

Recap:

- Requiring that the geometry of 4-vectors in spacetime be invariant to their representation yields rules for how their components and their unit vectors transform:

$$\vec{v} = \sum_{\alpha=0}^3 v^{\alpha} \vec{e}_{\alpha} = \sum_{\mu'=0}^3 v^{\mu'} \vec{e}_{\mu'}$$

$$v^{\mu'} = \sum_{\alpha=0}^3 \Lambda^{\mu'}_{\alpha} v^{\alpha}$$

$$\vec{e}_{\mu'} = \sum_{\alpha=0}^3 \Lambda^{\alpha}_{\mu'} \vec{e}_{\alpha}$$

$\Lambda^{\mu'}_{\alpha}$  = Element of Lorentz transformation matrix that goes from unprimed frame to primed frame. Row  $\mu'$ , column  $\alpha$ .

$\Lambda^{\alpha}_{\mu'}$  = Element of matrix for the Lorentz transformation that inverts the previous one.

General rule: We go from the coordinates of the bottom index to the coordinates of the top index.

Mathematical expression of inverseness:

$$\sum_{\mu'=0}^3 \Lambda^{\alpha}_{\mu'} \Lambda^{\mu'}_{\beta} = \delta^{\alpha}_{\beta}$$

$$\sum_{\alpha=0}^3 \Lambda^{\mu'}_{\alpha} \Lambda^{\alpha}_{\nu'} = \delta^{\mu'}_{\nu'}$$

## Velocity addition rules in special relativity

Observer in frame T sees something move with velocity  $\underline{u}_T$  in that frame.

Frame T moves with  $\underline{v} = v \underline{e}_x$  relative to frame S. What is the velocity  $\underline{u}_S$ ?

$$u_S^x = \frac{u_T^x + v}{1 + u_T^x v / c^2}$$

$$u_S^y = \frac{u_T^y}{\gamma (1 + u_T^x v / c^2)}$$

$$u_S^z = \frac{u_T^z}{\gamma (1 + u_T^x v / c^2)}$$

$$\gamma = (1 - v^2 / c^2)^{-1/2}$$

If velocity gets messed up, momentum will get messed up too. Begin an analysis by carefully laying out how things work in Newtonian mechanics.

Imagine we have  $N_i$  bodies that come together in some fashion ( $i$  for "initial"), and we end up with  $N_f$  bodies at the end. Conservation of momentum tells us

$$\sum_{i=1}^{N_i} m_i^{initial} \underline{u}_i^{initial} = \sum_{i=1}^{N_f} m_i^{final} \underline{u}_i^{final}$$

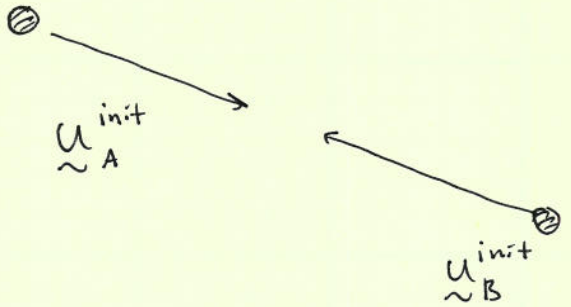
As long as  $\sum_{i=1}^{N_i} m_i^{initial} = \sum_{i=1}^{N_f} m_i^{final}$ , this relation holds in all Galilean inertial reference frames.

Does this work when we go from Galilean frames to Lorentz frames? Yes... but we have to make some modifications.

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To see why, consider an elastic collision between 2 identical particles.

