shows the relative error of $T_c^{(D)}$ compared to T_c for various D . While the decrease in error is not monotonic with D , there is an overall trend which appears to be roughly exponential in the cutoff, so that the error at $D = 24$, 0.02%, is two orders of magnitude smaller than at $D = 4$.

This segregation of the flows between two distinct fixed surfaces can be seen directly in Fig. 4, which plots one tensor element $|T_{111}^{(n)}|$ as a function of iteration number n for $D = 8$ and $D = 12$. The flows are shown for different values of $|\Delta T| = |T - T_c^{(D)}|$, from 10^{-2} to 10^{-10} . There are two curves for each $|\Delta T|$, one corresponding to $T > T_c^{(D)}$, and the other to $T < T_c^{(D)}$. The two curves stay close to one another for a number of iterations, but then veer off in opposite directions and reach different fixed values $|T_{111}^*|$. These fixed values change continuously as $|\Delta T|$ is varied, as they map out a slice of the two fixed surfaces corresponding to the low- and high-temperature phases.

As $|\Delta T|$ gets smaller, there is an interesting difference in the flow behaviors of the $D = 8$ and $D = 12$ cases. For $D = 8$, as seen in Fig. 4(a) and in more detail in Fig. 4(b), the $\Delta T > 0$ and $\Delta T < 0$ curves are nearly horizontal before turning away to their respective fixed surfaces. This is true in fact for all the $|T_{\alpha\beta\gamma}|$ elements, since the flows are attracted to a unique critical fixed point, which we denote $|T_{\alpha\beta\gamma}^{c*}|$. The smaller the value of $|\Delta T|$, the larger the number of iterations which are spent in the vicinity of $|T_{\alpha\beta\gamma}^{c*}|$ before flowing to one of the fixed surfaces. Once we are in the vicinity of the critical fixed point, we can isolate it to high precision using a Newton-Raphson procedure. The analysis of the fixed point proceeds just as in a standard renormalization-group approach: we calculate a recursion matrix, whose eigenvalues can be related to the critical exponents of the system. To do this, let us denote the nonzero elements of

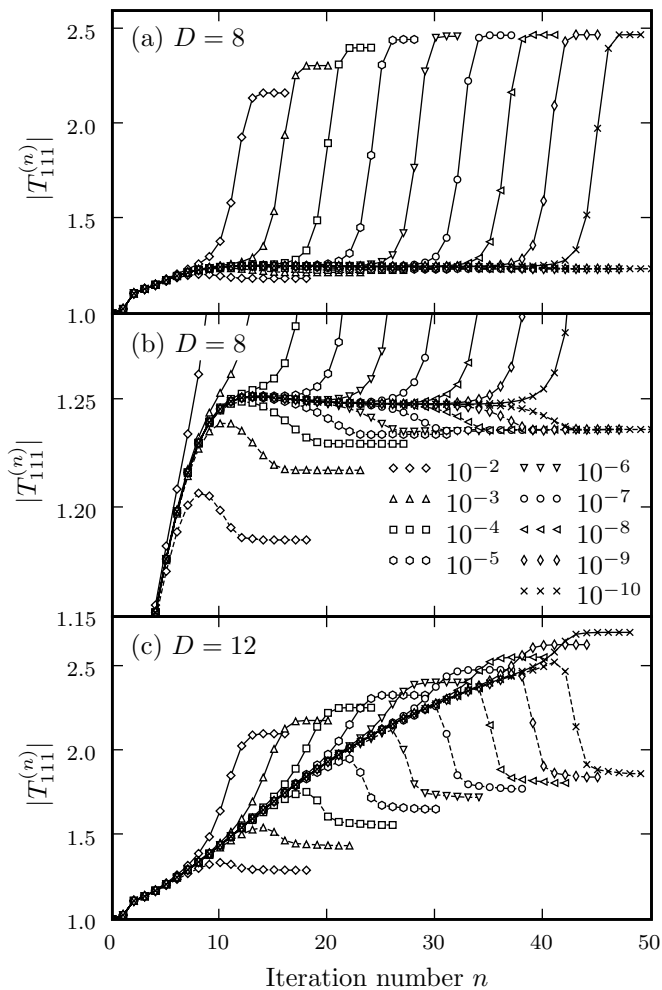


FIG. 4: The behavior of tensor element $|T_{111}^{(n)}|$ as a function of iteration number n . The different data sets correspond to flows at different temperatures T near $T_c^{(D)}$, with each symbol in the legend corresponding to a value of $|\Delta T| = |T - T_c^{(D)}|$ between 10^{-2} and 10^{-10} . For each $|\Delta T|$ there are two data sets, one for $\Delta T > 0$ connected by solid lines, and the other for $\Delta T < 0$ connected by dashed lines. For clarity, the flows are only shown up to the iteration where they have approximately converged to a fixed value. (a) $|T_{111}^{(n)}|$ flows with cutoff $D = 8$. (b) Same as in (a), but zoomed in to see more clearly the flows for $\Delta T < 0$. (c) $|T_{111}^{(n)}|$ flows with cutoff $D = 12$.

$|T_{\alpha\beta\gamma}^{c*}|$, not related by cyclical symmetry, as K_1 through K_m . In the case of $D = 8$, $m = 80$. For small perturbations away from the critical fixed point, the number and locations of these nonzero elements stay the same after a renormalization-group transformation, which allows us to numerically evaluate the $m \times m$ recursion matrix $R_{ij} \equiv \partial K'_i / \partial K_j$. Writing the eigenvalues of R in the form b^{y_i} , $i = 1, \dots, m$, we find only one eigenvalue where $y_i > 0$, as expected at a critical fixed point. This relevant eigenvalue, which we denote y_T , is related to the specific heat critical exponent α by $\alpha = (2y_T - 2)/y_T$. For $D = 8$, $y_T = 1.01543$, giving $\alpha = 0.03039$, which

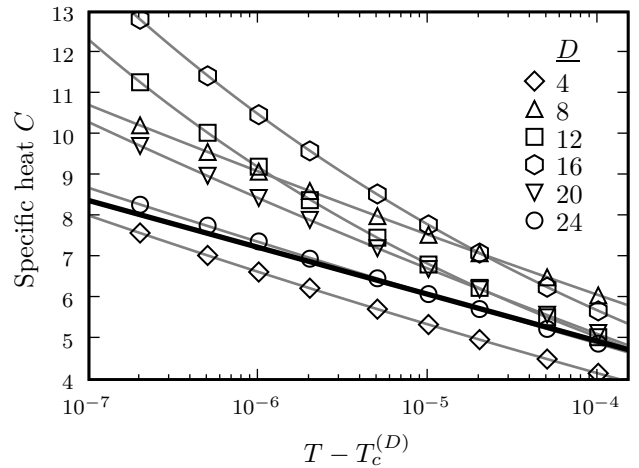


FIG. 5: Specific heat per site C of the triangular lattice Ising model, calculated using TRG for various cutoffs $D = 4$ to 24 as a function of $T - T_c^{(D)}$ in the high-temperature phase near criticality. The gray curves superimposed on the data points are best-fit curves of the form $A + B(T - T_c^{(D)})^{-\alpha}$, with parameters A , B , and α . The thick black line is the exact specific heat as a function of $T - T_c$.

D	$T_c^{(D)}$	$T_c^{(D)} - T_c$	y_T
4	3.73840	9.7×10^{-2}	1.01543
8	3.60873	-3.2×10^{-2}	1.01543
12	3.64958	8.6×10^{-3}	1.0644 ± 0.0048
16	3.63847	-2.5×10^{-3}	1.0574 ± 0.0022
20	3.64147	5.1×10^{-4}	1.0165 ± 0.0032
24	3.64183	8.7×10^{-4}	1.0089 ± 0.0075
exact	3.64096	—	1