Before collision:

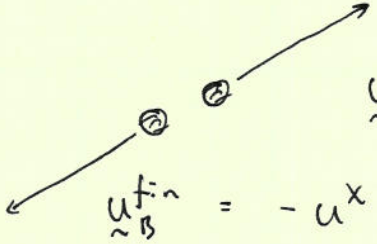


$$m_a = m_b \equiv m$$

$$\vec{u}_A^{init} = u^x \underline{e}_x - u^y \underline{e}_y$$

$$\vec{u}_B^{init} = -u^x \underline{e}_x + u^y \underline{e}_y$$

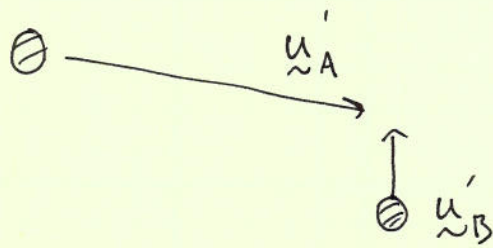
After:



$$\vec{u}_A^{fin} = u^x \underline{e}_x + u^y \underline{e}_y$$

$$\vec{u}_B^{fin} = -u^x \underline{e}_x - u^y \underline{e}_y$$

Now, examine this situation from the frame that cancels out the horizontal motion of B:



An observer at rest in the first frame we used will see that this frame moves with  $\underline{v} = -u^x \underline{e}_x$ .

What are the velocity vectors in this frame? Use our new velocity addition formula to find it:

$$u_A^{x'} = \frac{u^x + u^x}{1 + (u^x)^2/c^2}$$

$$u_B^{x'} = \frac{u^x - u^x}{1 - (u^x)^2/c^2} = 0$$

} Horizontal momentum no longer balances... but we don't expect it to after changing frames.

$$u_A^{y'} = \frac{-u^y}{\gamma(1 + (u^x)^2/c^2)} = -\frac{u^y \sqrt{1 - (u^x)^2/c^2}}{1 + (u^x)^2/c^2}$$

$$u_B^{y'} = \frac{u^y}{\gamma(1 - (u^x)^2/c^2)} = \frac{+u^y}{\sqrt{1 - (u^x)^2/c^2}}$$

→ Notice that vertical components no longer balance: Changing to a frame that moves along the x-direction has broken conservation of momentum along the vertical direction.

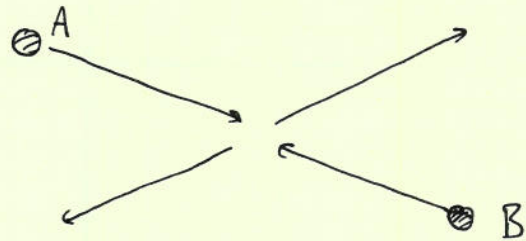
→ This is disturbing!

Hypothesis: We can define a modified version of momentum which allows us to recover a useful notion of momentum conservation.

Let us postulate that  $\underline{p} = \alpha(|\underline{u}|) m \underline{u}$

Scalar correction to "normal" momentum law.

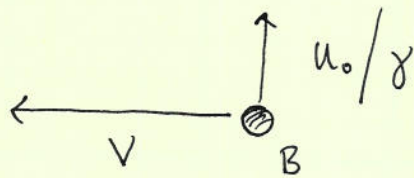
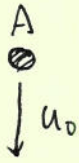
Re-examine the collision:



In particular, we'll now analyze this in "Frame A," the Lorentz frame in which body A has no velocity in the x-direction. We will also consider "Frame B," the Lorentz frame in which body B has no velocity along x.

Physics: The bodies have the same "mass." (I.e., when at rest, they each have mass  $m$ .) In Frame A, the magnitude of particle A's velocity is  $u_0$ ; in Frame B, the magnitude of B's velocity is  $u_0$ .

Examine collision in Frame A. Before collision:

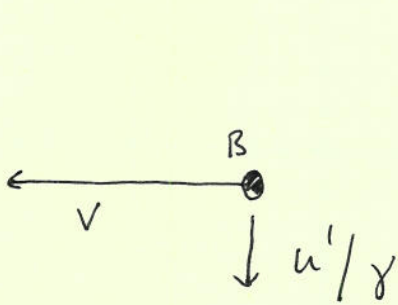


$$\gamma = (1 - v^2/c^2)^{-1/2}$$

$v$  is the result for B's horizontal component after we transform into Frame A.

Why  $u_0/\gamma$  for the vertical component of B's velocity? In frame B, the vertical component of B is  $u_0$ . Use velocity addition formula to change to Frame A - get  $u_0/\gamma$ .

After collision in Frame A:



Logic here: The horizontal speed cannot be affected, so it remains  $v$ . The vertical speed might be affected, and the vertical direction must reverse.

Impose conservation of horizontal momentum:

$$\alpha (\sqrt{v^2 + (u_0/\gamma)^2}) m v = \alpha (\sqrt{v^2 + (u'/\gamma)^2}) m v$$

→ Only true if  $u_0 = u'$ :  $y$ -components only switch direction, no change in magnitude.

Now, require  $y$ -component to be conserved:

$$\begin{aligned}
 & -\alpha(u_0) m u_0 + \alpha\left(\sqrt{v^2 + u_0^2 / \gamma^2}\right) m u_0 / \gamma \\
 & = \alpha(u_0) m u_0 - \alpha\left(\sqrt{v^2 + u_0^2 / \gamma^2}\right) m u_0 / \gamma \\
 & \rightarrow \alpha\left(\sqrt{v^2 + u_0^2 / \gamma^2}\right) = \gamma \alpha(u_0)
 \end{aligned}$$

Let's assume  $\alpha(0) = 1$ . This means that our formula reduces to "normal" momentum for small velocities. Then,

$$\alpha(v) = \gamma$$

and we obtain

$$\underline{p} = \gamma(v) m \underline{v}$$

This notion of momentum is conserved during interactions in special relativity.

Note: Some texts define  $m(\underline{v}) = \gamma m_0$  (where  $m_0$  is the "rest mass") as the "relativistic mass." This term is now deprecated; modern terminology leaves  $m$  as an invariant, and builds the relativistic stuff in elsewhere.



Energy: In Newtonian physics, the change in kinetic energy is the work done on a body:

$$\begin{aligned}
K_b - K_a &= \int_a^b \frac{d\underline{p}}{dt} \cdot d\underline{r} \\
&= \int_a^b \frac{d}{dt} (m\underline{u}) \cdot \underline{u} dt \\
&= \int_a^b m \underline{u} \cdot d\underline{u} \\
&= \frac{1}{2} m (u_b^2 - u_a^2)
\end{aligned}$$

Now, consider how it will look in relativity:

$$\begin{aligned}
K_b - K_a &= \int_a^b \frac{d}{dt} \left[ \gamma(u) m \underline{u} \right] \cdot \underline{u} dt \\
&= \int_a^b \underline{u} \cdot d \left[ \frac{m \underline{u}}{\sqrt{1 - u^2/c^2}} \right]
\end{aligned}$$

$$\underline{u} \cdot d \left[ \frac{\underline{u}}{\sqrt{1 - u^2/c^2}} \right] = d \left[ \frac{u^2}{\sqrt{1 - u^2/c^2}} \right] - \frac{\underline{u} \cdot d\underline{u}}{\sqrt{1 - u^2/c^2}}$$

So,

$$\begin{aligned}
K_b - K_a &= \frac{m u^2}{\sqrt{1 - u^2/c^2}} \Big|_a^b - \int_a^b \frac{m \underline{u} \cdot d\underline{u}}{\sqrt{1 - u^2/c^2}} \\
&= \frac{m u^2}{\sqrt{1 - u^2/c^2}} \Big|_a^b + m c^2 \sqrt{1 - \frac{u^2}{c^2}} \Big|_a^b
\end{aligned}$$

Define:  $\underline{u}(b) \equiv \underline{u}$ ,  $\underline{u}(a) = 0 \rightarrow K_a = 0$

$$\rightarrow K_b = K = \frac{mu^2}{\sqrt{1-u^2/c^2}} + mc^2 \sqrt{1-\frac{u^2}{c^2}} - mc^2$$

-or-

$$K = \frac{mc^2}{\sqrt{1-u^2/c^2}} - mc^2$$

$$= (\gamma(u) - 1) mc^2$$

Interpretation: Define

$$E = \gamma mc^2$$

as the total energy of a body, and let

$$E_0 = mc^2$$

be its "rest energy." The quantity  $K$  is then the "energy of motion" - i.e., the kinetic energy - associated with the body.