TABLE I: Critical properties calculated using the TRG approach, at various cutoffs D , compared to the exact values in the last row. The thermal eigenvalues y_T for $D = 4$ and 8 are calculated from the recursion matrix evaluated at the critical fixed point. For $D > 8$ the estimate for y_T is from the best-fit result to the specific heat near $T_c^{(D)}$, as plotted in Fig. 5.

compare well to the exact values of $y_T = 1$ and $\alpha = 0$. We can check this result using an alternative approach, by calculating the specific heat from derivatives of the calculated free energy for small $T - T_c^{(D)}$, and we find that the singularity in the specific heat agrees with the α derived from the thermal eigenvalue y_T of the recursion matrix.

For the six values of the cutoff D where we investigated the near-critical flows in detail, $D = 4, 8, 12, 16, 20, 24$, we were able to isolate the critical fixed point for $D = 4$ and 8, namely in 24- and 196-dimensional flow spaces. Despite the different dimensionalities of the flow spaces, both cases yielded the same eigenvalue y_T , within the precision of 5 decimal places. Higher values of D showed very different flow behaviors, as exemplified in Fig. 4(c) for $D = 12$. Here the $\Delta T > 0$ and $\Delta T < 0$ curves for $|T_{111}^{(n)}|$ do not stay nearly horizontal before diverging

to the fixed surfaces: regardless of how small $|\Delta T|$ is made, the flows do not gravitate toward a unique critical fixed point, but map out a continuous spectrum of points which attract the flows before the two curves spread out. Using an arbitrary precision version of the TRG algorithm implemented in *Mathematica*, we checked $|\Delta T|$ values as small as 10^{-43} without finding convergence toward a critical fixed point. Nevertheless, in these cases for $D > 8$ we can still extract the critical behavior, by resorting to the alternative approach mentioned earlier: looking directly at the specific heat C per site near $T_c^{(D)}$ as obtained from the numerical derivative of the calculated free energy. We plot C within the high-temperature phase for various D in Fig. 5, for $T - T_c^{(D)}$ between 10^{-7} and 10^{-4} . For each D the data points are fit to a function $A + B(T - T_c^{(D)})^{-\alpha}$, which provides an accurate description of the singularity, and the best-fit value of α is used to determine the thermal eigenvalue y_T . The results are listed in Table I. For $D = 12$, $y_T = 1.0644 \pm 0.0048$, worse than our fixed-point determined values at $D = 4$ or 8 , but this value improves as D is increased, reaching $y_T = 1.0089 \pm 0.0075$ at $D = 24$. Moreover, as seen in Fig. 5, our calculated C curve for $D = 24$ nearly overlaps the exact C as a function of $T - T_c$, which diverges with a logarithmic singularity at the critical point.

IV. CONCLUSION

In summary, we have seen that the flows of the tensor elements in the TRG transformation can be used to extract the phase diagram structure and critical behavior of a classical two-dimensional lattice Hamiltonian. For

the triangular lattice Ising model, the low- and high-temperature phase regions are basins of attraction for two distinct surfaces of fixed points. The boundary between these basins defines a critical temperature $T_c^{(D)}$, dependent on the TRG cutoff D . At small cutoffs such as $D = 4$ and 8 , the flows near the boundary between the basins are controlled by a critical fixed point, while at higher D the flows show more complicated behavior, never converging at a unique point. In the former case the thermal exponent y_T is found from the eigenvalues of the recursion matrix at the critical fixed point, while in the latter we can deduce the exponent from the scaling of the calculated specific heat near $T_c^{(D)}$. The free energy at all temperatures systematically converges to the exact Ising result with increasing D , particularly fast away from the critical region. For the critical properties the improvement is not monotonic in D , but both the critical temperature $T_c^{(D)}$ and the exponent y_T tend toward the exact Ising values at larger cutoffs. With very modest computational effort, the TRG method provides an accurate portrait of global phase diagram characteristics. It thus warrants further study, both on applications to other two-dimensional lattice models, and possible generalization to systems with quenched randomness [14] and/or higher spatial dimensions.

Acknowledgments

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